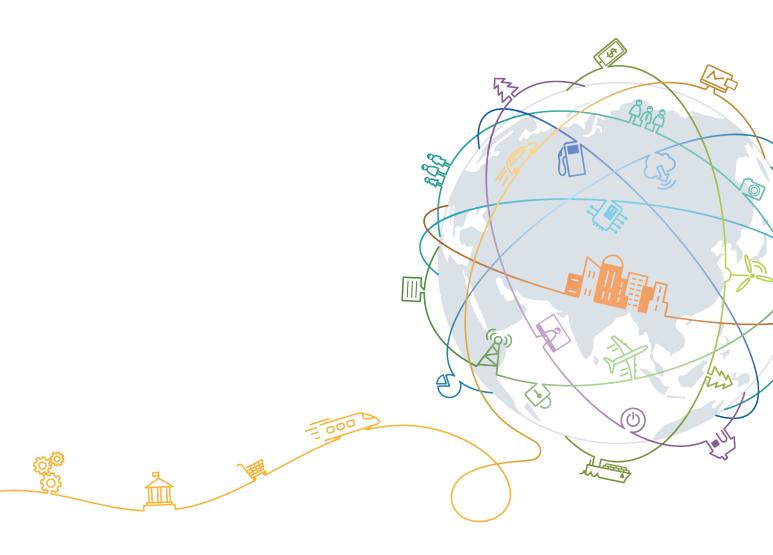
OpenStack FusionStorage Driver

Configuration Guide

Issue 01

Date 2019-06-06





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$oldsymbol{1}$ Overview

This chapter describes the definition of Cinder Driver.

Cinder Driver is a plug-in that is deployed on the OpenStack Cinder module. The plug-in can be used to provide functions such as the logical volume and snapshot for virtual machines (VMs) in OpenStack.

2 Version Mappings

This chapter describes the version mappings among Cinder Driver, FusionStorage, and OpenStack.

Version mapping between OpenStack and storage products

OpenStack Version	Storage Product Version
Rocky	FusionStorage V100R006C30
Stein	FusionStorage V100R008C00

You can query the version mapping table of eSDK plug-ins to obtain the storage system versions. To obtain the version mapping table, log in to http://support.huawei.com/ enterprise/en/index.html. In the search box, enter eSDK Cloud Storage Plugins to search for and download the eSDK Cloud Storage Plugins x.x.xxx Version Mapping. x.x.xxx indicates the version number.

Mappings among Cinder Driver, features, and the OpenStack version (\checkmark : supported, x: not supported)

Feature	Rocky
Create Volume	✓
Delete Volume	✓
Attach Volume	✓
Detach Volume	✓
Extend Volume	✓
Create Snapshot	✓
Delete Snapshot	1
Create Volume from Snapshot	1
Create Volume from Image	√

Feature	Rocky
Create Volume from Volume	√
Create Image from Volume	√
SmartThin	√
Manage/Unmanage Volume	√
Manage/Unmanage Snapshot	√
Multipath	√
QoS	X
Retype	X
Volume Migration	X
Auto zoning	X
SmartTier	X
SmartCache	X
SmartThick	X
SmartPartition	X
HyperMetro	X
Replication V2.1	X
HyperMetro Consistency Group	X
Backup Snapshot	X
Snapshot Consistency Group	X
Consistency Group	X

3 Deployment

To obtain the operating systems supported by FusionStorage Block 6.3, access http://support-open.huawei.com/en/, choose Interoperability Center > Storage Interoperability, set Storage System to FusionStorage and Storage Service Type to Block, and select the desired operating system. The following uses Red Hat as an example to describe how to deploy Cinder Driver.

- 3.1 Obtaining Cinder Driver
- 3.2 Deploying FusionStorage Driver for the Cinder Volume Service in Non-Containerized Mode
- 3.3 Deploying FusionStorage Driver for the Cinder Volume Service in Containerized Mode

3.1 Obtaining Cinder Driver

Two ways to obtain FusionStorage OpenStack Driver:

- OpenStack community warehouse. Since Rocky, Huawei has contributed Huawei Storage Driver to OpenStack, so that users can download FusionStorage OpenStack Driver from the OpenStack community for free. After installing the specified OpenStack version, FusionStorage OpenStack Driver will be placed under directory ../cinder/cinder/volume/drivers/fusionstorage. If you cannot find the corresponding installation files, you can download FusionStorage OpenStack Driver from the OpenStack community warehouse at https://github.com/openstack/cinder.
- Huawei OpenStack Driver warehouse. By visiting https://github.com/Huawei/ FusionStorage_OpenStack_Driver, you can download FusionStorage OpenStack Driver that corresponds to OpenStack community version.

3.2 Deploying FusionStorage Driver for the Cinder Volume Service in Non-Containerized Mode

Red Hat OpenStack deployment steps are as follows:

Step 1 Before installation, delete all the installation files of Huawei OpenStack Driver. The default installation path is /usr/lib/python2.7/site-packages/cinder/volume/drivers/fusionstorage.

\square NOTE

On the host, the version of Python is 2.7. If another version is used, use the correct version number. You can obtain the Cinder Driver installation directory by running the following commands:

```
root@redhatL004:~# find / -name dsware.py
/usr/lib/python2.7/dist-packages/cinder/volume/drivers/fusionstorage/dsware.py
```

- **Step 2** Copy OpenStack Cinder Driver to the Cinder Driver installation directory.
- **Step 3** Make configuration by referring to **4 Configuring Basic Properties**.
- **Step 4** After configuration, restart the Cinder-Volume service by running the following command: systemctl restart openstack-cinder-volume.service
- **Step 5** Check the status of service restart by running the **cinder service-list** command. If **State** is **up**, the Cinder-Volume service has been restarted.

----End

3.3 Deploying FusionStorage Driver for the Cinder Volume Service in Containerized Mode

Step 1 (Optional) Run the **docker save** command to back up the Cinder Volume container image.

NOTE

To obtain the image version, run the docker image ls command.

Step 2 Run the following command to create temporary directory **build** in any directory and go to the created directory:

```
# mkdir ***/build;cd ***/build
```

Step 3 Run the following commands to copy the obtained FusionStorage Driver code files to the current directory:

```
# ls -1
-rw-rw-r-- 1 root root 1138 May 15 08:23 constants.py
-rw-rw-r-- 1 root root 22174 May 15 08:23 dsware.py
-rw-rw-r-- 1 root root 18880 May 15 08:23 fs_client.py
-rw-rw-r-- 1 root root 4799 May 15 08:23 fs_conf.py
-rw-rw-r-- 1 root root 14419 May 15 08:23 fs_flow.py
-rw-rw-r-- 1 root root 2988 May 15 08:23 fs_utils.py
-rw-rw-r-- 1 root root 0 May 15 08:23 __init__.py
```

Step 4 Create the **Dockerfile** file in the current directory and edit the following content:

```
FROM ***:***
COPY *.py /fusionstorage/cinder/driver/path/
```

NOTE

- Replace ***: *** with the name and version of the original Cinder Volume container image.
- Replace /fusionstorage/cinder/driver/path with the path of Huawei Driver in the container.

Step 5 Run the following command to build an image:

docker build -t ***:*** .

NOTE

Replace ***: *** with the name and version of the original Cinder Volume container image.

- **Step 6** Make configuration by referring to **4 Configuring Basic Properties**.
- **Step 7** Restart the Cinder Volume container.

----End

4 Configuring Basic Properties

This chapter describes how to configure the FusionStorage Cinder Driver.

- 4.1 Configuring a conf File
- 4.2 conf Configuration File Parameters
- 4.3 Configuring iSCSI Multipathing

4.1 Configuring a conf File

At the end of /etc/cinder/cinder.conf, configure the FusionStorage back end with DSWAREDriver. volume_driver indicates the loaded driver file, volume_backend_name indicates the name of the back end, each row of manager_ips indicates the name and IP address of an FSA host, dsware_rest_url indicates the IP address of an FSM, san_login and san_password are the login information of the FSM, and dsware_storage_pools indicates the storage pools name on the FSM. For details, see Table 4-1.

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Ensure that both the owner and user group of /etc/cinder/cinder.conf are cinder.

```
-rw-r--r- 1 cinder cinder 2839 Aug 29 15:29 cinder.conf
```

Step 1 Add the FusionStorage back end. Configure parameters for the back end according to Table 4-1.

NOTE

Once ISCSI mode is used, "volume_driver" needs to be configured as "cinder.volume.drivers.fusionstorage.dsware.DSWAREISCSIDriver"

[fusionstorage]

 $... \\ volume_driver = cinder.volume.drivers.fusionstorage.dsware.DSWAREISCSIDriver$

Step 2 In the [DEFAULT] section, configure the FusionStorage back end.

```
[DEFAULT]
...
enabled_backends = fusionstorage
```

----End

4.2 conf Configuration File Parameters

Table 4-1 Parameter description

Parameter	Description	Mandator y
volume_backend _name	Back end name of the default driver.	Yes
volume_driver	Default driver.	Yes
dsware_rest_url	URL and port number used by the Cinder node to access FusionStorage.	Yes
san_login	User name used by the Cinder node to access FusionStorage.	Yes
san_password	Password used by the Cinder node to access FusionStorage.	Yes
dsware_storage_ pools	Names of existing storage pools on FusionStorage.	Yes
manager_ips	Management host name and its corresponding IP address. ':' is preceded by a host name, and followed by the corresponding host IP address. Each IP host is separated using commas (,). Add spaces at the start of each row.	Yes when selecting SCSI mode
target_ips	Default IP address of the iSCSI target port IP(the FSA node IP configured with the service IP) provided for compute nodes by the storage device.	Yes when selecting iSCSI mode

4.3 Configuring iSCSI Multipathing

Step 1 Configure multiple IP addresses in the **target_ips** item of the Cinder Driver conf, and separate them with a comma (,).

```
[fusionstorage]
...
target_ips = x.x.x.x,y.y.y.y
```

Step 2 Enable multipathing for the OpenStack Nova module.

Add volume_use_multipath = True in [libvirt] of /etc/nova/nova.conf.

NOTE

If "/etc/nova/nova-cpu.conf" exists in the Nova Compute node, add "volume_use_multipath = True" to its [libvirt].

Step 3 Restart the nova-compute service.

----End