Introduction to the SysML v2 Language Graphical Notation

(2023-01-16)

This presentation uses the graphical notation to complement the textual syntax (i.e., notation) to represent a SysML model. The graphical notation is generated manually with Microsoft Visio.

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Agenda

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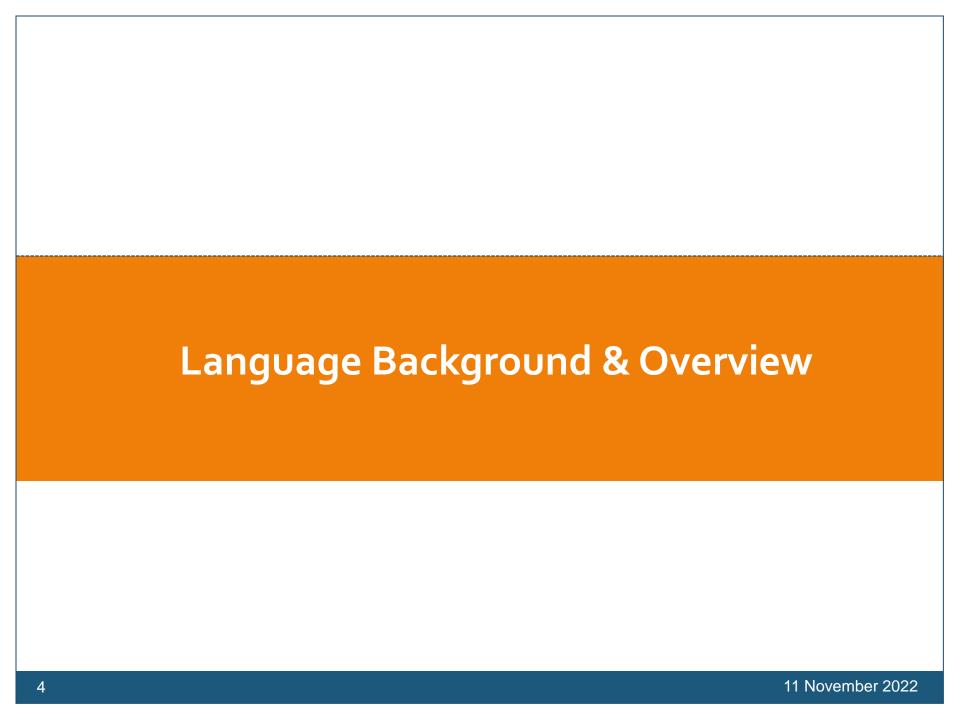
- Language Background and Overview
- SysML v2 Functional Areas
- Contrasting SysML v2 with SysML v1
- Summary

Refer to date in lower right on each slide to see when it was last modified



General Caveats

- The graphical and textual notation (i.e., syntax) are different renderings of the same model
 - The textual syntax is formally specified
 - O The graphical syntax is being formally specified using graphical BNF
 - O The graphical visualization in this presentation is captured in Visio
 - Two visualization prototypes are under development (Tom Sawyer and PlantUML)
- SysML v2 Marker
 - Some of the more significant SysML v2 changes in functionality and terminology relative to SysML v1 are designated with the SysML v2 marker **V2**





Systems Modeling Language™ (SysML®)

SST

Supports the specification, analysis, design, and verification and validation of complex systems that may include hardware, software, information, processes, personnel, and facilities

- SysML has evolved to address user and vendor needs
 - v1.0, adopted in 2006; v1.6, current version; v1.7, in process
- SysML has facilitated awareness and adoption of MBSE
- Much has been learned from using SysML for MBSE



SysML v2 Objectives

Increase adoption and effectiveness of MBSE by enhancing...

- Precision and expressiveness of the language
- Consistency and integration among language concepts
- Interoperability with other engineering models and tools
- Usability by model developers and consumers
- Extensibility to support domain specific applications
- Migration path for SysML v1 users and implementors

Key Elements of SysML v2

- New Metamodel that is not constrained by UML
 - O Preserves most of UML modeling capabilities with a focus on systems modeling
 - Grounded in formal semantics
- Robust visualizations based on flexible view & viewpoint specification
 - O Graphical, Tabular, Textual
- Standardized API to access the model



SysML v2 API & Services

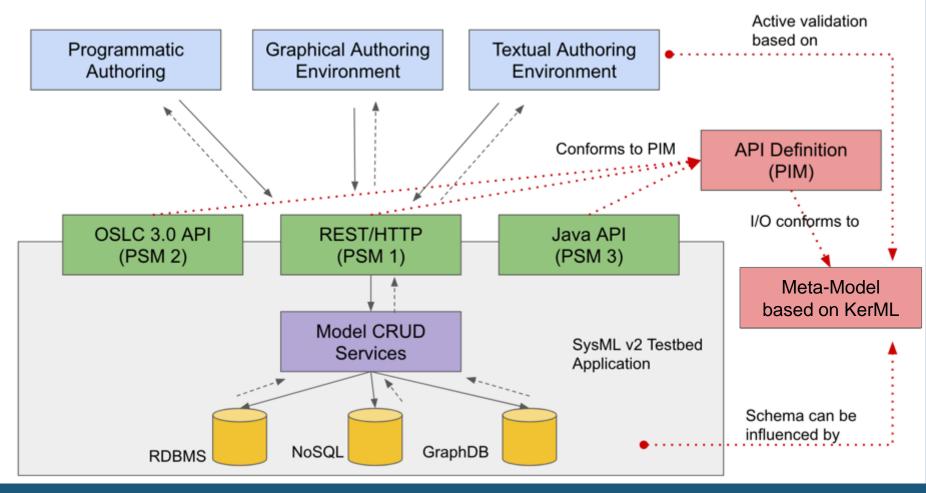
- Enables other tools and applications to access SysML models in a standard way
- Provides services to:
 - O Create, update, and delete elements
 - Query and navigate model
 - Other services including support for model management, analysis, transformation, and file export generation
- Supports common patterns called recipes (<u>GitHub Systems-Modeling/SysML-v2-API-Cookbook: Recipes for using the SysML v2 API</u>)
 - Navigating a decomposition tree
 - Creating a branch
 - Query with multiple constraints
- Facilitates use of different implementation technologies such as REST/HTTP,
 Java, or OSLC



Pilot Implementation Using Standard API

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High-Level Architecture of SysML v2 Testbed





SysML v2 Language Capabilities

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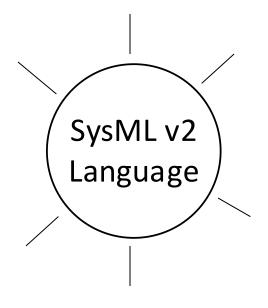
Requirements

Behavior

- function-based
- state-based
- sequence-based
- use cases

Structure

- decomposition
- interconnection
- classification



Analysis

- analysis cases
- expression language

Verification

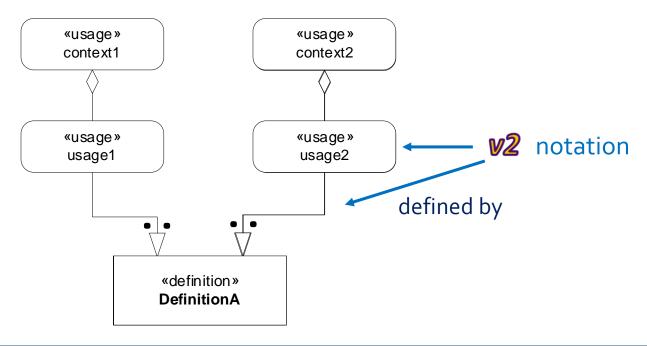
- verification cases

View & Viewpoint



Definition and Usage Reuse Pattern

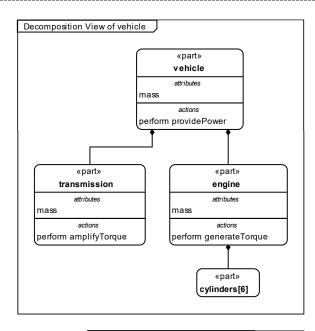
- A definition element defines an element such as a part, action, or requirement
- A usage element is a usage of a definition element in a particular context
 - There can be different usages of the same definition element in either different contexts or the same context
- Pattern is applied consistently throughout the language

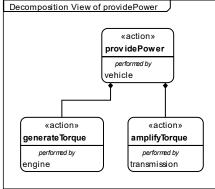




SysML v2 Notation (1 of 2) Textual and Graphical

```
package 'Vehicle Parts Tree' {
 part vehicle {
   attribute mass;
   perform providePower;
   part engine {
     attribute mass;
     perform providePower.generateTorque;
     part cylinders [6];
   part transmission {
     attribute mass;
     perform providePower.amplifyTorque;
 action providePower {
   action generateTorque;
   action amplifyTorque;
```





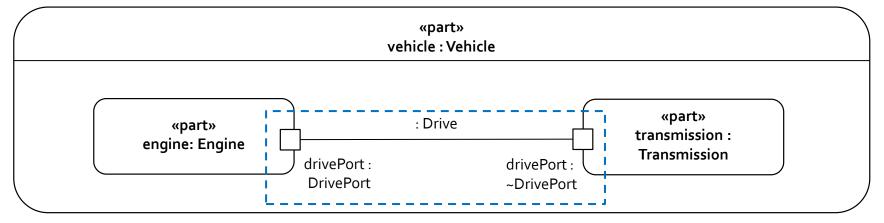


SysML v2 Notation (2 of 2) Textual and Graphical

```
interface def Drive {
    end enginePort : DrivePort;
    end transmissionPort : ~DrivePort;
}

part vehicle : Vehicle {
    part engine : Engine { port drivePort : DrivePort; }
    part transmission : Transmission { port drivePort : ~DrivePort; }

    interface : Drive
        connect engine.drivePort to transmission.drivePort;
}
```



Tom Sawyer Visualization Prototype



SysML v2 Spec (Clause 7) SysML v2 Language Description

| 7.2 Elements and Relationship |
|-------------------------------|
|-------------------------------|

- 7.3 Annotations
- 7.4 Namespaces and Packages
- 7.5 Dependencies
- 7.6 Definition and Usage
- 7.7 Attributes
- 7.8 Enumerations
- 7.9 Occurrences
- 7.10 Items
- **7.11** Parts
- 7.12 Ports
- 7.13 Connections

- 7.14 Interfaces
- 7.15 Allocations
- 7.16 Actions
- 7.17 States
- 7.18 Calculations
- 7.19 Constraints
- 7.20 Requirements
- **7.21** Cases
- 7.22 Analysis Cases
- 7.23 Verification Cases
- 7.24 Use Cases
- 7.25 Views and Viewpoints
- 7.26 Metadata (incl. Language Extension)

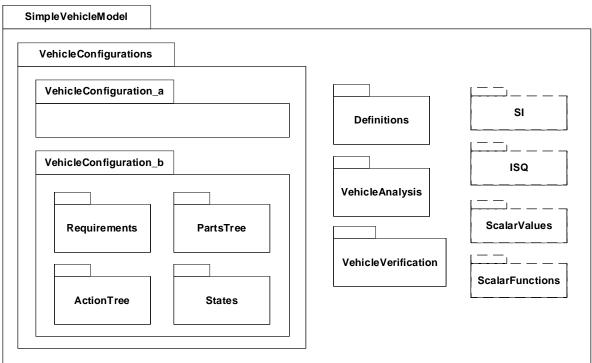
Module 1 Packages & Element Names 11 November 2022 16



Model Organization

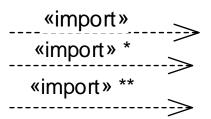


- A hierarchy of packages, where packages can contain other packages and elements
- Packages are namespaces that contain member elements that may be owned or unowned
- A package can import members of another package as unowned members, where deletion semantics do not apply, and they can be referred to by their local name
 - Nested import notation enables flexible organization



Import Notation

- no star is element import
- single star is package import (content of package)
- double star is recursive including outer package

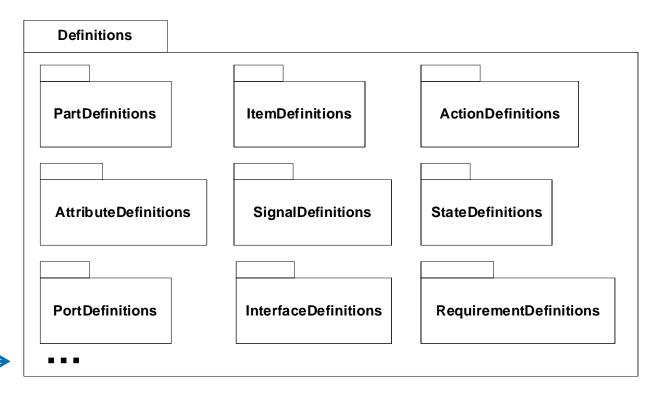


- Imports can apply to any namespace, but packages are most commonly used
- A package import can include filter criteria to select elements based on their metadata



Definitions Package

- Example: Definitions package contains packages to define different kinds of elements
 - Ellipsis indicates there is more content



Package Compartments

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- Packages can include textual compartments
- Filter can be applied to select element kinds **V2**

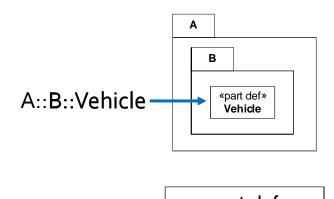
Part Definitions

members
part def Vehicle
part def Engine

. . .

Qualified Names

- A qualified name of a model element is prepended by the name of its owner followed by a double colon (::)
- A fully qualified name is prepended by the concatenated names of its owners in its containment hierarchy separated by double colons (::)



«part def» A::B::Vehicle



Element Names

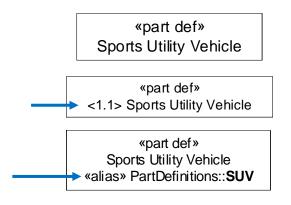
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- Each element includes a universally unique identifier (UUID) that is not visible
 - Managed by the tool
 - Does not change over the life of the element
- Each element can include a name
 - O Required for an element to be referenced in the textual notation
- Each element can optionally include a short name in angle brackets

V2

- O Can be a user or tool selected id
- An element can have one or more aliases in the context of a namespace

v2



«part def» «alias» SUV

«part def» alias SUV Note: reserved words can be shown in ('guillemet') or **bold**

Module 2 **Definition Elements** 23 11 November 2022

Part Definition

- A Part Definition can contain features such as attributes, ports, actions, and states
 - A modular unit of structure

«part def» Vehicle

attributes

mass:>ISQ::mass dryMass cargoMass electricalPower position velocity acceleration

. . .

ports
pwrCmdPort
vehicleToRoadPort

•••

perform actions providePower provideBraking controlDirection

• •

exhibit states vehicleStates



Other Kinds of Definition Elements



Terminology **V2**

- Each kind of definition element can contain specific kinds of features
 - Attribute definition
 - Data type that defines a set of data values
 - Primitive attribute definitions include integer, Real, Complex, Boolean, String,
 - Can include quantity kinds such as Torque with units
 - Can include complex data types such as vectors
 - Port definition
 - Defines a connection point on parts that enable interactions
 - Contain kinds of features including directed features with in, out, and in/out
 - Ports can be conjugated (i.e., reverse direction of directed features)
 - Item definition V2
 - Defines kind of entity that is acted on, such as an input, output or a stored item
 - Action definition
 - Defines kind of behavior that transforms inputs and outputs
 - State definition
 - Defines kind of behavior that responds to events
 - Enables entry, exit, and do actions

«state def» VehicleStates «action def» ProvidePower

parameters

out torqueToWheels:Torque [*]

in pwrCmd:PwrCmd

actions **do** providePower

«attribute def» Real

«attribute def» Torque

«port def»
 ➤ FuelCmdPort

directed features
in item fuelCmd:FuelCmd

attributes x:Real

> «item def» FuelCmd

«item def» Fuel



Specialization

Definition elements can be specialized

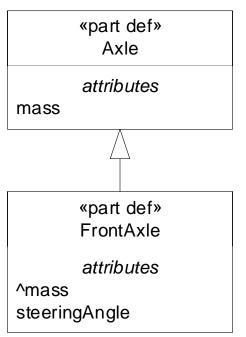
inherited

added

- O Subclass inherits features from its superclass that can be redefined or subsetted
- Subclass can add new features

O Subclass can be a specialization of more than one superclass (i.e., multiple

inheritance)



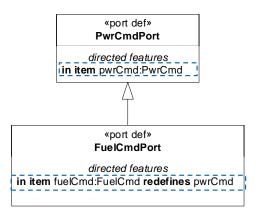


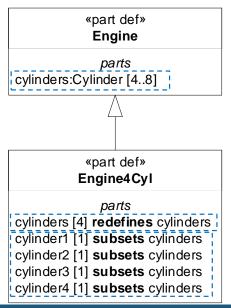


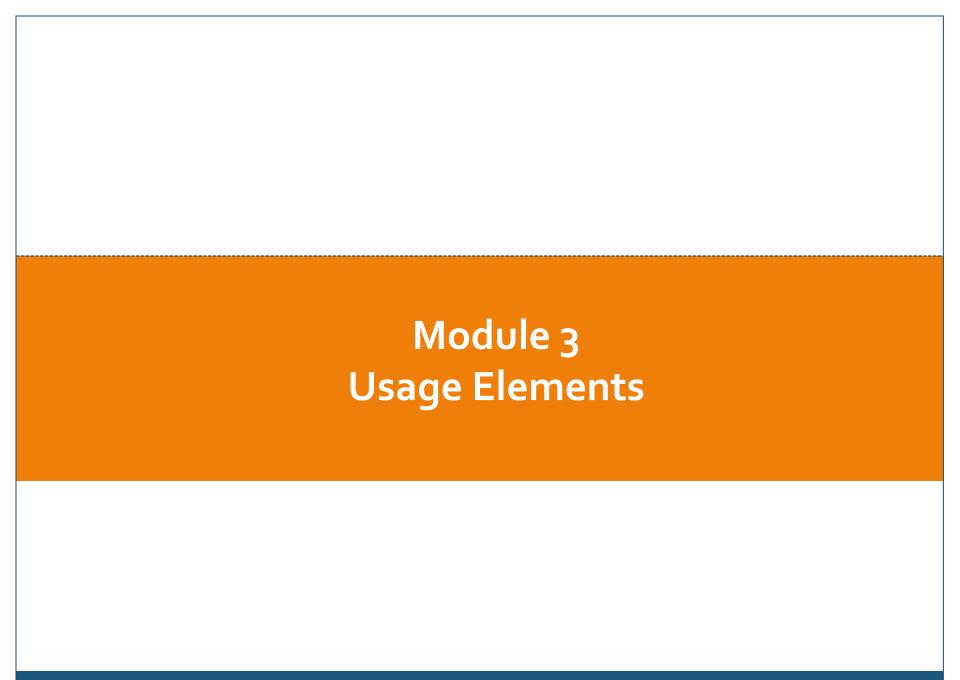
Redefinition and Subsetting

- An inherited feature can be redefined by a feature whose definition is more specialized
 - The more specialized feature overrides the inherited feature
 - Symbol for redefines (:>>) **V2**
- An inherited feature can be subsetted by one or more features with a more constrained multiplicity
 - The Engine4Cyl contains a subset of the cylinders contained by Engine
 - First redefine multiplicity to 4
 - Then identify the subsetting features
 - Symbol for subsets (:>)







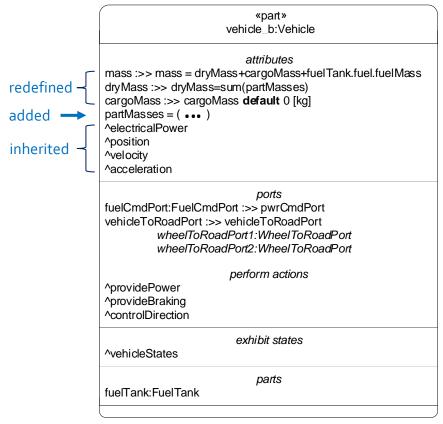




Part

SST

- A part is a usage of a part definition
- Inherited features can be redefined or subsetted, and new features can be added



Other Usage Elements



Terminology w2

- Other kinds of usage elements are defined by specific kinds of definition elements
 - Attributes defined by attribute definition
 - O Ports defined by port definition
 - Items defined by item definition
 - Actions defined by action definition
 - States defined by state definition
 - 0 ...

Enumeration



- A data type whose range is restricted to a set of discrete values
 - Without units
 - Definition: enum def Colors {red; blue; green;}
 - Usage: attribute color1: Colors = Colors::blue;

| «enum def» |
|------------|
| Colors |
| enums |
| red |
| blue |
| green |

- O With units:
 - Definition: enum def DiameterChoices :> ISQ::LengthValue {

```
enum = 60 [mm];
enum = 70 [mm];
enum = 80 [mm];
```

```
«enum def»
DiameterChoices

enums
=60 [mm]
=70 [mm]
=80 [mm]
```

v2

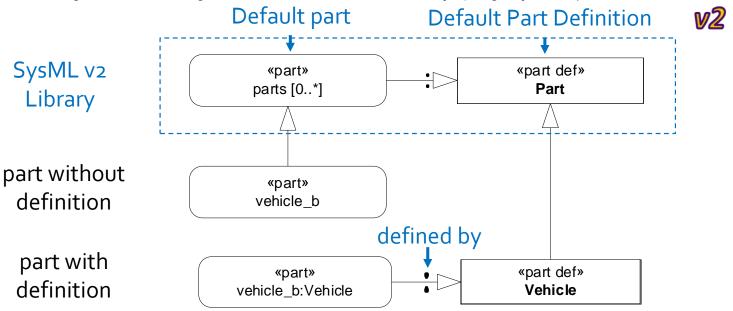
Usage: attribute cylinderDiameter: DiameterChoices = 80 [mm];



Usage Elements Defined By Default Definition Elements

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- A definition element is a subclass of the most general definition element in the SysML v2 library (e.g., Part) **V2**
- A usage element is defined by a definition element
 - defined by is a kind of specialization
- A usage element that is not provided a definition by the modeler is a subset of the most general usage element in the library (e.g., parts)



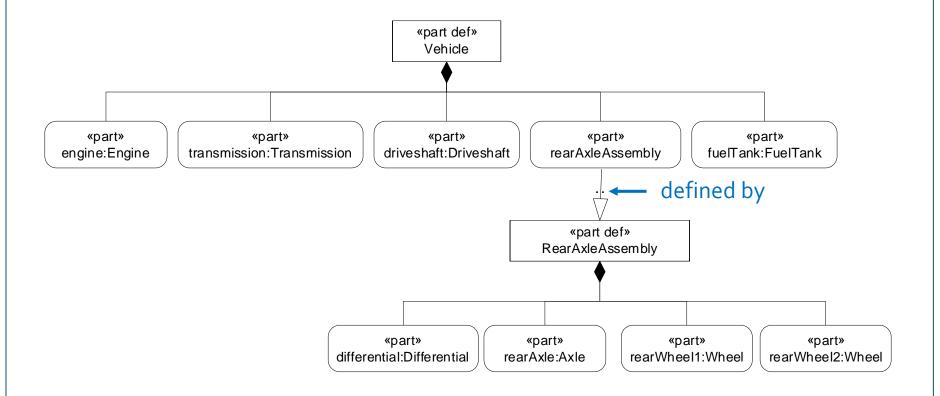
Module 4 **Part Decomposition** 11 November 2022 33



SysML v1 Decomposition in SysML v2

SST

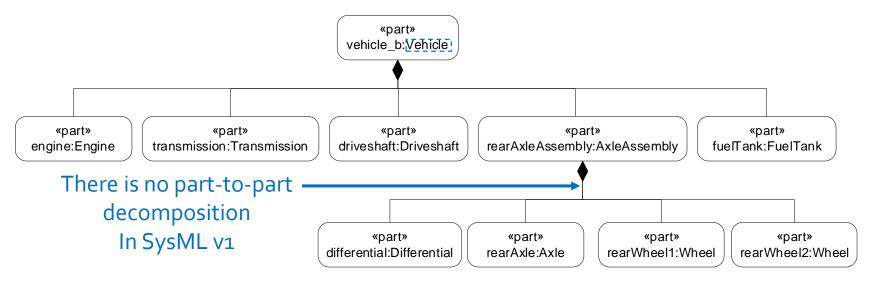
defined by relationship is used to create next level of decomposition of a part def





Parts Decomposition

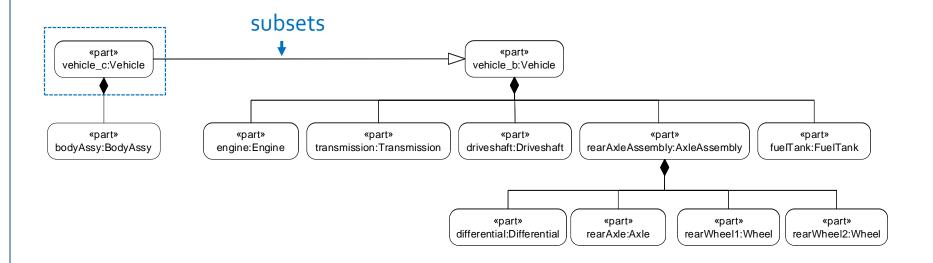
- A parts tree is a composition of a part from other parts
 - SysML v1 only supports block decomposition
 - O Definition element can serve as black-box specification without committing to an internal structure (e.g., part decomposition)
 - O Can provide significant advantages (more intuitive, less ambiguous, easier to modify a design configuration)





Parts Tree Reuse & Modification Subsetting a Part

- A part can be a subset of another part
 - Equivalent to specializing a part V2
 - Inherits the part decomposition and other features
 - Can modify inherited parts and features through redefinition and subsetting
 - Can add new parts **V2**



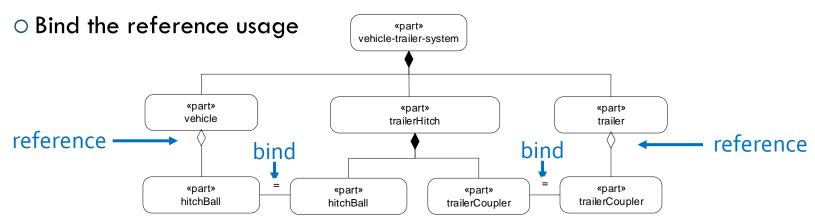
References



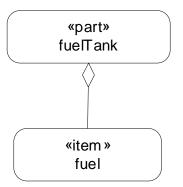
A part can refer to other parts that are part of another decomposition w2



Not composite (i.e., lifetime semantics do not apply)



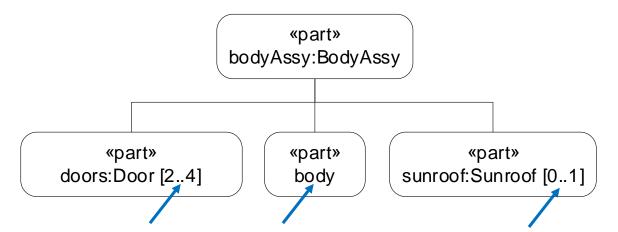
V2A part can refer to an item that it stores

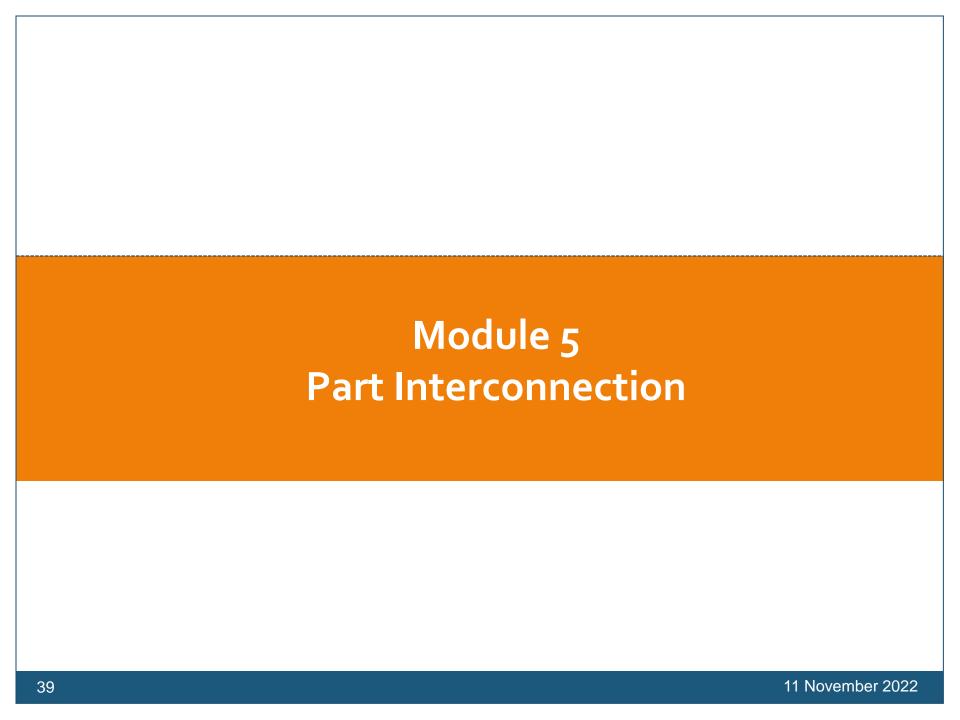




Multiplicity

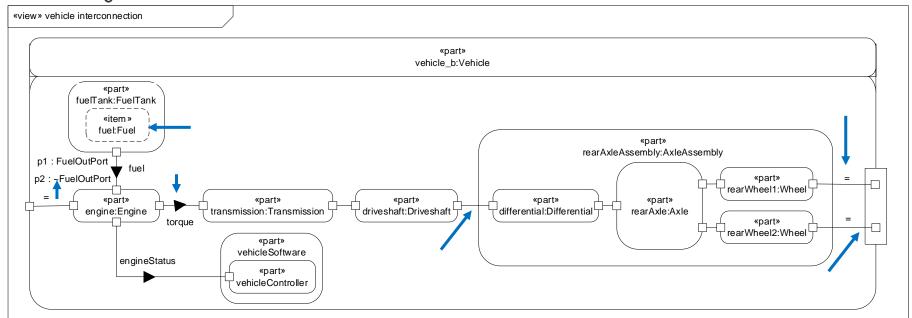
- Defines the number of features (e.g., parts) in a particular context
 - O Defines a range with a lower bound and upper bound
 - O Lower and upper bounds are integers
 - Can be parameterized [x..y] where x and y are expressions
 - O Default multiplicity is [1..1]
 - Optional multiplicity [0..1]





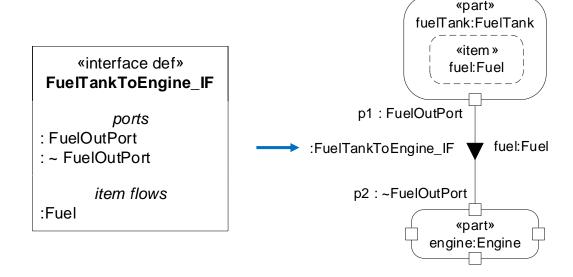
Connecting Parts

- Parts can be connected via their ports or without ports
 - O Parts can be connected directly without connecting to the composite part
 - O Ports can contain nested ports
 - Flows can be shown on connections
 - References are dashed
 - Conjugate port
 - Binding connection



Interfaces

- A connection definition connects two usage elements (e.g., two parts)
- An interface definition is a connection definition whose ends are compatible ports
 - Can contain flows
 - Can contain other kinds of features
- An interface defined by an interface definition is used to connects ports
 - O Ports on parts must be compatible with the interface definition





Interface Connecting a Wheel to a Hub

SST

- Usage of WheelToHub interface definition specifies a compatible connection between a wheel and a hub
 - O Connects composite ports on wheel and hub
 - Decomposes into 5 Wheel Fastener interfaces
- Wheel Fastener interface species a compatible connection between a lugnut and shank
 - Contains features needed for a compatible connection



«port def» LugNutCompositePort

ports
lugNutPort:LugNutPort [*]

«port def» LugNutPort

attributes threadDia = 14 [mm] threadPitch = 1.5 [mm]

«interface def» WheeltoHub IF

ports
lugNutCompositePort:LugNutCompositePort [1]
shankCompositePort:ShankCompositePort [1]

interfaces
wheelFastener_IF: WheelFastener_IF [5]
connect lugNutCompositePort.lugNutPort to
shankCompositePort.shankPort

«interface def» WheelFastener IF

ports lugNutPort:LugNutPort shankport:ShankPort

attributes maxTorque = 90 [ft-lbs]

constraints
{lugNutPort.threadDia ==
shankPort.threadDia}

«port def» ShankCompositePort

ports shankPort:ShankPort [*]

«port def» ShankPort

attributes threadDia = 14 [mm] threadPitch = 1.5 [mm] shaftLength = 70 [mm]

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Wheel Hub Interface

Usage of WheelHubInterface to specify interface between rear axle and wheels

```
part wheelHubAssy3{
                                                                            interface def WheelFastenerInterface{
   part wheel1:Wheel{
                                                                                 end lugNutPort:LugNutPort;
       port lugNutCompositePort :>> lugNutCompositePort {
                                                                                 end shankPort:ShankPort;
           port lugNutPort [5] :>> lugNutPort {
               attribute :>> threadDia = 14 [mm];
                                                                                 attribute maxTorque : Torque;
               attribute :>> threadPitch = 1.5 [mm];
                                                                                 constraint {lugNutPort.threadDia == shankPort.threadDia}
           port lugNutPort1 [1] :> lugNutPort;
                                                                            interface def WheelHubInterface{
           port lugNutPort2 [1] :> lugNutPort;
           port lugNutPort3 [1] :> lugNutPort;
                                                                                 end lugNutCompositePort:LugNutCompositePort;
                                                                                 end shankCompositePort:ShankCompositePort;
                                                                                 interface wheelFastenerInterface:WheelFastenerInterface [5]
   part hub1:Hub{
                                                                                      connect lugNutCompositePort.lugNutPort to shankCompositePort.shankPort;
       port shankCompositePort :>> shankCompositePort {
           port shankPort [5] :>> shankPort {
               attribute :>> threadDia = 14 [mm];
               attribute :>> threadPitch = 1.5 [mm];
               attribute :>> shaftLength = 70 [mm];
           port shankPort1 [1] :> shankPort;
           port shankPort2 [1] :> shankPort;
           port shankPort3 [1] :> shankPort;
   interface wheelHubInterface:WheelHubInterface
       connect lugNutCompositePort ::> wheel1.lugNutCompositePort [1] to shankCompositePort ::> hub1.shankCompositePort [1] {
           interface wheelFastenerInterface1 :> wheelFastenerInterface
               connect lugNutPort ::> lugNutCompositePort.lugNutPort1 to shankPort ::> shankCompositePort.shankPort1 {
                  attribute :>> maxTorque = 90 * 1.356 [N*m];
           interface wheelFastenerInterface2 :> wheelFastenerInterface
               connect lugNutPort ::> lugNutCompositePort.lugNutPort2 to shankPort ::> shankCompositePort.shankPort2 {
                  attribute :>> maxTorque = 90 * 1.356 [N*m];
           interface wheelFastenerInterface3 :> wheelFastenerInterface
               connect lugNutPort ::> lugNutCompositePort.lugNutPort3 to shankPort ::> shankCompositePort.shankPort3 {
                  attribute :>> maxTorque = 90 * 1.356 [N*m];
```

«interface def»

ports lugNutCompositePort:LugNutCompositePort [1] shankCompositePort::ShankCompositePort [1]

WheeltoHub IF

wheelFastener_IF: WheelFastener_IF [5] connect lugNutCompositePort.lugNutPort to shankCompositePort.shankPort

«interface def» WheelFastener IF

lugNutPort:LugNutPort shankport:ShankPort

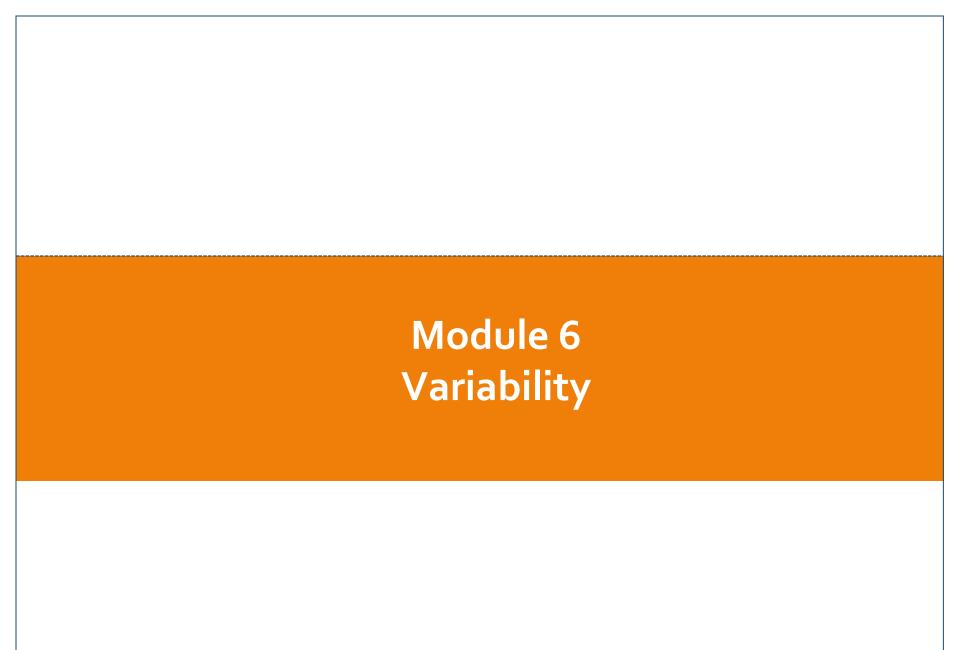
attributes maxTorque = 90 [ft-lbs]

constraints {lugNutPort.threadDia == shankPort.threadDia}



Nested Wheel Hub Interface

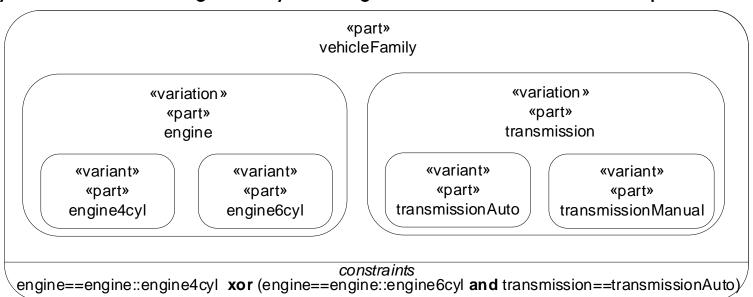
```
wheelHub_IF: WheeltoHub_IF
lugNutCompositePort:
                          shankCompositePort:
LugNutCompositePort
                          ShankCompositePort
     wheelFastener_IF1 : WheeltoFastener_IF
lugNutPort1:LugNutPort
                          shankPort1:ShankPort
     wheelFastener IF2: WheeltoFastener IF
                          shankPort2:ShankPort
TugNutPort2:LugNutPort
      wheelFastneer IF3: WheelFastener IF
                          shankPort3:ShankPort
lugNutPort3:LugNutPort
```





Variability **v2**

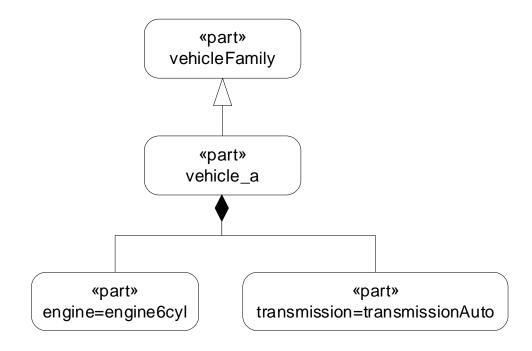
- Vehicle family is the superset model (150%)
- Variation points represent elements that can vary
 - Can be applied to all definition and usage elements
- A variant represents a particular choice at a variation point
- A choice at one variation point can constrain choices at other variation points
- A system can be configured by making choices at each variation point

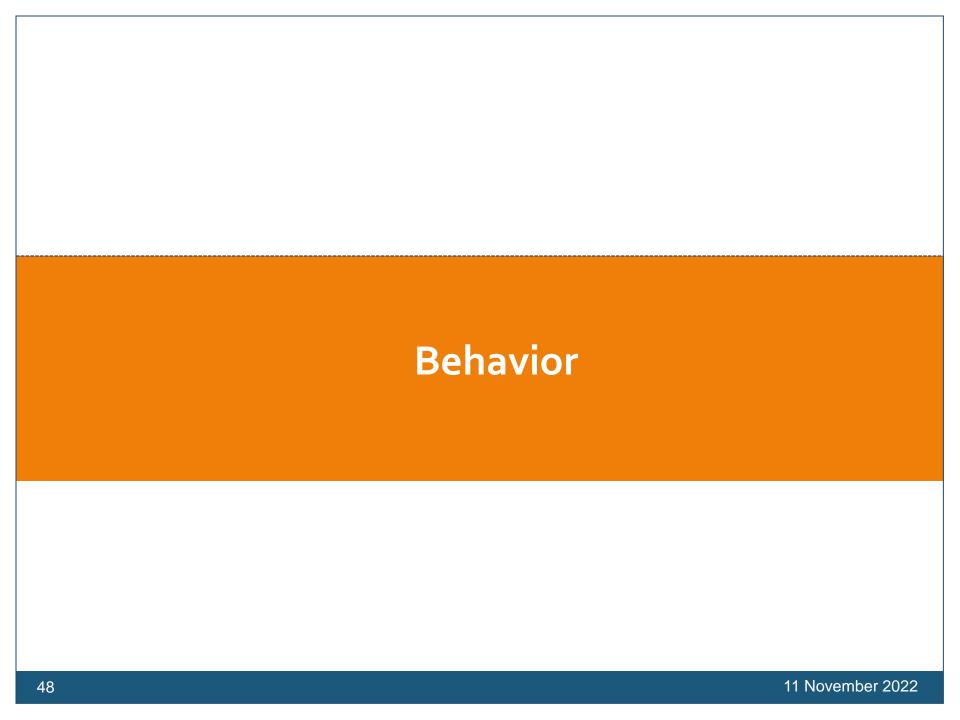


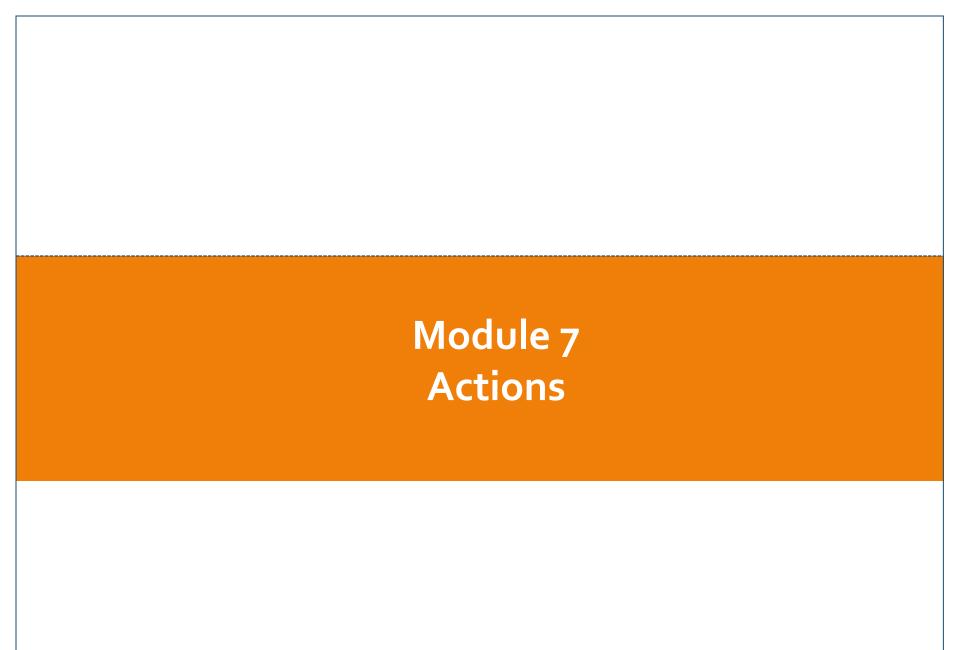


Selected Vehicle Configuration

- Vehicle_a subsets vehicleFamily to represent a particular design configuration
- Selected parts must satisfy variability constraints
 - Model is inconsistent if constraints are not satisfied
 - Variability modeling applications can automate the selection of valid configurations





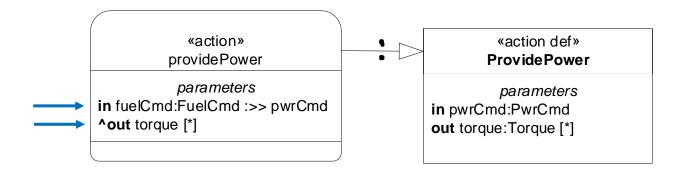


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Actions

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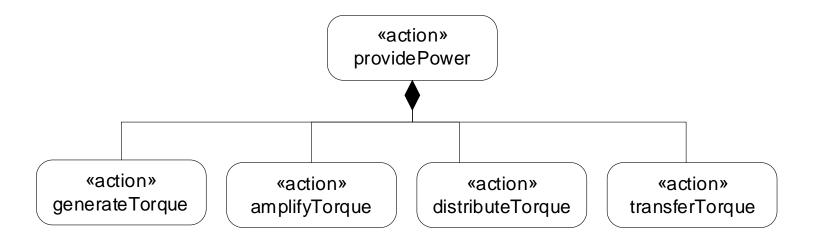
- Actions are defined by action definitions
 - Inherit features (e.g., input and output parameters)
 - O Can redefine or subset inherited features or add new features



Action Decomposition

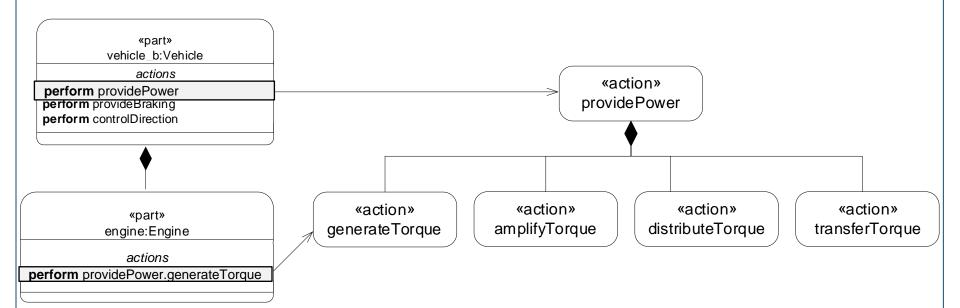
• Actions can be decomposed in a similar way as parts





Part Performs Actions

• A part that performs an action can reference an action in an action tree





Perform Action

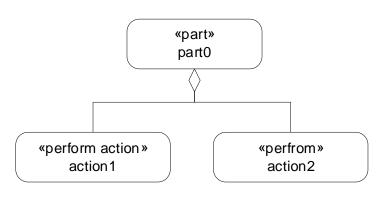
- Show two kinds
 - o perform action1
 - perform action action1
- The difference between these two is as follows
 - O Line with arrow part part 1 {perform action1} (example from previous slide) this creates an anonymous reference feature that subsets action1 which is often in a separate action tree. Name is properly qualified such as package1::action1). This is like a call action.
 - Line with white diamond
 part part | {perform action action | }
 This creates an explicit reference feature called action | that can either subset or bind to another action
 - O This pattern is repeated for many different kinds of features.



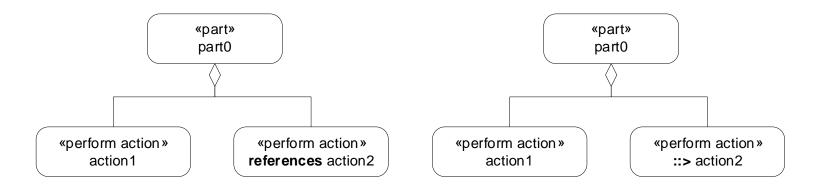
Perform Action Simple Example

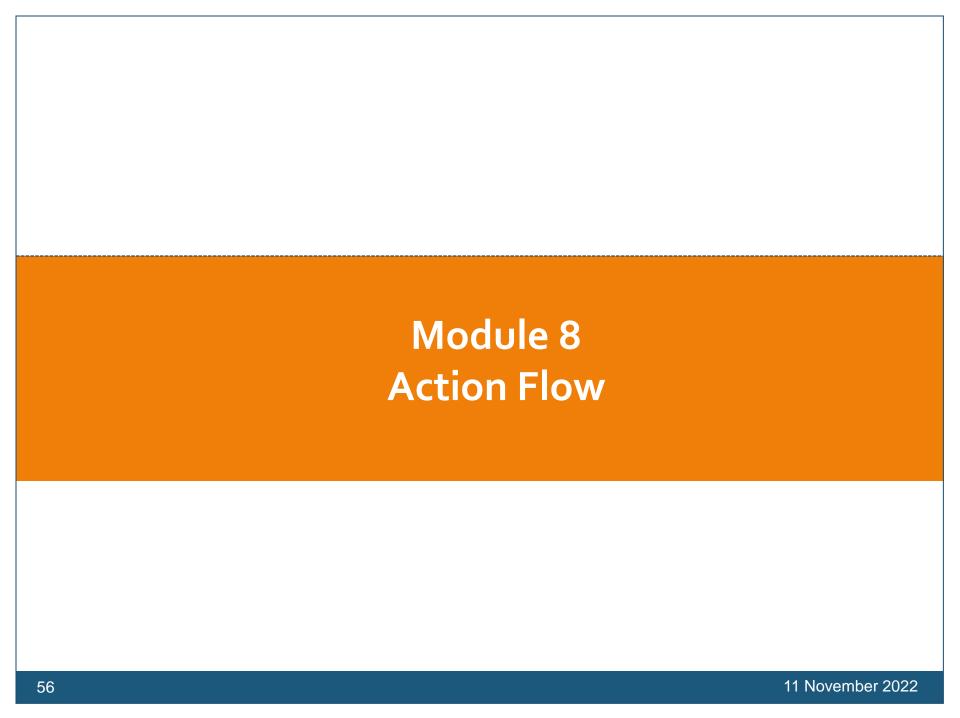
SST

```
package PerformActions{
   part part0{
     perform action action1;
     perform action2;
   }
   action action2;
}
```



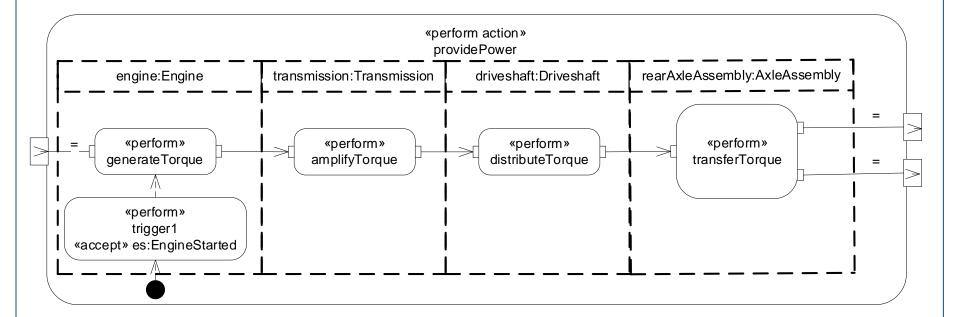
Alternatives





Action Flow

- Actions can include successions and input/output flows
- Control nodes include decision, merge, fork, and join nodes
- Actions can include send and accept actions
- Swimlanes represent performers of actions

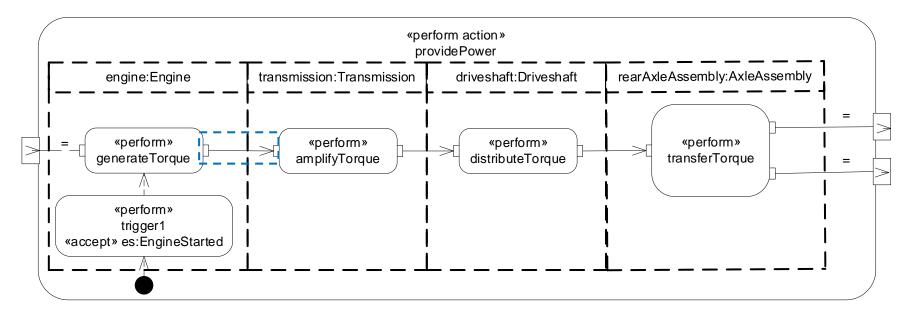


Note: Parameter notation subject to change



Input/Output Flows

- A flow is a kind of connection that transfers items from a source output to a target input
 - A flow is a transfer that continues while the source and target actions execute
 (this is the default) v2
 - A succession flow is a transfer that only occurs after the source action ends and before the target action starts

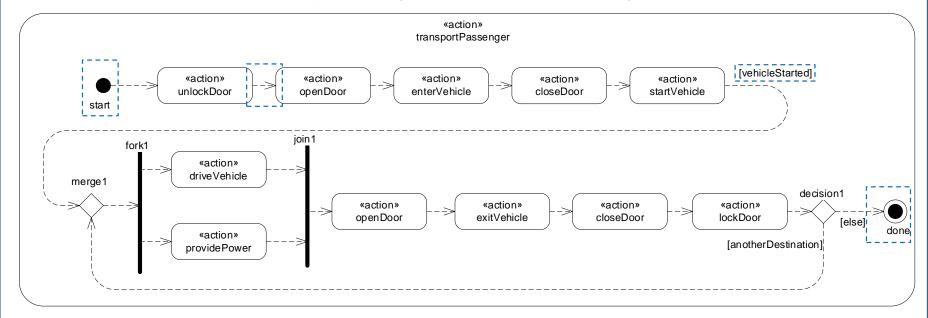


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Controlling Actions [1]

- A start action and done action represent the start and end of an action sequence
- A succession asserts that the target action can start execution only after the source action ends execution $\sqrt{2}$
- A conditional succession asserts that the target action can start only if the guard condition is true (if...then). If the guard is false, the target action cannot start



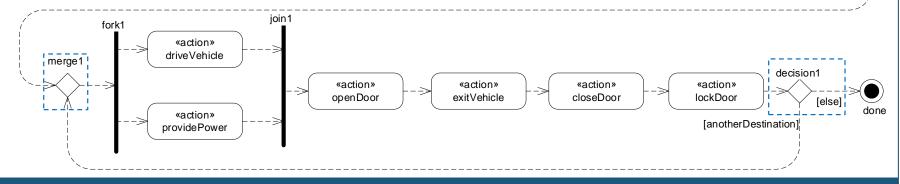


Controlling Actions [2]

- Control nodes are kinds of actions (with names) that control outgoing successions in response to incoming successions
 - O Decision node
 - 1 incoming succession and 1.. many outgoing successions
 - One outgoing succession is selected based on the guard condition that is satisfied ("else" condition is the complement of all other guard conditions)
 - Merge node
 - 1.. many incoming successions and 1 outgoing succession

[vehicleStarted]

The outgoing succession occurs when any of its incoming successions occur

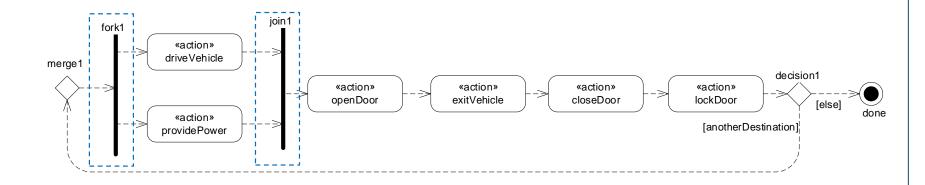




Controlling Actions [3]

- Fork node
 - 1 incoming succession and 1.. many outgoing successions
 - All outgoing successions occur when its incoming succession occurs
- O Join node
 - 1.. many incoming successions and 1 outgoing succession
 - Outgoing succession occurs when all its incoming successions occur

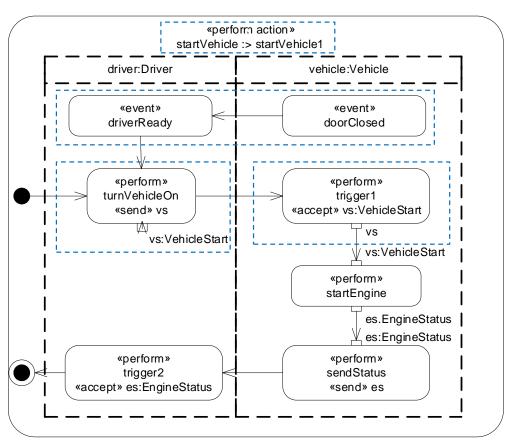
Note: Control nodes cannot currently be applied to input/output flows





Controlling Actions [4]

- startVehicle subsets startVehicle1 behavior which is independent of structure
- Event occurrences
- Accept actions and send actions
 - When a send action executes, it transfers an item to a target part
 - When a triggering input item is received, an accept action executes and can transfer the input item to another action
- driver and vehicle are in a shared context (not shown)



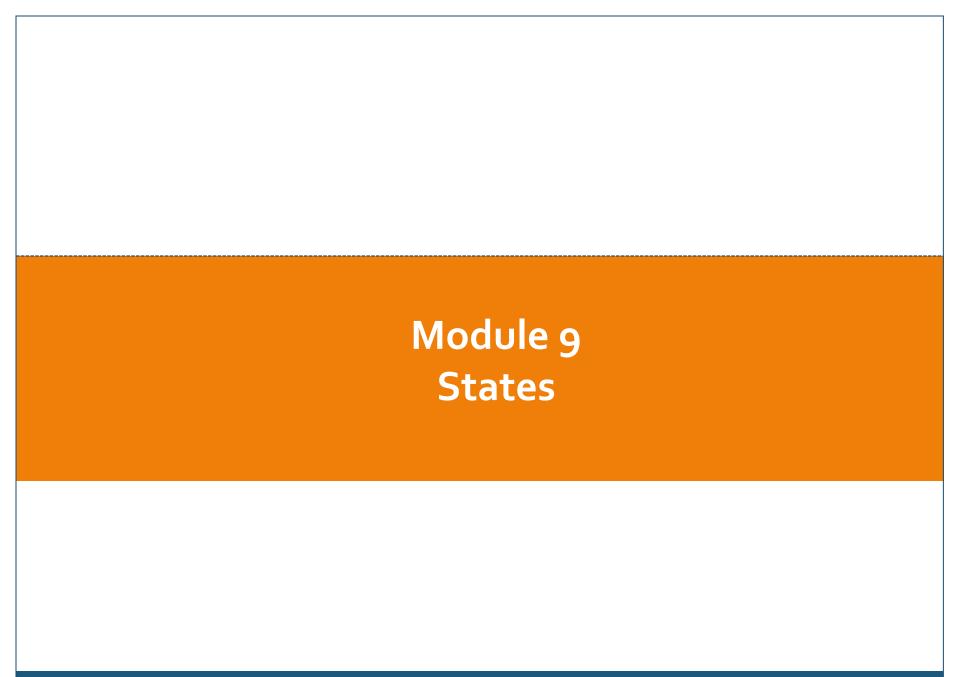


Scenario_1o Textual Notation

SST

```
package Scenario_10{
       item def VehicleStart;
      item def EngineStatus;
      action startVehicle1
         event occurrence doorClosed:
        event occurrence driverReady;
        first doorClosed then driverReady;
        first driverReady then turnVehicleOn;
        action turnVehicleOn send vs via source{
          in vs:VehicleStart;
          in source default self;
        action trigger1 accept vs:VehicleStart;
        flow of VehicleStart from trigger1.vs to startEngine.vs;
        action startEngine{
          in item vs:VehicleStart;
          out item es:EngineStatus;
        flow of EngineStatus from startEngine.es to sendStatus.es;
         action sendStatus send es via source{
          in es:EngineStatus;
          in source default self;
        action trigger2 accept es:EngineStatus;
        message of VehicleStart from turnVehicleOn to trigger1;
        message of es:EngineStatus from sendStatus to trigger2;
```

```
part def Driver{
 port p1;
 port p2;
part def Vehicle{
  port p1;
part parto{
  perform action startVehicle:>startVehicle1{
   action :>> turnVehicleOn send vs via source{
     in :>> source = driver.p1;
   action :>> trigger1 accept vs:VehicleStart via vehicle.p1;
   action :>> sendStatus send es via source{
     in es:EngineStatus;
     in :>> source = vehicle.p1;
   action:>> trigger2 accept es:EngineStatus via vehicle.p1;
  part driver : Driver {
   perform startVehicle.turnVehicleOn;
   perform startVehicle.trigger2;
   event startVehicle.driverReady;
  part vehicle : Vehicle {
   perform startVehicle.trigger1;
   perform startVehicle.startEngine;
   perform startVehicle.sendStatus;
   event startVehicle.doorClosed;
 interface driver.p1 to vehicle.p1;
 interface driver.p2 to vehicle.p1;
```

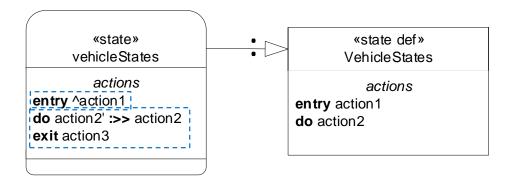




States

SST

- States can be defined by state definitions **V2**
 - O Inherit features (e.g., actions, nested states, transitions) from its state definition
 - O Can redefine or subset inherited features or add new features



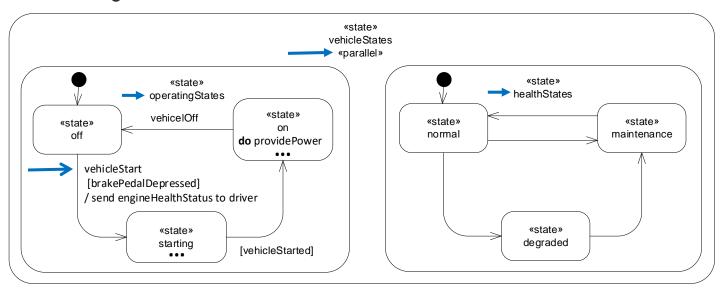
State-based Behavior [1]



• States decompose into nested states (without regions, which were in SysML v1)



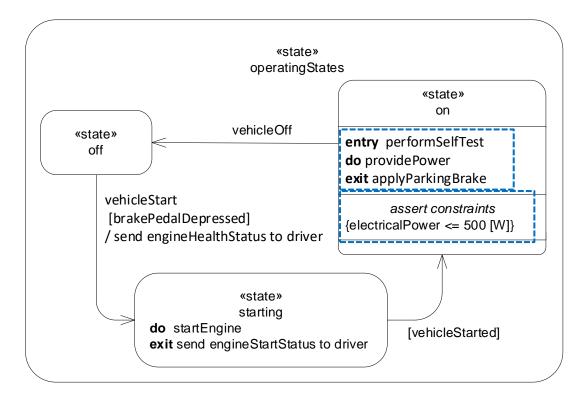
- A parallel state decomposes into concurrent states
- A non-parallel state (default) decomposes into sequential/exclusive states
- Transitions between sequential states
 - Triggered by events
 - Can include guard and action





State-based Behavior [2]

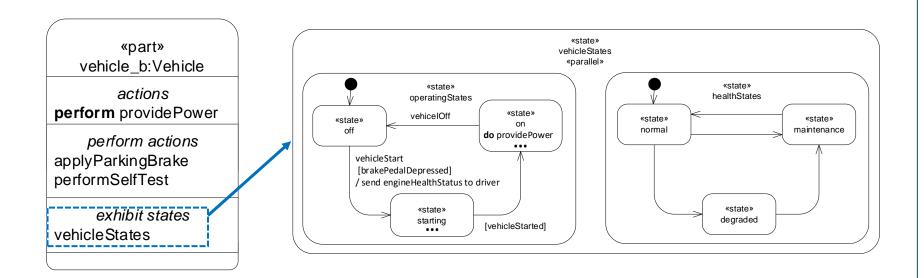
- States can have entry, exit, and do actions that can refer to actions in action trees or be defined locally
- States can include constraints

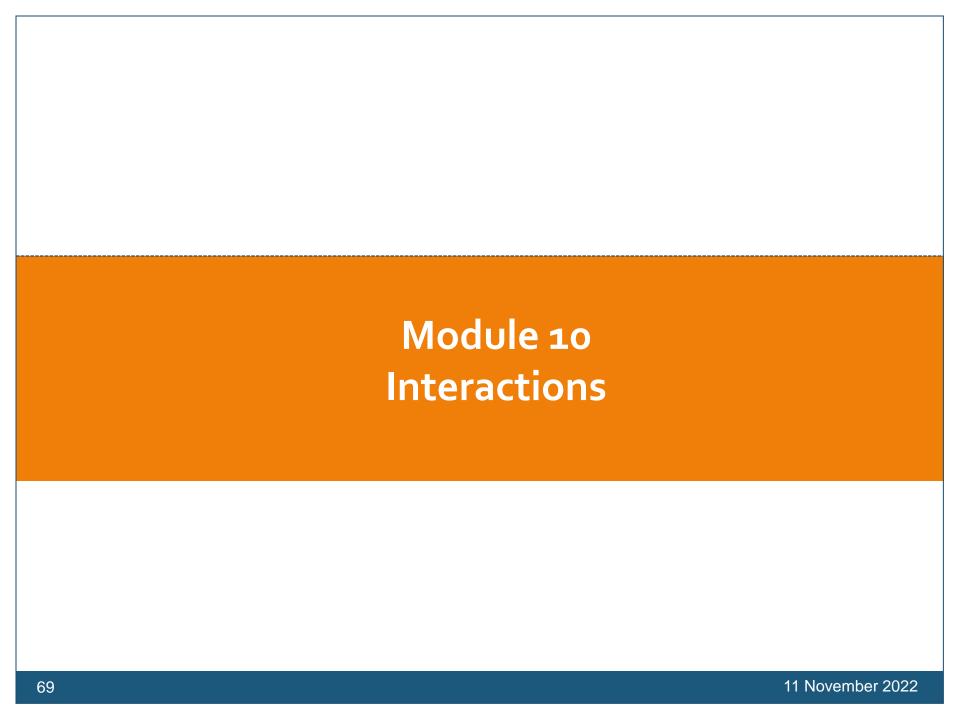


Part Exhibits States



- A part exhibits states **V2**
- References its state-based behavior

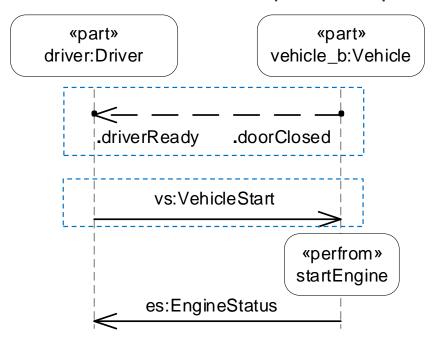




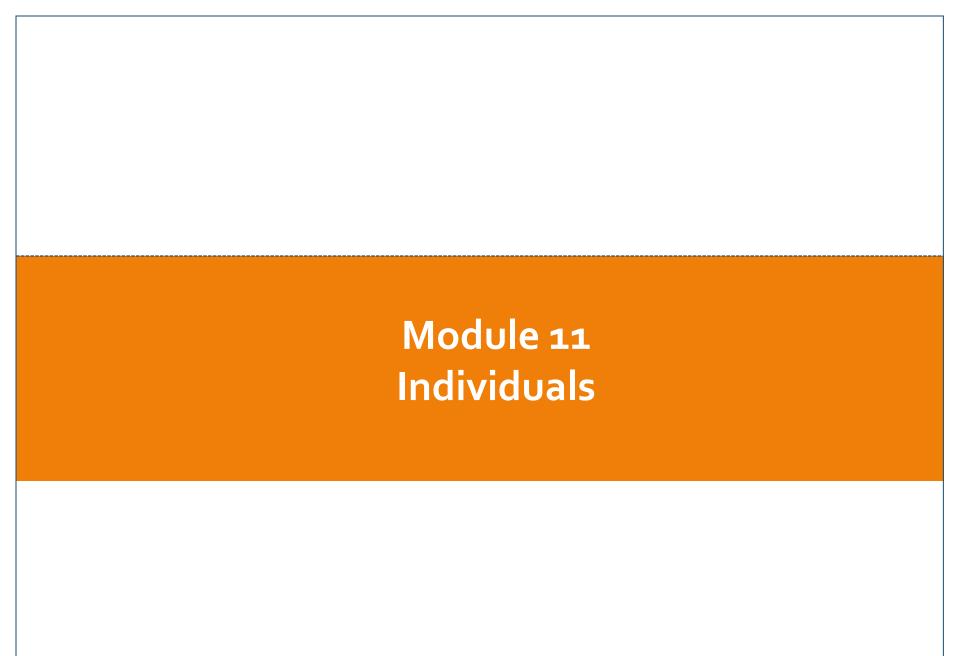


Sequence View

- Represents an event sequence and messages (refer to action flow on slide 62)
 - Event sequence
 - Message
 - O Driver and vehicle are in a shared context (not shown)



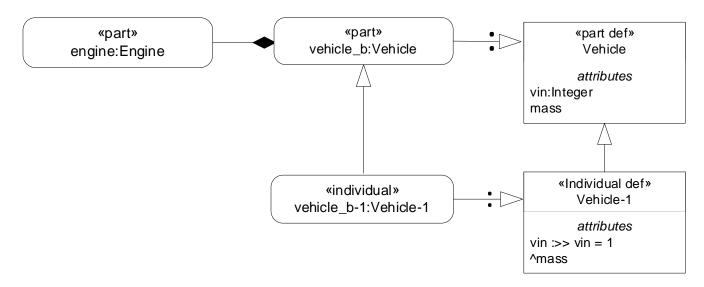
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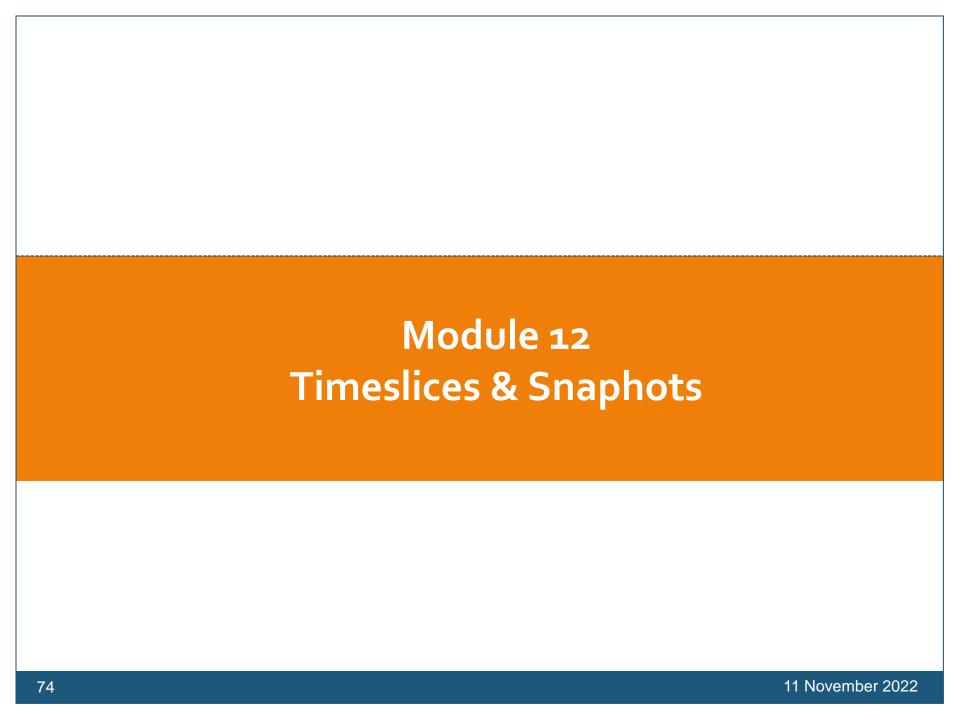


Individuals **v2**

- An individual definition is a unique member of a class with identity
 - A specialization of a class, having only one member
 - Has a unique lifetime
- An individual is a usage that is defined by an individual definition
 - O Can subset a part to represent a particular configuration
 - O Can have different configurations across Vehicle-1 lifetime



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4D Model & Occurrences

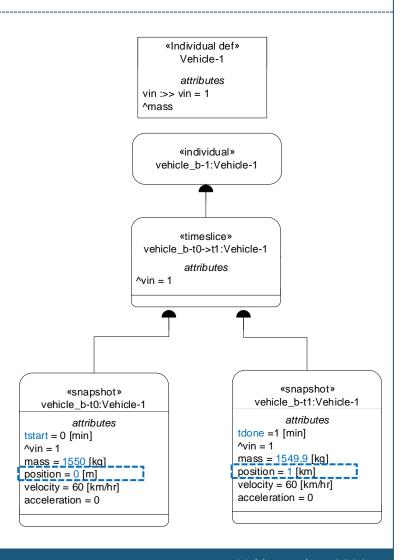
- Each entity called an occurrence has a lifetime
 - O Distinct from attributes which do not have a lifetime
 - Includes a reference clock that can quantify time (defaults to universal clock)
 - Can specify time slices and snapshots
- Spatial items are kinds of occurrences that have spatial extent that can change over their lifetime
 - O Specified by shapes with position and orientation within coordinate frames
- Individuals
 - Unique occurrence with a lifetime



Lifetime with Snapshots and Time Slices **v2**



- Each individual definition has a unique lifetime
 - Begins when it is created
 - Ends when it is destroyed
- Individual usage exists over some portion of Vehicle-1 lifetime
- Individual lifetime can be segmented into time slices (i.e., durations of time)
- A time slice whose duration is zero is a snapshot
 - O Beginning and ending snapshot of a time slice is designated as start and done snapshot
- The condition of an individual for a time slice or snapshot can be specified in terms of the values of its features

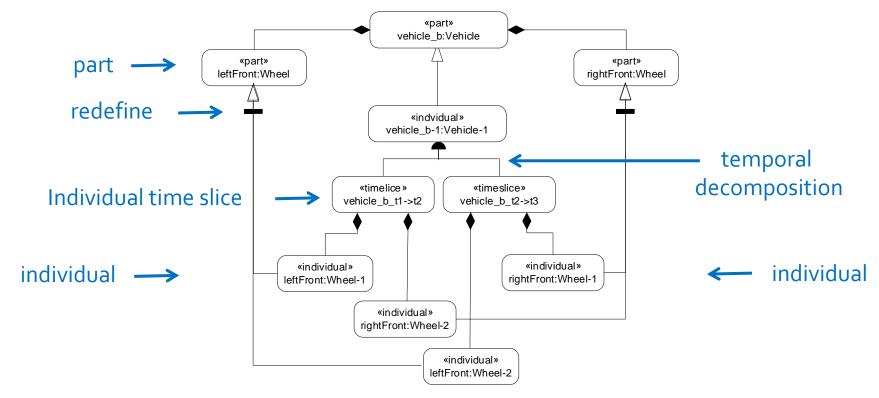




Individuals Playing Different Roles **v2 557**



- An individual can play different roles and have different configurations in different time slices
 - Individual wheel (Wheel-1) is left front wheel during vehicle b t1-t2 time slice
 - Individual wheel (Wheel-1) is right front wheel during vehicle_b_t2-t3 time slice



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Module 13 **Expressions and Calculations** 11 November 2022 78

Expressions **v2**

- Used to compute a result
- Library of mathematical functions (e.g., sum, max, ...)
 - Includes arithmetic operators that also apply to vectors and tensors
- Default value means value can be over-ridden using redefinition

```
«part»
vehicle_b:Vehicle
```

attributes

```
mass ::>> mass=dryMass+cargoMass+fuelTank.fuel.fuelMass dryMass :>> dryMass=sum(partMasses) | cargoMass :>> cargoMass default 0 kg | partMasses=(fuelTank.mass,frontAxleAssembly.mass,rearAxleAssembly.mass,engine.mass,transmission.mass,driveshaft.mass)
```

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Calculations v2

- A kind of behavior generally used to represent reusable mathematical functions
 - O Inputs
 - Expression
 - O Returns a single result
 - Can have multiplicity

return f :> ISQ::force = m*a

Represent a calculation definition using the textual notation

```
calc def Force {
   in attribute m:>ISQ::mass;
   in attribute a:>ISQ::acceleration;
   return f:>ISQ::force = m * a;
}
```



Calculations v2

- Evaluate usage
 - O Bind values to input parameters. Then evaluate expression and return a result

```
o calc force : Force {
    in m=1500 [kg];
    in a=9.806 [m/s^2];
}
```

- Can bind a calc return value to an attribute
 - o attribute f1 = Force (m=1500 [kg], a = 9.806 [m/s ^2]);

«calc def» Force

parameters

in m :> ISQ::mass

in a :> ISQ::acceleration return f :> ISQ::force = m*a «calc» force:Force

parameters

in m=1500 [kg]

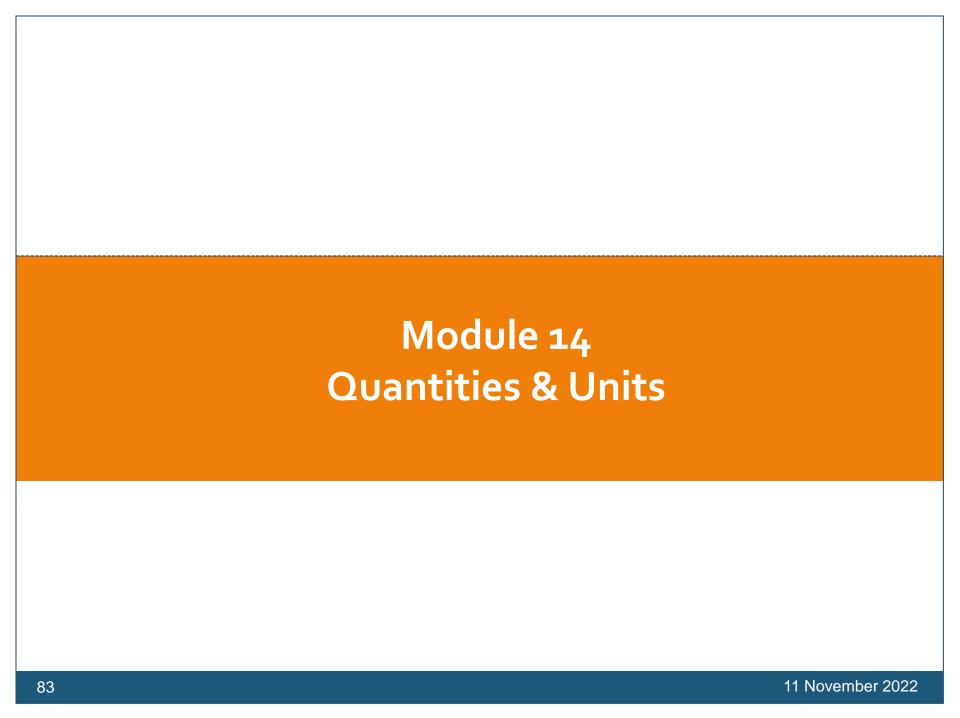
in a=9.806 [m/s^2]

*return :> ISQ::force = m*a



Binding Connection

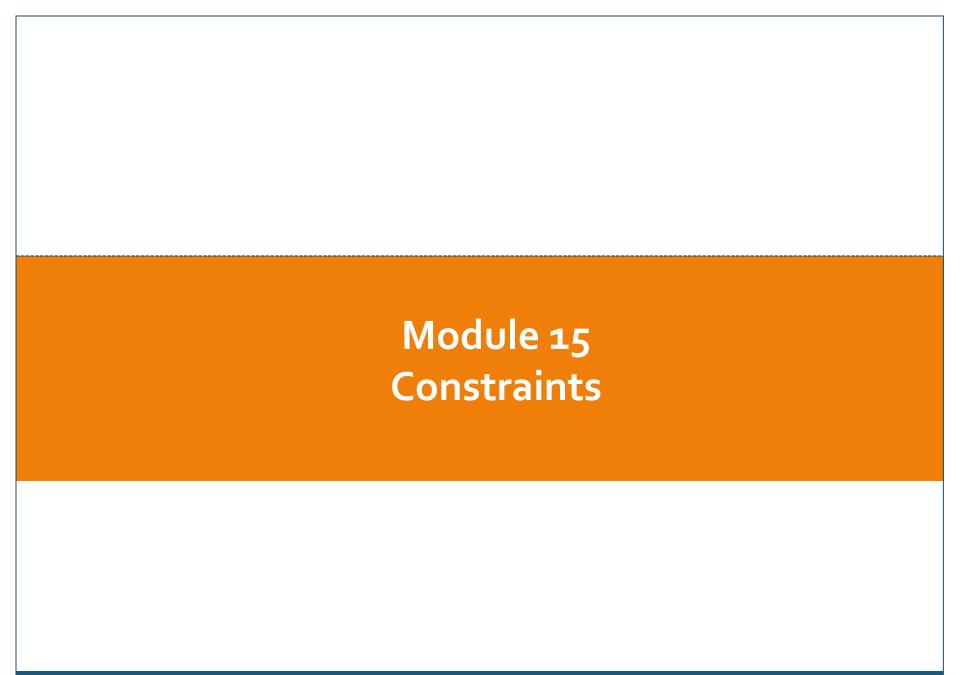
- A binding is a kind of connection where both sides of the connection are asserted to be equal at all times
 - O Symbol is «bind» or =
 - \circ If both sides are not equal, the model is inconsistent (e.g., 3=4) is inconsistent
 - O A tool could make both sides equal if the values are not the same
 - In the above example, the values can be set to (3=3) or (4=4)
 - For y = x+3, when x is 1, then y can be set to 4 so that both sides are equal
 - O Different from the Boolean operator '==', which evaluates whether both sides of the '==' have the same value or not, and returns a value of true or false (e.g., $\{3==4\}$ returns a value of false)
- Binding can be used to establish equality of any kind of feature
 - \circ A part can be bound (e.g., engine = engine4cyl)
 - O A port on a composite part can be bound to a port on a nested part to constrain them to have equal values





Quantities and Units

- Quantity is an attribute (e.g., mass) **V2**
- Quantity is defined by an attribute def of a quantity kind (e.g., MassValue)
- Units conform to the quantity kind (e.g., kilograms conform to MassValue)
- The values are associated with the units **V2**
- A change in a unit can apply the unit conversion factor if a tool supports this
 - o attribute m:MassValue = 25 [kg] (an equivalent value to 55.1 [lbs])
 - In SysML v1, a change in unit requires a change in the value type
- Complex quantities and units can be derived from primitive quantities and units
 - distancePerVolume :> scalarQuantities = distance / volume
- Libraries
 - International System of Quantities (ISQ)
 - International System of Units (SI)
 - US Customary Units (USCustomaryUnits) **V2**





Constraint Expression [1]

- A Boolean expression that evaluates to true or false, which includes
- V2

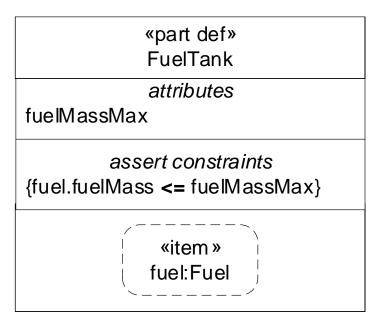
- Constraint operators (==), (>), (>=), (<), (<=), (!=)
 - Used to compare expressions (e.g., $\{a < b\}$)
- Boolean operators include and, or, xor, not
 - Used to logically combine expressions (e.g., {A and B or C})
- Asserting a constraint to be true means the evaluation must be true for the model to be consistent

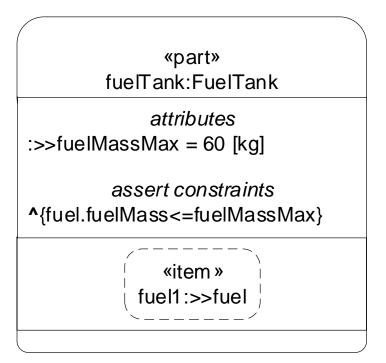
```
part def FuelTank {
    attribute mass :> ISQ::mass;
    ref item fuel:Fuel{
        attribute redefines fuelMass;
    }
    attribute fuelMassMax:>ISQ::mass;
    assert constraint {fuel.fuelMass<=fuelMassMax}
}</pre>
```



Constraint Expression [2]

Usage inherits constraint expression and redefines constraint parameters







Constraint Definition

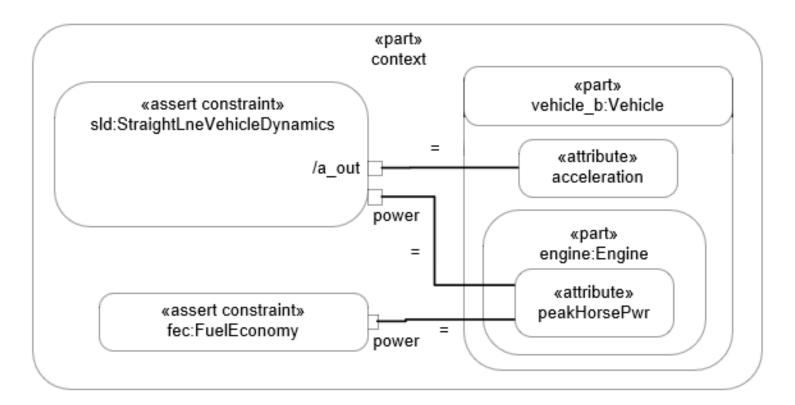
- Enables reuse of a constraint expression
- Default parameter direction is 'in'
- Can assert a constraint on the usage
- Bind parameters on the usage
- Can mark dependent parameters as derived with slash

"constraint def" StraightLineDynamics parameters power :> ISQ::power m :> ISQ::mass delta_t :> ISQ::time x_in :> ISQ:: length v_in:>ISQ:: speed x_out :> ISQ::length v_out :> ISQ::speed a_out :> ISQ::acceleration expression a_out == power/(mass*v_avg) and v_out == v_in +a_out*delta_t and x_out == x_in+v_avg*delta_t

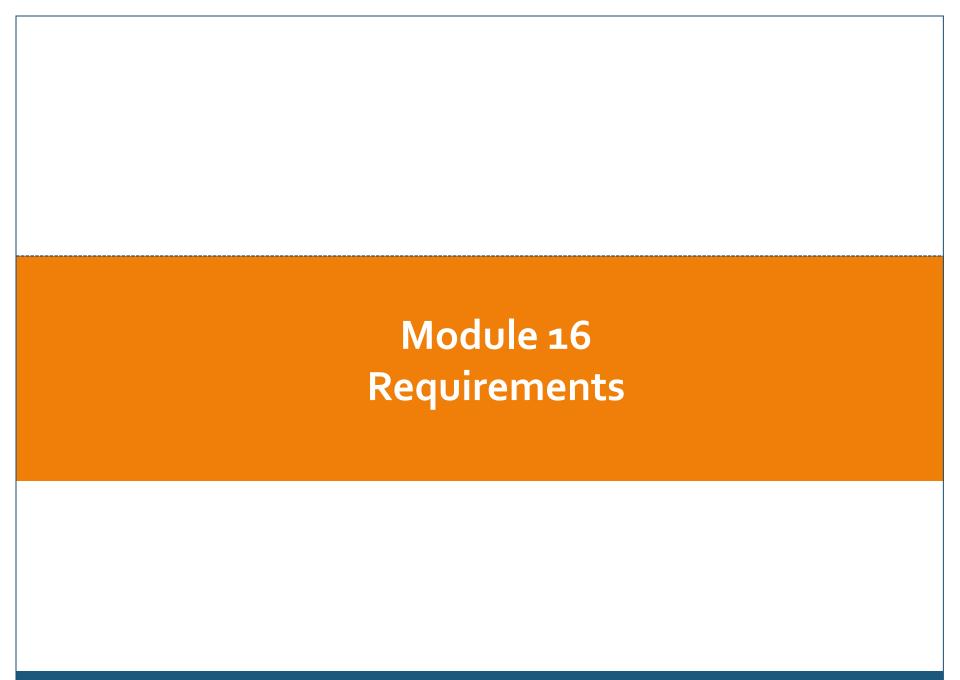


Binding Constraints

Equivalent to SysML v1 parametric diagram



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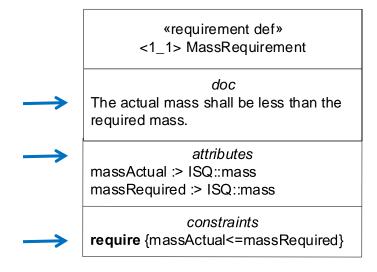
Requirement Definition



• A constraint definition that a valid design solution must satisfy that can include:



- Identifier
- Shall statement
- O Constraint expression that can be evaluated to true or false
 - can apply to performance, functional, interface and other kinds of requirements if desired
- Assumed constraint expression that is asserted to be true for the requirement to be valid
- Attributes of the constraint expressions



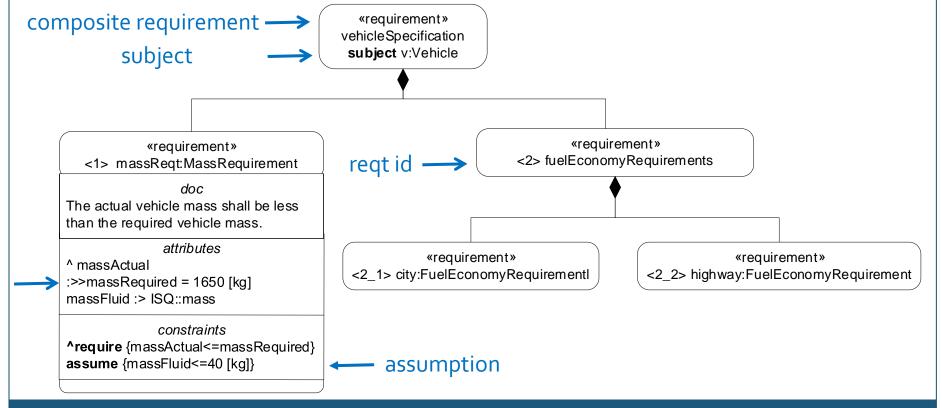
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Requirement Specification

SST

- A tree of requirements that contains nested requirement usages
- V2
- Composite requirement can own or reference other requirements
- Subject of nested requirements is the kind of entity being specified
- Requirement features can redefine features of the requirement definition



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Satisfying a Requirement

- The vehicleSpecification imposes constraints on the vehicle
 - The modeler can assert the vehicle mass satisfies the massRequired
 - Bind the vehicle mass to massActual of the requirement

«requirement» vehicle Specification subject v:Vehicle



«requirement» <1> massReqt:MassRequirement

doc

The actual vehicle mass shall be less than the required vehicle mass.

attributes

^ massActual :>>massRequired = 1650 [kg] massFluid :> ISQ::mass

constraints

^require {massActual<=massRequired} assume {massFluid<=40 [kg]}

«part» vehicle_b:Vehicle

attributes

:>>mass = dryMass + fluidMass :>>dryMass=sum(partMasses) :>>fluidMass = 36 [kg]

requirements satisfy vehicleSpecification

massRegt.massActual = mass

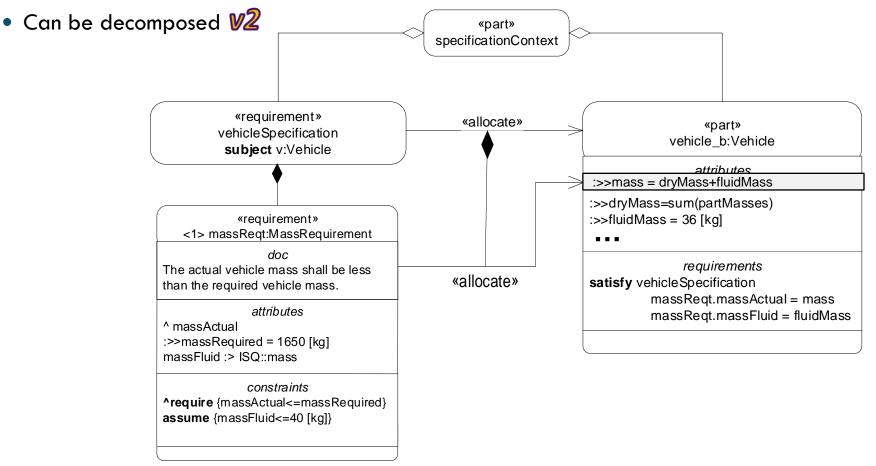
massRegt.massFluid = fluidMass



Requirement Allocation vs. Requirement Satisfaction

SST

- Allocating a requirement assigns responsibility for realizing a requirement
- Less formal than requirement satisfaction (no explicit constraint assertion)



Derived Requirement

#original

V2

#derive

«#derivation»

#derive

SST

 Single original requirement with one or more derived requirements

• If the original requirement is satisfied, then all the

derived requirements must be satisfied

«requirement» vehicleSpecification

«requirement»
<1> massReqt:MassRequirement

doc

The actual vehicle mass shall be less than the required vehicle mass.

«requirement» engineSpecification

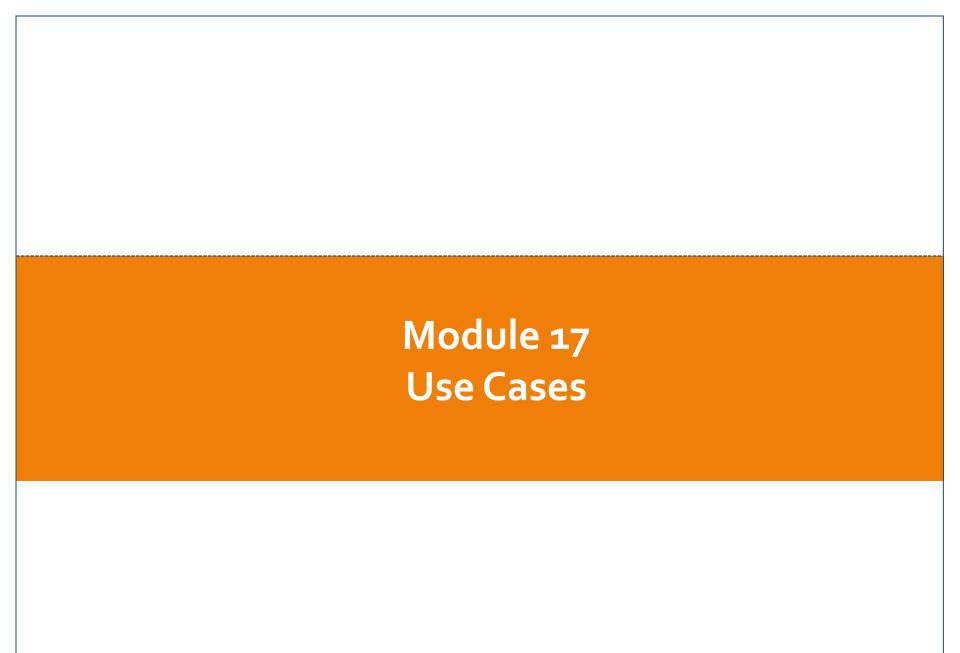
doc

The actual engine mass shall be less than the required engine mass.

«requirement» transmissionSpecification

doc

The actual transmission mass shall be less than the required transmission mass.

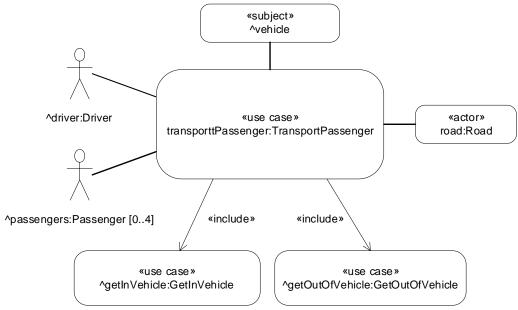


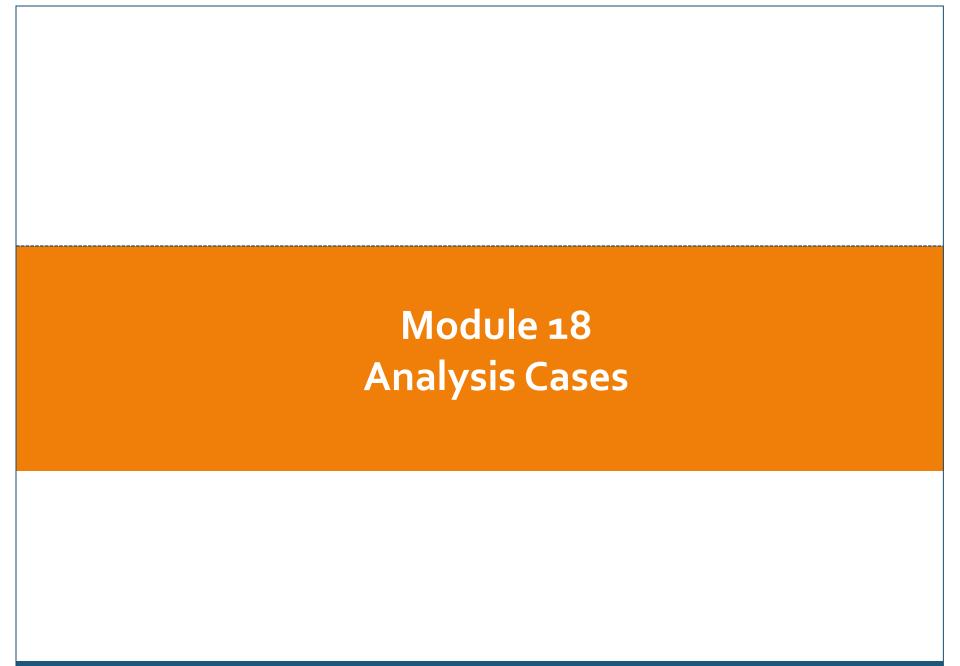
Use Case

A kind of case

- Subject of the use case (often the system of interest)
- Objective is to provide value to one or more actor
 - Stakeholders are typically external to the system of interest referred to as actors
- Required actions/steps performed by actors and subject to achieve the objective
- O Include use cases are always performed as part of the base use case
- Constraints can specify pre and post conditions

| «use case def» TransportPassenger |
|---|
| objective |
| doc Deiver passenger to destination |
| safely, comfortably, and within acceptable time |
| acceptable time |
| subject |
| vehicle:Vehicle |
| actors |
| driver:Driver |
| passengers:Passenger [04] |
| include use cases |
| getInVehicle:GetInVehicle |
| getOutOfVehicle:GetOutOfVehicle |
| constraints |
| start.vehicle.position==startingLocation |
| done.vehicle.position==endingLocation |



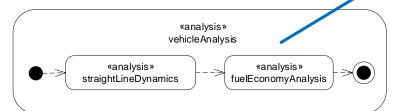






Analysis Case **v2**

- A set of steps with an objective to evaluate a result about a subject of the analysis
 - O A kind of behavior
 - Each step can be an action, calc, or an analysis case that can contain
 - subject
 - objective
 - input and output parameters
 - single return parameter (i.e., the result)
 - attributes bound to calculations and/or constraints to be solved by a solver
 - bind parameters to the subject



```
«analysis»
                   fuelEconomyAnalysis
                      subject
v=vehicle b
                     objective
doc Estimate the vehicle fuel economy
                       parameters
in scenario: Scenario
return_calculatedFuelEconomy:> km/l
                        attributes
distance = Traveled Distance (scenario)
tpd avg = AverageTravelTimePerDistance(scenario)
bsfc = ComputeBSFC(vehicle b.engine)
f a = BestFuelConsumptionPerDistance(vehicle b.mass, bsfc,
tpd avg, distance)
f b = IdlingFuelConsumptionPerTime(vehicle b.engine)
calculatedFuelEconomy=FuelConsumption(f_a, f_b, tpd_avg)
```

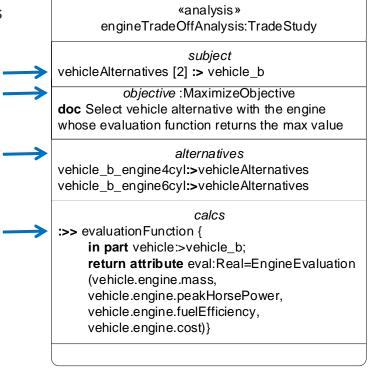
convert to liters / 100 km

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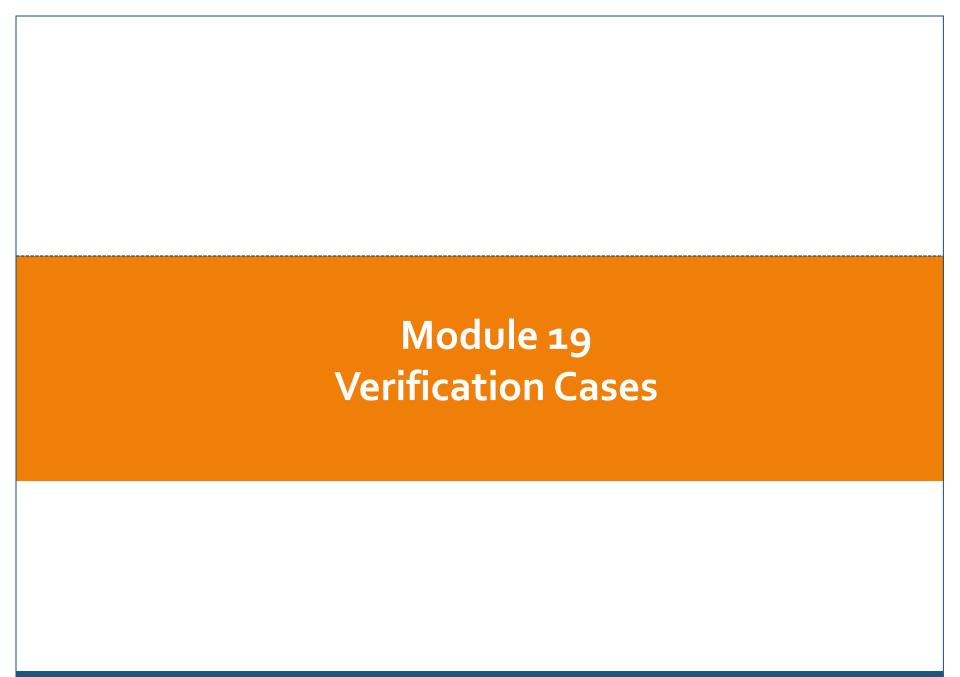
Trade-off Analysis **V2**

• A kind of analysis case

- Trade study objective is to select preferred solution that maximizes or minimizes some evaluation function
- Subject of the trade study are the vehicle alternatives with different engines
 - Alternatives can be modeled as variants
- Evaluate evaluation function for each alternative
 - Criteria are parameters of evaluation function
 - Each criteria may require separate analysis
- Rationale is a kind of annotation

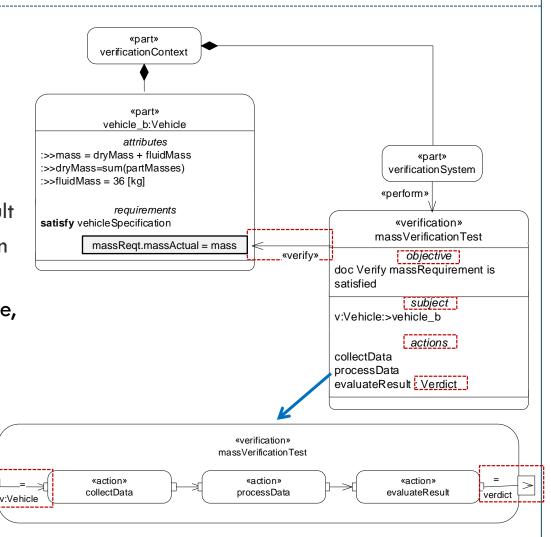


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Verification Case

- A set of steps with an objective to evaluate whether the subject of the verification satisfies one or more requirements
 - A kind of behavior
 - Steps typically include collect data, process/reduce data, evaluate result
 - Subject is an input to the verification
 - Returns a result called a verdict whose value is pass, fail, inconclusive, or error
 - Verify relationship relates verification case to requirement
 - Verification system interacts with subject to perform the verification case

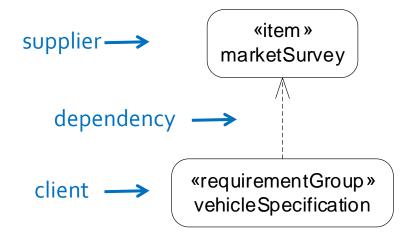


Module 20 Dependency, Allocation, and Cause-Effect Relationships



Dependency

- A directed relationship where the element on the client end may be impacted when the element on the supplier end changes
 - Example: Use of dependency to represent traceability between specification and source document
 - O Can have 1.. many clients and 1.. many suppliers



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Allocation

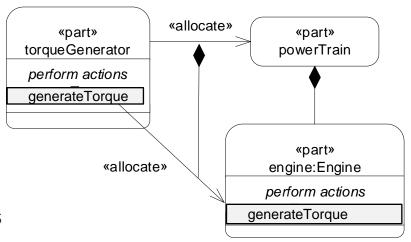
WZ

W2

SST

- A statement of intent that assigns responsibility
 from one set of elements to another set of elements
 - A kind of mapping (1 to n)
 - Includes definition and usage
 - Can include suballocations
- Examples
 - Actions to components
 - Logical components to physical components
 - Logical connections to physical connections
 - Budget allocation (e.g. weight budget)
 - Software to hardware
 - Requirements to design elements

O ...



The torque generator
Is allocated to the powertrain,
and realized by the engine



Cause-Effect Relationship **v2**

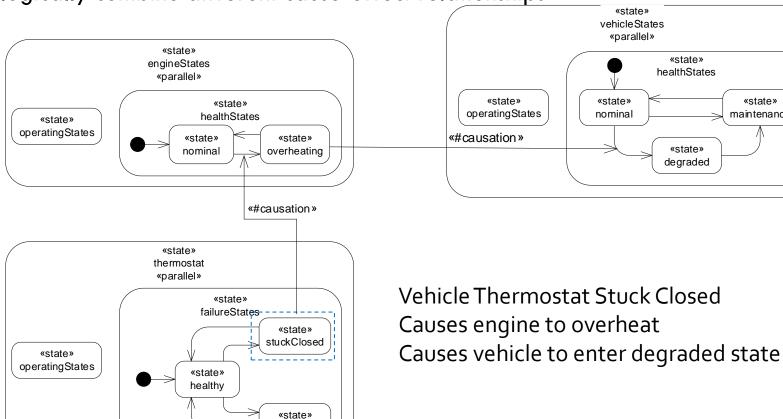


«state»

maintenance

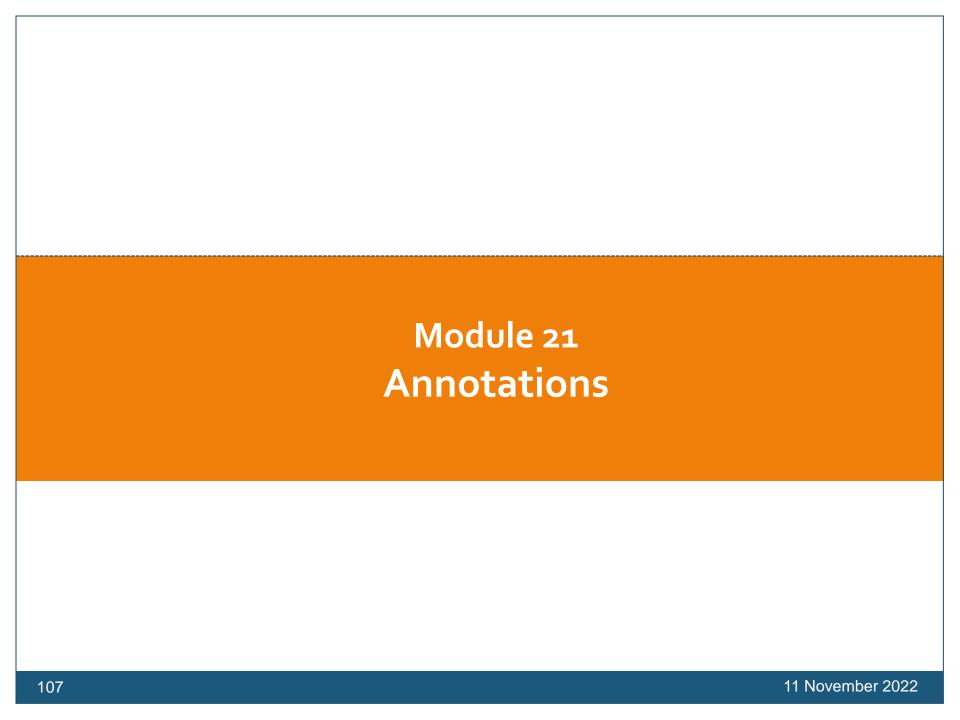
Single relationship can have multiple causes of multiple effects

Can logically combine different cause-effect relationships



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stuckOpen



Annotations

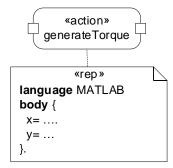
- An Annotating Element is an Element that is used to provide additional information about other elements
 - Can be named

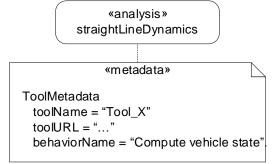
- Can apply to 0.. many elements
- An annotation is a kind of relationship that relates the VZ annotating element to the element being annotated
- Kinds of annotating elements
 - Comment
 - Documentation is an owned comment
 - Textual representation (e.g., opaque expression)
 - Includes name of language and body

- Metadata feature
 - Used to add structured metadata



«part» vehicle_b:Vehicle «comment» Refer to document xyz for full description





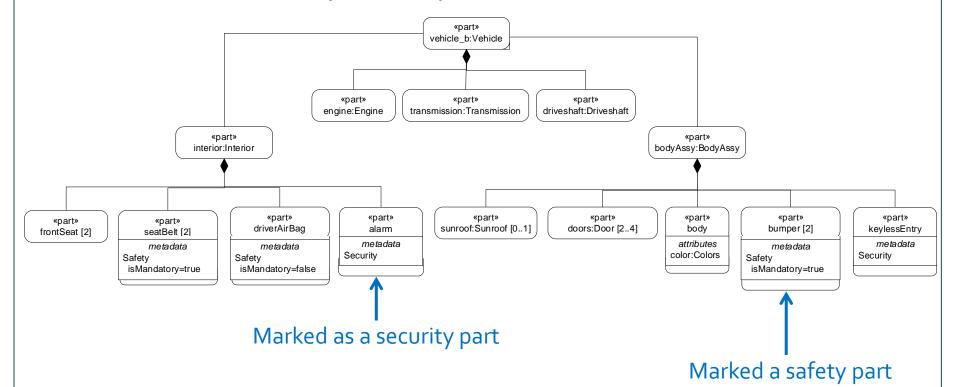
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Metadata

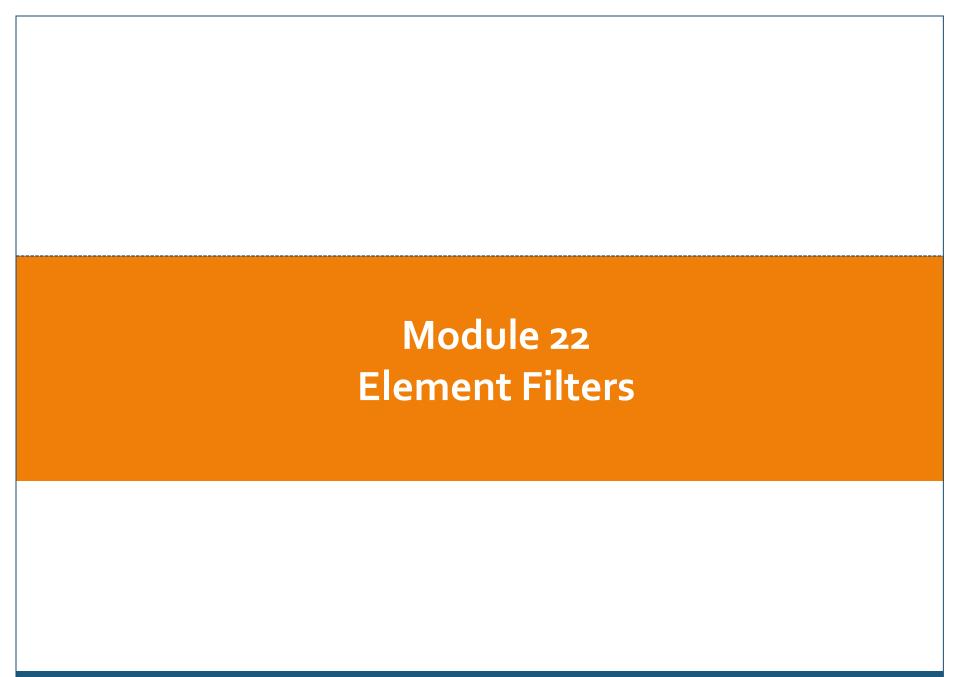
SST

- Use metadata to mark elements
 - Oldentify parts that are Security or Safety parts (e.g., members of Security of Safety group)
 - Can add additional security and safety information



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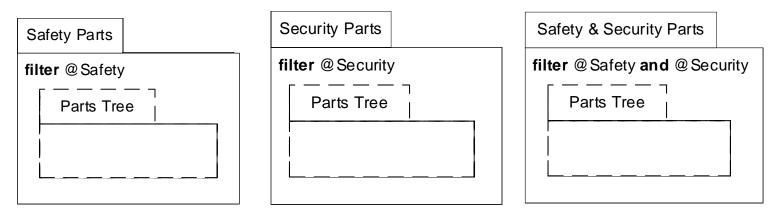
Additional info: isMandatory



Element Filters **v2**

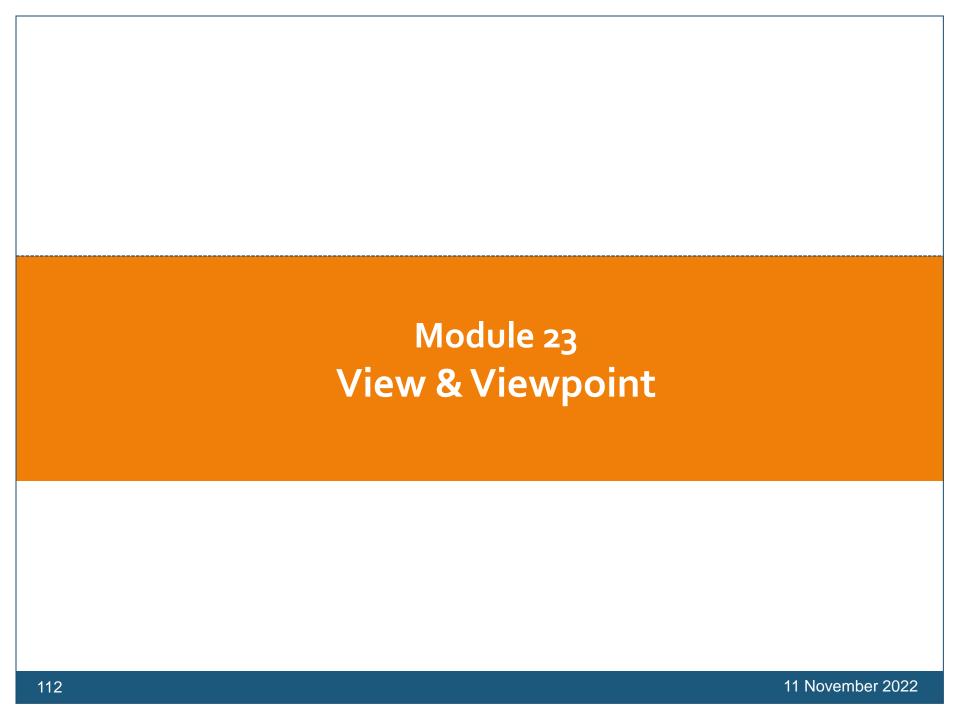


- Used to select elements from a group of elements
 - Create a package
 - Olmport the part of the model that contains the elements of interest
 - Use a recursive import to include all nested elements
 - O Define the filter expression to select the imported elements based on the selection criteria



Filter selects parts marked with Safety metadata

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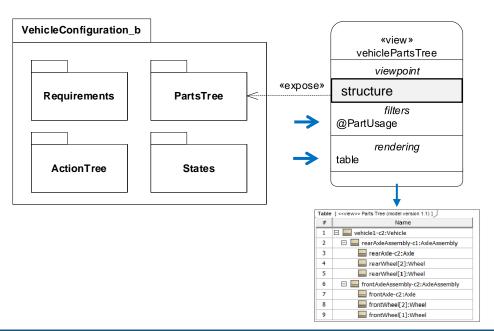
View and Viewpoint

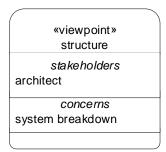


- A Viewpoint reflects the concerns of one more stakeholders in terms of what they care about relative to a domain of interest
- A View specifies an artifact to present to a stakeholder to satisfy their viewpoint
 - Exposes the scope of the model to be viewed
 - O Filters the model to select a particular subset based on a scope and filter criteria



- O Renders the filtered results using a particular presentation form and style
- Intended to support document generation (e.g., OpenMBEE)





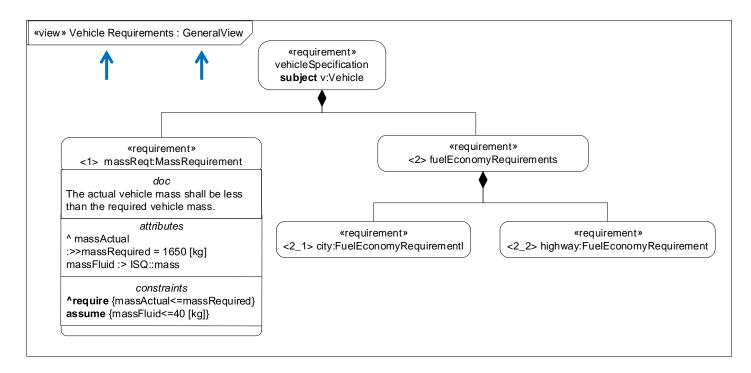
Include rendering in view compartment

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SysML v2 Views and Diagrams

- A view is a rendering of a selected model elements based on filter expression and exposed elements
 - Frame is the view element with view name **V2**
 - O View is defined by a view definition (e.g., diagram kind)
 - View content





Standard View Definitions (SysML v2 vs SysML v1) Baseline as of January 04, 2023

SST

| Legend | □ SysML v1 Diagrams | | | | | | | | | |
|---|---------------------|---------------------|--------------------|----------------------|----------------------|-------------------|--------------------|-------------------|--------------------|---------------------|
| → Allocated To | | agra | tion | Š | gram | ne | iagr | iagra | it Di | Diag |
| Standard views are normative, but user defined views are valid if they are consistent with the abstract syntax and graphical bnf. | | 🔲 1 Package Diagrat | 2 Block Definition | 🔲 3 Internal Block D | 🔲 4 Activity Diagram | S State Machine E | 🔲 6 Sequence Diagr | T Use Case Diagra | 🔲 8 Requirement Di | 🔲 9 Parametric Diag |
| ☐ SysML v2 Standard View Definitions | | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 1 |
| 1 General View (gv) | 3 | / | / | | | | | | / | |
| 2 Interconnection View (iv) | 2 | | | / | | | | | | / |
| - 3 Action Flow View - (afv) w and w/o swimlane | 1 | | | | / | | | | | |
| - 4 State Transition View (stv) | 1 | | | | | / | | | | |
| - 5 Sequence View (sv) | 1 | | | | | | / | | | |
| - 6 Case View (cv) | 1 | | | | | | | / | | |
| - 7 Geometry View (gev) | | | | | | | | | | |
| 8 Grid View (grv) | 1 | | | | | | | | / | |
| 9 Browser View (bv) | | | | | | | | | | |



SysML v2 Compartments



- Compartments are views of the element represented by the node VZ

- Compartment names represent view definitions
- Standard compartments / view definitions
 - Textual view of contained elements of a particular kind (e.g., attributes, actions, ports)
 - Textual view of elements at the other end of relationships (e.g., allocation, specialization, ...)
- A compartment can also be rendered using graphical notation
- Ports and parameters are connectable nested nodes on the boundary of a structure or behavior

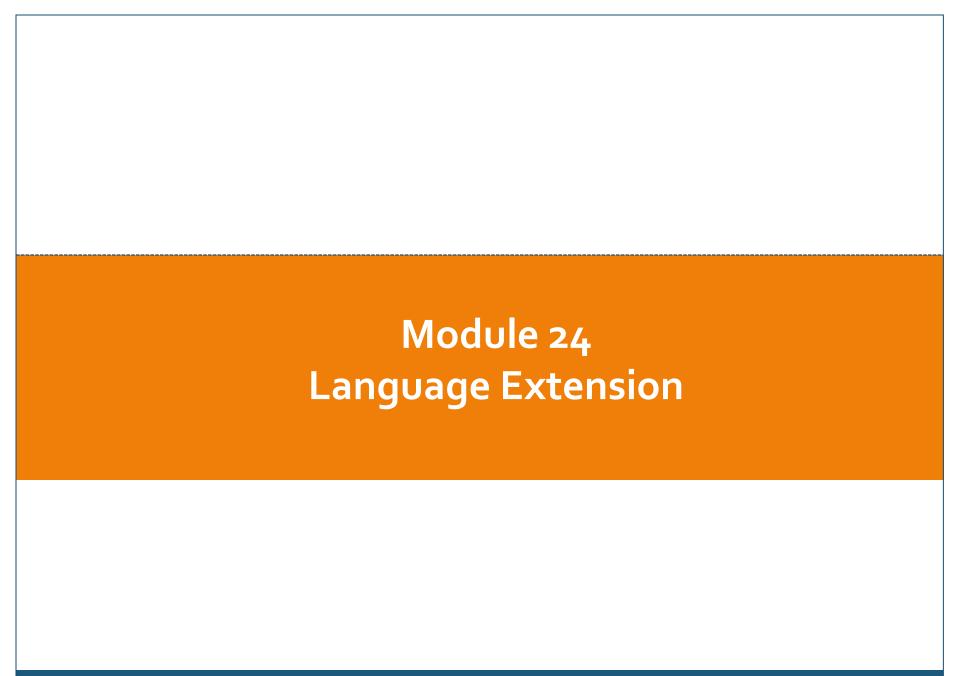
«part def» Vehicle

attributes mass:>ISQ::mass dryMass cargoMass electricalPower position velocity accele ration

ports pwrCmdPort vehicleToRoadPort

perform actions provide Power provideBraking controlDirection

exhibit states vehicleStates





Language Extension

- Provides ability to extend concepts in SysML v2 to address domain-specific concepts and terminology
- Define concept by subclassing an element in the SysML Model Library
- Define the keyword using metadata state 'failure modes'[*] nonunique;

define the concept

```
SysML Model
Library
```

«stateUsage» states

«stateUsage» failure modes

 Apply the concept to an element by annotating it with the metadata

#'failure mode' flatTire;

#fm flatTire;

«#failure mode»
flatTire

apply the concept ->

«#fm»
flatTire





SysML v2 to v1 Terminology Mapping (partial)

SST

| SysML v2 | SysML v1 |
|-------------------------------|--|
| part / part def | part property / block |
| attribute / attribute def | value property / value type |
| port / port def | proxy port / interface block |
| action / action def | action / activity |
| state / state def | state / state machine |
| constraint / constraint def | constraint property / constraint block |
| requirement / requirement def | requirement |
| connection / connection def | connector / association block |
| view / view def | view |

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Contrasting SysML v1 with SysML v2 SST

Simpler to learn and use

- Systems engineering concepts designed into metamodel versus added-on
- Consistent definition and usage pattern
- More consistent terminology
- Ability to decompose parts, actions, ...
- More flexible model organization (unowned members, package filters)...

More precise

- Textual syntax and expression language
- Formal semantic grounding
- Requirements as constraints
- Reified relationships (e.g., membership, annotation)

More expressive

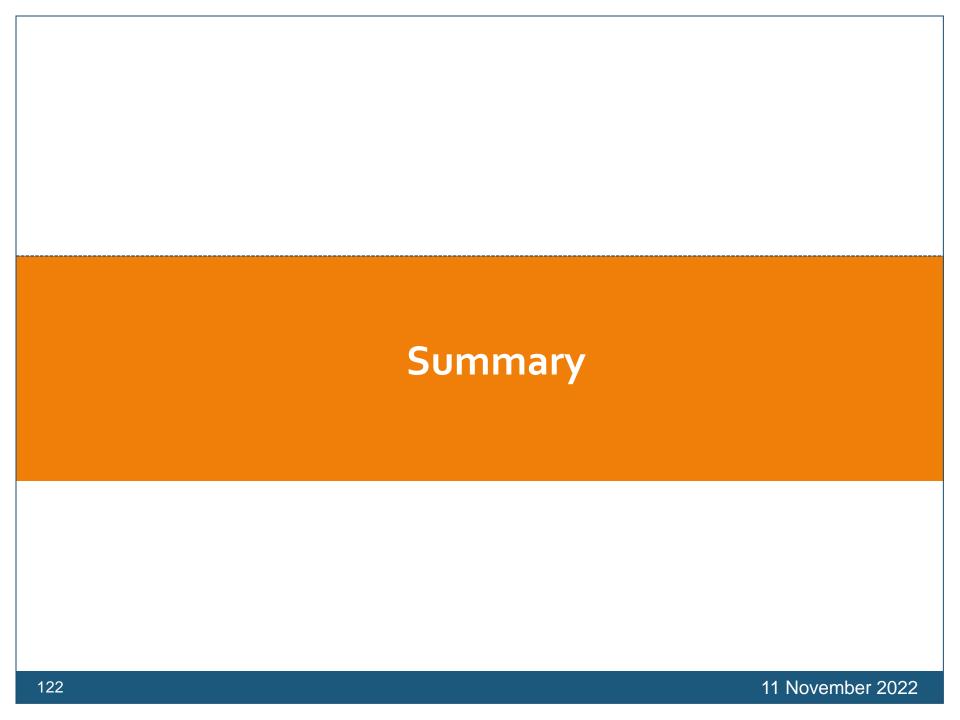
- Variant modeling
- Analysis case
- Trade-off analysis
- Individuals, snapshots, time slices
- More robust quantitative properties (e.g., vectors, ..)
- Simple geometry
- Query/filter expressions
- Metadata

More extensible

- Simpler language extension capability
 - Based on model libraries

More interoperable

Standardized API





Summary



- SysML v2 is addressing SysML v1 limitations to improve MBSE adoption and effectiveness
 - O Precision, expressiveness
 - Regularity, usability
 - Interoperability with other engineering models and tools
- Approach
 - Simplified SysML v2 metamodel with formal semantics overcomes fundamental UML limitations
 - O Flexible graphical notations and textual notation
 - Standardized API for interoperability
- Roadmap established to final submission



References

- Monthly Release Repository (release 2021-12)
 - O https://github.com/Systems-Modeling/SysML-v2-Release
- SysML v2 Specification (revised submission)
 - O Note: refer to Annex B for Example Vehicle Model
- Introduction to the SysML v2 Language Textual Notation (release 2021-08)
- Friedenthal S., Seidewitz E., A Preview of the Next Generation System Modeling Language (SysML v2), Project Performance International (PPI), <u>Systems</u>
 <u>Engineering Newsletter, PPI SyEN 95 27 November, 2020</u>

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