# Manual for the numerical functions package\*

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March 1, 2013

<sup>\*</sup>This work was performed under the auspices of the U.S. Department of Energy by Lawrence Livermore National Laboratory under contract #W-7405-ENG-48.

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# 1 Introduction

The **ptwXY** C object (i.e., an instance of C typedef **ptwXYPoints**) and supporting C routines are designed to handle point-wise interpolative data representing a function of one independent variable (i.e., y = f(x)). That is, a **ptwXY** object consist of an list of pairs  $(x_i, y_i)$  where  $x_i < x_{i+1}$  and  $y_i = f(x_i)$ . Henceforth, the **ptwXY** C object and supporting C routines are called the **ptwXY** model. Routines supporting common operations on the points of f(x) are included in this package. As example, a function exists to add two **ptwXY** instances returning the sum as a **ptwXY** instances (i.e., h(x) = f(x) + g(x) where f(x), g(x) and h(x) are all **ptwXY** objects). The main intent for developing this library is for a fast XY math object for LLNL's FUDGE package which manipulates nuclear data (e.g., it can be used to add cross section from different reactions). However, this library may be useful for other packages.

As example of the usage of  $\mathbf{ptwXY}$  objects consider the data in Table 1. This table list the male and female populations of a bird species on an island for several census years. In this example,  $x_i$  represents a census year and  $y_i$  represents the population for that year. Note that the male population is not given for the year 1885. A portion of a simple C routine to put the male and female populations into  $\mathbf{ptwXY}$  objects and add them together to get the total population is:

```
#include <ptwXY.h>
#define nPairs 7
   double maleData[2 * (nPairs-1)] = { 1871, 1212, 1883, 1215, 1889,
        51, 1895, 11, 1905, 9, 1915,
                                       9 };
    double femaleData[2 * nPairs] =
                                        { 1871, 1231, 1883, 1241, 1885,
        621, 1889, 229, 1895, 31, 1905, 23, 1915, 21 };
    ptwXYPoints *males, *females, *total;
   ptwXY_interpolation linlin = ptwXY_interpolationLinLin;
   nfu_status status;
   males = ptwXY_new( linlin, 5, 1e-3, nPairs, 4, &status, 0 );
   ptwXY_setXYData( males, nPairs - 1, maleData );
   females = ptwXY_new( linlin, 5, 1e-3, nPairs, 4, &status, 0 );
   ptwXY_setXYData( females, nPairs, femaleData );
   total = ptwXY_add_ptwXY( males, females, &status );
   printf( "\nMale population\n" );
   printf( " Year | Count\n" );
```

year	Male	Female
1871	1212	1231
1883	1215	1241
1885		621
1889	51	229
1895	11	31
1905	9	23
1915	9	21

Table 1: Males and females population of a bird species on an island for the years census were taken. There was no census taken of the male population in 1885.

```
printf( " -----+----\n" );
ptwXY_simplePrint( males, " %5.0f | %5.0f\n" );

printf( "\nFemale population\n" );
printf( " Year | Count\n" );
printf( " -----+----\n" );
ptwXY_simplePrint( females, " %5.0f | %5.0f\n" );

printf( "\nTotal population\n" );
printf( " Year | Count\n" );
printf( " Year | Count\n" );
printf( " -----+----\n" );
ptwXY_simplePrint( total, " %5.0f | %5.0f\n" );
```

The output of this code - compressed into fewer lines - is:

Output from first | Output from second | Output from third ptwXY\_simplePrint | ptwXY\_simplePrint | ptwXY\_simplePrint

Male population		Female population		Total population
Year   Count	-	Year   Count		Year   Count
1871   1212		1871   1231		1871   2443
1883   1215		1883   1241		1883   2456
1889   51		1885   621		1885   1448
1895   11	-	1889   229		1889   280
1905   9		1895   31		1895   42
1915   9		1905   23	-	1905   32

| 1915 | 21 | 1915 | 30

In this example no error checking is shown. The routine **ptwXY\_new** allocates memory for a new **ptwXYPoints** object, initializes it and returns a pointer to the object. The first argument of this routine in an interpolation flag. For all other arguments see Section 5.1.1 The routine **ptwXY\_setXYData** takes a pointer to a **ptwXYPoints** object as its first argument and copies the list of doubles given by the third argument into the **ptwXYPoints** object's internal memory, deleting any data currently in the object. The second argument is the number of pairs of points in the third argument's data.

The routine **ptwXY\_add\_ptwXY** takes a **ptwXYPoints** object as its first and second arguments and returns a new **ptwXYPoints** object that is the sum. The summed object's x values are a union between the x value's of the operants. As can be seen from the example, this routine interpolates to fill in missing data for either data set. That is, the male population was linear-linear interpolated to give 827 for the year 1885.

# 1.1 Important concepts

This section describes several important concepts and rules that the **ptwXY** model is build on.

### 1.1.1 accuracy

# 1.1.2 Mutual domains

Most routines that have two or more **ptwXYPoints** instances as input (e.g., ptwXY\_add\_ptwXY, ptwXY\_groupThreeFunctions) require that their domains be mutual. This section explains why mutual domains are needed and what a mutual domain is.

Consider the two point-wise linear-linear interpolable functions

$$f1 = (1,1), (9,3)$$
  
 $f2 = (1,2), (9,4).$ 

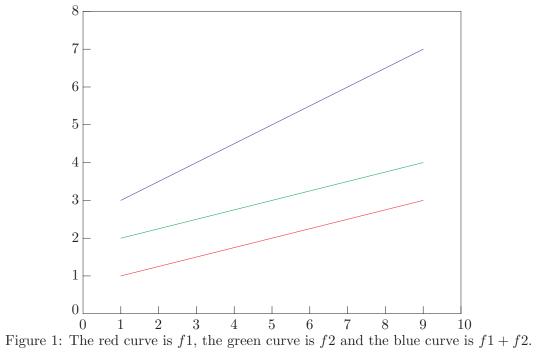
where a point-wise function with n points is written as

$$(x_0, y_0), (x_1, y_1), (x_2, y_2), \dots (x_{n-1}, y_{n-1})$$

and each point is the pair  $(x_i, y_i)$  with  $x_i < x_{i+1}$ . Each of these functions contains only two points. The first has domain  $1 \le x \le 9$  with the y-value going from 1 to 3 and can be represented symbolically as y = f1(x) = (x - 1)/4 + 1 for the domain  $1 \le x \le 9$ . The second has the same domain with the y-value going from 2 to 4 and can be represented symbolically as y = f2(x) = (x - 1)/4 + 2. The rule that should be implemented for adding these two functions is clear and is s(x) = (x - 1)/2 + 3 = f1(x) + f2(x) or in point-wise form

$$(1,3), (9,7) = f1 + f2$$

For the domain  $1 \le x \le 9$ , the point-wise linear-linear interpolable sum and the symbolic sum yield the same results. For example, both yield s(3) = 4. Figure 1 graphically shows f(1), f(2) and f(1) and f(3) are f(3) and f(3) and f(3) are f(3) and f(3) and f(3) are f(3) are f(3) are f(3) are f(3) and f(3) are f(3) are f(3) and f(3) are f(3) are f(3) are f(3) are f(3) and f(3) are f(3) are f(3) are f(3) are f(3) are f(3) are f(3) and f(3) are f(3)



Now consider the point-wise linear-linear interpolable function

$$f3 = (3,1), (7,3).$$

This function also contains only two points and has domain  $3 \le x \le 7$  with a y-value going of 1 to 3. This function can be represented symbolically as y = f3(x) = (x-3)/2 + 1. The rule that should be implemented for adding f1 and f3 is not obvious. For example, one could implement the rule which makes a union of the x-values in f1 and f3 (i.e., 1, 3, 7 and 9), interpolate each function onto these points using 0 where the function is not defined and then add the y-values. Let f1' and f3' be the functions f1 and f3 with the union points and the y-values filled in. In point-wise representation, f1' and f3' are

$$f1' = (1,1), (3,1.5), (7,2.5), (9,3)$$
  
 $f3' = (1,0), (3,1), (7,3), (9,0).$ 

The sum resulting from this rule is then

$$(1,1)$$
,  $(3,2.5)$ ,  $(7,5.5)$ ,  $(9,3) = f1' + f3' = f1 + f3$ .

and is shown as the blue curve in Fgure 2. The blue curve is not vary appealing in part because for this addition rule the sum of f3 with f1 makes the assumption that f3(x) = (x-1)/2 for  $1 \le x \le 3$ . But what is worse, this rule does not guarantee the associativity rule for addition. To see this, consider the three linear-linear point-wise functions

$$g1 = (1,0), (1,1),$$
 (10,10)  
 $g2 = (1,0),$  (10,10)  
 $g3 =$  (2,1), (10,1).

Note that q1 and q2 represent the same function. The addition (q1+q2)+q3 is

$$(0,0)$$
,  $(1,2)$ ,  $(2,5)$ ,  $(10,21) = (g1 + g2) + g3$ 

while the addition g1 + (g2 + g3) is

$$(0,0)$$
,  $(1,2.5)$ ,  $(2,5)$ ,  $(10,21) = g1 + (g2 + g3)$ .

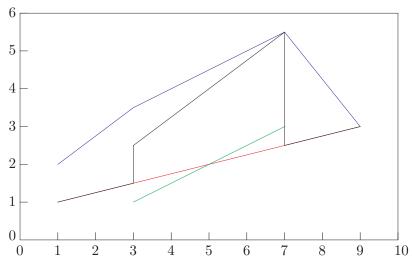


Figure 2: The red curve is f1, the green curve is f2 and the blue curve is f1 + f3 using the first rule and the black curve is f1 + f3 using the second rule.

Another rule one could implement would effectively add a point with y = 0 just below the first point of f3, one just above the last point of f3, one at x = 1 and one at x = 9 to yield an f3' as

$$f3' = (1,0), (2.99999,0), (3,1), (7,3), (7.00001,0), (9,0).$$

and the sum f1 + f3 would then be

$$(1,1)$$
,  $(2.99999,1.4999975, (3,2.5), (7,5.5), (7.00001, 2.5000025), (9,3)$ 

The sum resulting from this latter rule is shown as the black curve in Fgure 2. This rule looks much better and is. However, when designing the **ptwXYPoints** model, this rule was also rejected as it would require the **ptwXYPoints** library to know the appropriate distance below and above the end-points to add 0's.

The rule that the **ptwXYPoints** model implements is called "mutual domain". This rule states that the domains of the functions operated on must be the same with one exception. This exception will now be explained. Let h1 and h2 be two **ptwXYPoints** instances with the lower and upper domain limits of h1 being  $x_{1,l}$  and  $x_{1,u}$  and that of h2 being  $x_{2,l}$  and  $x_{2,u}$ . If  $x_{1,l} \neq x_{2,l}$  then the y-value for the greater lower-x-limit must be 0. For example, if  $x_{1,l} > x_{2,l}$  then  $h2(x_{2,l}) = 0$ . If  $x_{1,u} \neq x_{2,u}$  then the y-value for the lesser upper-x-limit must be 0. For example, if  $x_{1,u} < x_{2,u}$  then  $h1(x_{1,u}) = 0$ . This rule works because the **ptwXYPoints** model assumes that if the y-value is 0 at the lower limit, then it is 0 for all x less than the lower limit. Likewise if the y-value is 0 at the upper limit, then it is 0 for all x greater than the upper limit.

If f4 and f5 have mutual domains, and f4 and f6 have mutual domains, the it is not guaranteed that f5 and f6 have mutual domains. As an example, let

```
f4 = (1,4), (8,4)

f5 = (3,0), (8,2)

f6 = (4,3), (6,0).
```

Then, f4 and f5 have mutual domains and so do f5 and f6. However, f4 and f6 do not have mutual domains. Because of this fact, the function ptwXY\_groupThreeFunctions has to check the domains of ptwXY1 to ptwXY2, ptwXY1 to ptwXY3 and ptwXY2 to ptwXY3. Acutally, ptwXY\_groupThreeFunctions first limits the domains of ptwXY1, ptwXY2 and ptwXY3 to that of groupBoundaries first.

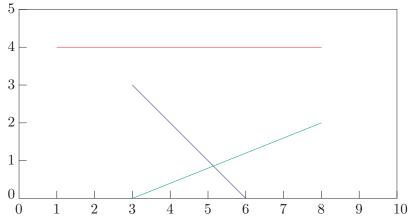


Figure 3: The red curve is f4, the green curve is f5 and the blue curve is f6. The domains of f4 and f5 are mutual as are the domains of f5 and f6. However, the domains of f4 and f6 are not mutual.

### 1.1.3 Infill

The addition of two linear functions yields another linear function. As example, the sum of  $f1(x) = s1 \times x + y1$  and  $f2(x) = s2 \times x + y2$  is  $f1(x) + f2(x) = (s1 + s2) \times x + y1 + y2$ . Hence, when the function **ptwXY\_add\_ptwXY** adds two linear-linear pointwise functions, it only needs to make a union of the x-values of the two addends to maintain accuracy. However, the multiplication of f1(x) and f2(x) is not a linear function but a quadratic function (e.g.,  $f1(x) \times f2(x) = s1 \times s2 \times x^2 + (s1 \times y2 + s2 \times y1) \times x + y1 \times y2$ ). In an attempt to maintain accuracy, the function **ptwXY\_mul2\_ptwXY** may add additional points between the union points. For example, consider the following linear-linear point-wise functions f3 and f4,

$$f3 = (0,0), (1,1)$$
  
 $f4 = (0,1), (1,0)$ 

which have the symbolic forms  $f_3(x) = x$  and  $f_4(x) = 1 - x$  over the domain  $0 \le x \le 1$  and the symbolic product x(1-x). Making a union of the x-values and evaluating the product on the x-values yields

$$(0,0), (1,0) = f3 * f4$$

which is clearly inadequate. For this example, the only way to maintain the accuracy is to add points between x = 0 and x = 1. The adding of points in an attempt to maintain accuracy is called infilling and is done automatically by some **ptwXYPoints** functions including **ptwXY\_mul2\_ptwXY** but not by **ptwXY\_mul\_ptwXY**.

Infilling is done by bisecting (i.e., generating the point midway between) two consecutive points and asking if the accuracy of the operation (e.g., mutiplication) is satisfied. If it is, the midpoint is not added. However, if the accuracy is not satisfied, the midpoint is added then the segments on both side of the midpoint are tested.

In some cases, infilling can add a lot of points, more than one may like. Each **ptwXYPoints** instance has a member called **biSectionMax** to limit bisecting. The union function sets the **biSectionMax** of the returned **ptwXYPoints** instance, to the maximum of **biSectionMax** of its inputted **ptwXYPoints** instances. For each initial segment of the union at most **biSectionMax** bisections are performed. Table 2 contains a snippet of code which demonstrates the multiplication f3 and f4, without any error checking of course, for **biSectionMax** set to 0, 1, 2, and 3, and Figure 4 show the output from this code.

```
int main( int argc, char **argc ) {
    double f3[4] = \{ 0., 0., 1., 1. \}, f4[4] = \{ 0., 1., 1., 0. \};
    double accuracy = 1e-3;
    ptwXYPoints *ptwXY3, *ptwXY4;
    nfu_status status;
    ptwXY_interpolation linlin = ptwXY_interpolationLinLin;
    ptwXY3 = ptwXY_create( linlin, 0, accuracy, 10, 10, 2, f3, &status, 0 );
    ptwXY4 = ptwXY_create( linlin, 0, accuracy, 10, 10, 2, f4, &status, 0 );
    doProduct( ptwXY3, ptwXY4, 0 );
    doProduct( ptwXY3, ptwXY4, 1 );
    doProduct( ptwXY3, ptwXY4, 2 );
    doProduct( ptwXY3, ptwXY4, 3 );
}
void doProduct( ptwXYPoints *ptwXY3, ptwXYPoints *ptwXY4, double biSection ) {
    ptwXYPoints *product;
    nfu_status status;
    ptwXY_setBiSectionMax( ptwXY3, biSection );
    product = ptwXY_mul2_ptwXY( ptwXY3, ptwXY4, &status );
}
```

Table 2: This table show a snippet of the code used to generate the curves in Figure 4

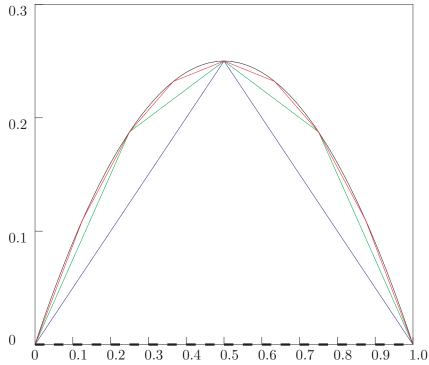


Figure 4: The solid black curve is the function x(1-x). The blue, grean and red curves are products of  $f3 \times f4$  from ptwXY\_mul2\_ptwXY for biSectionMax of 1, 2 and 3 respectively. The solid black curve and the red curve are nearly identical. The dashed thicker black line at the bottom of the plot is the product for biSectionMax = 0.

If infilling is needed, the **biSectionMax** member of the returned **ptwXYPoints** instance is reduced by  $\ln(l_f/l_u)/\ln(2)$  where  $l_u$  is the length of the union and  $l_f$  is the final length after all bisections<sup>1</sup>. An **ptwXYPoints** instance's **biSectionMax** can be set using **ptwXY\_setBiSectionMax** and got using **ptwXY\_setBiSectionMax**. A **ptwXYPoints**'s **biSectionMax** is limited to the range 0 to **ptwXY\_maxBiSectionMax**.

# 1.1.4 Safe divide

# 2 Name convention

This section defines some of the names used in this document.

**point:** A point is a pair of (x, y) values.

cache and array: In this document there is a distinction between a cache and an array of a cache. A cache is allocated memory used to store data. An array of a cache is a region of a cache containing valid data. As example, for the primary cache described in section 3, points are added to the cache as needed. The current points in the cache constitute the array of that cache.

# 3 Two-cached, Dynamic-Growth Data Array

Built into the  $\mathbf{ptwXY}$  model is the ability to insert a point at any x. The supporting routines will automatically increase the size of an internal data cache if needed to accommodate a new x value. However, to make adding and deleting points potentially more efficient, the  $\mathbf{ptwXY}$  model has two data caches, dubbed primary and secondary. In the primary cache, data are stored in a C array in ascending order which allows for quick accessing. However, inserting a new x value at any place other than the end of the array can be slow as it requires moving all x values that are greater than the new value up one element in the array. To over come this, a newly added x value is inserted into the secondary cache if: 1) the value cannot be inserted after the last element of the primary array<sup>2</sup> and 2) space is available in the secondary cache. The secondary cache is a static, linked list. Here, static means that the elements of the linked list are allocated during setup so there is no overhead associated with allocating or freeing elements of the linked list later. Typically, re-allocation of the memory of the primary cache is only required when a new x value cannot be inserted into either cache.

There are four parameters, two for each cache, that describe the current state of the caches. Each cache has a size which is the amount, in units of an element of that cache, of memory allocated

<sup>&</sup>lt;sup>1</sup>This reduction is derived by setting  $2^z = l_f/l_u$  and solving for z.

<sup>&</sup>lt;sup>2</sup>A value can only be inserted after the last element of the primary array if its x is greater than the current maximum x value and there is room in the primary cache.

for the cache and a length which is the amount, in units of an element of that cache, of the cache that is currently used (i.e., the size of the array of that cache).

The initial size of the two caches is set either through the routine **ptwXY\_new** or **ptwXY\_setup** via their **primarySize** and **secondarySize** arguments. The size of the primary and secondary caches can be directly altered after they have been created via the routines **ptwXY\_reallocatePoints** and **ptwXY\_reallocateOverflowPoints** respectively. In general these last two routines should not be called by the users unless they know that the a cache is woefully too small.

The routine **pwtXY\_coalescePoints** can be called to transfer all secondary points into the primary cache.

# 4 ptwXYPoints's C structs, macros and enums

The following definitions are defined in the C header file "ptwXY.h".

# 4.1 ptwXYPoints

```
The ptwXYPoints type is defined as:
```

```
typedef
    struct ptwXYPoints_s {
        nfu_status status;
        ptwXY_sigma typeX, typeY;
        ptwXY_interpolation interpolation;
        int userFlag;
        double biSectionMax;
        double accuracy;
        double minFractional_dx;
        int64_t length;
        int64_t allocatedSize;
        int64_t overflowLength;
        int64_t overflowAllocatedSize;
        int64_t mallocFailedSize;
        ptwXYOverflowPoint lessThanEqualXPoint, greaterThanXPoint;
        ptwXYOverflowPoint overflowHeader;
        ptwXYPoint *points;
        ptwXYOverflowPoint *overflowPoints;
    } ptwXYPoints;
```

The **ptwXYPoint** type is defined as:

typedef

```
struct ptwXYPoint_s {
    double x, y;
} ptwXYPoint;
```

The type **ptwXYOverflowPoint** will not be described here as it is not used as an argument in any routine and its members in **ptwXYPoints** should not be accessed user codes.

### 4.2 C macros

This section lists some of the C macros defined in "ptwXY.h".

# 4.3 Interpolation

For an x value that is within the domain of a **ptwXYPoints** object but not one of its points, the **ptwXYPoints** routines interpolate, as instructed by the member **interpolation**, to obtain the y value. Interpolation types are defined using the type **ptwXY\_interpolation** which is defined as:

```
typedef enum ptwXY_interpolation_e {
   ptwXY_interpolationLinLin, /* x and y linear. */
   ptwXY_interpolationLinLog, /* x linear and y logarithmic. */
   ptwXY_interpolationLogLin, /* x logarithmic and y linear. */
   ptwXY_interpolationLogLog, /* x and y logarithmic. */
   ptwXY_interpolationFlat, /* see below */
   ptwXY_interpolationOther /* see below */
} ptwXY_interpolation;
```

The latter two interpolation types have many restrictions. For ptwXY\_interpolationFlat the y for  $x_i \leq x < x_{i+1}$  is  $y_i$ . This type is good for storing histogram type data. Many of the functions in the **ptwXY** library cannot handle the flat interpolation and return the error nfu\_invalidInterpolation via their nfu\_status argument. The interpolation type ptwXY\_interpolationOther allows the use of ptwXY storage type for data that does not fit into one the other defined interpolation types. Most functions cannot handle the other interpolation and also return the error nfu\_invalidInterpolation.

### 4.4 Data types

Currently, the **ptwXY** model only supports a point as an (x, y) pair. In the future uncertainty values may be added to both the x and y values. For examples, the y value could have an uncertainty dy, in which case a point would require 3 values (x, y, dy). The data type **ptwXY\_sigma** specify the the number of values and their meaning for each axis and is defined as:

```
ptwXY_sigma_plusMinus, /* Currently not supported. */
ptwXY_sigma_Minus, /* Currently not supported. */
ptwXY_sigma_plus /* Currently not supported. */
} ptwXY_sigma;
```

# 4.5 Miscellaneous types

The routine **ptwXY\_getPointsAroundX** is used by other routines to determine where an x value fits into a **ptwXYPoints** object. The return value of this routine is of type **ptwXY\_lessEqual-GreaterX** which is defined as:

Here, xMin and xMax are the minimum and maximum x values of the **ptwXYPoints** object, and  $x_i$  and  $x_{i+1}$  are the  $(i-1)^{th}$  and  $i^{th}$  x values of the **ptwXYPoints** object respectively.

# 5 Routines

### **5.1** Core

This section decribes all the routines in the file "ptwXY\_core.c".

# 5.1.1 ptwXY\_new

This routine allocates memory for a new **ptwXYPoints** object and initializes it by calling **ptwXY-**\_**setup**.

### C declaration:

interpolation: The type of interpolation to use.
biSectionMax: The maximum disection allowed.

accuracy: The interpolation accuracy of the data.

primarySize: Initial size of the primary cache. secondarySize: Initial size of the secondary cache.

status: On return, the status value.

userFlag: An user defined integer value not used by any ptwXY function.

If this routine fails, NULL is returned.

### 5.1.2 ptwXY\_setup

This routine initializes a **ptwXYPoints** object and must be called for a **ptwXYPoints** object before that object can be used by any other routine in this package.

### C declaration:

ptwXY: A pointer to a ptwXYPoints object to initialize.

interpolation: The type of interpolation to use.

biSectionMax: The maximum disection allowed.

accuracy: The interpolation accuracy of the data.

primarySize: Initial size of the primary cache. secondarySize: Initial size of the secondary cache.

userFlag: An user defined integer value not used by any ptwXY function.

The primary and secondary caches are allocated with routines **ptwXY\_reallocatePoints** and **ptwXY\_reallocateOverflowPoints** respectively.

# 5.1.3 ptwXY\_create

This routines combines ptwXY\_new and ptwXY\_setXYData.

# C declaration:

double biSectionMax,
double accuracy,
int64\_t primarySize,

int64\_t secondarySize,

int64\_t length,
double \*xy ),
fnu\_status \*status,

int userFlag );

interpolation: The type of interpolation to use.
biSectionMax: The maximum disection allowed.

accuracy: The interpolation accuracy of the data.

primarySize: Initial size of the primary cache.
secondarySize: Initial size of the secondary cache.

length: The number of points in xy.

xy: The new points given as  $x_0, y_0, x_1, y_1, \ldots, x_n, y_n$  where n = length - 1.

status: On return, the status value.

userFlag: An user defined integer value not used by any ptwXY function.

If this routine fails, NULL is returned.

### 5.1.4 ptwXY\_createFrom\_Xs\_Ys

This routines is like **ptwXY\_create** except the x and y data are given in separate arrays.

interpolation: The type of interpolation to use.
biSectionMax: The maximum disection allowed.

accuracy: The interpolation accuracy of the data.

primarySize: Initial size of the primary cache.
secondarySize: Initial size of the secondary cache.

length: The number of points in xy.

Xs: The new x points given as  $x_0, x_1, \ldots, x_n$  where n = length - 1. Ys: The new y points given as  $y_0, y_1, \ldots, y_n$  where n = length - 1.

status: On return, the status value.

userFlag: An user defined integer value not used by any ptwXY function.

If this routine fails, NULL is returned.

# 5.1.5 ptwXY\_copy

This routine clears the points in **dest** and then copies the points from **src** into **dest**. The **src** object is not modified.

# C declaration:

dest: A pointer to the destination ptwXYPoints object.src: A pointer to the source ptwXYPoints object.

# 5.1.6 ptwXY\_clone

This routine creates a new **ptwXYPoints** object and sets its points to the points in its first argument.

```
ptwXY: A pointer to the ptwXYPoints object.
status: On return, the status value.
```

If an error occurs, NULL is returned.

#### 5.1.7ptwXY\_slice

This routine creates a new ptwXYPoints object and sets its points to the points from index index1 inclusive to index2 exclusive of ptwXY.

#### C declaration:

```
ptwXYPoints *ptwXY_slice( ptwXYPoints *ptwXY,
                            int64_t index1,
                            int64_t index2,
                            int64_t secondarySize,
                            fnu_status *status );
                 A pointer to the ptwXYPoints object.
ptwXY:
index1:
                 The lower index.
                 The upper index.
index2:
```

Initial size of the secondary cance. secondarySize:

On return, the status value. status:

If an error occurs, NULL is returned.

# 5.1.8 ptwXY\_xSlice

This routine creates a new ptwXYPoints object and sets its points to the points from the points between the domain xMin and xMax of ptwXY. If fill is true, points at xMin and xMax are added if not in the inputted **ptwXY**.

# C declaration:

```
ptwXYPoints *ptwXY_xSlice( ptwXYPoints *ptwXY,
                            double xMin,
                            double xMax,
                            int64_t secondarySize,
                            int fill,
                            fnu_status *status );
```

A pointer to the **ptwXYPoints** object. ptwXY:

xMax: The lower domain value. xMax: The upper domain value.

secondarySize: Initial size of the secondary cahce. fill: Initial size of the secondary cahce. status: On return, the status value.

If an error occurs, NULL is returned.

# 5.1.9 ptwXY\_xMinSlice

This routine creates a new **ptwXYPoints** object and sets its points to the points from the points between the domain **xMin** to the end of **ptwXY**. If **fill** is true, point at xMin is added if not in the inputted **ptwXY**.

# C declaration:

ptwXY: A pointer to the ptwXYPoints object.

xMin: The lower domain value.

secondarySize: Initial size of the secondary cahce.

fill: Initial size of the secondary cahce.

status: On return, the status value.

If an error occurs, NULL is returned.

# 5.1.10 ptwXY\_xMaxSlice

This routine creates a new **ptwXYPoints** object and sets its points to the points from the points between the domain of the beginning of **ptwXY** to xMax. If fill is true, point at xMax is added if not in the inputted **ptwXY**.

### C declaration:

```
ptwXYPoints *ptwXY_xMaxSlice( ptwXYPoints *ptwXY, double xMax, int64_t secondarySize, int fill, fnu_status *status );

ptwXY: A pointer to the ptwXYPoints object.

xMax: The upper domain value.

secondarySize: Initial size of the secondary cahce.

fill: Initial size of the secondary cahce.
```

status: On return, the status value.

If an error occurs, NULL is returned.

### 5.1.11 ptwXY\_getUserFlag

This routine returns the value of **ptwXY**'s userFlag member.

### C declaration:

# 5.1.12 ptwXY\_setUserFlag

This routine sets the value of the ptwXY's userFlag member to userFlag.

#### C declaration:

# 5.1.13 ptwXY\_getAccuracy

This routine returns the value of **ptwXY**'s accuracy member.

### C declaration:

```
double ptwXY_getAccuracy( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

### 5.1.14 ptwXY\_setAccuracy

This routine sets the value of the **ptwXY**'s accuracy member to accuracy.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object. accuracy: The value to set ptwXY's accuracy to.

Becuase the range of accuracy is limited, the actual value set may be different then the argument accuracy. The actual value set in ptwXY is returned.

# 5.1.15 ptwXY\_getBiSectionMax

This routine returns the value of **ptwXY**'s biSectionMax member.

#### C declaration:

```
double ptwXY_getBiSectionMax( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

# 5.1.16 ptwXY\_setBiSectionMax

This routine sets the value of the **ptwXY**'s biSectionMax member to biSectionMax.

#### C declaration:

```
double ptwXY_setBiSectionMax( ptwXYPoints *ptwXY, double biSectionMax );

ptwXY: A pointer to the ptwXYPoints object.
biSectionMax: The value to set ptwXY's biSectionMax to.
```

Becuase the range of biSectionMax is limited, the actual value set may be different then the argument biSectionMax. The actual value set in ptwXY is returned.

### 5.1.17 ptwXY\_reallocatePoints

This routine changes the size of the primary cache.

### C declaration:

```
fnu_status ptwXY_reallocatePoints( ptwXYPoints *ptwXY, int64\_t \ size, \\ int \ forceSmallerResize );
```

ptwXY: A pointer to the ptwXYPoints object. size: The desired size of the primary cache.

forceSmallerResize: If true (i.e. non-zero) and size is smaller than the current size, the

primary cache is resized. Otherwise, the primary cache is only reduced if the inputted size is significantly smaller than the current

size.

The actual memory allocated is the maximum of size, the current length of the primary cache and ptwXY\_minimumSize.

# 5.1.18 ptwXY\_reallocateOverflowPoints

This routine changes the size of the secondary cache.

### C declaration:

The actual memory allocated is the maximum of size and ptwXY\_minimumOverflowSize. The function ptwXY\_coalescePoints is called if the current length of the secondary cache is greater than the inputted size.

# 5.1.19 ptwXY\_coalescePoints

This routine adds the points from the secondary cache to the primary cache and then removes the points from the secondary cache. If the argument **newPoint** is not-NULL it is also added to the primary cache.

#### C declaration:

ptwXY: A pointer to the ptwXYPoints object.
size: The desired size of the primary cache.
newPoint: If not NULL, an additional point to add.

forceSmallerResize: If true (i.e. non-zero) and size is smaller than the current size, the

primary cache is resized. Otherwise, the primary cache is only reduced if the new size is significantly smaller than the current size.

The actual memory allocated is the maximum of size, the new length of the **ptwXY** object and **ptwXY\_minimumSize**.

### 5.1.20 ptwXY\_simpleCoalescePoints

This routine is a simple wrapper for **ptwXY\_coalescePoints** when only coalescing of the existing points is needed.

### 5.1.21 ptwXY\_clear

This routine removes all points from a **ptwXYPoints** object but does not free any allocated memory. Upon return, the length of the **ptwXYPoints** object is zero.

### C declaration:

```
fnu_status ptwXY_clear( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

# 5.1.22 ptwXY\_release

This routine frees all the internal memory allocated for a ptwXYPoints object.

### C declaration:

```
fnu_status ptwXY_release( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

# 5.1.23 ptwXY\_free

This routine calls **ptwXY\_release** and then calls free on **ptwXY**.

# C declaration:

```
fnu_status ptwXY_free( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

Any **ptwXYPoints** object allocated using **ptwXY\_new** should be freed calling **ptwXY\_free**. Once this routine is called, the **ptwXYPoints** object should never be used.

### 5.1.24 ptwXY\_length

This routine returns the length (i.e., number of points in the primary and secondary caches) for a **ptwXY** object.

# C declaration:

```
int64_t ptwXY_length( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

# $5.1.25 \quad ptwXY\_getNonOverflowLength$

This routine returns the length of the primary caches (note, this is not its size).

```
int64_t ptwXY_getNonOverflowLength( ptwXYPoints *ptwXY );
```

ptwXY: A pointer to the ptwXYPoints object.

### 5.1.26 ptwXY\_setXYData

This routine replaces the current points in a ptwXY object with a new set of points.

### C declaration:

```
fnu_status ptwXY_setXYData( ptwXYPoints *ptwXY, int64_t length, double *xy ); ptwXY: A pointer to the ptwXYPoints object. length: The number of points in xy. xy: The new points given as x_0, y_0, x_1, y_1, \ldots, x_n, y_n where n = length - 1.
```

### 5.1.27 ptwXY\_setXYDataFromXsAndYs

This routines is like **ptwXY\_setXYData** except the x and y data are given in separate arrays.

### C declaration:

```
fnu_status ptwXY_setXYDataFromXsAndYs( ptwXYPoints *ptwXY, int64_t length, double *Xs, double *Xs, double *Ys); ptwXY: A pointer to the ptwXYPoints object. length: The number of points in xy.  
Xs: The new x points given as x_0, x_1, \ldots, x_n where n = length - 1.  
Ys: The new y points given as y_0, y_1, \ldots, y_n where n = length - 1.
```

### 5.1.28 ptwXY\_deletePoints

This routine removes all the points from index i1 inclusive to index i2 exclusive. Indexing is 0 based.

As example, if an  $\mathbf{ptwXY}$  object contains the points (1.2, 4), (1.3, 5), (1.6, 6), (1.9, 3) (2.0, 6), (2.1, 4) and (2.3, 1). Then calling  $\mathbf{ptwXY\_deletePoints}$  with i1 = 2 and i2 = 4 removes the points (1.6, 6) and (1.9, 3). The indices i1 and i2 must satisfy the relationship ( $0 \le i1 \le i2 \le n$ ) where n is the length of the  $\mathbf{ptwXY}$  object; otherwise, no modification is done to the  $\mathbf{ptwXY}$  object and the error  $\mathbf{nfu\_badIndex}$  is returned.

# 5.1.29 ptwXY\_getPointAtIndex

This routine checks that the index argument is valid, and if it is, this routine returns the result of **ptwXY\_getPointAtIndex\_Unsafely**. Otherwise, NULL is returned.

### C declaration:

# 5.1.30 ptwXY\_getPointAtIndex\_Unsafely

This routine returns the point at index. This routine does not check if index is valid and thus is not intended for general use. Instead, see **ptwXY\_getPointAtIndex** for a general use version of this routine.

### 5.1.31 ptwXY\_getXYPairAtIndex

This routine calls **ptwXY\_getPointAtIndex** and if the index is valid it returns the point's x and y values via the arguments \*x and \*y. Otherwise, \*x and \*y are unaltered and an error signal is returned.

```
ptwXY: A pointer to the ptwXYPoints object.
```

index: The index of the point to return.

\*x: The point's x value is returned in this argument.

\*y: The point's y value is returned in this argument.

# 5.1.32 ptwXY\_getPointsAroundX

This routine sets the **lessThanEqualXPoint** and **greaterThanXPoint** members of the **ptwXY** object to the two points that bound a point x.

If the ptwXY object is empty then the return value is ptwXY\_lessEqualGreaterX\_empty. If x is less than xMin, then ptwXY\_lessEqualGreaterX\_lessThan is return. If x is greater than xMax, then ptwXY\_lessEqualGreaterX\_greaterThan is return. If x corresponds to a point in the ptwXY\_lessEqualGreaterX\_equal is returned. Otherwise, ptwXY\_lessEqualGreaterX\_between is returned.

### 5.1.33 ptwXY\_getValueAtX

This routine gets the y value at x, interpolating if necessary.

#### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

x: The x value.

y: Upon return, contains the y value.

If the x value is outside the domain of the  $\mathbf{ptwXY}$  object, y is set to zero and the returned value is  $\mathbf{nfu}_{-}\mathbf{XOutsideDomain}$ .

#### 5.1.34 ptwXY\_setValueAtX

This routine sets the point at x to y, if x does not correspond to a point in the **ptwXY** object then a new point is added.

### C declaration:

### 5.1.35 ptwXY\_setXYPairAtIndex

This routine sets the x and y values at index.

### C declaration:

If index is invalid, **nfu\_badIndex** is returned. If the x value is not valid for index (i.e.  $x \le x_{\text{index}-1}$  or  $x \ge x_{\text{index}+1}$ ) then **nfu\_badIndexForX** is return.

### 5.1.36 ptwXY\_getSlopeAtX

This routine calculates the slope at the point x assuming linear-linear interpolation. That is, for  $x_i < x < x_{i+1}$ , the slope is  $(y_{i+1} - y_i)/(x_{i+1} - x_i)$ . If  $x = x_j$  is the point in **ptwXY** at index j then for side = '+', i = j is used in the above slope equation. Else, if side = '-', i = j - 1 is used in the above slope equation.

```
fnu_status ptwXY_getSlopeAtX( ptwXYPoints *ptwXY, double x, const char side, double *slope );

ptwXY: A pointer to the ptwXYPoints object.

index: The index of the point to set.

x: The x value.
y: The y value.
```

If side is neither '-' or '+', the error **nfu\_badInput** is returned.

# 5.1.37 ptwXY\_getXMinAndFrom — Not for general use

This routine returns the xMin value and indicates whether the minimum value resides in the primary or secondary cache.

ptwXY: A pointer to the ptwXYPoints object.

dataFrom: The output of this argument indicates which cache the minimum value resides in.

The return value from this routine is xMin. If there are no data in the **ptwXYPoints** object, then **dataFrom** is set to **ptwXY\_dataFrom\_Unknown**. Otherwise, it is set to **ptwXY\_dataFrom\_Points** or **ptwXY\_dataFrom\_Overflow** if the minimum value is in the primary or secondary cache respectively.

### 5.1.38 ptwXY\_getXMin

This routine returns the xMin value returned by **ptwXY\_getXMinAndFrom**. The calling routine should check that the **ptwXYPoints** object contains at least one point (i.e., that the length is greater than 0). If the length is 0, the return value is undefined.

### C declaration:

```
double ptwXY_getXMin( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

### 5.1.39 ptwXY\_getXMaxAndFrom — Not for general use

This routine returns the xMax value and indicates whether the maximum value resides in the primary or secondary cache.

```
C declaration: — This routine is not intended for general use. — double ptwXY_getXMaxAndFrom( ptwXYPoints *ptwXY, ptwXY_dataFrom *dataFrom );
```

ptwXY: A pointer to the ptwXYPoints object.

dataFrom: The output of this argument indicates which cache the maximum value resides in.

The return value from this routine is xMax. If there are no data in the **ptwXYPoints** object, then **dataFrom** is set to **ptwXY\_dataFrom\_Unknown**. Otherwise, it is set to **ptwXY\_data-**

From\_Points or ptwXY\_dataFrom\_Overflow if the maximum value is in the primary or secondary cache respectively.

### 5.1.40 ptwXY\_getXMax

This routine returns the xMax value returned by **ptwXY\_getXMinAndFrom**. The calling routine should check that the **ptwXYPoints** object contains at least one point (i.e., that the length is greater than 0). If the length is 0, the return value is undefined.

# C declaration:

```
double ptwXY_getXMax( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

### 5.1.41 ptwXY\_getYMin

This routine returns the minimum y value in **ptwXY**.

### C declaration:

```
double ptwXY_getYMin( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

# 5.1.42 ptwXY\_getYMax

This routine returns the maximum y value in **ptwXY**.

# C declaration:

```
double ptwXY_getYMax( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

### 5.1.43 ptwXY\_initialOverflowPoint — Not for general use

This routine initializes a point in the secondary cache.

```
C declaration: — This routine is not intended for general use. — void ptwXY_initialOverflowPoint(
```

```
ptwXYOverflowPoint *overflowPoint,
ptwXYOverflowPoint *prior,
ptwXYOverflowPoint *next);
```

ptwXY: A pointer to the ptwXYPoints object.

prior: The prior point in the linked list.
next: The next point in the linked list.

### 5.2 Methods

This section decribes all the routines in the file "ptwXY\_method.c".

## 5.2.1 ptwXY\_clip

This routine clips the y-values of **ptwXY** to be within the range **yMin** and **yMax**.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

yMin: All y-values in **ptwXY** will be greater than or equal to this value.

yMax: All y-values in **ptwXY** will be less than or equal to this value.

## 5.2.2 ptwXY\_thicken

This routine thicken the points in  $\mathbf{ptwXY}$  by adding points as determined by the input parameters.

#### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

sectionSubdivideMax: The maximum number of points to add between two initial consec-

utive points.

dxMax: The desired maximum absolute x step between consecutive points.

fxMax: The desired maximum relative x step between consecutive points.

This routine adds points so that  $x_{j+1}-x_j \leq \mathbf{dxMax}$  and  $x_{j+1}/x_j \leq \mathbf{fxMax}$  but will never add more then **sectionSubdivideMax** points bewteen any of the original points. If **sectionSubdivideMax** < 1 or  $\mathbf{dxMax} < 0$  or  $\mathbf{fxMax} < 1$ , the error  $\mathbf{nfu\_badInput}$  is return.

## 5.2.3 ptwXY\_thin

This routine thins (i.e., removes) points from **ptwXY** while maintaining interpolation **accuracy** with **ptwXY**.

ptwXY: A pointer to the ptwXYPoints object.

accuracy: The accuracy of the thinned ptwXYPoints object.

status: On return, the status value.

### 5.2.4 ptwXY\_trim

This routine removes all extra 0.'s at the beginning and end of **ptwXY**.

#### C declaration:

```
fnu_status ptwXY_trim( ptwXYPoints *ptwXY );
```

ptwXY: A pointer to the ptwXYPoints object.

If **ptwXYPoints** starts (ends) with more than two 0.'s then all intermediary are removed.

### 5.2.5 ptwXY\_union

This routine creates a new **ptwXY** instance whose x-values are the union of **ptwXY1**'s and **ptwXY2**'s x-values. The domains of **ptwXY1** and **ptwXY2** do not have to be mutual.

## C declaration:

ptwXY1: A pointer to a ptwXYPoints object. ptwXY2: A pointer to a ptwXYPoints object.

status: On return, the status value. unionOptionSpecifies options (see below).

If an error occurs, NULL is returned. The default behavior of this routine can be altered by setting bits in the argument unionOptions. Currently, there are two bits, set via the C marcos ptwXY\_union\_fill and ptwXY\_union\_trim, that alter ptwXY\_union's behavior. The macro ptwXY\_union\_fill causes all y-values of the new ptwXYPoints object to be filled via the y-values of ptwXY1; otherwise, the y-values are all zero. Normally, the new ptwXYPoints object's x domain spans all x-values in both ptwXY1 and ptwXY2. The macro ptwXY\_union\_trim limits the x domain to the common x domain of ptwXY1 and ptwXY2.

The returned **ptwXYPoints** object will always contain no points in the **overflowPoints** region.

# 5.3 Unitary operators

This section decribes all the routines in the file "ptwXY\_unitaryOperators.c".

## 5.3.1 ptwXY\_abs

This routine applies the math absolute operation to every y-value in **ptwXY**.

## C declaration:

```
fnu_status ptwXY_abs( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

# 5.3.2 ptwXY\_neg

This routine applies the math negate operation to every y-value in **ptwXY**.

```
fnu_status ptwXY_neg( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

# 5.4 Binary operators

This section decribes all the routines in the file "ptwXY\_binaryOperators.c".

## 5.4.1 ptwXY\_slopeOffset

This routine applies the math operation ( $y_i = \text{slope} \times y_i + \text{offset}$ ) to the y-values of **ptwXY**.

### C declaration:

### 5.4.2 ptwXY\_add\_double

This routine applies the math operation ( $y_i = y_i + \text{offset}$ ) to the y-values of **ptwXY**.

### C declaration:

## 5.4.3 ptwXY\_sub\_doubleFrom

This routine applies the math operation ( $y_i = y_i$  - offset) to the y-values of **ptwXY**.

### C declaration:

## 5.4.4 ptwXY\_sub\_fromDouble

This routine applies the math operation ( $y_i = \text{offset - } y_i$ ) to the y-values of **ptwXY**.

ptwXY: A pointer to the ptwXYPoints object.

offset: The offset.

### 5.4.5 ptwXY\_mul\_double

This routine applies the math operation ( $y_i = \text{slope} \times y_i$ ) to the y-values of **ptwXY**.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

slope: The slope.

## 5.4.6 ptwXY\_div\_doubleFrom

This routine applies the math operation ( $y_i = y_i$  / divisor) to the y-values of **ptwXY**.

## C declaration:

ptwXY: A pointer to the ptwXYPoints object.

divisor: The divisor.

If divisor is zero, the error nfu\_divByZero is returned.

## 5.4.7 ptwXY\_div\_fromDouble

This routine applies the math operation ( $y_i = \text{dividend} / y_i$ ) to the y-values of **ptwXY**.

## C declaration:

ptwXY: A pointer to the ptwXYPoints object.

dividend: The dividend.

This routine does not handle safe division (see Section 5.4.14). One way to do safe division is to use the routine **ptwXY\_valueTo\_ptwXY** to convert the **dividend** value to a **ptwXYPoints** object and then use **ptwXY\_div\_ptwXY**.

## 5.4.8 ptwXY\_mod

This routine gives the remainer of  $y_i$  divide by m. That is, it set  $\mathbf{ptwXY}$ 's y-values to

$$y_i = \text{mod}(y_i, m) \quad . \tag{1}$$

#### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

m: The modulus.

pythonMod: Controls whether the Python or C form of mod is implemented.

Python's and C's mod functions act differently for negative values. If **pythonMod** then the Python form is executed; otherwise, the C form is executed.

## 5.4.9 ptwXY\_binary\_ptwXY

This routine creates a new **ptwXYPoints** object from the union of **ptwXY1** and **ptwXY2** and then applies the math operation

$$y_i(x_i) = s_1 \times y_1(x_i) + s_2 \times y_2(x_i) + s_{12} \times y_1(x_i) \times y_2(x_i)$$
(2)

to the new object. Here  $(x_i, y_i)$  is a point in the new object,  $y_1(x_i)$  is **ptwXY1**'s y-value at  $x_i$  and  $y_2(x_i)$  is **ptwXY2**'s y-value at  $x_i$ . This routine is used internally to add, subtract and multiply two **ptwXYPoints** objects. For example, addition is performed by setting  $s_1$  and  $s_2$  to 1. and  $s_{12}$  to 0.

### C declaration:

```
ptwXYPoints *ptwXY_binary_ptwXY( ptwXYPoints *ptwXY1,
                                    ptwXYPoints *ptwXY2,
                                    double s1,
                                    double s2,
                                    double s12,
                                    fnu_status *status );
ptwXY1:
          A pointer to a ptwXYPoints object.
          A pointer to a ptwXYPoints object.
ptwXY2:
s1:
          The value s_1.
          The value s_2.
s2:
          The value s_{12}.
s12:
          On return, the status value.
status:
```

## 5.4.10 ptwXY\_add\_ptwXY

This routine adds two **ptwXYPoints** objects and returns the result as a new **ptwXYPoints** object (i.e., it calls ptwXY\_binary\_ptwXY with  $s_1 = s_2 = 1$ . and  $s_{12} = 0$ .).

### C declaration:

```
ptwXYPoints *ptwXY_add_ptwXY( ptwXYPoints *ptwXY1, ptwXYPoints *ptwXY2, fnu_status *status );
ptwXY1: A pointer to a ptwXYPoints object.
ptwXY2: A pointer to a ptwXYPoints object.
status: On return, the status value.
```

## 5.4.11 ptwXY\_sub\_ptwXY

This routine subtracts one **ptwXYPoints** objects from another, and returns the result as a new **ptwXY** object (i.e., it calls ptwXY\_binary\_ptwXY with  $s_1 = 1$ .,  $s_2 = -1$ . and  $s_{12} = 0$ .)

#### C declaration:

```
ptwXYPoints *ptwXY_sub_ptwXY( ptwXYPoints *ptwXY1, ptwXYPoints *ptwXY2, fnu_status *status );
ptwXY1: A pointer to a ptwXYPoints object which is the minuend. ptwXY2: A pointer to a ptwXYPoints object which is the subtrahend.
```

status: On return, the status value.

## 5.4.12 ptwXY\_mul\_ptwXY

This routine multiplies two **ptwXYPoints** objects and returns the result as a new **ptwXY** object (i.e., it calls ptwXY\_binary\_ptwXY with  $s_1 = s_2 = 0$ . and  $s_{12} = 1$ .).

#### C declaration:

```
ptwXYPoints *ptwXY_mul_ptwXY( ptwXYPoints *ptwXY1, ptwXYPoints *ptwXY2, fnu_status *status );
ptwXY1: A pointer to a ptwXYPoints object.
ptwXY2: A pointer to a ptwXYPoints object.
status: On return, the status value.
```

## 5.4.13 ptwXY\_mul2\_ptwXY

This routine multiplies two **ptwXYPoints** objects and returns the result as a new **ptwXY** object. Unlike **ptwXY\_mul\_ptwXY**, this routine will infill to obtain the desired accuracy.

ptwXY1: A pointer to a ptwXYPoints object.ptwXY2: A pointer to a ptwXYPoints object.

status: On return, the status value.

## 5.4.14 ptwXY\_div\_ptwXY

This routine divides two **ptwXYPoints** objects and returns the result as a new **ptwXY** object.

## C declaration:

ptwXY1: A pointer to a ptwXYPoints object. ptwXY2: A pointer to a ptwXYPoints object.

status: On return, the status value. safeDivide: If true safe division is performed.

### 5.5 Functions

This section decribes all the routines in the file "ptwXY\_functions.c".

## 5.5.1 ptwXY\_pow

This routine applies the math operation  $y_i = y_i^p$  to the y-values of **ptwXY**.

### C declaration:

This routine infills to maintain the initial accuracy.

### 5.5.2 ptwXY\_exp

This routine applies the math operation  $y_i = \exp(a y_i)$  to the y-values of **ptwXY**.

### C declaration:

This routine infills to maintain the initial accuracy.

## 5.5.3 ptwXY\_convolution

This routine returns the convolution of ptwXY1 and ptwXY2.

#### C declaration:

ptwXY1: A pointer to a ptwXYPoints object.ptwXY2: A pointer to a ptwXYPoints object.

status: On return, the status value.

mode: Flag to determine the initial x-values for calculating the convolutions.

User should set **mode** to 0.

## 5.6 Interpolation

This section decribes all the routines in the file "ptwXY\_interpolation.c".

## 5.6.1 ptwXY\_interpolatePoint

This routine interpolates an x value between the points (x1,y1) and (x2,y2) to obtain its y value.

### C declaration:

```
fnu_status ptwXY_interpolatePoint( ptwXY_interpolation interpolation,
                                       double x,
                                       double *y,
                                       double x1,
                                       double v1,
                                       double x2,
                                       double y2);
interpolation:
                  Type of interpolation to perform (see Section 4.3).
                  The x value at which the y value is desired.
x:
                  The x value of the first point.
x1:
                  The y value of the first point.
y1:
                  The x value of the second point.
x2:
                  The y value of the second point.
y2:
```

If the interpolation flag is invalid or (x1 > x2) then **nfu\_invalidInterpolation** is returned. If logarithm interpolation is requested for an axis, and one of the input values for that axis is less than or equal to 0., then **nfu\_invalidInterpolation** is also returned. If interpolation is **ptwXY\_interpolationOther** then **nfu\_otherInterpolation** is returned.

### 5.6.2 ptwXY\_flatInterpolationToLinear

This routine returns a linear-linear interpolated representation of **ptwXY**.

```
ptwXYPoints *ptwXY_flatInterpolationToLinear( ptwXYPoints *ptwXY, double lowerEps, double upperEps, nfu_status *status );
ptwXY: A pointer to a ptwXYPoints object.
lowerEps: The amount to adjust every interior point down in x.
upperEps: The amount to adjust every interior point up in x status: On return, the status value.
```

	$x_m$	$x_p$
$x_i < 0$	$x_i(1+\epsilon_l)$	$x_p = x_i(1 - \epsilon_p)$
$x_i == 0$	$-\epsilon_l$	$\epsilon_p$
$x_i > 0$	$x_i(1-\epsilon_l)$	$x_p = x_i(1 + \epsilon_p)$

Table 3: The value of  $x_m$  and  $x_p$  used to adjust interior points in **ptwXY\_fla-InterpolationTo-Linear**. Here,  $\epsilon_l = \mathbf{lowerEps}$  and  $\epsilon_p = \mathbf{upperEps}$ .

For every interior point (i.e.,  $x_i, y_i$  for 0 < i < n-1 where n is the number of points), two points are added. The positions of these points depend on **lowerEps** and **upperEps** as follows:

lowerEps == 0 and upperEps == 0: This condition is not allowed. status is set to nfu\_badInput and NULL is returned. This condition is also returned if either lowerEps or upperEps is negative.

lowerEps > 0 and upperEps == 0: At each interior point  $x_i, y_i$  the two points  $x_m, y_{i-1}$  and  $x_i, y_i$  are set.

lowerEps == 0 and upperEps > 0: At each interior point  $x_i, y_i$  the two points  $x_i, y_{i-1}$  and  $x_p, y_i$  are set.

lowerEps > 0 and upperEps > 0: At each interior point  $x_i, y_i$ , this point is removed and the two points  $x_m, y_{i-1}$  and  $x_p, y_i$  are set.

where  $x_m$  and  $x_p$  are given in Table 3.

### 5.6.3 ptwXY\_toOtherInterpolation

This routine returns **ptwXY** converted to interpolation **interpolation**.

### C declaration:

ptwXY: A pointer to a ptwXYPoints object.

interpolation: The interpolation to convert to.
accuracy: The accuracy of the conversion.
status: On return, the status value.

Currently, interpolation can only be ptwXY\_interpolationLinLin.

## 5.6.4 ptwXY\_toUnitbase

This routine returns a unit-based version of ptwXY.

#### C declaration:

Unitbasing maps the domain to 0 to 1 by scaling each x-value as  $x_i = (x_i - x_0)/(x_{n-1} - x_0)$  and scaling each y-value as  $y_i = y_i \times (x_{n-1} - x_0)$ . Unitbasing is most useful on pdf's.

## 5.6.5 ptwXY\_fromUnitbase

This routine undoes the unit base mapping done by ptwXY\_toUnitbase.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

xMin: The lower domain for the returned ptwXYPoints instances.xMax: The upper domain for the returned ptwXYPoints instances.

status: On return, the status value.

Each x-value is scaled as  $x_i = (xMax - xMax) \times x_i + xMax$  and each y-value is scaled as  $y_i = y_i/(xMax - xMax)$ .

### 5.6.6 ptwXY\_unitbaseInterpolate

This routine returns a **ptwXYPoints** instance that is the unit-base interpolation of **ptwXY1** at  $w_1$  and **ptwXY2** at  $w_2$  at the w-value w.

w: The w-value to interpole to.

w1: The lower w-value

ptwXY1: A pointer to a ptwXYPoints object at w1.

w2: The upper w-value

ptwXY2: A pointer to a ptwXYPoints object at w2.

status: On return, the status value.

## 5.7 Integration

This section decribes all the routines in the file "ptwXY\_integration.c".

## 5.7.1 ptwXY\_f\_integrate

This routine returns the integral bewteen two points.

### C declaration:

```
nfu_status ptwXY_f_integrate( ptwXYPoints *ptwXY,
                                ptwXY_interpolation interpolation,
                                double x1,
                                double v1,
                                double x2,
                                double y2,
                                double *value );
                  A pointer to a ptwXYPoints object.
ptwXY:
                  The interpolation bewteen the two points.
interpolation:
x2:
                  The x-value of the lower point.
                  The y-value of the lower point
y2:
x2:
                  The x-value of the upper point.
                  The y-value of the upper point
y2:
                  On return, the value of the integral.
value:
```

## 5.7.2 ptwXY\_integrate

The return value is  $\int_{xl}^{xu} f(x) dx$ .

This routine returns the integral of **ptwXY** from **xMin** to **xMax**.

## 5.7.3 ptwXY\_integrateDomain

This routine returns the integral of **ptwXY** over its domain.

### C declaration:

```
ptwXPoints *ptwXY_integrateDomain( ptwXYPoints *ptwXY, nfu_status *status); ptwXY: A pointer to the ptwXYPoints object. status:On return, the status value.
```

The return value is  $\int f(x)dx$  over the domain of **ptwXY**.

## 5.7.4 ptwXY\_normalize

This routine multiplies each y-value of **ptwXY** by a constant so that its integral is then normalized to 1.

#### C declaration:

```
ptwXPoints *ptwXY_normalize( ptwXYPoints *ptwXY );
ptwXY: A pointer to the ptwXYPoints object.
```

## 5.7.5 ptwXY\_integrateDomainWithWeight\_x

This routine returns the integral of **ptwXY** weighted by x over its domain.

#### C declaration:

The return value is  $\int x f(x) dx$  over the domain of **ptwXY**.

## 5.7.6 ptwXY\_integrateWithWeight\_x

This routine returns the integral of **ptwXY** weighted by x from xMin to xMax.

ptwXY: A pointer to the ptwXYPoints object.

xMin: The lower limit of the integration.

xMax: The upper limit of the integration.

status:On return, the status value.

The return value is  $\int_{xMin}^{xMax} x f(x) dx$  over the domain of **ptwXY**.

# $5.7.7 \quad ptwXY\_integrateDomainWithWeight\_sqrt\_x$

This routine returns the integral of **ptwXY** weighted by  $\sqrt{x}$  over its domain.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

status:On return, the status value.

The return value is  $\int \sqrt{x} f(x) dx$  over the domain of **ptwXY**.

## 5.7.8 ptwXY\_integrateWithWeight\_sqrt\_x

This routine returns the integral of **ptwXY** weighted by x from xMin to xMax.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

xMin: The lower limit of the integration.

xMax: The upper limit of the integration.

status:On return, the status value.

The return value is  $\int_{xMin}^{xMax} \sqrt{x} f(x) dx$  over the domain of **ptwXY**.

## 5.7.9 ptwXY\_groupOneFunction

This routine integrates **ptwXY** between each pair of consecutive points in **groupBoundaries** and returns each integral's value as an element of the returned **ptwXPoints**.

ptwXPoints \*ptwXY\_groupOneFunction( ptwXYPoints \*ptwXY,

ptwXPoints \*groupBoundaries, ptwXY\_group\_normType normType,

ptwXPoints \*norm,
nfu\_status \*status );

ptwXY: A pointer to the ptwXYPoints object.

groupBoundaries: A list of x-values.

normType: The type of normalization to apply to integration.

norm: A list of normalizations to be applied when normType is ptwXY-

 $\_group\_normType\_norm.$ 

status: On return, the status value.

Let **groupBoundaries** contain n x-values with  $x_i < x_{i+1}$ . The returned **ptwXPoints** will contain n-1 values  $I_i$  such that

$$I_i = \frac{1}{n_i} \int_{x_i}^{x_{i+1}} f(x) dx \tag{3}$$

where  $n_i$  is determined by **normType** as,

 $ptwXY\_group\_normType\_none: n_i = 1.$ 

ptwXY\_group\_normType\_dx:  $n_i = x_{i+1} - x_i$ .

**ptwXY\_group\_normType\_norm:**  $n_i = \text{the } (i-1)^{th} \text{ element of norm.}$ 

## 5.7.10 ptwXY\_groupTwoFunctions

This routine integrates the product of **ptwXY1** and **ptwXY2** between each pair of consecutive points in **groupBoundaries** and returns each integral's value as an element of the returned **ptwX-Points**.

#### C declaration:

ptwXPoints \*ptwXY\_groupTwoFunctions( ptwXYPoints \*ptwXY1,

ptwXYPoints \*ptwXY2,

ptwXPoints \*groupBoundaries,

ptwXY\_group\_normType normType,

ptwXPoints \*norm,
nfu\_status \*status );

ptwXY: A pointer to the ptwXYPoints object.

groupBoundaries: A list of x-values.

normType: The type of normalization to apply to integration.

norm: A list of normalizations to be applied when normType is ptwXY-

\_group\_normType\_norm.

status: On return, the status value.

Let **groupBoundaries** contain n x-values with  $x_i < x_{i+1}$ . The returned **ptwXPoints** will contain n-1 values  $I_i$  such that

 $I_{i} = \frac{1}{n_{i}} \int_{x_{i}}^{x_{i+1}} f(x) g(x) dx$  (4)

where  $n_i$  is determined by **normType** as,

 $ptwXY\_group\_normType\_none: n_i = 1.$ 

ptwXY\_group\_normType\_dx:  $n_i = x_{i+1} - x_i$ .

**ptwXY\_group\_normType\_norm:**  $n_i = \text{the } (i-1)^{th} \text{ element of norm.}$ 

# 5.7.11 ptwXY\_groupThreeFunctions

This routine integrates the product **ptwXY1**, **ptwXY2** and **ptwXY3** between each pair of consecutive points in **groupBoundaries** and returns each integral's value as an element of the returned **ptwXPoints**.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

groupBoundaries: A list of x-values.

normType: The type of normalization to apply to integration.

norm: A list of normalizations to be applied when normType is ptwXY-

\_group\_normType\_norm.

status: On return, the status value.

Let **groupBoundaries** contain n x-values with  $x_i < x_{i+1}$ . The returned **ptwXPoints** will contain n-1 values  $I_i$  such that

$$I_i = \int_{x_i}^{x_{i+1}} \frac{f(x)g(x)h(x)}{n_i} dx \tag{5}$$

where  $n_i$  is determined by **normType** as,

 $ptwXY\_group\_normType\_none: n_i = 1.$ 

ptwXY\_group\_normType\_dx:  $n_i = x_{i+1} - x_i$ .

**ptwXY\_group\_normType\_norm:**  $n_i = \text{the } (i-1)^{th} \text{ element of norm.}$ 

### 5.8 Convenient

This section decribes all the routines in the file "ptwXY\_convenient.c".

## 5.8.1 ptwXY\_getXArray

This routine returns, as an **ptwXPoints**, the list of x values in **ptwXY**. The returned object is allocated by **ptwXY\_getXArray** and must be freed by the user.

## C declaration:

ptwXY: A pointer to the ptwXYPoints object.

\*status: The status. Returns NULL if an error occured.

### 5.8.2 ptwXY\_dullEdges

This function insures that the y-values at the end-points of **ptwXY** are 0. This can be usefull for making sure two **ptwXYPoints** instances have mutual domains.

#### C declaration:

ptwXY: A pointer to the ptwXYPoints object.
lowerEps: The amount to adjust the first points.
upperEps: The amount to adjust the last points.
positiveXOnly: The next point in the linked list.

The description here will mainly focuses on the dulling of the low point of ptwXY, the upper point's dulling is similar. Let  $\epsilon_l$  = lowerEps,  $x_0$  and  $y_0$  be the first point of ptwXY and  $x_1$  and  $y_1$  be the second point of ptwXY. Also, if  $x_0 \neq 0$  then let  $\Delta x = |\epsilon_l|x_0$  otherwise let  $\Delta x = |\epsilon_l|$ . Then, the points around  $x_0$  are modified only if lowerEps  $\neq 0$  and  $y_0 \neq 0$ . The dulling of the lower edge can have one of the four outcomes listed here,

	$x_0, 0$	$x_p, y_p$	$x_1, y_1$	outcome 1
	$x_0, 0$		$x_1, y_1$	outcome 2
$x_m, 0$	$x_0, y_0'$	$x_p, y_p$	$x_1, y_1$	outcome 3
$x_m, 0$	$x_0, y'_0$		$x_1, y_1$	outcome 4

In all outcomes, the lower point now has y=0. The point is added at  $x_p=x_0+\Delta x$  with  $y=f(x_p)$  only if  $x_0+2\Delta x < x_2$ . If the point at  $x_m=x_0-\Delta x$  is not added, then  $y_0$  is set to 0 as shown in outcomes 1 and 2. The point  $x_m$  is not added if  $\epsilon_l > 0$ , or positive XOnly is true and  $x_m < 0$  and  $x_0 \ge 0$ .

The dulling of the upper edge can have one of the four outcomes listed here,

$x_{k-1}, y_{k-1}$	$x_m, y_m$	$x_k, 0$		outcome 1
$x_{k-1}, y_{k-1}$		$x_k, 0$		outcome $2$
$x_{k-1}, y_{k-1}$	$x_m, y_m$	$x_k, y_k$	$x_p, 0$	outcome 3
$x_{k-1}, y_{k-1}$		$x_k, y_k$	$x_p, 0$	outcome 4

where k is the index of the last point.

## 5.8.3 ptwXY\_mergeClosePoints

Removes and/or moves points so that no two consecutive points are too close to others.

### C declaration:

```
fnu_status ptwXY_mergeClosePoints( ptwXYPoints *ptwXY, double epsilon);

ptwXY: A pointer to the ptwXYPoints object.
epsilon: The minimum relative spacing desired.
```

Points are removed and/or moved so the  $x_{i+1} - x_i \leq \text{epsilon} \times (x_i + x_{i+1})/2$ .

## 5.8.4 ptwXY\_intersectionWith\_ptwX

This routine returns an **ptwXYPoints** instance whose x-values are the intersection of **ptwXY**'s and **ptwX**'s x-values. The domains of **ptwXY** and **ptwX** do not have to be mutual.

## C declaration:

```
ptwXY_intersectionWith_ptwX( ptwXYPoints *ptwXY, ptwXPoints *ptwX, nfu_status *status );

ptwXY: A pointer to the ptwXYPoints object.
ptwX: A pointer to the ptwXPoints object.
status: On return, the status value.
```

### 5.8.5 ptwXY\_areDomainsMutual

This routine returns nfu\_Okay if ptwXY1 and ptwXY2 are mutual.

## C declaration:

ptwXY1: A pointer to a ptwXYPoints object.

A pointer to a ptwXYPoints object.

A pointer to a ptwXYPoints object.

If one or both of **ptwXY1** and **ptwXY2** are empty, **nfu\_empty** is returned. If one or both of **ptwXY1** and **ptwXY2** has only one point, **nfu\_tooFewPoints** is returned. If the domains are not mutual, **nfu\_domainsNotMutual** is returned.

## 5.8.6 ptwXY\_mutualifyDomains

If possible and needed, this routine mutualifies the domains of **ptwXY1** and **ptwXY2** by calling **ptwXY\_dullEdges** on one or both of **ptwXY1** and **ptwXY2** if needed.

#### C declaration:

ptwXY1: A pointer to a ptwXYPoints object.

lowerEps1: If needed the value of lowerEps passed to ptwXY\_dullEdges when

dulling ptwXY1.

upperEps1: If needed the value of upperEps passed to ptwXY\_dullEdges when

dulling ptwXY1.

positiveXOnly1: The value of positiveXOnly passed to ptwXY\_dullEdges when dulling

ptwXY1.

ptwXY2: A pointer to a ptwXYPoints object.

lowerEps2: If needed the value of lowerEps passed to ptwXY\_dullEdges when

dulling ptwXY2.

upperEps2: If needed the value of upperEps passed to ptwXY\_dullEdges when

dulling ptwXY2.

positiveXOnly2: The value of positiveXOnly passed to ptwXY\_dullEdges when dulling

ptwXY2.

## 5.8.7 ptwXY\_copyToC\_XY

This routine copies the points from index index1 inclusive to index2 exclusive of ptwXY into the address pointed to by xys.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

index1: The lower index.
index2: The upper index.

allocatedSize: The size of the space allocated for xys in pairs of C-double.

numberOfPoints: The number of (x,y) points filled into \*xys. xys:

A pointer to the space to write the data.

The size of **xys** must be at least 2 × sizeof( double ) × **allocatedSize** bytes. The values of **index1** and **index2** are ajusted as follows. If **index1** is less than 0, it is set to 0. Then if **index2** is less than **index1**, it is set to **index1**. Finally, if **index2** is greater than the length of **ptwXY**, it is set to the length of **ptwXY**. If **allocatedSize** is less than the number of points to be copied (i.e., **index2** - **index1** after **index1** and **index2** are adjusted) then **nfu\_insufficientMemory** is returned;

The returned **ptwXYPoints** object will always contain no points in the **overflowPoints** region.

## 5.8.8 ptwXY\_valueTo\_ptwXY

This routine creates a **ptwXYPoints** object with the two points (x1,y), (x2,y) where x1 < x2.

#### C declaration:

```
ptwXYPoints *ptwXY_valueTo_ptwXY( ptwXY_interpolation interpolation, double x1, double x2, double x2, double y, fnu_status *status);

interpolation: Type of interpolation to perform (see Section 4.3).

x1: x value for the lower point.

x2: x value for the upper point.
```

y: y value for both points.
status: On return, the status value.

If an error occurs, NULL is returned.

# ${\bf 5.8.9 \quad ptwXY\_createGaussianCenteredSigma1}$

This routine returns a **ptwXYPoints** instance of the simple Gaussian  $y(x) = \exp(-x^2/2)$ .

### C declaration:

```
ptwXYPoints *ptwXY_createGaussianCenteredSigma1( double accuracy, nfu_status *status ); accuracy: The returned points are accurate to accuracy. status: On return, the status value. The domain ranges from -\sqrt{2\log(y\mathrm{Min})} to \sqrt{2\log(y\mathrm{Min})} where yMin = 10^{-10}.
```

## 5.8.10 ptwXY\_createGaussian

This routine returns a **ptwXYPoints** instance of the Gaussian  $y(x) = a \exp(-(x-c)^2/(2s))$ .

### C declaration:

accuracy: The returned points are accurate to accuracy.

xCenter: The center of the Gaussian.
sigma: The width of the Gaussian.
amplitude: The amplitude of the Gaussian.

xMin: The lower domain of the returned Gaussian.

xMax: The upper lower domain of the returned Gaussian.

dullEps: Currently not implemented. status: On return, the status value.

In the equation a = amplitude, c = xCenter and s = sigma. This routine calls  $\text{ptwXY\_create-GaussianCenteredSigma1}$  and then scales the x and y values.

### 5.9 Miscellaneous

This section decribes all the routines in the file "ptwXY\_misc.c".

## 5.9.1 ptwXY\_update\_biSectionMax — Not for general use

This routine is used by **ptwXY** routines to update the member **biSectionMax** base on the prior length, given by **oldLength**, and the current length of **ptwXY**.

## 5.9.2 ptwXY\_applyFunction

This routine is used by other routines to map  $y_i$  to func(  $x_i$ ,  $y_i$  ) with infilling as needed. For example, this routine is used by  $\mathbf{ptwXY\_pow}$ .

# C declaration:

## 5.9.3 ptwXY\_showInteralStructure — Not for general use

This routine writes out details of the data in a **ptwXYPoints** object, including much of the internal data normally not useful to a user. This routine is intended for debugging.

ptwXY: A pointer to the ptwXYPoints object.

f: The stream where the structure is written.

printPointersAsNull: If true, all pointers are printed as if their value is NULL.

## 5.9.4 ptwXY\_simpleWrite

This routine writes out the (x,y) points of the **ptwXYPoints** object to a specified stream.

#### C declaration:

f: The stream where the points are written.

format: The format specifier to use for writing an (x,y) point.

The **format** must contain two C double specifier (e.g., "%12.4f %17.7e\n"), one each for the x-and y-values of a point. No line feed characters (e.g., "\n") are printed, except those in **format**.

## 5.9.5 ptwXY\_simplePrint

This routine calls **ptwXY\_simpleWrite** with stdout as the output stream.

### C declaration:

ptwXY: A pointer to the ptwXYPoints object.

format: The format specifier to use for writing an (x,y) point.

## 6 The detail of the calculations

The following sub-sections describe the details on some of the calculations. Consider two consecutive points  $(x_1, y_1)$  and  $(x_2, y_2)$  where  $x_1 \le x \le x_2$  and  $x_1 < x_2$ , then interpolation is defined as

Lin-lin interpolation

$$y = \frac{y_2(x - x_1) + y_1(x_2 - x)}{(x_2 - x_1)} \tag{6}$$

Lin-log interpolation

$$y = y_1 \left(\frac{y_2}{y_1}\right)^{\frac{x - x_1}{x_2 - x_1}} \tag{7}$$

Log-lin interpolation

$$y = \frac{y_1 \log(x_2/x) + y_2 \log(x/x_1)}{\log(x_2/x_1)}$$
 (8)

Log-log interpolation

$$y = y_1 \left(\frac{x}{x_1}\right)^{\frac{\log(y_2/y_1)}{\log(x_2/x_1)}} \tag{9}$$

In some calculation we will need the x location for the maximum of the relative error, (y'-y)/y, between the approximate value, y', and the "exact" value, y. This x location occurs where the derivative of the relative error is zero:

$$\frac{d((y'-y)/y)}{dx} = \frac{d(y'/y-1)}{dx} = \frac{d(y'/y)}{dx} = \frac{1}{y^2} \left( y \frac{dy'}{dx} - y' \frac{dy}{dx} \right) = 0$$
 (10)

## 6.1 Converting log-log to lin-lin

This section describes how fudge2dmath converts a **fudge2dmathXY** object with interpolation of **f2dmC\_interpolationLogLog** (hence called log-log) to one with interpolation of **f2dmC\_interpolation-LinLin** (hence called lin-lin).

From Eq. 10 the maximum of the relative error occurs where,

$$\frac{1}{y} \left( \frac{dy'}{dx} - \frac{y'}{y} \frac{dy}{dx} \right) = \left( \frac{1}{y} \right) \left\{ \frac{y_2 - y_1}{x_2 - x_1} - \left( \frac{y'}{x} \right) \frac{\log(y_2/y_1)}{\log(x_2/x_1)} \right\} = 0 \tag{11}$$

The solution is

$$\frac{x}{x_1} = \frac{a(x_2/x_1 - y_2/y_1)}{(1-a)(y_2/y_1 - 1)} \tag{12}$$

where  $a = \log(y_2/y_1)/\log(x_2/x_1)$ .