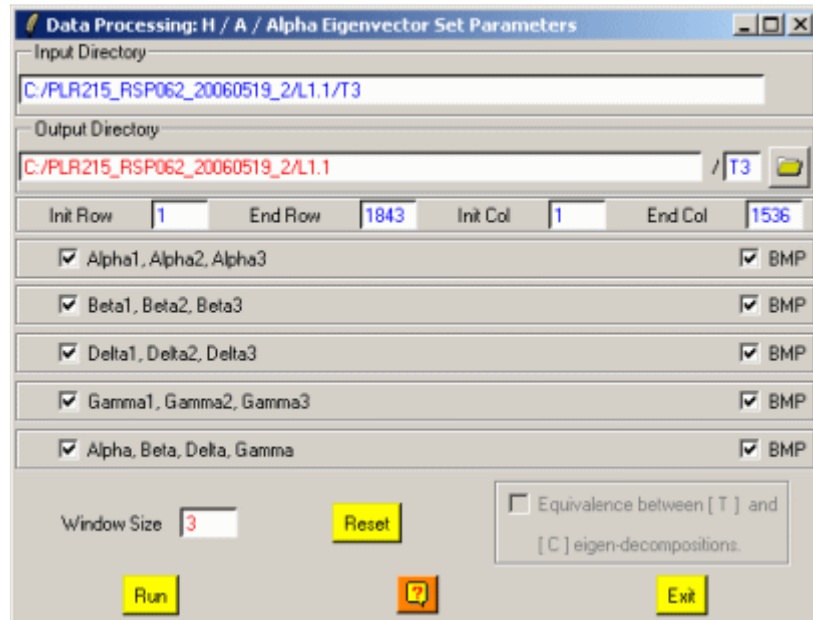


Coherency [T3] matrix - H/A/Alpha Eigenvector Set



This program creates binary files corresponding to the different polarimetric descriptors obtained from the H/A/Alpha decomposition of the (3x3) complex Coherency matrix [T3] raw binary data.

An option may be set to simultaneously create the corresponding bitmap image files.

Description:

The H/A/Alpha polarimetric decomposition is based on an eigenvector decomposition of the (3*3) complex Coherency [T3] matrix.

The (3x3) complex Coherency [T3] matrix being hermitian, semi-definite positive, its eigenvectors are orthogonal and its eigenvalues are real positive.

The eigenvector decomposition of a distributed target coherency matrix is considered as a simple statistical model consisting in the expansion of the (3x3) complex Coherency matrix into a weighted sum of three coherency matrices.

Pseudo-probabilities of the (3x3) complex Coherency [T3] matrix expansion elements are defined, from the set of sorted eigenvalues.

Each unitary eigenvector of the (3x3) complex Coherency [T3] matrix may be parameterized using 4 real angular variables.

The condition of mutual orthogonality between the eigenvectors involve that the 3 polarimetric parameters sets resulting from the expansion are not independent. For this reason, each polarimetric parameter is associated to a 3 symbol Bernoulli

statistical process.

In this way, the estimate of the mean polarimetric parameter set is given by:

A physical interpretation has been given to these 4 polarimetric descriptors (S.R Cloude, E. Pottier).

Comments:

Parameters written in Red can be modified directly by the user from the keyboard.

Input/Output Arguments:

Input Directory	Indicates the complete location of the considered Main Directory / T3 (MD / T3) containing the [T3] matrix data to be processed.
Output Directory	Indicates the location of the processed data output directory. The default value is set automatically to : Main Directory / T3 (MD / T3).

Output Image Number of Rows/Columns:

The output image numbers of rows and columns are initialised to the input data set dimensions.

Users wishing to process a sub-part of the initial image can modify the **Init** and **End** values of the converted images rows and columns.

Note: init and end values have to remain within the range defined by the input image dimensions.

Processing parameters:

Window Size	Data to be decomposed may be processed through an additional filtering procedure consisting of a boxcar filter. Users have then to set the size of the (N*N) sliding window used to compute the local estimate of the average matrix. The default value of N is set to 0. Users wishing to avoid additional filtering may set N to 1.
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