

# Recovering\_rf\_mixture

The objective of these simulations are to examine whether mixture parameters are recoverable with spatial data. We'll start by simulating some data on a grid from two gaussian random fields. We will initially assume that the fields have the same shape/scale parameters of the gaussian covariance function, but the variances are different – this allows one field to be normal, and the other fat-tailed.

```
library(cluster)
library(mvtnorm)
library(R2jags)
```

```
## Loading required package: rjags
## Loading required package: coda
## Linked to JAGS 3.4.0
## Loaded modules: basemod,bugs
##
## Attaching package: 'R2jags'
##
## The following object is masked from 'package:coda':
##
##      traceplot
```

```
library(fields)
```

```
## Loading required package: spam
## Loading required package: grid
## Spam version 1.0-1 (2014-09-09) is loaded.
## Type 'help( Spam)' or 'demo( spam)' for a short introduction
## and overview of this package.
## Help for individual functions is also obtained by adding the
## suffix '.spam' to the function name, e.g. 'help( chol.spam)'.
##
## Attaching package: 'spam'
##
## The following objects are masked from 'package:base':
##
##      backsolve, forwardsolve
##
## Loading required package: maps
```

```
grid = as.matrix(expand.grid("lon" = seq(5,15,1), "lat" = seq(5,15,1)))
nLocs = dim(grid)[1]
```

## Approximating data with spatial random field

We could use RandomField, or other packages to do this. Initially we'll just simulate data using the estimation model. Use pam() to choose a number of knots on the grid. We'll specify 20 initially. We'll also jitter them slightly so knot locations don't fall exactly on stations.

```
nKnots = 20
knots = jitter(pam(grid,nKnots)$medoids)
```

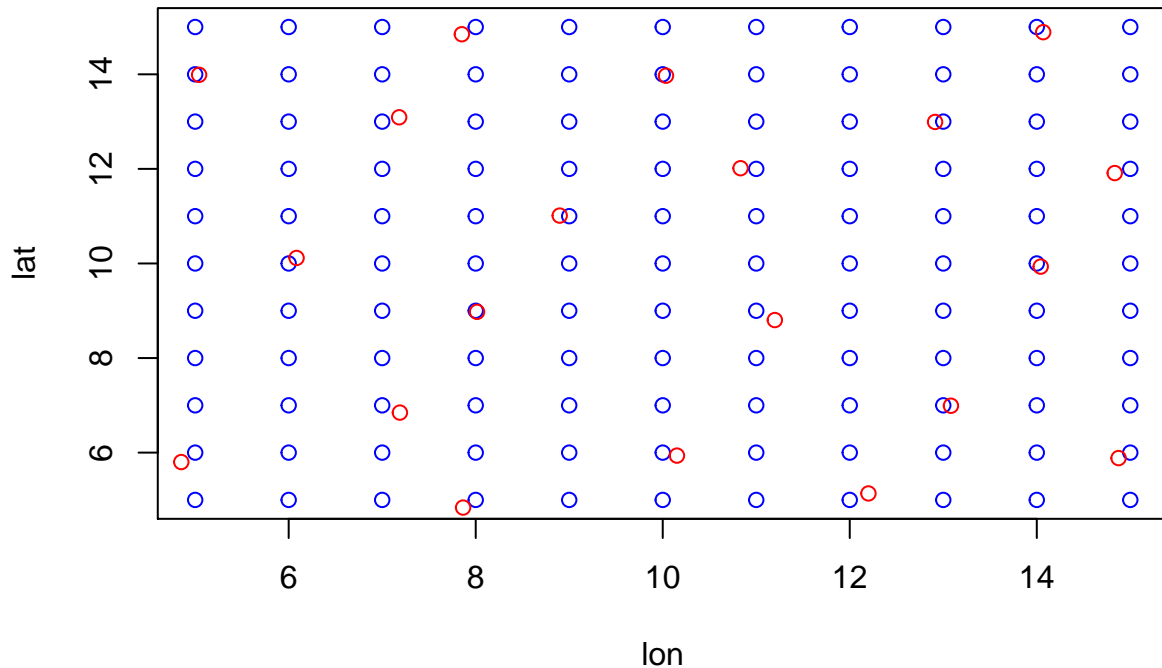


Figure 1: Simulated grid (blue) and knots for random effects (red)

## Approximating data with spatial random field

Initially, we'll assume all data is observed in the same year, so there'll just be a single random effect field for normal years, and a single effect for catastrophic / abnormal years.

```
# distance matrix of knots
distKnots = as.matrix(dist(knots))
distKnotsSq = distKnots^2 # squared distances
# note: shape parameter scaled to distance matrix
gp_scale = 0.001
sigma.norm = 0.001
sigma.fat = 0.002
corKnots = exp(-gp_scale*distKnotsSq)
Sigma.normal = corKnots * sigma.norm * sigma.norm
Sigma.fat = corKnots * sigma.fat * sigma.fat
```

Calculate distance matrix from stations to knots, and covariance matrices,

```
# Calculate distance from knots to grid
distAll = as.matrix(dist(rbind(grid, knots)))^2
distKnots21Sq = t(distAll[1:nKnots, -c(1:nKnots)])

Sigma21.normal = exp(-gp_scale*distKnots21Sq) * sigma.norm * sigma.norm
Sigma21.fat = exp(-gp_scale*distKnots21Sq) * sigma.fat * sigma.fat
```

Generate single MVN field for each of the normal and ‘fat-tailed’ distributions.

```
re.norm = rmvnorm(1, mean = rep(0, nKnots), Sigma.normal)
re.fat = rmvnorm(1, mean = rep(0, nKnots), Sigma.fat)
```

Project to the station / grid locations, and combine the random fields using some proportion of ‘fat-tailed’ events. Initially, we’ll use 0.05.

```
# take inverse
invSigmaKnots.norm = solve(Sigma.normal)
invSigmaKnots.fat = solve(Sigma.fat)

# Project
proj.norm = Sigma21.normal %%% invSigmaKnots.norm %%% matrix(re.norm,ncol=1)
proj.fat = Sigma21.fat %%% invSigmaKnots.fat %%% matrix(re.fat,ncol=1)

# Combine to single RF
pfat = 0.05
proj = (1-pfat)*proj.norm + pfat*proj.fat
```

Next, we’ll simulate 3 kinds of data from the spatial mixture: gaussian, binomial, and poisson counts.

```
nPoints = 250
#indices = sample(seq(1,nLocs), size=nPoints, replace=T)
indices = seq(1,nLocs)
# assume no observation error, so observed/simulated gaussian data are same
x = grid[indices,]
y.gaussian = proj[indices,1]

y.binomial = rbinom(nPoints, size=1, prob=plogis(proj[indices,1]))

y.poisson = rpois(nPoints, lambda = exp(proj[indices,1]))

diagKnots = diag(nKnots)
muZeros = rep(0, nKnots)
```

## Estimating normal mixture

The most important parameter we’re interested in trying to recover is the contribution of the mixtures, and secondarily it’s important to recover the variances scaling how extreme those events are.

As a first pass, we’ll do it in JAGS, and we’ll switch to TMB for the faster models linked with INLA.

```
jagsscript = cat("
model {
  # priors on parameters for gaussian process
  gp_scaleInv ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_scale <- 1/gp_scaleInv;
  gp_sigmaSqInv_fat ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_sigmaSq_fat <- 1/gp_sigmaSqInv_fat;
  gp_sigmaSqInv_norm ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_sigmaSq_norm <- 1/gp_sigmaSqInv_norm;
```

```

gp_jitterSqInv ~ dgamma(0.01,0.01); # shared btw normal/fat
gp_jitterSq <- 1/gp_jitterSqInv;

# This builds the 2 cov matrices needed
# SigmaKnots is the COV matrix between knots
# SigmaOffDiag is the COV matrix between new locations and knots, e.g. it's (100 x 10)
for(i in 1:nKnots) {
  for(j in 1:nKnots) {
    # this adds some jitter to the diagonal but not the off-diags
    SigmaKnotsNorm[i,j] <- (1-diagKnots[i,j]) * gp_sigmaSq_norm * exp(-gp_scale * distKnotsSq[i,j]) + diagKnots[i,j]
    SigmaKnotsFat[i,j] <- (1-diagKnots[i,j]) * gp_sigmaSq_fat * exp(-gp_scale * distKnotsSq[i,j]) + diagKnots[i,j]
  }
}
for(i in 1:nLocs) {
  for(j in 1:nKnots) {
    SigmaOffDiagNorm[i,j] <- gp_sigmaSq_norm * exp(-gp_scale * distKnots21Sq[i,j]);
    SigmaOffDiagFat[i,j] <- gp_sigmaSq_fat * exp(-gp_scale * distKnots21Sq[i,j]);
  }
}
invSigmaKnotsNorm <- inverse(SigmaKnotsNorm[,,]); # inverse of matrix for projection and mvn distribution
invSigmaKnotsFat <- inverse(SigmaKnotsFat[,,]); # inverse of matrix for projection and mvn distribution

# mixture contribution of fat tailed events
pfat ~ dunif(0,0.3);

# Spatial random effects
spatialEffectsKnotsNorm[1:nKnots,1] ~ dmnorm(muZeros, invSigmaKnotsNorm);
spatialEffectsKnotsFat[1:nKnots,1] ~ dmnorm(muZeros, invSigmaKnotsFat);
spatialEffects[1:nLocs,1] <- (1-pfat)*((SigmaOffDiagNorm %*% invSigmaKnotsNorm) %*% spatialEffectsKnotsNorm) + pfat*
                                     (SigmaOffDiagFat %*% invSigmaKnotsFat) %*% spatialEffectsKnotsFat;

# evaluate the likelihood
resid.tau ~ dgamma(0.001,0.001);

for(i in 1:nPoints) {
  pred[i] <- spatialEffects[indices[i], 1];
  y.gaussian[i] ~ dnorm(pred[i], resid.tau);
}

} " ,file="recover_rf_gaussian.txt")

```

Run the model,

```

jags.data = list("nLocs", "nKnots", "y.gaussian", "distKnotsSq", "distKnots21Sq", "diagKnots", "muZeros", "pfat",
               "gp_sigmaSq_fat", "gp_sigmaSq_norm", "spatialEffectsKnotsNorm", "spatialEffectsKnotsFat", "spatialEffects")
jags.params=c("pfat", "gp_sigmaSq_fat", "gp_sigmaSq_norm", "spatialEffectsKnotsNorm", "spatialEffectsKnotsFat", "spatialEffects")
jagsmodel.gaussian = jags.parallel(jags.data, inits=NULL, parameters.to.save=jags.params, model.file="recover_rf_gaussian.txt")

```

## Estimating binomial mixture

We can also extend this to the binomial distribution by changing a single line in the JAGS script.

```

jagssscript = cat("
model {
  # priors on parameters for gaussian process
  gp_scaleInv ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_scale <- 1/gp_scaleInv;
  gp_sigmaSqInv_fat ~ dgamma(0.01,0.01); # not shared btw normal/fat
  gp_sigmaSq_fat <- 1/gp_sigmaSqInv_fat;
  gp_sigmaSqInv_norm ~ dgamma(0.01,0.01); # not shared btw normal/fat
  gp_sigmaSq_norm <- 1/gp_sigmaSqInv_norm;
  gp_jitterSqInv ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_jitterSq <- 1/gp_jitterSqInv;

  # This builds the 2 cov matrices needed
  # SigmaKnots is the COV matrix between knots
  # SigmaOffDiag is the COV matrix between new locations and knots, e.g. it's (100 x 10)
  for(i in 1:nKnots) {
    for(j in 1:nKnots) {
      # this adds some jitter to the diagonal but not the off-diags
      SigmaKnotsNorm[i,j] <- (1-diagKnots[i,j]) * gp_sigmaSq_norm * exp(-gp_scale * distKnotsSq[i,j]) + c
      SigmaKnotsFat[i,j] <- (1-diagKnots[i,j]) * gp_sigmaSq_fat * exp(-gp_scale * distKnotsSq[i,j]) + di
    }
  }
  for(i in 1:nLocs) {
    for(j in 1:nKnots) {
      SigmaOffDiagNorm[i,j] <- gp_sigmaSq_norm * exp(-gp_scale * distKnots21Sq[i,j]);
      SigmaOffDiagFat[i,j] <- gp_sigmaSq_fat * exp(-gp_scale * distKnots21Sq[i,j]);
    }
  }
  invSigmaKnotsNorm <- inverse(SigmaKnotsNorm[,,]); # inverse of matrix for projection and mvn distribut
  invSigmaKnotsFat <- inverse(SigmaKnotsFat[,,]); # inverse of matrix for projection and mvn distributi

  # mixture contribution of fat tailed events
  pfat ~ dunif(0,0.3);

  # Spatial random effects
  spatialEffectsKnotsNorm[1:nKnots,1] ~ dmnorm(muZeros, invSigmaKnotsNorm);
  spatialEffectsKnotsFat[1:nKnots,1] ~ dmnorm(muZeros, invSigmaKnotsFat);
  spatialEffects[1:nLocs,1] <- (1-pfat)*((SigmaOffDiagNorm %%% invSigmaKnotsNorm) %%% spatialEffectsKno

  # evaluate the likelihood
  for(i in 1:nPoints) {
    logit(pred[i]) <- min(max(spatialEffects[indices[i], 1],-20),20);
    y.binomial[i] ~ dbern(pred[i]);
  }
}
",file="recover_rf_binomial.txt")

```

Run the model,

```

jags.data = list("nLocs", "nKnots", "y.binomial", "distKnotsSq", "distKnots21Sq", "diagKnots", "muZeros", "
jags.params=c("pfat", "gp_sigmaSq_fat", "gp_sigmaSq_norm", "spatialEffectsKnotsNorm", "spatialEffectsKno
jagsmodel.binomial = jags.parallel(jags.data, inits=NULL, parameters.to.save=jags.params, model.file="r

```

## Estimating Poisson mixture

We can also extend this to the Poisson distribution by changing a single line in the JAGS script.

```
jagsscript = cat("
model {
  # priors on parameters for gaussian process
  gp_scaleInv ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_scale <- 1/gp_scaleInv;
  gp_sigmaSqInv_fat ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_sigmaSq_fat <- 1/gp_sigmaSqInv_fat;
  gp_sigmaSqInv_norm ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_sigmaSq_norm <- 1/gp_sigmaSqInv_norm;
  gp_jitterSqInv ~ dgamma(0.01,0.01); # shared btw normal/fat
  gp_jitterSq <- 1/gp_jitterSqInv;

  # This builds the 2 cov matrices needed
  # SigmaKnots is the COV matrix between knots
  # SigmaOffDiag is the COV matrix between new locations and knots, e.g. it's (100 x 10)
  for(i in 1:nKnots) {
    for(j in 1:nKnots) {
      # this adds some jitter to the diagonal but not the off-diags
      SigmaKnotsNorm[i,j] <- (1-diagKnots[i,j]) * gp_sigmaSq_norm * exp(-gp_scale * distKnotsSq[i,j]) + gp_jitterSq;
      SigmaKnotsFat[i,j] <- (1-diagKnots[i,j]) * gp_sigmaSq_fat * exp(-gp_scale * distKnotsSq[i,j]) + gp_jitterSq;
    }
  }
  for(i in 1:nLocs) {
    for(j in 1:nKnots) {
      SigmaOffDiagNorm[i,j] <- gp_sigmaSq_norm * exp(-gp_scale * distKnots21Sq[i,j]);
      SigmaOffDiagFat[i,j] <- gp_sigmaSq_fat * exp(-gp_scale * distKnots21Sq[i,j]);
    }
  }
  invSigmaKnotsNorm <- inverse(SigmaKnotsNorm[,]); # inverse of matrix for projection and mvn distribution
  invSigmaKnotsFat <- inverse(SigmaKnotsFat[,]); # inverse of matrix for projection and mvn distribution

  # mixture contribution of fat tailed events
  pfat ~ dunif(0,0.3);

  # Spatial random effects
  spatialEffectsKnotsNorm[1:nKnots,1] ~ dmnorm(muZeros, invSigmaKnotsNorm);
  spatialEffectsKnotsFat[1:nKnots,1] ~ dmnorm(muZeros, invSigmaKnotsFat);
  spatialEffects[1:nLocs,1] <- (1-pfat)*((SigmaOffDiagNorm %*% invSigmaKnotsNorm) %*% spatialEffectsKnotsNorm) + pfat * spatialEffectsKnotsFat;

  # evaluate the likelihood
  for(i in 1:nPoints) {
    y.poisson[i] ~ dpois(exp(spatialEffects[indices[i], 1]));
  }
}
",file="recover_rf_poisson.txt")
```

Run the model,

```
jags.data = list("nLocs", "nKnots", "y.poisson", "distKnotsSq", "distKnots21Sq", "diagKnots", "muZeros", "i
jags.params=c("pfat", "gp_sigmaSq_fat", "gp_sigmaSq_norm", "spatialEffectsKnotsNorm", "spatialEffectsKno
jagsmodel.poisson = jags.parallel(jags.data, inits=NULL, parameters.to.save=jags.params, model.file="re
```

```
par(mfrow=c(2,2),mgp=c(2,1,0),mai=c(0.5,0.5,0.3,0.1))
attach.jags(jagsmodel.gaussian)
```

```
## The following object is masked _by_ .GlobalEnv:
##
##      pfat
```

```
hist(pfat,40,col="grey",main="Gaussian",xlab="P(fat tail)")
attach.jags(jagsmodel.binomial)
```

```
## The following object is masked _by_ .GlobalEnv:
##
##      pfat
```

```
hist(pfat,40,col="grey",main="Binomial",xlab="P(fat tail)")
attach.jags(jagsmodel.poisson)
```

```
## The following object is masked _by_ .GlobalEnv:
##
##      pfat
```

```
hist(pfat,40,col="grey",main="Poisson",xlab="P(fat tail)")
```

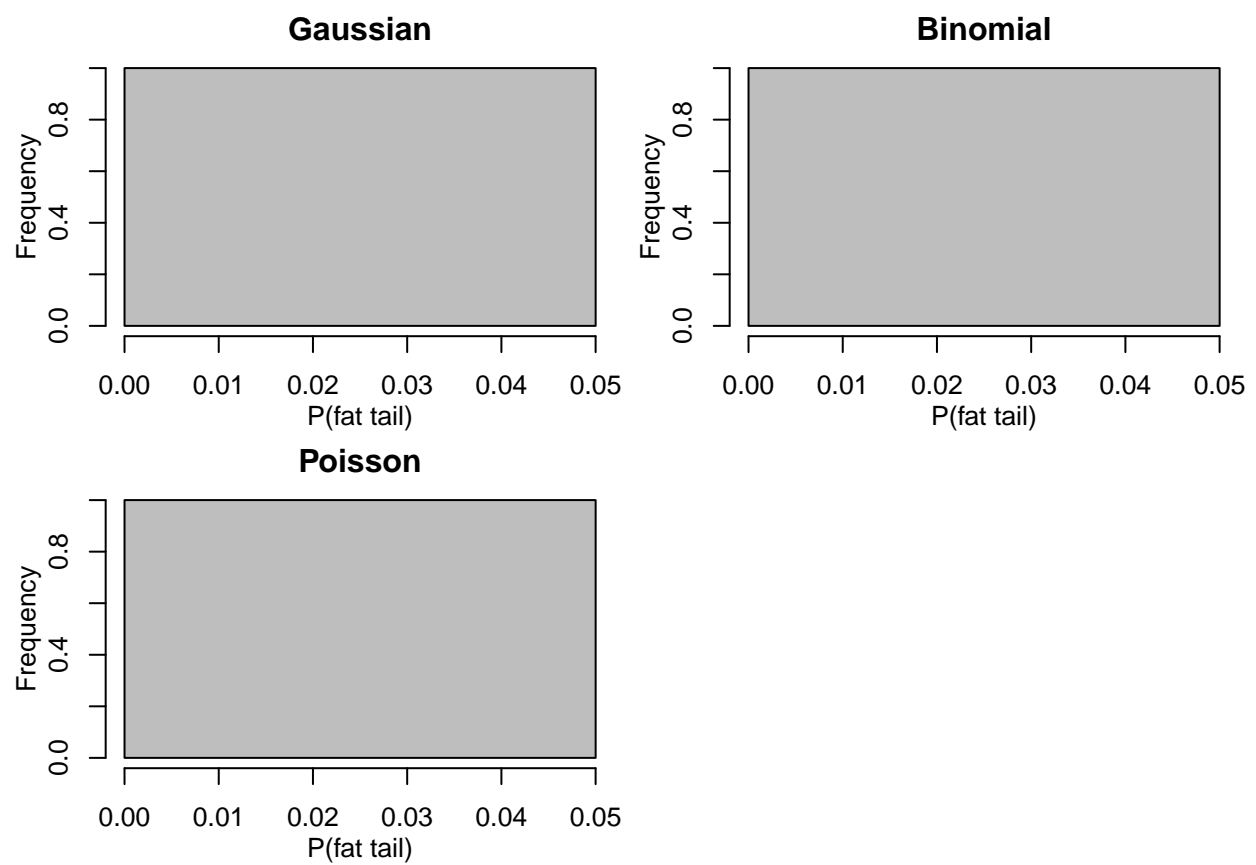


Figure 2: