- P11: O and U maps
- P12: O and U Signal-to-Noise maps

P16: Polarised intensity maps

- P14: pol2map I map errors compared to Q/U map errors

P17: Polarised intensity Signal-to-Noise maps

- P13: O/U pixel errors (central region only) P15: pol2map I map compared to non-POL2 SCUBA-2 map

P18: De-biased vector maps - binned 5x5 and cut at (dp<3)>&(dang<10)