Perseus B1

P38 : Q and U maps
P39 : Q and U Signal-to-Noise maps
P40 : Q/U pixel errors (central region only)
P41 : pol2map I map errors compared to Q/U map errors
P42 : pol2map I map compared to non-POL2 SCUBA-2 map
P43 : Polarised intensity maps
P44 : Polarised intensity Signal-to-Noise maps
P45 : De-biased vector maps - binned 5x5 and cut at (dp<3)>&(dang<10)