ZAP : An ARM v4T Compatible Soft Processor

Revanth Kamaraj

October 19, 2016

MIT License

Copyright (c) 2016 Revanth Kamaraj (Email: revanth91kamaraj@gmail.com)

Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions:

The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software.

THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.

1 INTRODUCTION 2

1 Introduction

ZAP is an ARM® v4T compatible soft processor core. The code is fully open source and is released under the MIT license.

1.1 Features

• Fully ARM v4T compatible.

- Executes the 32-bit wide ARM v4 instruction set.
- Executes the 16-bit wide compressed instruction set.

• Deeper pipeline for better clock speed.

- The processor is super-pipelined with a 9 stage pipeline to achieve a high operating frequency. The pipeline has a data forwarding capability to allow back to back instructions to execute without stalls. Non trivial shifts require their operands a cycle early. Loads have a 3 cycle latency and the pipeline will stall if an attempt is made to access the register within the latency period.

· Supports interrupt and abort signaling

- Features dedicated high level sensitive IRQ, FIQ and memory abort pins.

• Can be interfaced with caches/MMU.

- The CPSR of the processor is exposed as a port allowing for implementation of a virtual memory system.
- Memory stall may be indicates to the core via dedicated ports to allow caches to be connected.

• Coprocessor interface provided.

The coprocessor interface simply exposes internal signals of the core. It is up to the coprocessor
to interpret and process instructions correctly.

• Supports M-variant multiplication instructions

- These instructions are supported:

```
MUL, MLA, SMULL, UMULL, SMLAL, UMLAL
```

• The core is configurable

 The processor may be synthesized without compressed instruction support and/or coprocessor interface support to save area and improve speed.

• Designed for FPGA synthesis

- Most memory structures of the processor map efficiently onto FPGA block RAMs. The register file is overclocked by a 2x clock to allow for 2 write ports.
- The branch predictor memory also efficiently maps to FPGA block RAM.
- No device specific instantiations are made to allow for portability across FPGA vendors.

1 INTRODUCTION 3

• Faster performance of memory instructions

 Memory instructions with writeback can be issued as a single instruction since the register file is built to have 2 write ports. This may improve performance.

- The processor core is written entirely in synthesizable Verilog-2001.
- A branch predictor is installed to compensate for the longer pipeline.
 - Branches within a 2KB block of memory can be mapped into the predictor without conflict.
 The predictor basically uses a bimodal prediction algorithm (2-bit saturating counter per branch entry).

· Uses a base restored abort model

Uses a base restored abort model making it easier to write exception handlers. Basically, on a
fault in between a multiple memory transfer, the processor rolls back the base pointer register as
it were before the operation took place.

1.2 About This Manual

The purpose of this manual is to document the processor core's design. This document is very incomplete. I will try my best to update it.

2 Configuring the core and testbench

Throughout, it is assumed that \$ZAP_HOME points to the working directory of the project. Core/testbench configuration may be done using defines. The defines file is located in \$ZAP_HOME/includes/config.vh.

Define	Purpose	Required for	Comments
CORE CONFIGURATION			
THUMB_EN	Enabling compressed	Core Setup	Enabling this increases
	instruction support		core area and reduces
			performance.
COPROC_IF_EN	Enabling coprocessor	Core Setup	Enabling this increases
	suport. Extra ports get		core area and reduces
	added.		performance.
TESTBENCH CONFIGURATION			
IRQ_EN	Generates periodic IRQ	Testbench	_
	pulses.		
SIM	Generates extra mes-	Testbench	Must be UNDEFINED
	sages.		for correct synthesis of
			the core in Xilinx since
			some debugging struc-
			tures in RTL are re-
			moved if this is not de-
			fined.
VCD_FILE_PATH	Set the path to the VCD	Testbench	_
	data dump.		
MEMORY_IMAGE	Path to the memory im-	Testbench	_
	age Verilog file.		
MAX_CLOCK_CYCLES	Set the number of	Testbench	_
	cycles the simulation		
	should run before		
	terminating.		
SEED	Set the testbench seed.	Testbench	_
	The seed influences ran-		
	domness.		

3 Compiling Code and Running Simulation

3.0.1 Generating a binary using GNU tools

You can use the existing GNU toolchain to generate code for the processor. This section will briefly explain the procedure. For the purposes of this discussion, let us assume these are the source files...

```
main.c
fact.c
startup.s
misc.s
linker.ld This is the linker script.
```

Generate a bunch of object files.

```
arm-none-eabi-as -mcpu=arm7tdmi -g startup.s -o startup.o arm-none-eabi-as -mcpu=arm7tdmi -g misc.s -o misc.o arm-none-eabi-gcc -c -mcpu=arm7tdmi -g main.c -o main.o arm-none-eabi-gcc -c -mcpu=arm7tdmi -g fact.c -o fact.o
```

Link them up using a linker script...

```
arm-none-eabi-ld -T linker.ld startup.o misc.o main.o fact.o -o prog.elf
```

```
Finally generate a flat binary... arm-none-eabi-objcopy -0 binary prog.elf prog.bin
```

The .bin file generated is the flat binary.

3.0.2 Generating a Verilog memory map

```
perl $ZAP_HOME/scripts/bin2mem.pl prog.bin prog.v The prog.v file looks like this...
```

```
mem[0] = 8'b00;
mem[1] = 8'b01;
```

3.0.3 Invoking the simulator

Ensure config. vh is set up correctly.

Your command must look like this (It is a single command)...

```
iverilog $ZAP_HOME/rtl/*.v $ZAP_HOME/rtl/*/*.v $ZAP_HOME/testbench/*.v
$ZAP_HOME/models/ram/ram.v -I$ZAP_HOME/includes -DSEED=22
```

The rtl/*.v and rtl/*/*.v collect all of the synthesizable Verilog-2001 files, the testbench/*.v collects all of the testbench (In this situations, the ram.v file is a part of the testbench).

Provide some seed value (22 is used in the example). Ensure you edit the config.vh file before running the simulation to correctly point to the memory map, vcd target output path etc for the simulator to pick up.

3.1 Run Sample Code quickly...

A sample .s and .c file is present in \$ZAP_HOME/sw/s and \$ZAP_HOME/sw/c respectively. To translate them to binary and to a Verilog memory map, you can run the Perl script (See NOTE below)

```
perl $ZAP_HOME/debug/run_sim.pl
```

NOTE: Ensure you set all the variables in the Perl script as per the table below...

Variable	Purpose
ZAP_HOME	Set this to the project working directory.
LOG_FILE_PATH	Set this to the place where you want the log file to be created.
ASM_PATH	Set this to the location of your startup assembly file.
C_PATH	Set this to the location of your C file.
LINKER_PATH	Set this to the location of the linker script.
TARGET_BIN_PATH	Set this to the target bin file location.
VCD_PATH	Set this to location where the VCD is to be created. This must match what is in config.vh
MEMORY_IMAGE	Set this to the location where the memory image must be created. This must match what is in config.vh

4 Top Level Description