





Posture Recognition Based on Deep Learning

Team: *PR023*

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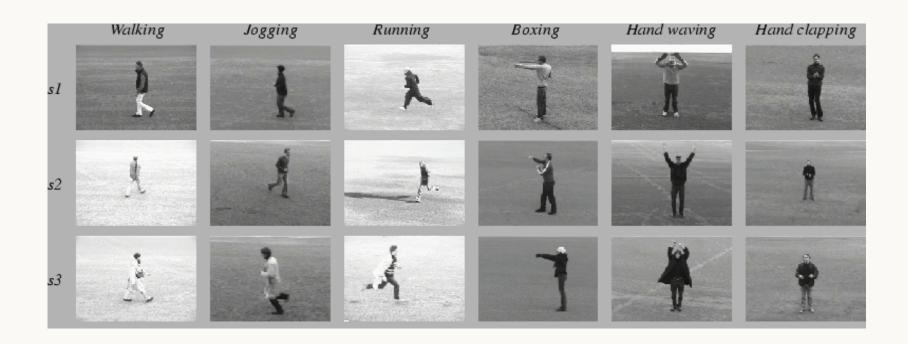
Microelectronics R & D Center, Shanghai University

Posture Recognition Based on Vision

Pedestrian Detection: find where the person is

Posture Recognition: recognize what posture it is

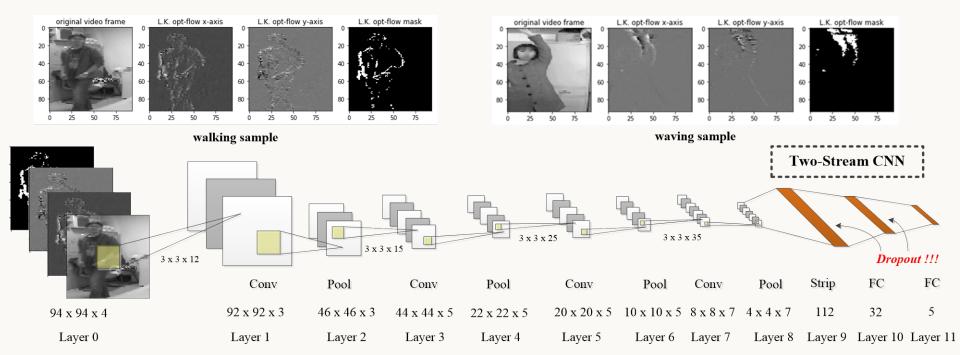
Applications: somatic games, abnormal behavior detection, ...



Posture Recognition Scheme

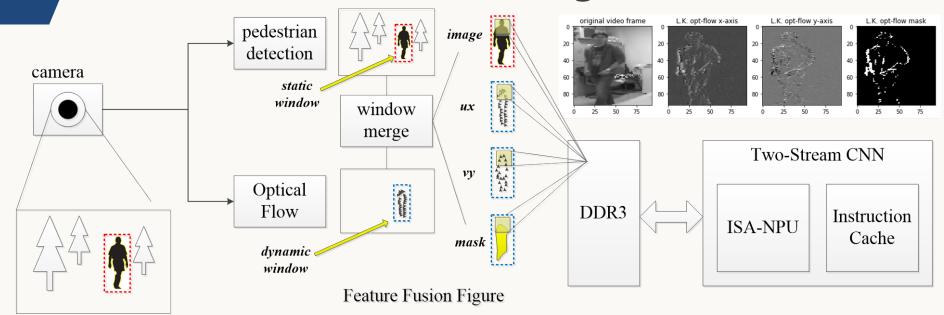
Two-Stream Convolution: compute optical flow in the video stream, and use video and optical flow as the input channels of CNN to recognize the posture

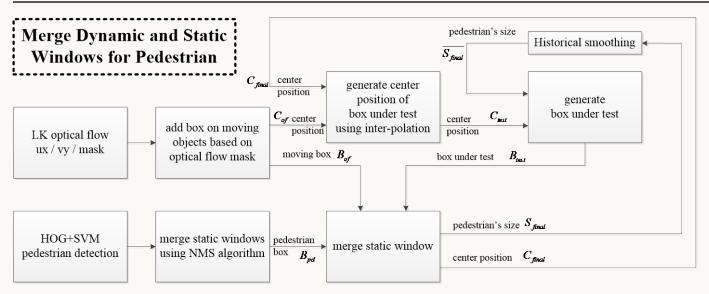
ISA-NPU: ADD / MULT / CONV / POOL / SIGM / TANH / ...



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The Flow of Posture Recognition







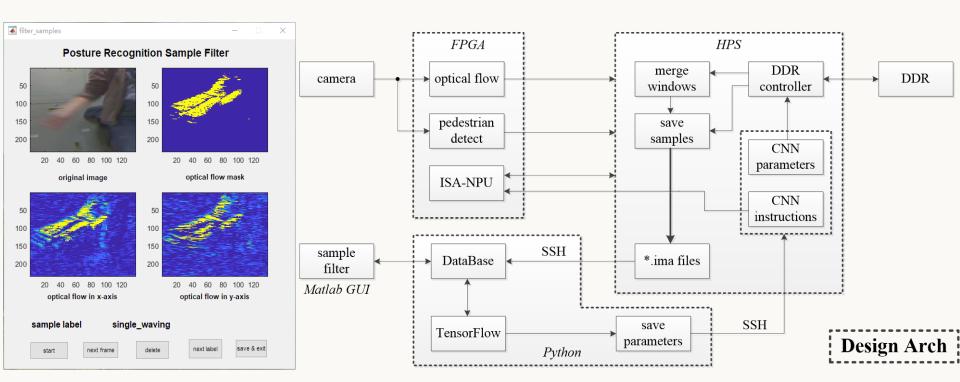
Framework of the System

Co-process of software and hardware on DE10-Nano

FPGA: optical flow, static detection, ISA-NPU, memory scheduler,

video output; HPS: add box, NPU command;

Matlab: filter samples; Python: train the CNN model



Performance of the System

The resource usage of the total hardware system

ltem	ALMs	Memory Bits	DSPs
Utility	37,933 (91 %)	2,513,876 (44 %)	106 (95 %)

The theoretic limit of performance of modules

Performance		LK Optical Flow	HOG + SVM	ISA-NPU
Speed	Fmax	118.68 MHz	76.8 MHz	79.6 MHz
	Period	800 x 600	800 x 600	814,177
	FPS	247	160	97.7
Area	ALMs	7,799	14,105	3,530
	Memory Bits	188,202	1,167,512	73,984
	DSPs	41	16	43

The experimental performance of hardware and software modules

Performance		LK Optical Flow	HOG + SVM	ISA-NPU
Speed	Fmax	35 MHz	35 MHz	66.67 MHz
	Period	800 x 600	800 x 600	814,177
	FPS	20	20	3.84
Performance		Dynamic Window	Static Window	Merge Window
Time		70.2 ms	11 us	8 us

Conclusion and Outlook

We propose a posture recognition system that:

- process optical flow, static pedestrian detection very fast, actually it is pipeline processing;
- **2. flexible for different CNN models**, if the model changes, only parameters and NPU instructions should be regenerated;
- 3. recognize four postures with **high precision**: standing, squatting, waving and walking;

We can improve the system later in these aspects:

- **1. more postures** can be recognized once the CNN model grows;
- high performance can be achieved if bandwidth of DDR increases







Thanks for Your Attention

GitHub https://github.com/cxdzyq1110/posture_recognition_CNN

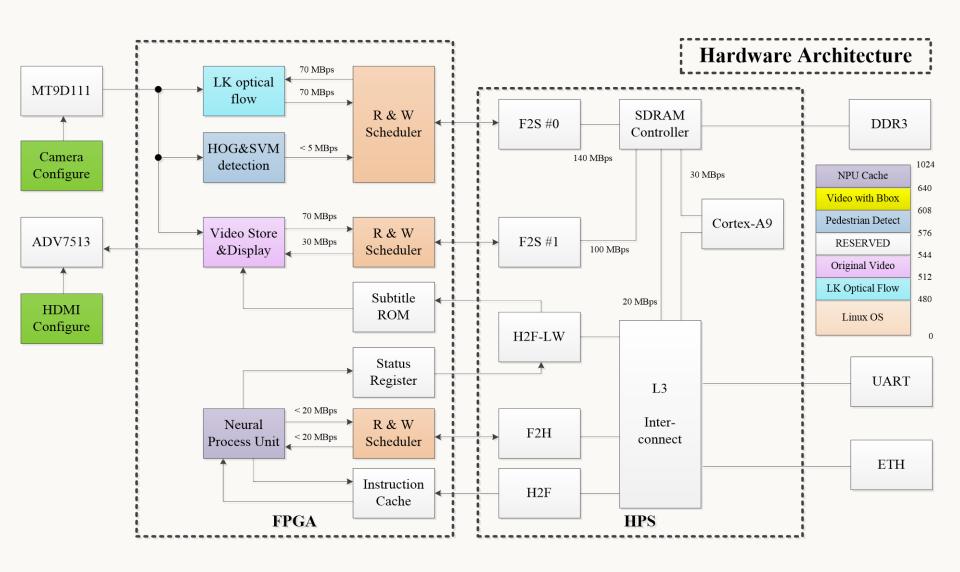
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Hardware Architecture

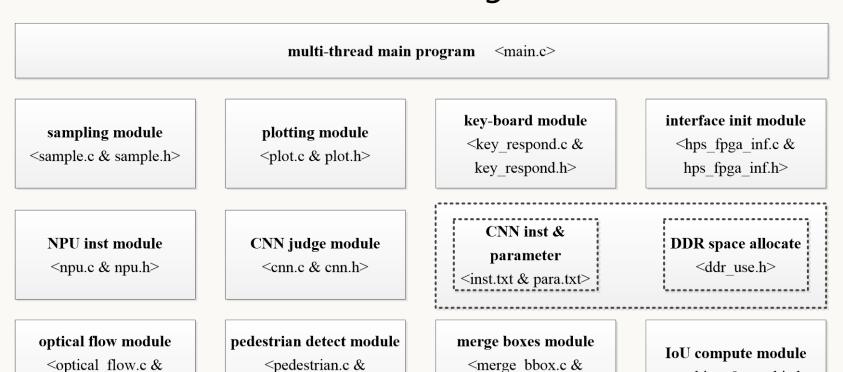


Software Architecture

Different Mode:

optical flow.h>

- 1. running mode: merge windows and recognize
- 2. sampling mode: merge windows and sample
- 3. testcnn mode: use training set to test CNN



merge bbox.h>

pedestrian.h>

<graphic.c & graphic.h>