Exceptional Control Flow: Signals and Nonlocal Jumps

Introduction to Computer Systems

ECF Exists at All Levels of a System

- **Exceptions**
  - Hardware and operating system kernel software
- **Process Context Switch**
  - Hardware timer and kernel software

Previous Lecture

- **Signals**
  - Kernel software and application software
- **Nonlocal jumps**
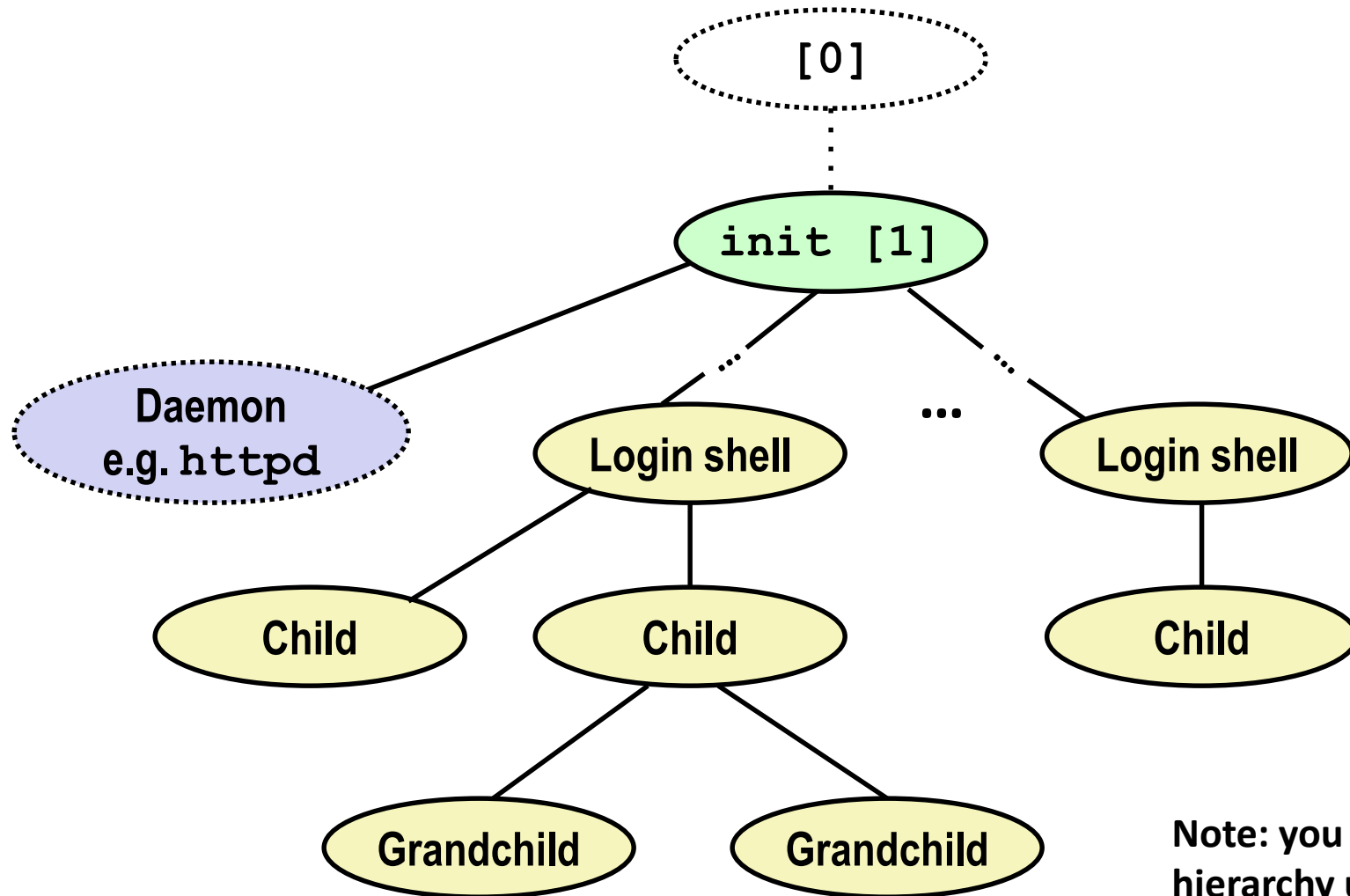 - Application code

This Lecture

Today

- **Shells**
- **Signals**
- **Nonlocal jumps**

Linux Process Hierarchy

Note: you can view the hierarchy using the Linux `pstree` **command**

Shell Programs

- **A *shell* is an application program that runs programs on behalf of the user.**
  - **sh**   Original Unix shell (Stephen Bourne, AT&T Bell Labs, 1977)
  - **csh/tcsh**   BSD Unix C shell
  - **bash**   "Bourne-Again" Shell (default Linux shell)

```c
int main()
{
    char cmdline[MAXLINE]; /* command line */

    while (1) {
        /* read */
        printf("> ");
        Fgets(cmdline, MAXLINE, stdin);
        if (feof(stdin))
            exit(0);

        /* evaluate */
        eval(cmdline);
    }
}
                                        shellex.c
```

Execution is a sequence of read/evaluate steps

Simple Shell `eval` Function

```
void eval(char *cmdline)
{
    char *argv[MAXARGS]; /* Argument list execve() */
    char buf[MAXLINE];   /* Holds modified command line */
    int bg;              /* Should the job run in bg or fg? */
    pid_t pid;           /* Process id */

    strcpy(buf, cmdline);
    bg = parseline(buf, argv);
    if (argv[0] == NULL)
        return;   /* Ignore empty lines */

    if (!builtin_command(argv)) {
        if ((pid = Fork()) == 0) {   /* Child runs user job */
            if (execve(argv[0], argv, environ) < 0) {
                printf("%s: Command not found.\n", argv[0]);
                exit(0);
            }
        }

        /* Parent waits for foreground job to terminate */
        if (!bg) {
            int status;
            if (waitpid(pid, &status, 0) < 0)
                unix_error("waitfg: waitpid error");
        }
        else
            printf("%d %s", pid, cmdline);
    }
    return;
}
```

shellex.c

What Is a "Background Job"?

- **Users generally run one command at a time**
  - Type command, read output, type another command

- **Some programs run "for a long time"**
  - Example: "delete this file in two hours"

```
unix> sleep 7200; rm /tmp/junk  # shell stuck for 2 hours
```

- **A "background" job is a process we don't want to wait for**

```
unix> (sleep 7200 ; rm /tmp/junk) &
[1] 907
unix> # ready for next command
```

Problem with Simple Shell Example

■ **Our example shell correctly waits for and reaps foreground jobs**

■ **But what about background jobs?**
- Will become zombies when they terminate
- Will never be reaped because shell (typically) will not terminate
- Will create a memory leak that could run the kernel out of memory

ECF to the Rescue!

- **Solution: Exceptional control flow**
  - The kernel will interrupt regular processing to alert us when a background process completes
  - In Unix, the alert mechanism is called a *signal*

Today

- **Shells**
- **Signals**
- **Nonlocal jumps**

Signals

- **A *signal* is a small message that notifies a process that an event of some type has occurred in the system**
  - Akin to exceptions and interrupts
  - Sent from the kernel (sometimes at the request of another process) to a process
  - Signal type is identified by small integer ID's (1-30)
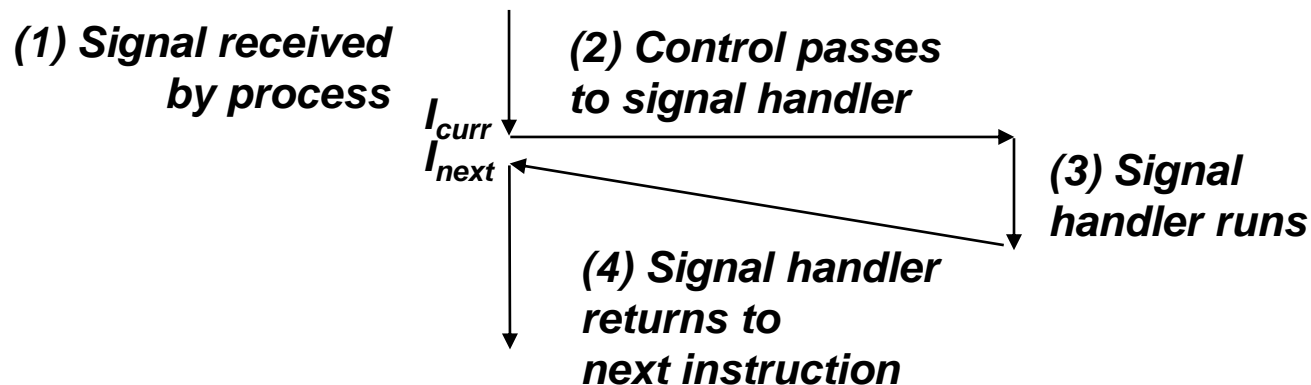 - Only information in a signal is its ID and the fact that it arrived

ID	Name	Default Action	Corresponding Event
2	SIGINT	Terminate	User typed ctrl-c
9	SIGKILL	Terminate	Kill program (cannot override or ignore)
11	SIGSEGV	Terminate	Segmentation violation
14	SIGALRM	Terminate	Timer signal
17	SIGCHLD	Ignore	Child stopped or terminated

Signal Concepts: Sending a Signal

- **Kernel *sends* (delivers) a signal to a *destination process* by updating some state in the context of the destination process**

- **Kernel sends a signal for one of the following reasons:**
  - Kernel has detected a system event such as divide-by-zero (SIGFPE) or the termination of a child process (SIGCHLD)
  - Another process has invoked the `kill` system call to explicitly request the kernel to send a signal to the destination process

Signal Concepts: Receiving a Signal

- **A destination process *receives* a signal when it is forced by the kernel to react in some way to the delivery of the signal**

- **Some possible ways to react:**
  - *Ignore* the signal (do nothing)
  - *Terminate* the process (with optional core dump)
  - *Catch* the signal by executing a user-level function called *signal handler*
    - Akin to a hardware exception handler being called in response to an asynchronous interrupt:

(1) Signal received by process

I_{curr}
I_{next}

(2) Control passes to signal handler

(3) Signal handler runs

(4) Signal handler returns to next instruction

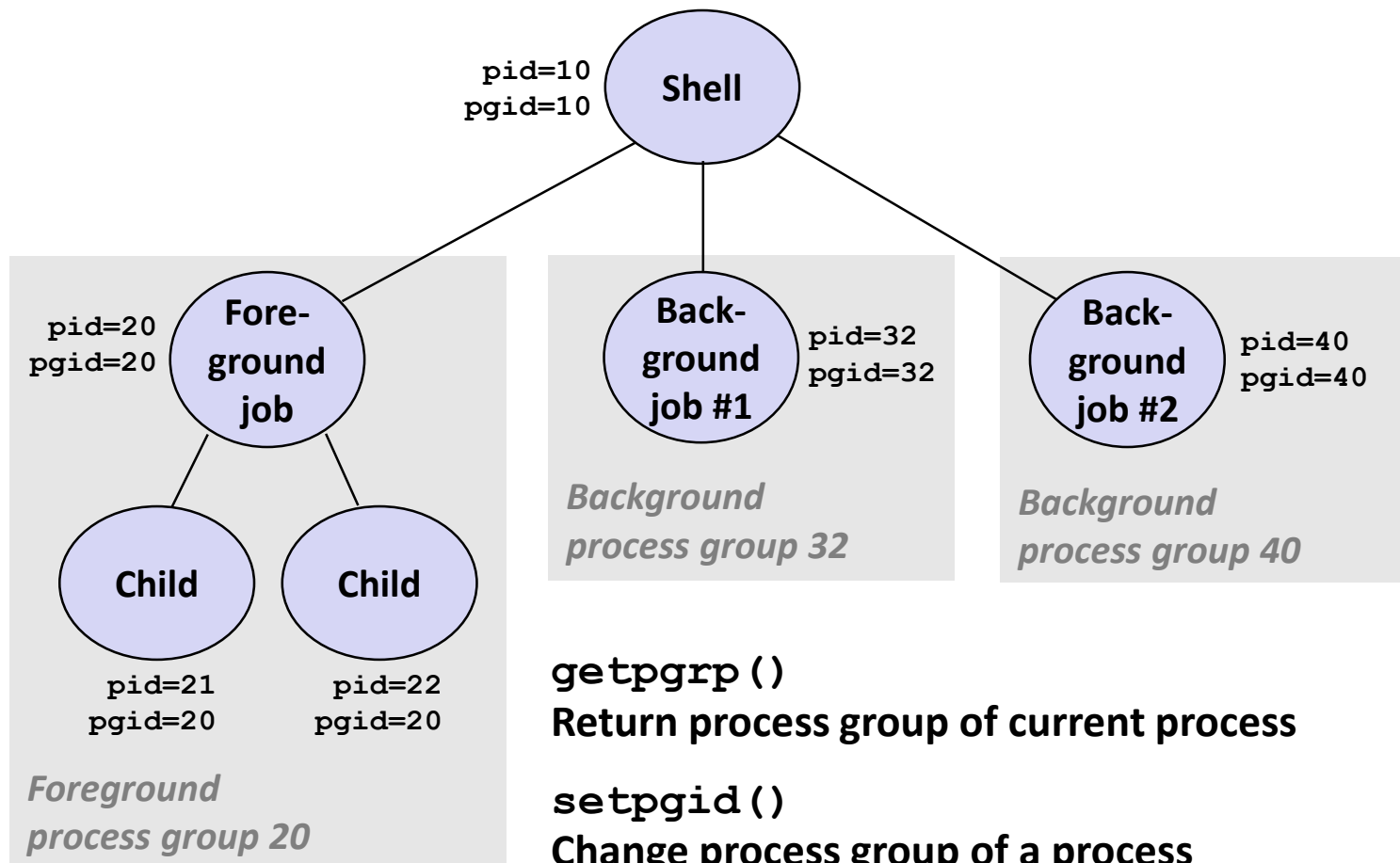# Signal Concepts: Pending and Blocked Signals

- **A signal is *pending* if sent but not yet received**
  - There can be at most one pending signal of any particular type
  - Important: Signals are not queued
    - If a process has a pending signal of type k, then subsequent signals of type k that are sent to that process are discarded

- **A process can *block* the receipt of certain signals**
  - Blocked signals can be delivered, but will not be received until the signal is unblocked

- **A pending signal is received at most once**

Signal Concepts: Pending/Blocked Bits

- **Kernel maintains `pending` and `blocked` bit vectors in the context of each process**
  - **`pending`**: represents the set of pending signals
    - Kernel sets bit k in **`pending`** when a signal of type k is delivered
    - Kernel clears bit k in **`pending`** when a signal of type k is received

  - **`blocked`**: represents the set of blocked signals
    - Can be set and cleared by using the **`sigprocmask`** function
    - Also referred to as the *signal mask*.

Sending Signals: Process Groups

■ **Every process belongs to exactly one process group**

```
pid=10
pgid=10
```
Shell

```
pid=20
pgid=20
```
Fore-ground job

```
pid=32
pgid=32
```
Back-ground job #1

```
pid=40
pgid=40
```
Back-ground job #2

Child
Child

```
pid=21
pgid=20
```
```
pid=22
pgid=20
```

Foreground process group 20

Background process group 32

Background process group 40

`getpgrp()`
Return process group of current process

`setpgid()`
Change process group of a process

Sending Signals with /bin/`kill` Program

- **/bin/kill program sends arbitrary signal to a process or process group**

- **Examples**
  - **/bin/kill –9 24818**
    Send SIGKILL to process 24818

  - **/bin/kill –9 –24817**
    Send SIGKILL to every process in process group 24817

```
linux> ./forks 16
Child1: pid=24818 pgrp=24817
Child2: pid=24819 pgrp=24817

linux> ps
  PID TTY          TIME CMD
24788 pts/2    00:00:00 tcsh
24818 pts/2    00:00:02 forks
24819 pts/2    00:00:02 forks
24820 pts/2    00:00:00 ps
linux> /bin/kill -9 -24817
linux> ps
  PID TTY          TIME CMD
24788 pts/2    00:00:00 tcsh
24823 pts/2    00:00:00 ps
linux>
```
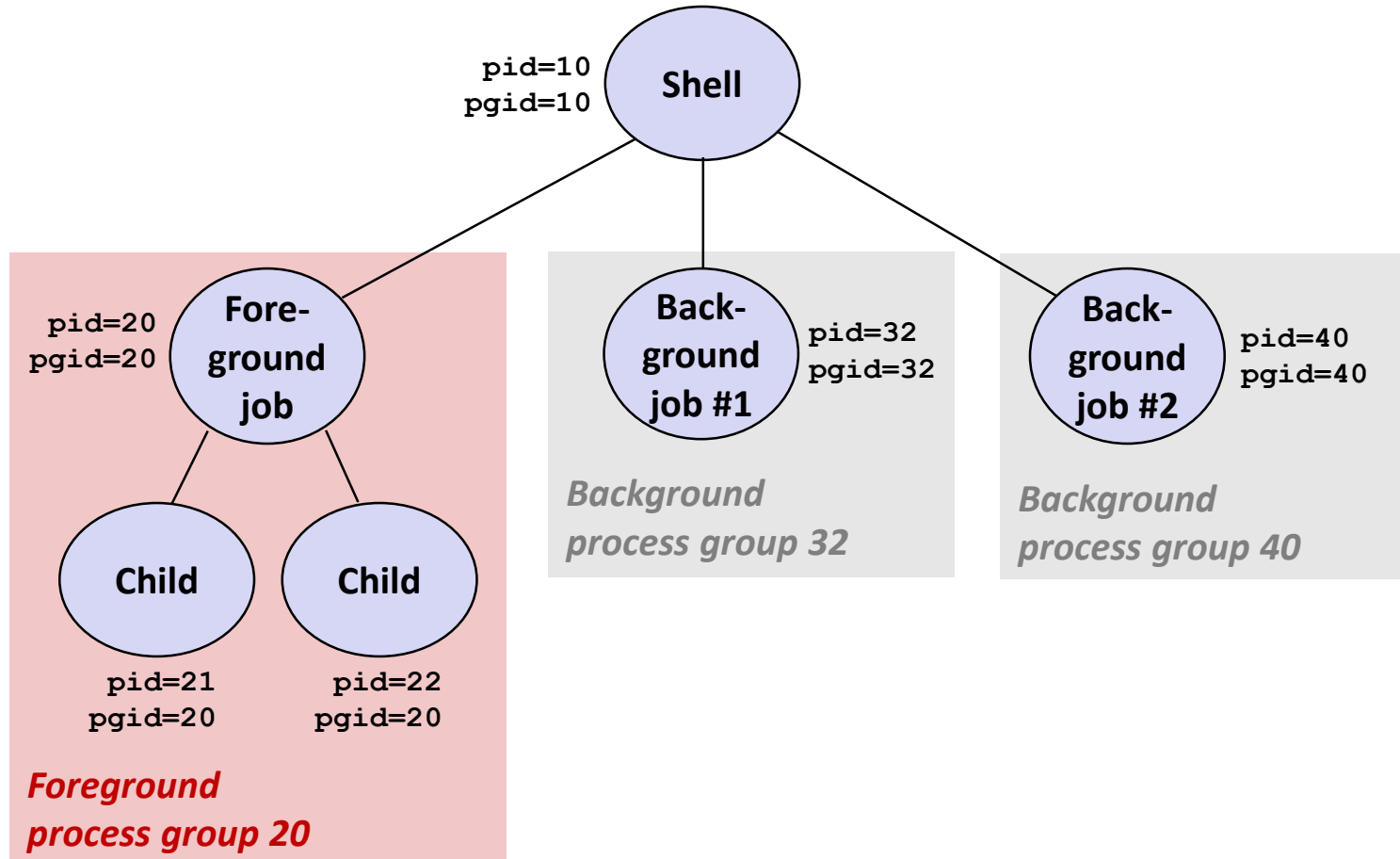
Sending Signals from the Keyboard

- **Typing ctrl-c (ctrl-z) causes the kernel to send a SIGINT (SIGTSTP) to every job in the foreground process group.**
  - SIGINT – default action is to terminate each process
  - SIGTSTP – default action is to stop (suspend) each process

`pid=10`
`pgid=10` Shell

`pid=20`
`pgid=20` Fore-ground job

Child `pid=21`
`pgid=20`

Child `pid=22`
`pgid=20`

Foreground process group 20

Back-ground job #1 `pid=32`
`pgid=32`

Background process group 32

Back-ground job #2 `pid=40`
`pgid=40`

Background process group 40

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Example of `ctrl-c` and `ctrl-z`

```
bluefish> ./forks 17
Child: pid=28108 pgrp=28107
Parent: pid=28107 pgrp=28107
<types ctrl-z>
Suspended
bluefish> ps w
  PID TTY        STAT    TIME COMMAND
27699 pts/8      Ss      0:00 -tcsh
28107 pts/8      T       0:01 ./forks 17
28108 pts/8      T       0:01 ./forks 17
28109 pts/8      R+      0:00 ps w
bluefish> fg
./forks 17
<types ctrl-c>
bluefish> ps w
  PID TTY        STAT    TIME COMMAND
27699 pts/8      Ss      0:00 -tcsh
28110 pts/8      R+      0:00 ps w
```

STAT (process state) Legend:

First letter:
S: sleeping
T: stopped
R: running

Second letter:
s: session leader
+: foreground proc group

See "man ps" for more details

Sending Signals with `kill` Function

```c
void fork12()
{
    pid_t pid[N];
    int i;
    int child_status;

    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0) {
            /* Child: Infinite Loop */
            while(1)
                ;
        }

    for (i = 0; i < N; i++) {
        printf("Killing process %d\n", pid[i]);
        kill(pid[i], SIGINT);
    }

    for (i = 0; i < N; i++) {
        pid_t wpid = wait(&child_status);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n",
                    wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminated abnormally\n", wpid);
    }
}
```
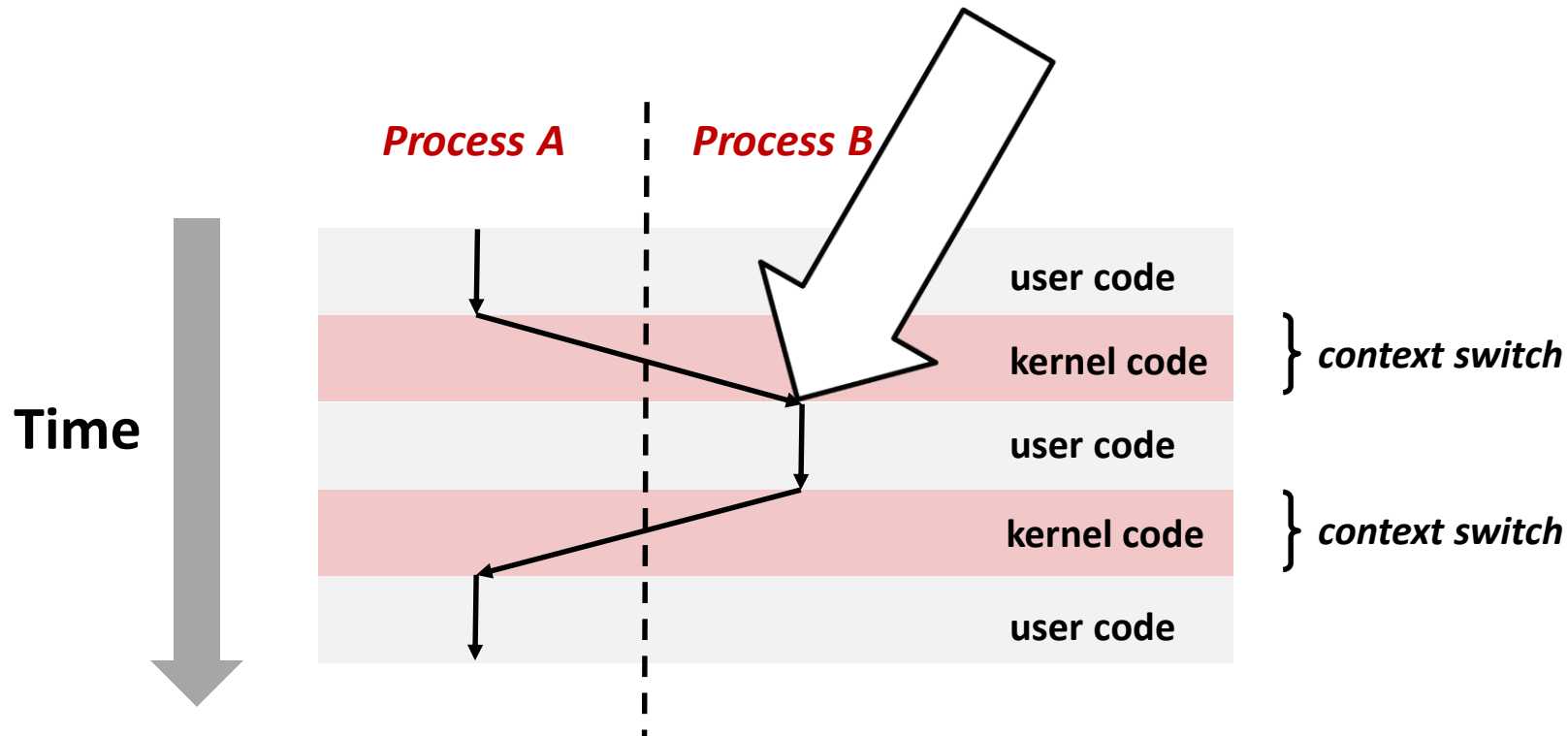
forks.c

Receiving Signals

■ **Suppose kernel is returning from an exception handler and is ready to pass control to process *p***

Important: All context switches are initiated by calling some exception hander.

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Receiving Signals

- **Suppose kernel is returning from an exception handler and is ready to pass control to process *p***

- **Kernel computes `pnb = pending & ~blocked`**
  - The set of pending nonblocked signals for process *p*

- **If (`pnb == 0`)**
  - Pass control to next instruction in the logical flow for *p*
- **Else**
  - Choose least nonzero bit *k* in `pnb` and force process *p* to ***receive*** signal *k*
  - The receipt of the signal triggers some ***action*** by *p*
  - Repeat for all nonzero *k* in `pnb`
  - Pass control to next instruction in logical flow for *p*

Default Actions

- **Each signal type has a predefined *default action*, which is one of:**
  - The process terminates
    - The process terminates and dumps core
  - The process stops until restarted by a SIGCONT signal
  - The process ignores the signal

Installing Signal Handlers

- **The `signal` function modifies the default action associated with the receipt of signal `signum`:**
  - **`handler_t *signal(int signum, handler_t *handler)`**

- **Different values for `handler`:**
  - SIG_IGN: ignore signals of type `signum`
  - SIG_DFL: revert to the default action on receipt of signals of type `signum`
  - Otherwise, **`handler`** is the address of a user-level *signal handler*
    - Called when process receives signal of type `signum`
    - Referred to as *"installing"* the handler
    - Executing handler is called *"catching"* or *"handling"* the signal
    - When the handler executes its return statement, control passes back to instruction in the control flow of the process that was interrupted by receipt of the signal

Signal Handling Example

```c
#include "csapp.h"

void sigint_handler(int sig) /* SIGINT handler */
{
    printf("So you think you can stop the bomb with ctrl-c, do you?\n");
    sleep(2);
    printf("Well...");
    fflush(stdout);
    sleep(1);
    printf("OK. :-)\n");
    exit(0);
}

int main()
{

    /* Install the SIGINT handler */
    if (signal(SIGINT, sigint_handler) == SIG_ERR)
        unix_error("signal error");

    /* Wait for the receipt of a signal */
    pause();

    return 0;
}
```
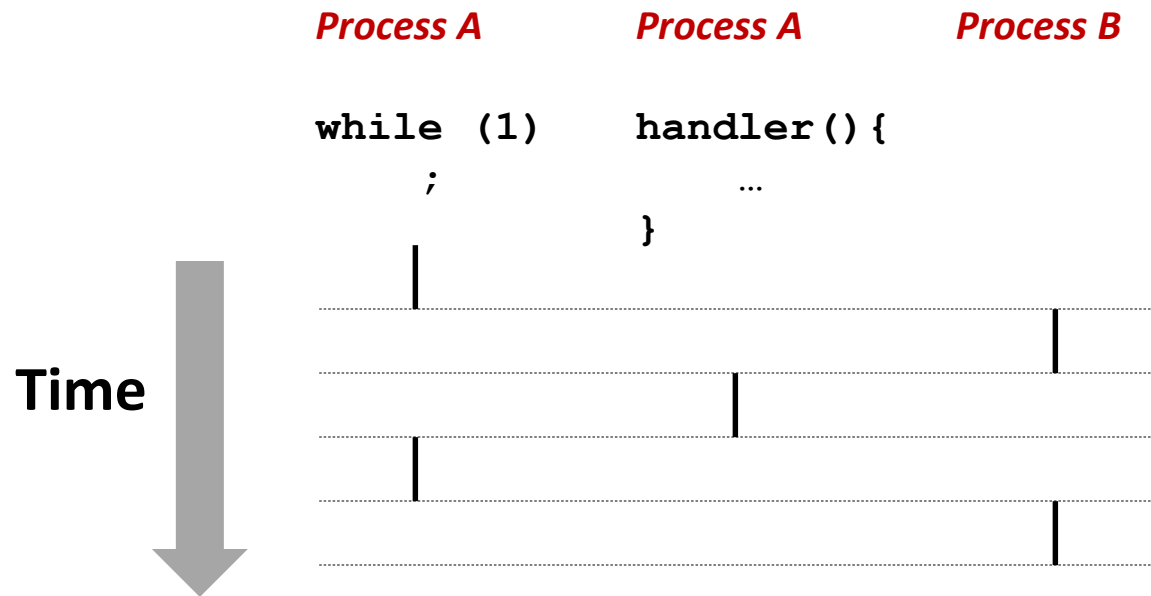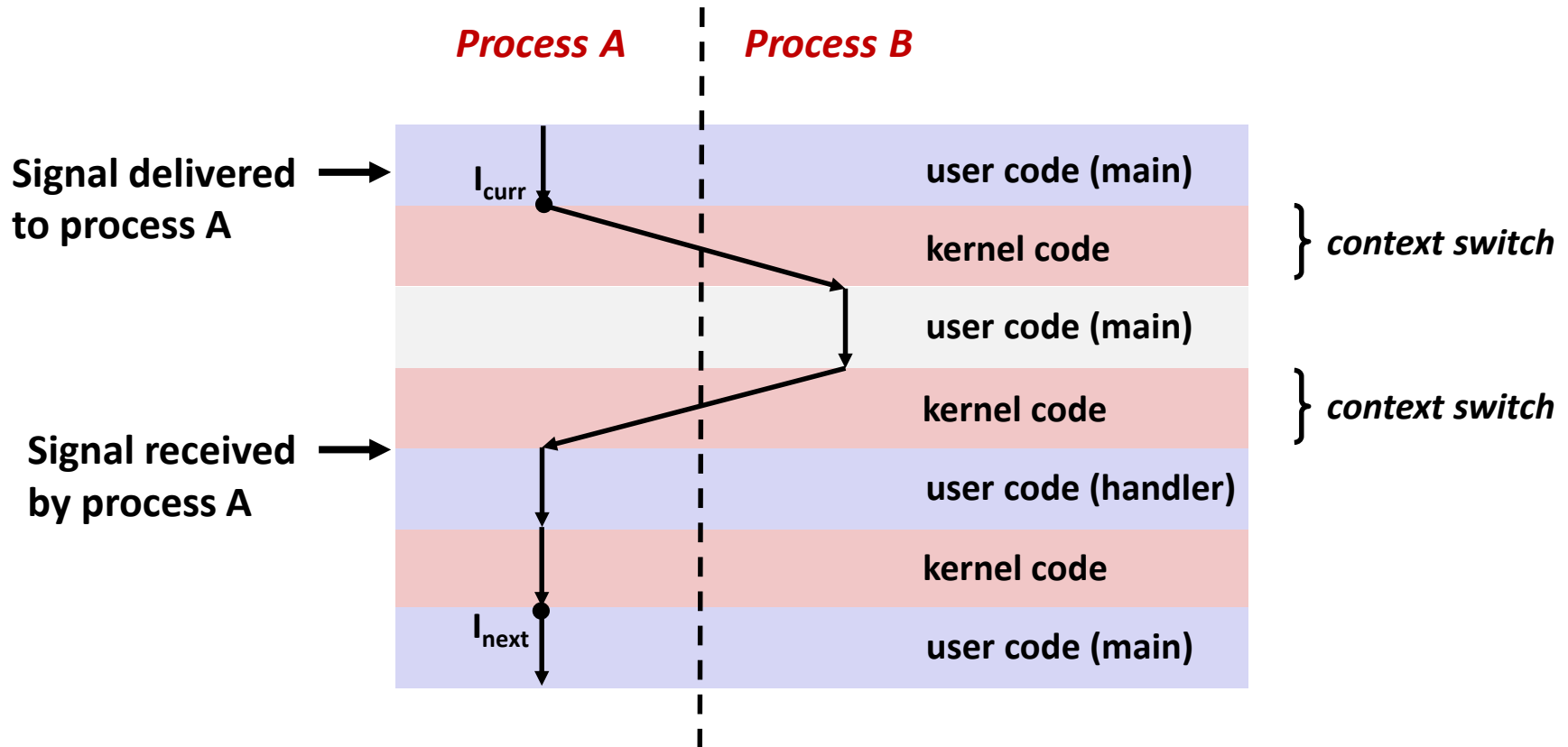
```
linux> ./sigint
<ctrl-c>
So you think you can stop the bomb
with ctrl-c, do you?
Well...OK. :-)
linux>
```

sigint.c

Signals Handlers as Concurrent Flows

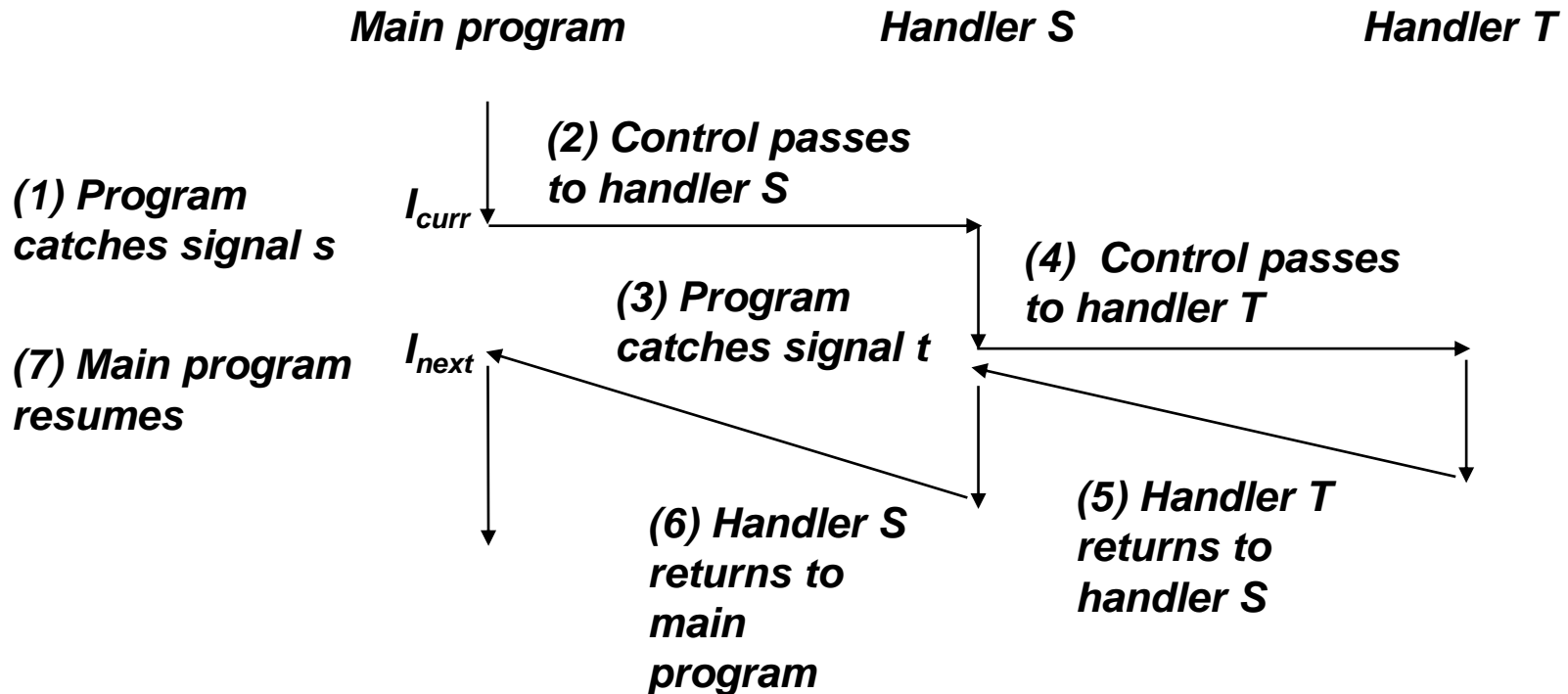- **A signal handler is a separate logical flow (not process) that runs concurrently with the main program**

Process A   *Process A*   *Process B*

```
while (1)     handler(){
   ;               …
               }
```

Time

Another View of Signal Handlers as Concurrent Flows

Process A   *Process B*

Signal delivered
to process A

I_{curr}

user code (main)

kernel code   } *context switch*

user code (main)

kernel code   } *context switch*

Signal received
by process A

user code (handler)

kernel code

I_{next} user code (main)

Nested Signal Handlers

■ **Handlers can be interrupted by other handlers**

Main program   *Handler S*   *Handler T*

*(2) Control passes
to handler S*

*(1) Program
catches signal s* I_{curr}

*(4) Control passes
to handler T*

*(3) Program
catches signal t*

*(7) Main program
resumes* I_{next}

*(5) Handler T
returns to
handler S*

*(6) Handler S
returns to
main
program*

Blocking and Unblocking Signals

- **Implicit blocking mechanism**
  - Kernel blocks any pending signals of type currently being handled.
  - E.g., A SIGINT handler can't be interrupted by another SIGINT

- **Explicit blocking and unblocking mechanism**
  - `sigprocmask` function

- **Supporting functions**
  - `sigemptyset` – create empty set
  - `sigfillset` – add every signal number to set
  - `sigaddset` – add signal number to set
  - `sigdelset` – delete signal number from set

Temporarily Blocking Signals

```
sigset_t mask, prev_mask;

Sigemptyset(&mask);
Sigaddset(&mask, SIGINT);

/* Block SIGINT and save previous blocked set */
Sigprocmask(SIG_BLOCK, &mask, &prev_mask);

  ⋮    /* Code region that will not be interrupted by SIGINT */

/* Restore previous blocked set, unblocking SIGINT */
Sigprocmask(SIG_SETMASK, &prev_mask, NULL);
```

Safe Signal Handling

- **Handlers are tricky because they are concurrent with main program and share the same global data structures.**
    - Shared data structures can become corrupted.

- **We'll explore concurrency issues later in the term.**

- **For now here are some guidelines to help you avoid trouble.**

Guidelines for Writing Safe Handlers

- **G0: Keep your handlers as simple as possible**
  - e.g., Set a global flag and return
- **G1: Call only async-signal-safe functions in your handlers**
  - `printf,` `sprintf,` `malloc,` and `exit` are not safe!
- **G2: Save and restore `errno` on entry and exit**
  - So that other handlers don't overwrite your value of `errno`
- **G3: Protect accesses to shared data structures by temporarily blocking all signals.**
  - To prevent possible corruption
- **G4: Declare global variables as `volatile`**
  - To prevent compiler from storing them in a register
- **G5: Declare global flags as `volatile sig_atomic_t`**
  - *flag*: variable that is only read or written (e.g. flag = 1, not flag++)
  - Flag declared this way does not need to be protected like other globals

Async-Signal-Safety

- **Function is *async-signal-safe* if either reentrant (e.g., all variables stored on stack frame, CS:APP3e 12.7.2) or non-interruptible by signals.**

- **Posix guarantees 117 functions to be async-signal-safe**
  - Source: "`man 7 signal`"
  - Popular functions on the list:
    - `_exit, write, wait, waitpid, sleep, kill`
  - Popular functions that are **not** on the list:
    - `printf, sprintf, malloc, exit`
    - Unfortunate fact: `write` is the only async-signal-safe output function

Safely Generating Formatted Output

■ **Option 1: temporarily block all signals during each call to `printf` EVERYWHERE in the program.**

```c
/* safe_printf – async-signal-safe wrapper for printf */
void safe_printf(const char *format, ...)
{
    char buf[MAXBUF];
    va_list args;
    sigset_t mask, prev_mask;

    sigfillset(&mask);
    sigprocmask(SIG_BLOCK, &mask, &prev_mask);

    va_start(args, format);
    vsnprintf(buf, sizeof(buf), format, args);
    va_end(args);
    write(1, buf, strlen(buf));

    sigprocmask(SIG_SETMASK, &prev_mask, NULL);
}
```

Safely Generating Formatted Output

- **Option 2: Use the reentrant SIO (Safe I/O library) from `csapp.c` in your handlers.**

    - `ssize_t sio_puts(char s[]) /* Put string */`
    - `ssize_t sio_putl(long v)    /* Put long */`
    - `void sio_error(char s[])    /* Put msg & exit */`

```
void sigint_handler(int sig) /* Safe SIGINT handler */
{
    Sio_puts("So you think you can stop the bomb with ctrl-c, do you?\n");
    sleep(2);
    Sio_puts("Well...");
    sleep(1);
    Sio_puts("OK. :-)\n");
    _exit(0);
}
```

sigintsafe.c

Signal Handling

```c
int ccount = 0;
void child_handler(int sig) {
    int olderrno = errno;
    pid_t pid;
    if ((pid = wait(NULL)) < 0)
        Sio_error("wait error");
    ccount--;
    Sio_puts("Handler reaped child ");
    Sio_putl((long)pid);
    Sio_puts(" \n");
    sleep(1);
    errno = olderrno;
}

void fork14() {
    pid_t pid[N];
    int i;
    ccount = N;
    Signal(SIGCHLD, child_handler);

    for (i = 0; i < N; i++) {
        if ((pid[i] = Fork()) == 0) {
            Sleep(1);
            exit(0);  /* Child exits */
        }
    }
    while (ccount > 0) /* Parent spins */
        ;
}
```

- **Pending signals are not queued**
  - For each signal type, one bit indicates whether or not signal is pending…
  - …thus at most one pending signal of any particular type.

- **You can't use signals to count events, such as children terminating.**
  - This program may get stuck in final loop

```
whaleshark> ./forks 14
Handler reaped child 23240
Handler reaped child 23241
```

forks.c

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Living With Nonqueuing Signals

- **Must wait for all terminated child processes**
  - Have handler loop with `waitpid` to get all jobs

```c
void child_handler2(int sig)
{
    int olderrno = errno;
    pid_t pid;
    while ((pid = waitpid(-1, &child_status, WNOHANG)) > 0) {
        ccount--;
        Sio_puts("Handler reaped child ");
        Sio_putl((long)pid);
        Sio_puts(" \n");
    }
    if (errno != ECHILD)
        Sio_error("wait error");
    errno = olderrno;
}
```

```
whaleshark> ./forks 15
Handler reaped child 23246
Handler reaped child 23247
Handler reaped child 23248
Handler reaped child 23249
Handler reaped child 23250
whaleshark>
```

Portable Signal Handling

- **Ugh! Different versions of Unix can have different signal handling semantics**

  - Some older systems restore action to default after catching signal
  - Some interrupted system calls can return with errno == EINTR
  - Some systems don't block signals of the type being handled

- **Solution: `sigaction`**

```c
handler_t *Signal(int signum, handler_t *handler)
{
    struct sigaction action, old_action;

    action.sa_handler = handler;
    sigemptyset(&action.sa_mask); /* Block sigs of type being handled */
    action.sa_flags = SA_RESTART; /* Restart syscalls if possible */

    if (sigaction(signum, &action, &old_action) < 0)
        unix_error("Signal error");
    return (old_action.sa_handler);
}
```

csapp.c

Synchronizing Flows to Avoid Races

■ **Simple shell with a subtle synchronization error because it assumes parent runs before child.**

```c
int main(int argc, char **argv)
{
    int pid;
    sigset_t mask_all, prev_all;

    Sigfillset(&mask_all);
    Signal(SIGCHLD, handler);
    initjobs(); /* Initialize the job list */

    while (1) {
        if ((pid = Fork()) == 0) { /* Child */
            Execve("/bin/date", argv, NULL);
        }
        Sigprocmask(SIG_BLOCK, &mask_all, &prev_all); /* Parent */
        addjob(pid);  /* Add the child to the job list */
        Sigprocmask(SIG_SETMASK, &prev_all, NULL);
    }
    exit(0);
}
```

Synchronizing Flows to Avoid Races

- **SIGCHLD handler for a simple shell**

```c
void handler(int sig)
{
    int olderrno = errno;
    sigset_t mask_all, prev_all;
    pid_t pid;

    Sigfillset(&mask_all);
    while ((pid = waitpid(-1, NULL, WNOHANG)) > 0) { /* Reap child */
        Sigprocmask(SIG_BLOCK, &mask_all, &prev_all);
        deletejob(pid); /* Delete the child from the job list */
        Sigprocmask(SIG_SETMASK, &prev_all, NULL);
    }
    if (errno != ECHILD)
        Sio_error("waitpid error");
    errno = olderrno;
}
```

Corrected Shell Program without Race

```c
int main(int argc, char **argv)
{
    int pid;
    sigset_t mask_all, mask_one, prev_one;

    Sigfillset(&mask_all);
    Sigemptyset(&mask_one);
    Sigaddset(&mask_one, SIGCHLD);
    Signal(SIGCHLD, handler);
    initjobs(); /* Initialize the job list */

    while (1) {
        Sigprocmask(SIG_BLOCK, &mask_one, &prev_one); /* Block SIGCHLD */
        if ((pid = Fork()) == 0) { /* Child process */
            Sigprocmask(SIG_SETMASK, &prev_one, NULL); /* Unblock SIGCHLD */
            Execve("/bin/date", argv, NULL);
        }
        Sigprocmask(SIG_BLOCK, &mask_all, NULL); /* Parent process */
          addjob(pid);  /* Add the child to the job list */
        Sigprocmask(SIG_SETMASK, &prev_one, NULL);  /* Unblock SIGCHLD */
    }
    exit(0);
}
```

Explicitly Waiting for Signals

- **Handlers for program explicitly waiting for SIGCHLD to arrive.**

```c
volatile sig_atomic_t pid;

void sigchld_handler(int s)
{
    int olderrno = errno;
    pid = Waitpid(-1, NULL, 0); /* Main is waiting for nonzero pid */
    errno = olderrno;
}

void sigint_handler(int s)
{
}
```

waitforsignal.c

Explicitly Waiting for Signals

> **Similar to a shell waiting for a foreground job to terminate.**

```c
int main(int argc, char **argv) {
    sigset_t mask, prev;
    Signal(SIGCHLD, sigchld_handler);
    Signal(SIGINT, sigint_handler);
    Sigemptyset(&mask);
    Sigaddset(&mask, SIGCHLD);

    while (1) {
        Sigprocmask(SIG_BLOCK, &mask, &prev); /* Block SIGCHLD */
        if (Fork() == 0) /* Child */
            exit(0);
        /* Parent */
        pid = 0;
        Sigprocmask(SIG_SETMASK, &prev, NULL); /* Unblock SIGCHLD */

        /* Wait for SIGCHLD to be received (wasteful!) */
        while (!pid)
            ;
        /* Do some work after receiving SIGCHLD */
        printf(".");
    }
    exit(0);
}
```

waitforsignal.c

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Explicitly Waiting for Signals

- **Program is correct, but very wasteful**

- **Other options:**

```
while (!pid)   /* Race! */
    pause();
```

```
while (!pid) /* Too slow! */
    sleep(1);
```

- **Solution: `sigsuspend`**

Waiting for Signals with `sigsuspend`

- `int sigsuspend(const sigset_t *mask)`
- **Equivalent to atomic (uninterruptable) version of:**

```
sigprocmask(SIG_BLOCK, &mask, &prev);
pause();
sigprocmask(SIG_SETMASK, &prev, NULL);
```

Waiting for Signals with `sigsuspend`

```c
int main(int argc, char **argv) {
    sigset_t mask, prev;
    Signal(SIGCHLD, sigchld_handler);
    Signal(SIGINT, sigint_handler);
    Sigemptyset(&mask);
    Sigaddset(&mask, SIGCHLD);

    while (1) {
        Sigprocmask(SIG_BLOCK, &mask, &prev); /* Block SIGCHLD */
        if (Fork() == 0) /* Child */
            exit(0);

        /* Wait for SIGCHLD to be received */
        pid = 0;
        while (!pid)
            Sigsuspend(&prev);

        /* Optionally unblock SIGCHLD */
        Sigprocmask(SIG_SETMASK, &prev, NULL);
        /* Do some work after receiving SIGCHLD */
        printf(".");
    }
    exit(0);
}
```

sigsuspend.c

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Today

- **Shells**
- **Signals**
- **Nonlocal jumps**

Nonlocal Jumps: `setjmp/longjmp`

- **Powerful (but dangerous) user-level mechanism for transferring control to an arbitrary location**
  - Controlled to way to break the procedure call / return discipline
  - Useful for error recovery and signal handling

- **`int setjmp(jmp_buf j)`**
  - Must be called before longjmp
  - Identifies a return site for a subsequent longjmp
  - Called **once**, returns **one or more** times

- **Implementation:**
  - Remember where you are by storing the current *register context*, *stack pointer*, and *PC value* in `jmp_buf`
  - Return 0

`setjmp/longjmp` (cont)

- **`void longjmp(jmp_buf j, int i)`**
    - Meaning:
        - return from the **`setjmp`** remembered by jump buffer **`j`** again …
        - … this time returning **`i`** instead of 0
    - Called after **`setjmp`**
    - Called **once**, but **never** returns

- **`longjmp` Implementation:**
    - Restore register context (stack pointer, base pointer, PC value) from jump buffer **`j`**
    - Set %**`eax`** (the return value) to **`i`**
    - Jump to the location indicated by the PC stored in jump buf **`j`**

`setjmp/longjmp` Example

■ **Goal: return directly to original caller from a deeply-nested function**

```
/* Deeply nested function foo */
void foo(void)
{
    if (error1)
        longjmp(buf, 1);
    bar();
}


void bar(void)
{
    if (error2)
        longjmp(buf, 2);
}
```

setjmp/longjmp Example (cont)

```
jmp_buf buf;

int error1 = 0;
int error2 = 1;

void foo(void), bar(void);

int main()
{
    switch(setjmp(buf)) {
    case 0:
        foo();
        break;
    case 1:
        printf("Detected an error1 condition in foo\n");
        break;
    case 2:
        printf("Detected an error2 condition in foo\n");
        break;
    default:
        printf("Unknown error condition in foo\n");
    }
    exit(0);
}
```
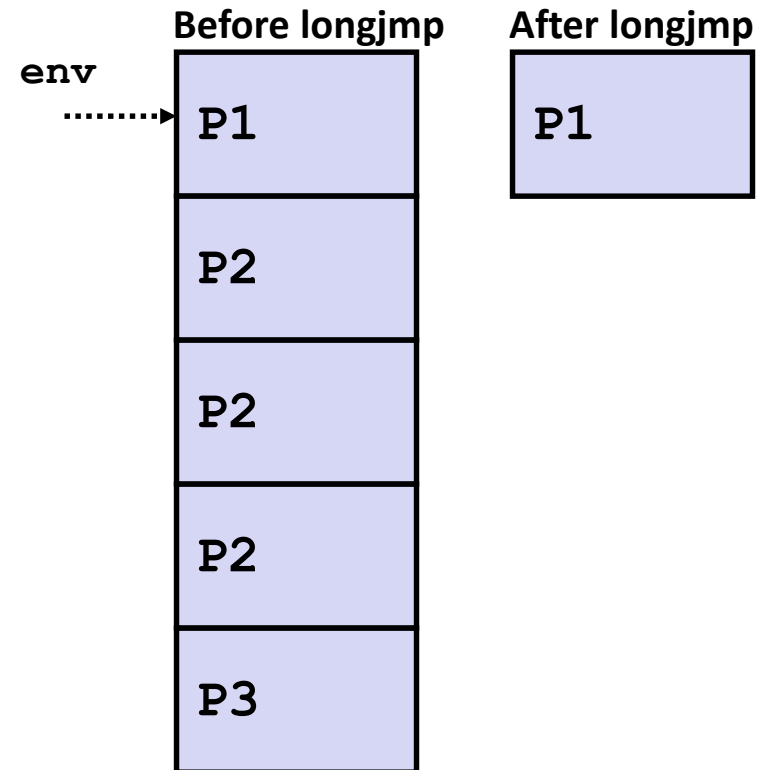
Limitations of Nonlocal Jumps

■ **Works within stack discipline**

■ Can only long jump to environment of function that has been called but not yet completed

```
jmp_buf env;

P1()
{
  if (setjmp(env)) {
    /* Long Jump to here */
  } else {
    P2();
  }
}


P2()
{  . . . P2(); . . . P3(); }

P3()
{
  longjmp(env, 1);
}
```

Before longjmp   **After longjmp**

env ·······▶

P1
P2
P2
P2
P3

P1

Limitations of Long Jumps (cont.)

- **Works within stack discipline**
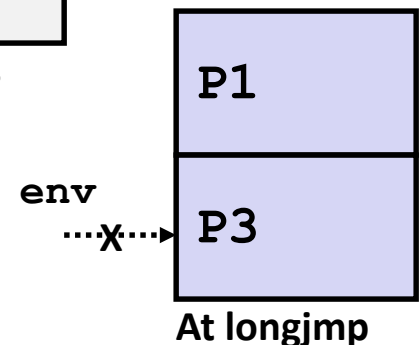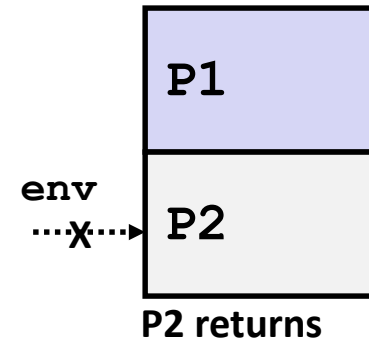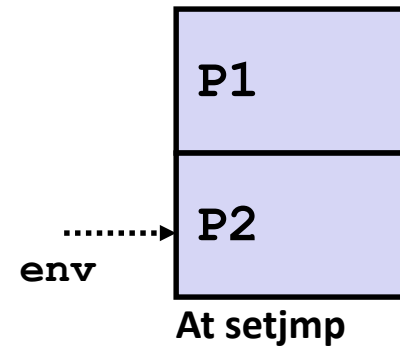 - Can only long jump to environment of function that has been called but not yet completed

```
jmp_buf env;

P1()
{
  P2(); P3();
}

P2()
{
   if (setjmp(env)) {
    /* Long Jump to here */
   }
}

P3()
{
  longjmp(env, 1);
}
```


At setjmp

P2 returns

At longjmp

Putting It All Together: A Program That Restarts Itself When `ctrl-c'd`

```c
#include "csapp.h"

sigjmp_buf buf;

void handler(int sig)
{
    siglongjmp(buf, 1);
}

int main()
{
    if (!sigsetjmp(buf, 1)) {
        Signal(SIGINT, handler);
        Sio_puts("starting\n");
    }
    else
        Sio_puts("restarting\n");

    while(1) {
        Sleep(1);
        Sio_puts("processing...\n");
    }
    exit(0); /* Control never reaches here */
}
```

restart.c

```
greatwhite> ./restart
starting
processing...
processing...
processing...
restarting
processing...          ⟵————— Ctrl-c
processing...
restarting
processing.            ⟵————— Ctrl-c
processing...
processing...
```

Summary

- **Signals provide process-level exception handling**
  - Can generate from user programs
  - Can define effect by declaring signal handler
  - Be very careful when writing signal handlers

- **Nonlocal jumps provide exceptional control flow within process**
  - Within constraints of stack discipline