# **Dynamic Memory Allocation: Explicit Allocators**

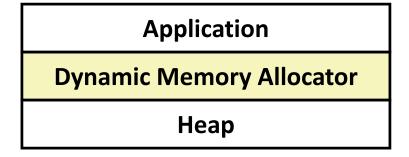
**Introduction to Computer Systems** 

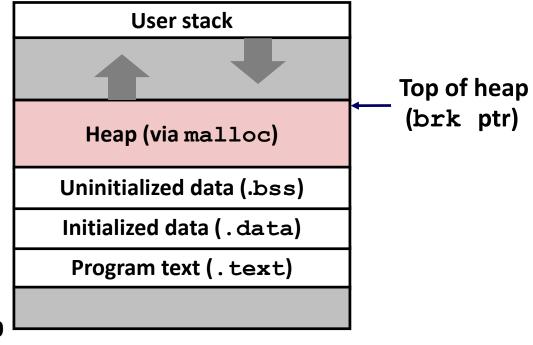
# **Today**

- Basic concepts
- Implicit free lists
- **Explicit free lists**
- Segregated free lists

### **Dynamic Memory Allocation**

- Programmers use dynamic memory allocators (such as malloc) to acquire VM at run time.
  - For data structures whose size is only known at runtime.
- Dynamic memory allocators manage an area of process virtual memory known as the heap.





### **Dynamic Memory Allocation**

- Allocator maintains heap as collection of variable sized blocks, which are either allocated or free
- Types of allocators
  - Explicit allocator: application allocates and frees space
    - E.g., malloc and free in C
  - Implicit allocator: application allocates, but does not free space
    - E.g. garbage collection in Java, ML, and Lisp
- Will discuss simple explicit memory allocation today

### The malloc Package

```
#include <stdlib.h>
void *malloc(size_t size)
```

- Successful:
  - Returns a pointer to a memory block of at least size bytes aligned to an 8-byte (x86) or 16-byte (x86-64) boundary
  - If size == 0, returns NULL
- Unsuccessful: returns NULL (0) and sets errno

### void free(void \*p)

- Returns the block pointed at by p to pool of available memory
- p must come from a previous call to malloc or realloc

#### Other functions

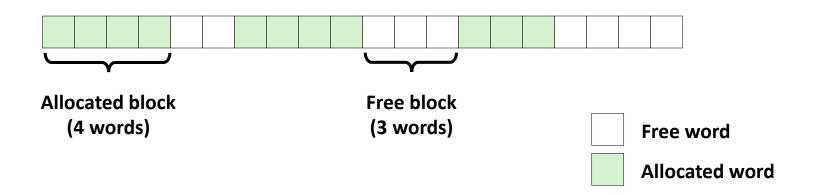
- calloc: Version of malloc that initializes allocated block to zero.
- realloc: Changes the size of a previously allocated block.
- **sbrk:** Used internally by allocators to grow or shrink the heap

### malloc Example

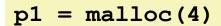
```
#include <stdio.h>
#include <stdlib.h>
void foo(int n) {
    int i, *p;
   /* Allocate a block of n ints */
    p = (int *) malloc(n * sizeof(int));
    if (p == NULL) {
        perror("malloc");
        exit(0);
    /* Initialize allocated block */
    for (i=0; i<n; i++)
        p[i] = i:
    /* Return allocated block to the heap */
    free(p);
```

### **Assumptions Made in This Lecture**

- Memory is word addressed.
- Words are int-sized.



# **Allocation Example**

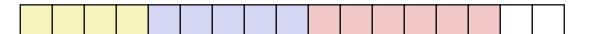




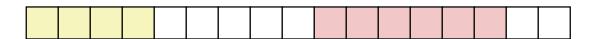
$$p2 = malloc(5)$$



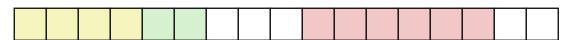
$$p3 = malloc(6)$$



free (p2)



$$p4 = malloc(2)$$



### **Constraints**

### Applications

- Can issue arbitrary sequence of malloc and free requests
- free request must be to a malloc'd block

#### Allocators

- Can't control number or size of allocated blocks
- Must respond immediately to malloc requests
  - *i.e.*, can't reorder or buffer requests
- Must allocate blocks from free memory
  - *i.e.*, can only place allocated blocks in free memory
- Must align blocks so they satisfy all alignment requirements
  - 8-byte (x86) or 16-byte (x86-64) alignment on Linux boxes
- Can manipulate and modify only free memory
- Can't move the allocated blocks once they are malloc'd
  - i.e., compaction is not allowed

### **Performance Goal: Throughput**

- Given some sequence of malloc and free requests:
  - $R_0, R_1, ..., R_k, ..., R_{n-1}$
- Goals: maximize throughput and peak memory utilization
  - These goals are often conflicting
- Throughput:
  - Number of completed requests per unit time
  - Example:
    - 5,000 malloc calls and 5,000 free calls in 10 seconds
    - Throughput is 1,000 operations/second

# Performance Goal: Peak Memory Utilization

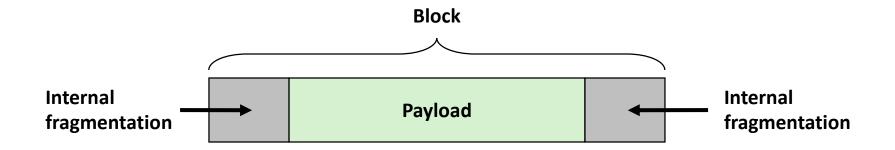
- Given some sequence of malloc and free requests:
  - $\blacksquare$   $R_0, R_1, ..., R_k, ..., R_{n-1}$
- Def: Aggregate payload P<sub>k</sub>
  - malloc(p) results in a block with a payload of p bytes
  - After request  $R_k$  has completed, the **aggregate payload**  $P_k$  is the sum of currently allocated payloads
- *Def:* Current heap size H<sub>k</sub>
  - Assume  $H_k$  is monotonically nondecreasing
    - i.e., heap only grows when allocator uses sbrk
- *Def*: Peak memory utilization after k+1 requests
  - $U_k = (\max_{i < =k} P_i) / H_k$

### **Fragmentation**

- Poor memory utilization caused by *fragmentation* 
  - *internal* fragmentation
  - external fragmentation

### **Internal Fragmentation**

■ For a given block, *internal fragmentation* occurs if payload is smaller than block size

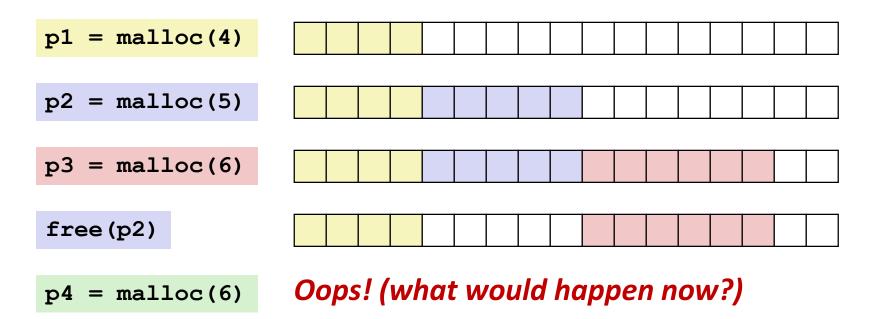


### Caused by

- Overhead of maintaining heap data structures
- Padding for alignment purposes
- Explicit policy decisions
   (e.g., to return a big block to satisfy a small request)
- Depends only on the pattern of previous requests
  - Thus, easy to measure

### **External Fragmentation**

Occurs when there is enough aggregate heap memory,
 but no single free block is large enough



- Depends on the pattern of future requests
  - Thus, difficult to measure

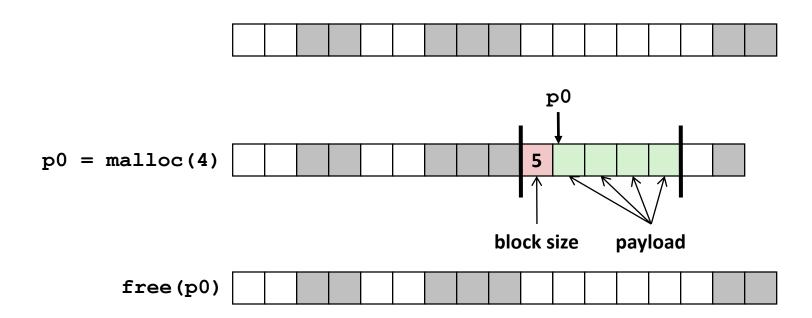
### Implementation Issues

- How do we know how much memory to free given just a pointer?
- How do we keep track of the free blocks?
- What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in?
- How do we pick a block to use for allocation -- many might fit?
- How do we reinsert freed block?

### **Knowing How Much to Free**

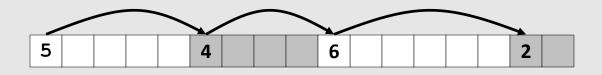
#### Standard method

- Keep the length of a block in the word preceding the block.
  - This word is often called the *header field* or *header*
- Requires an extra word for every allocated block

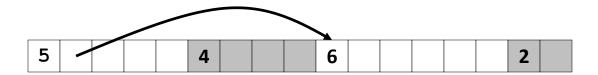


### **Keeping Track of Free Blocks**

Method 1: Implicit list using length—links all blocks



Method 2: Explicit list among the free blocks using pointers



- Method 3: Segregated free list
  - Different free lists for different size classes
- Method 4: *Blocks sorted by size* 
  - Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

# **Today**

- Basic concepts
- Implicit free lists
- **Explicit free lists**
- Segregated free lists

### **Method 1: Implicit List**

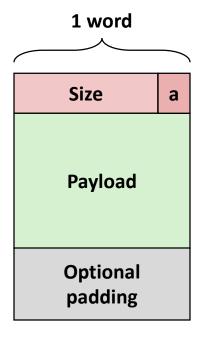
#### For each block we need both size and allocation status

Could store this information in two words: wasteful!

#### Standard trick

- If blocks are aligned, some low-order address bits are always 0
- Instead of storing an always-0 bit, use it as a allocated/free flag
- When reading size word, must mask out this bit

Format of allocated and free blocks



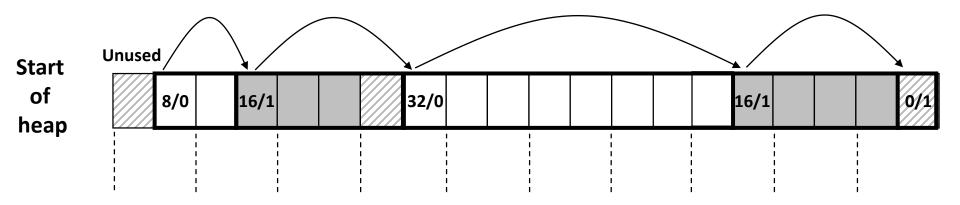
a = 1: Allocated block

a = 0: Free block

Size: block size

Payload: application data (allocated blocks only)

### **Detailed Implicit Free List Example**



Double-word aligned

Allocated blocks: shaded

Free blocks: unshaded

Headers: labeled with size in bytes/allocated bit

### Implicit List: Finding a Free Block

#### **■** First fit:

Search list from beginning, choose *first* free block that fits:

- Can take linear time in total number of blocks (allocated and free)
- In practice it can cause "splinters" at beginning of list

#### Next fit:

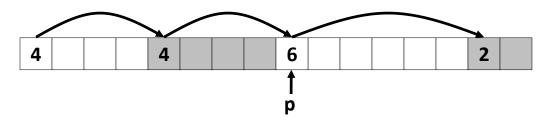
- Like first fit, but search list starting where previous search finished
- Should often be faster than first fit: avoids re-scanning unhelpful blocks
- Some research suggests that fragmentation is worse

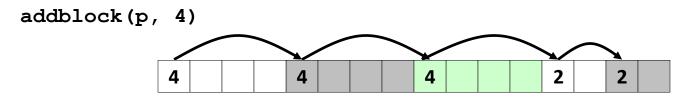
#### Best fit:

- Search the list, choose the best free block: fits, with fewest bytes left over
- Keeps fragments small—usually improves memory utilization
- Will typically run slower than first fit

### **Implicit List: Allocating in Free Block**

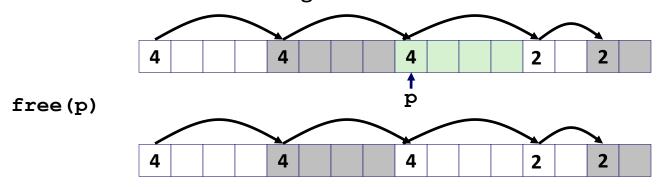
- Allocating in a free block: splitting
  - Since allocated space might be smaller than free space, we might want to split the block





### **Implicit List: Freeing a Block**

- Simplest implementation:
  - Need only clear the "allocated" flag
    void free\_block(ptr p) { \*p = \*p & -2 }
  - But can lead to "false fragmentation"

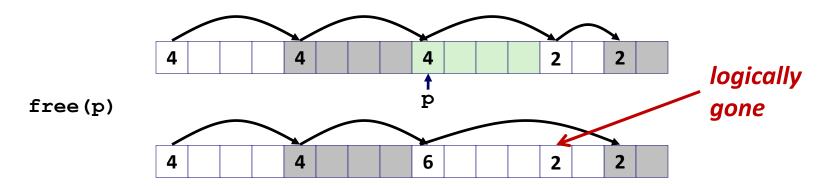


malloc(5) Oops!

There is enough free space, but the allocator won't be able to find it

### **Implicit List: Coalescing**

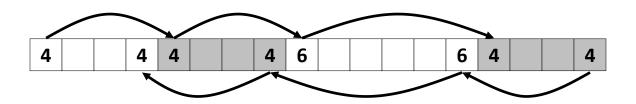
- Join (coalesce) with next/previous blocks, if they are free
  - Coalescing with next block

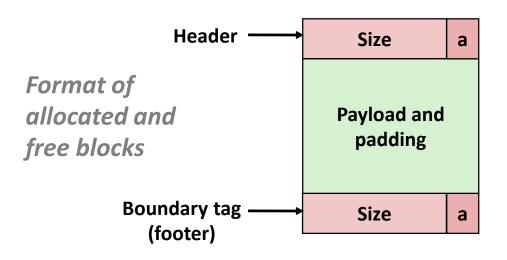


But how do we coalesce with previous block?

### **Implicit List: Bidirectional Coalescing**

- **Boundary tags** [Knuth73]
  - Replicate size/allocated word at "bottom" (end) of free blocks
  - Allows us to traverse the "list" backwards, but requires extra space
  - Important and general technique!





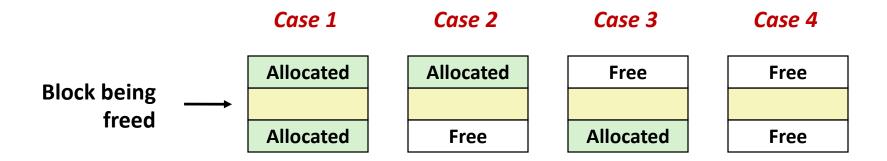
a = 1: Allocated block

a = 0: Free block

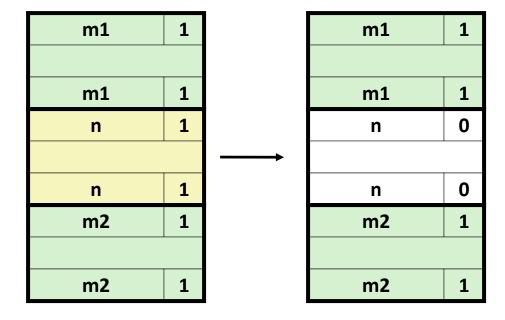
Size: Total block size

Payload: Application data (allocated blocks only)

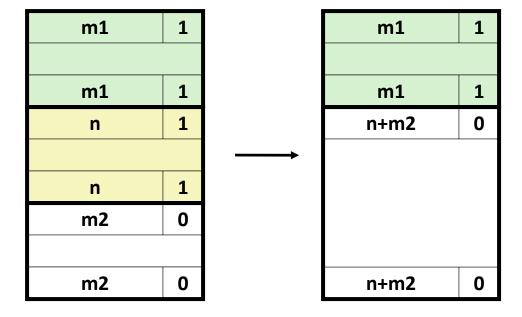
### **Constant Time Coalescing**



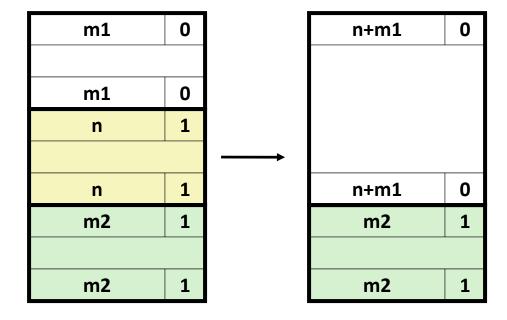
# **Constant Time Coalescing (Case 1)**



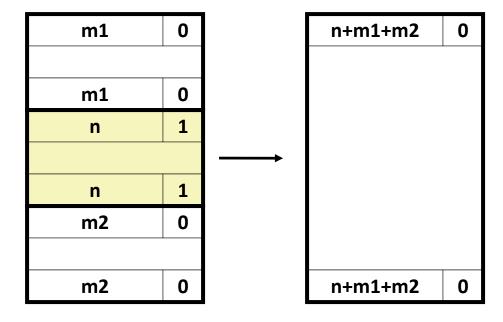
# **Constant Time Coalescing (Case 2)**



# **Constant Time Coalescing (Case 3)**



# **Constant Time Coalescing (Case 4)**



### **Disadvantages of Boundary Tags**

- Internal fragmentation
- Can it be optimized?
  - Which blocks need the footer tag?
  - What does that mean?

### **Summary of Key Allocator Policies**

### Placement policy:

- First-fit, next-fit, best-fit, etc.
- Trades off lower throughput for less fragmentation
- Interesting observation: segregated free lists approximate a best fit placement policy without having to search entire free list

### Splitting policy:

- When do we go ahead and split free blocks?
- How much internal fragmentation are we willing to tolerate?

### Coalescing policy:

- Immediate coalescing: coalesce each time free is called
- Deferred coalescing: try to improve performance of free by deferring coalescing until needed. Examples:
  - Coalesce as you scan the free list for malloc
  - Coalesce when the amount of external fragmentation reaches some threshold

### **Implicit Lists: Summary**

- Implementation: very simple
- Allocate cost:
  - linear time worst case
- Free cost:
  - constant time worst case
  - even with coalescing
- Memory usage:
  - will depend on placement policy
  - First-fit, next-fit or best-fit
- Not used in practice for malloc/free because of lineartime allocation
  - used in many special purpose applications
- However, the concepts of splitting and boundary tag coalescing are general to all allocators

### **Today**

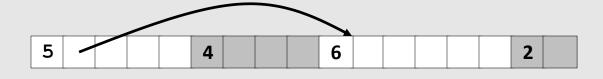
- Basic concepts
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- Explicit free lists
- Segregated free lists

### **Keeping Track of Free Blocks**

■ Method 1: *Implicit free list* using length—links all blocks



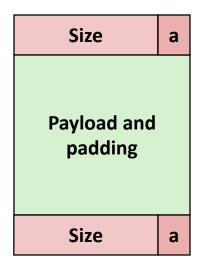
■ Method 2: *Explicit free list* among the free blocks using pointers



- Method 3: Segregated free list
  - Different free lists for different size classes
- Method 4: Blocks sorted by size
  - Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

### **Explicit Free Lists**

#### Allocated (as before)



#### Free



### ■ Maintain list(s) of *free* blocks, not *all* blocks

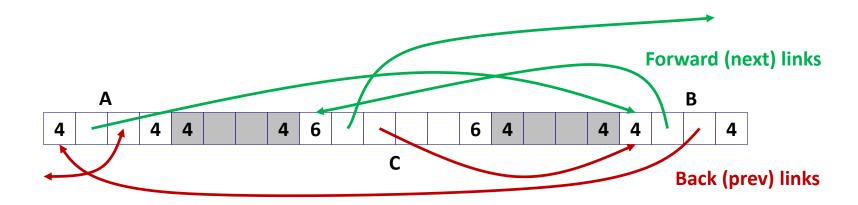
- The "next" free block could be anywhere
  - So we need to store forward/back pointers, not just sizes
- Still need boundary tags for coalescing
- Luckily we track only free blocks, so we can use payload area

## **Explicit Free Lists**

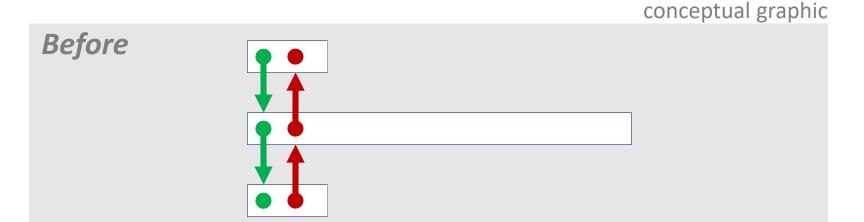
Logically:

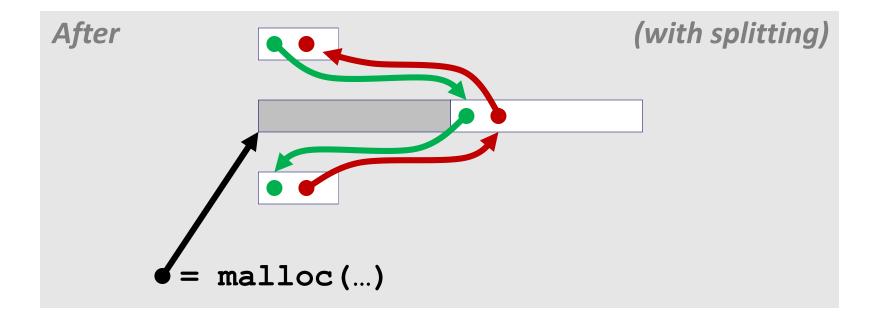


Physically: blocks can be in any order



#### **Allocating From Explicit Free Lists**





#### **Freeing With Explicit Free Lists**

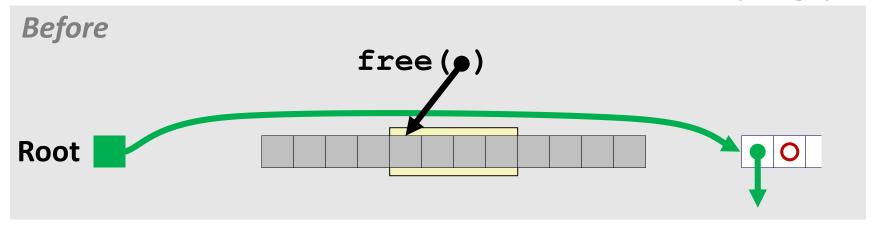
- Insertion policy: Where in the free list do you put a newly freed block?
- LIFO (last-in-first-out) policy
  - Insert freed block at the beginning of the free list
  - Pro: simple and constant time
  - Con: studies suggest fragmentation is worse than address ordered

#### Address-ordered policy

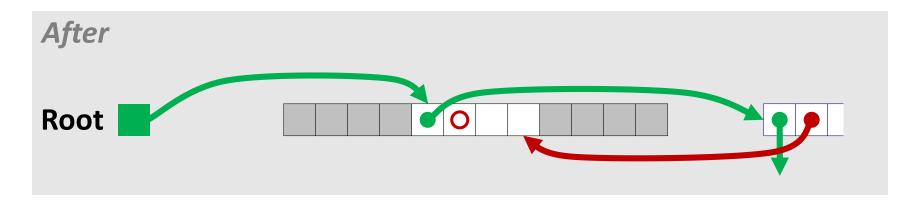
- Insert freed blocks so that free list blocks are always in address order:
  addr(prev) < addr(curr) < addr(next)</p>
- Con: requires search
- Pro: studies suggest fragmentation is lower than LIFO

## Freeing With a LIFO Policy (Case 1)

conceptual graphic

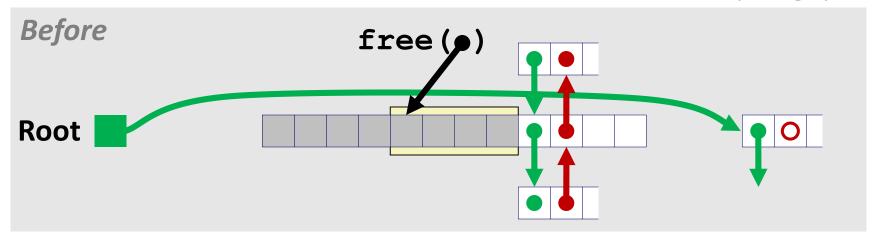


Insert the freed block at the root of the list

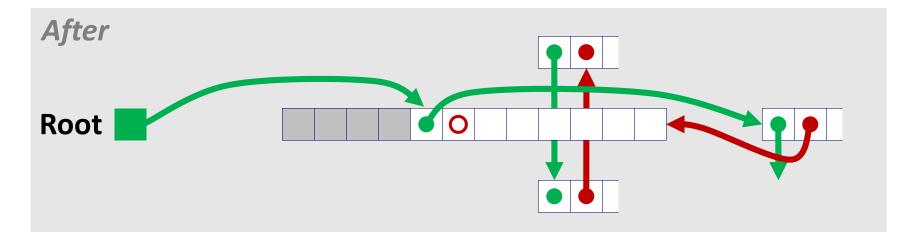


## Freeing With a LIFO Policy (Case 2)

conceptual graphic

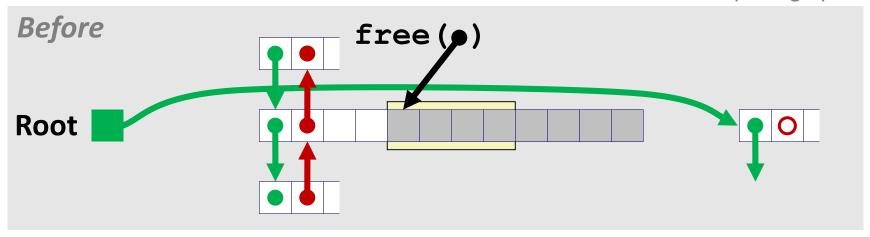


 Splice out successor block, coalesce both memory blocks and insert the new block at the root of the list

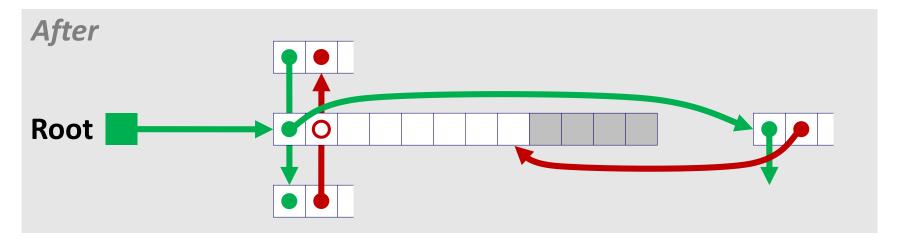


## Freeing With a LIFO Policy (Case 3)

conceptual graphic

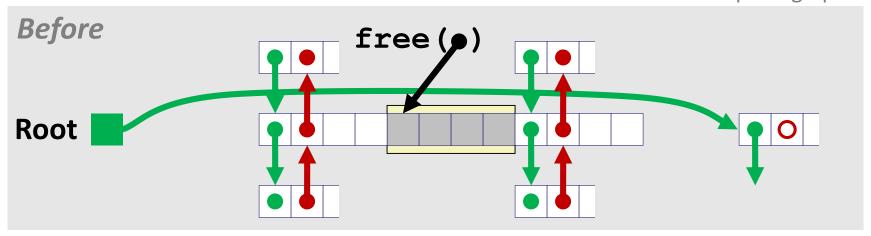


 Splice out predecessor block, coalesce both memory blocks, and insert the new block at the root of the list

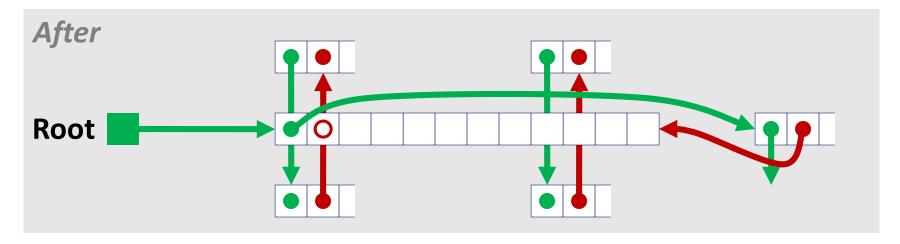


# Freeing With a LIFO Policy (Case 4)

conceptual graphic



 Splice out predecessor and successor blocks, coalesce all 3 memory blocks and insert the new block at the root of the list



## **Explicit List Summary**

#### Comparison to implicit list:

- Allocate is linear time in number of free blocks instead of all blocks
  - Much faster when most of the memory is full
- Slightly more complicated allocate and free since needs to splice blocks in and out of the list
- Some extra space for the links (2 extra words needed for each block)
  - Does this increase internal fragmentation?

#### Most common use of linked lists is in conjunction with segregated free lists

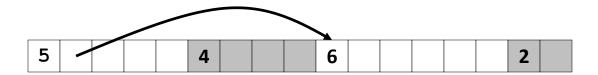
 Keep multiple linked lists of different size classes, or possibly for different types of objects

#### **Keeping Track of Free Blocks**

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Method 2: Explicit list among the free blocks using pointers



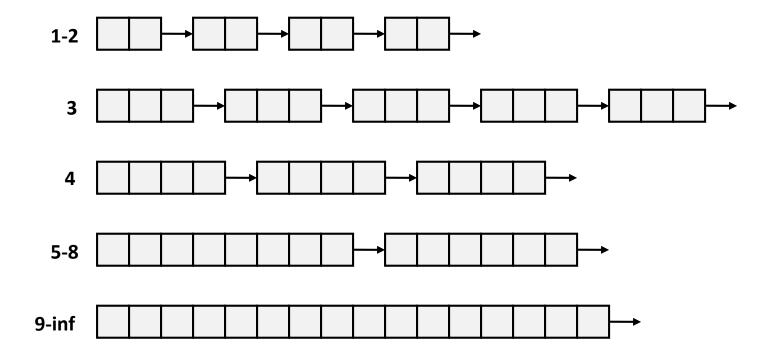
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- **Explicit free lists**
- Segregated free lists

#### **Segregated List (Seglist) Allocators**

Each size class of blocks has its own free list



- Often have separate classes for each small size
- For larger sizes: One class for each two-power size

## **Seglist Allocator**

Given an array of free lists, each one for some size class

#### To allocate a block of size n:

- Search appropriate free list for block of size m > n
- If an appropriate block is found:
  - Split block and place fragment on appropriate list (optional)
- If no block is found, try next larger class
- Repeat until block is found

#### If no block is found:

- Request additional heap memory from OS (using sbrk ())
- Allocate block of n bytes from this new memory
- Place remainder as a single free block in largest size class.

## **Seglist Allocator (cont.)**

#### To free a block:

Coalesce and place on appropriate list

#### Advantages of seglist allocators

- Higher throughput
  - log time for power-of-two size classes
- Better memory utilization
  - First-fit search of segregated free list approximates a best-fit search of entire heap.
  - Extreme case: Giving each block its own size class is equivalent to best-fit.

#### **More Info on Allocators**

- D. Knuth, "The Art of Computer Programming", 2<sup>nd</sup> edition,
   Addison Wesley, 1973
  - The classic reference on dynamic storage allocation
- Wilson et al, "Dynamic Storage Allocation: A Survey and Critical Review", Proc. 1995 Int'l Workshop on Memory Management, Kinross, Scotland, Sept, 1995.
  - Comprehensive survey
  - Available from CS:APP student site (csapp.cs.cmu.edu)