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Yocto with LSDK Components User Guide

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Introduction

Yocto with LSDK components provides recipes for the last Yocto release to use the latest and greatest components from LSDK as they get released. This eventually makes its way into the next community Yocto release at yoctoproject.org.

Supported Boards

The following table Yocto with LSDK components release supports the following QorIQ targets.

Target Type	Board	LE		BE	
		32b	64b	32b	64b
QorIQ LS Series Communications Processors	ls1012ardb	✔	✔	X	X
	ls1012afrdm	✔	✔	X	X
	ls1012afrwy	✔	✔	X	X
	ls1021atwr	✔	X	X	X
	ls1043ardb	✔	✔	X	✔
	ls1046ardb	✔	✔	X	✔
	ls1088ardb	X	✔	X	✔
	ls1088ardb-pb	X	✔	X	X
	ls2088ardb	X	✔	X	✔
QorIQ T Series Communications Processors	t1024rdb	X	X	✔	✔
	t1042d4rdb	X	X	✔	✔
	t2080rdb	X	X	✔	✔
	t4240rdb	X	X	✔	✔
QorIQ P Series Communications Processors	p1020rdb	X	X	✔	X
	p2020rdb	X	X	✔	X
	p2041rdb	X	X	✔	X
	p3041ds	X	X	✔	X
	p4080ds	X	X	✔	X
	p5040ds	X	X	✔	✔
QorIQ MPC Series Communications Processors	mpc8548cds	X	X	✔	X

Download Yocto Layer

To make sure the build host is prepared for Yocto running and build, please follow below guide to prepare the build environment.

https://www.yoctoproject.org/docs/2.6/brief-yoctoprojectqs/brief-yoctoprojectqs.html

- ## Get the Yocto layers from repo manifest

  The following is the step of how to use repo utility to download all Yocto layers according to the repo manifest.

  - ### Install the repo utility:

    ```
    $: mkdir ~/bin

    $: curl https://storage.googleapis.com/git-repo-downloads/repo >
    ~/bin/repo

    $: chmod a+x ~/bin/repo
    ```

  - ### Download the Yocto layers

    ```
    $: export PATH=${PATH}:~/bin

    $: mkdir yocto-sdk

    $: cd yocto-sdk

    $: repo init -u
    https://source.codeaurora.org/external/qoriq/qoriq-
    components/yocto-sdk -b thud

    $: repo sync --no-clone-bundle
    ```

- ## Get Yocto layers from community repository

  The following is the step of how to download all Yocto layers through git commands.

  ```
  $: mkdir yocto-sdk

  $: cd yocto-sdk

  $: mkdir sources

  $: cd sources

  $: git clone git://git.yoctoproject.org/poky

  $: cd  poky

  $: git reset --hard eddff2b361928e88e3628ebc22a1a0ebb119e01b

  $: cd ..

  $: git clone git://git.openembedded.org/meta-openembedded
  ```

```
$: cd meta-openembedded
$: git reset --hard f1511d254632a34c1deb51f4bf8b8c21e7423f51
$: cd ..
$: git clone git://git.yoctoproject.org/meta-freescale
$: cd  meta-freescale
$: git reset --hard 9c801795c886578bc4cd72d040143b18532b145d
$: cd ..
$: git clone git://git.yoctoproject.org/meta-virtualization
$: cd meta-virtualization
$: git reset --hard f226bea1083b2bf7373ac7e4780459d454830cc4
$: cd ..
$: git clone git://git.yoctoproject.org/meta-cloud-services
$: cd meta-cloud-services
$: git reset --hard 5dec08769e026980e3b5d3217dbbe2ebd87bf33c
$: cd ..
$: git clone git://git.yoctoproject.org/meta-security
$: cd meta-security
$: git reset --hard dcb0395033e1b4a5d44d467d041114c5cb5e13eb
$: cd ..
$: git clone https://github.com/Freescale/meta-freescale-distro
$: cd meta-freescale-distro
$: git reset --hard 771fb6d4c0c9530083fcc8c5452270bb9b3915ba
$: cd ..
$: git clone https://source.codeaurora.org/external/qoriq/qoriq-components/meta-qoriq-demos
$: cd meta-qoriq-demos
$: git reset –hard db3fe697fd9b381cc930aaeacc791c97494e20b1
$: cd ..
$: cp sources/meta-qoriq-demos/scripts/setup-env ./
```

Build Image

The build steps are common for all platforms, the document takes ls1046ardb for an example.

```
$ cd yocto-sdk

$: . ./setup-env -m ls1046ardb

$: bitbake fsl-image-networking

$: bitbake fsl-image-networking-full
```

Note:

1. The images will be available in yocto-sdk/build_ls1046ardb/tmp/deploy/images/ls1088ardb/ folder.
2. The following kernel config options are used for enabling the upstream version of DPAA driver for PowerPC targets:

   CONFIG_FSL_DPAA, CONFIG_FSL_FMAN and CONFIG_FSL_DPAA_ETH need to be enabled in kernel menuconfig as below:

```
Device Drivers  --->

   SOC (System On Chip) specific Drivers  --->

       [*] Freescale DPAA 1.x support  --->

   Device Drivers  --->

      [*] Network device support  --->

      [*]   Ethernet driver support  --->

            <*>     FMan support

            <*>     DPAA Ethernet  ----
```

Boot boards with Yocto image

Prerequisites

- The tftp server is setup for image download
- A serial cable is connected from your PC to UART1
- The ethernet cable is connected to the first ethernet port on the board.

Boot with ramdisk rootfs image

- Power up or reset the board and press a key on the terminal when prompted to get to the U-Boot command line
- Set up the environment in U-Boot

```
=> setenv ipaddr <board_ipaddr>

=> setenv serverip <tftp_serverip>
```

Board	Bootargs
ls1021atwr	=> setenv bootargs root=/dev/ram0 rw console=ttyS0,115200 ramdisk_size=0x1000000
ls1012a	=> setenv bootargs root=/dev/ram0 rw console=ttyS0,115200 earlycon=uart8250,mmio,0x21c0500 ramdisk_size=0x10000000
ls1043a	=> setenv bootargs root=/dev/ram0 rw console=ttyS0,115200 earlycon=uart8250,mmio,0x21c0500 ramdisk_size=0x10000000
ls1046a	=> setenv bootargs root=/dev/ram0 rw console=ttyS0,115200 earlycon=uart8250,mmio,0x21c0500 ramdisk_size=0x10000000
ls1088ardb	=> setenv bootargs root=/dev/ram0 rw console=ttyS0,115200 earlycon=uart8250,mmio,0x21c0500 ramdisk_size=0x2000000 default_hugepagesz=2m hugepagesz=2m hugepages=512
ls2088ardb	=> setenv bootargs root=/dev/ram0 rw console=ttyS1,115200 earlycon=uart8250,mmio,0x21c0600 ramdisk_size=0x2000000 default_hugepagesz=1024m hugepagesz=1024m hugepages=8
mpc8548cds	=> setenv bootargs root=/dev/ram rw console=ttyS1,115200 ramdisk_size=1000000 log_buf_len=128K
t1024rdb	=> setenv bootargs root=/dev/ram rw console=ttyS1,115200 ramdisk_size=1000000 log_buf_len=128K

Other PPC targets	=> setenv bootargs root=/dev/ram rw console=ttyS0,115200 ramdisk_size=1000000 log_buf_len=128K

- The ls1088ardb and ls2088ardb need the below commands to enable DPAA2 ethernet in Linux

Board	Commands
ls1088ardb	=> sf probe 0:0 => sf read 0x80000000 0xA00000 0x100000 => sf read 0x80100000 0xE00000 0x100000 => fsl_mc start mc 0x80000000 0x80100000 => sf read 0x80200000 0xd00000 0x100000 => fsl_mc apply dpl 0x80200000
ls2088ardb	=> fsl_mc start mc 0x580a00000 0x580e00000 => fsl_mc apply dpl 0x580d00000

- Download Images and bootup

Board	Commands
ls1021atwr	=> tftp 82000000 uImage-ls1021atwr.bin => tftp 88000000 fsl-image-networking-ls1021atwr.ext2.gz.u-boot => tftp 8f000000 uImage-ls1021a-twr.dtb => bootm 82000000 88000000 8f000000
mpc8548cds	=> tftpboot 0x01000000 uImage-mpc8548cds.bin => tftpboot 0x03000000 fsl-image-networking-mpc8548cds.ext2.gz.u-boot => tftpboot 0x02000000 uImage-

	mpc8548cds_32b.dtb => bootm 0x01000000 0x03000000 0x02000000
p1020rdb p2020rdb p2041rdb p3041ds p4080ds p5040ds	=> tftpboot 0x01000000 uImage-<board>.bin => tftpboot 0x02000000 fsl-image-networking-<board>.ext2.gz.u-boot => tftpboot 0x00c00000 uImage-<board>.dtb => bootm 0x01000000 0x04000000 0x02000000
t1024rdb t1042d4rdb t2080rdb t4240rdb	=> tftpboot 0x01000000 uImage-<board>.bin => tftpboot 0x05000000 fsl-image-networking-<board>.ext2.gz.u-boot => tftpboot 0x02000000 uImage-<board>.dtb => bootm 0x01000000 0x05000000 0x02000000
ls1012afrdm-32b ls1012afrdm ls1012afrwy-32b ls1012afrwy ls1012ardb-32b ls1012ardb ls1021atwr ls1043ardb-32b ls1043ardb-be ls1043ardb ls1046ardb-32b ls1046ardb-be ls1046ardb ls1088ardb-be ls1088ardb ls1088ardb-pb ls2080ardb ls2088ardb-be ls2088ardb	=> tftp a0000000 fitImage-fsl-image-networking-<board>.bin => bootm a0000000

- ## Booting with full rootfs from large storage device

  - Prepare the media (SATA/SD/USB) and format it to ext2 format, mount the ext2 partition and extract a full rootfs into this partition, unmount this partition.
  - Power up or reset the board and press a key on the terminal when prompted and get to the U-Boot command line.
  - Set up the environment in u-boot:

    ```
    => setenv ipaddr <board_ipaddr>

    => setenv serverip <tftp_serverip>
    ```

Board	Commands
ls1021atwr	=> setenv bootargs root=/dev/sda* rootdelay=5 rw console=ttyS0,115200 earlycon=uart8250,mmio,0x21c0500

ls1012a series ls1043a series ls1046a series	=> setenv bootargs root=/dev/sda* rootdelay=5 rw console=ttyS0,115200 earlycon=uart8250,mmio,0x21c0500
ls1088ardb	=> setenv bootargs root=/dev/sda* rootdelay=5 rw console=ttyS0,115200 earlycon=uart8250,mmio,0x21c0500 default_hugepagesz=2m hugepagesz=2m hugepages=512
ls2088ardb	=> setenv bootargs root=/dev/sda* rootdelay=5 rw console=ttyS1,115200 earlycon=uart8250,mmio,0x21c0600 default_hugepagesz=1024m hugepagesz=1024m hugepages=8
mpc8548cds	=> setenv bootargs root=/dev/sda* rootdelay=5 rw console=ttyS1,115200 log_buf_len=128K
P and T series	=> setenv bootargs root=/dev/sda* rootdelay=5 rw console=ttyS0,115200 log_buf_len=128K

- For ls1088ardb and ls2088ardb, please run below commands to enable DPAA2 ethernet in Linux:

Board	Commands
ls1088ardb	=> sf probe 0:0 => sf read 0x80000000 0xA00000 0x100000 => sf read 0x80100000 0xE00000 0x100000 => fsl_mc start mc 0x80000000 0x80100000 => sf read 0x80200000 0xd00000 0x100000 => fsl_mc apply dpl 0x80200000
ls2088ardb	=> fsl_mc start mc 0x580a00000 0x580e00000 => fsl_mc apply dpl 0x580d00000

- Download Image and bootup

Board	Commands
ls1021atwr	=> tftp 82000000 uImage-ls1021atwr.bin => tftp 8f000000 uImage-ls1021a-twr.dtb => bootm 82000000 - 8f000000
mpc8548cds	=> tftpboot 0x01000000 uImage-mpc8548cds.bin => tftpboot 0x02000000 uImage-mpc8548cds_32b.dtb => bootm 0x01000000 - 0x02000000
p2020rdb	=> tftpboot 0x01000000 uImage-p2020rdb.bin => tftpboot 0x00c00000 uImage-p2020rdb-pc_32b.dtb => bootm 0x01000000 - 0x00c00000

p1020rdb p2041rdb p3041ds p4080ds p5040ds t1024rdb t1042d4rdb t2080rdb t4240rdb	=> tftpboot 0x01000000 uImage-<board>.bin => tftpboot 0x02000000 uImage-<board>.dtb => bootm 0x01000000 - 0x02000000
ls1012afrdm-32b ls1012afrdm ls1012afrwy-32b ls1012afrwy ls1012ardb-32b ls1012ardb ls1021atwr ls1043ardb-32b ls1043ardb-be ls1043ardb ls1046ardb-32b ls1046ardb-be ls1046ardb ls1088ardb-be ls1088ardb ls1088ardb-pb ls2080ardb ls2088ardb-be ls2088ardb	=> tftp a0000000 fitImage-<board>.bin => bootm a0000000:kernel@1 - a0000000:<fdt name> NOTE: <fdt name> can be got by the following command: $: grep fdt@ fitImage-its-<board>.its

• Secure boot

To enable the secure boot on QorIQ platforms, please refer to the "6.1 Secure boot" section of the following LSDK documentation.

https://www.nxp.com/support/developer-resources/run-time-software/linux-software-and-development-tools/layerscape-software-development-kit:LAYERSCAPE-SDK?tab=Documentation_Tab

Prebuilt Toolchain

The prebuilt toolchain for support targets are available in NXP official image mirror.

ARM32: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-cortexa7hf-neon-toolchain-2.6.sh

ARM64: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-aarch64-toolchain-2.6.sh

ARM64-BE: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-aarch64_be-toolchain-2.6.sh

PPCE500V2: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-ppce500v2-toolchain-2.6.sh

PPCE500MC: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-ppce500mc-toolchain-2.6.sh

PPCE5500: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-ppce5500-toolchain-2.6.sh

PPCE5500-64B: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-ppc64e5500-toolchain-2.6.sh

PPCE6500: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-ppce6500-toolchain-2.6.sh

PPCE6500-64B: https://www.nxp.com/lgfiles/sdk/lsdk1809-yocto26/fsl-qoriq-glibc-x86_64-fsl-toolchain-ppc64e6500-toolchain-2.6.sh

Known Issue

ID	Description	Disposition	Opened In	Workarounds
QLINUX-10188	PM sleep test failed on T1042D4RDB	Open	LSDK-1809	

QLINUX-9692	T2 optical_xfi port not Works	Open	LSDK-1809	update t2080rdb.dts
				ethernet@f0000 {
				- phy-handle = <&xg_cs4315_phy1>;
				+ phy-handle = <&xg_cs4315_phy2>;
				phy-connection-type = "xgmii";
				};
				ethernet@f2000 {
				- phy-handle = <&xg_cs4315_phy2>;
				+ phy-handle = <&xg_cs4315_phy1>;
				phy-connection-type = "xgmii";
				};

Reference

- NXP LSDK official website: https://www.nxp.com/products/processors-and-microcontrollers/arm-based-processors-and-mcus/qoriq-layerscape-arm-processors/layerscape-software-development-kit-v18.09:LAYERSCAPE-SDK
- NXP LSDK github portal: https://lsdk.github.io/
- Yocto Open Source User Guide: https://www.yoctoproject.org/docs/