SOM-where in Chicago

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October 25, 2023

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Self-organizing maps, or Kohonen maps

Self-organizing maps are neural networks architectures used for dimensionality reduction.

Proposed by Tuevo Kohonen in 1980, hence also called Kohonen maps.

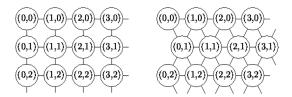
The mathematical description

The algorithm

```
initialize lattice nodes;
initialize weight vectors;
N ← iteration count;
for i in N:
    x ← pick random point in dataset;
    c ← select lattice closest to x;
    move weight vector of c closer to x;
    move weight vectors of the neighbors of c slightly closer to x
```

Lattice Architecture

Typically we initialize a lattice over the data as either square lattices or hexagonal lattices:



For rectangular lattice Kohonen suggests the (x, y) should be the ratio of the two largest eigenvalues of the autocorrelation matrix.

Weight initialization

The most common ways of initialization is:

- Random initialization Slow to converge but because SOMs are fast this may not be an issue
- **2** Random sampling initialization Take samples from the dataset.

Training the model: Step 1

Each lattice point has two vectors: w_i representing its weight and l_j representing its position within the lattice.

We start by picking a random point $x \in \mathbb{R}^d$ of our data. We calculate the Euclidean distance of each lattice point from that data and select the lattice point with the smallest such distance:

$$c_i = \arg\min_i \|x - w_i\| \tag{1}$$

Where c_i is the index of the best matching unit.

Training the model: Step 2

We update the weights for all the lattice points for the k + 1-th iteration:

$$w_{i}^{(k+1)} = w_{i}^{(k)} + \alpha_{k} \cdot \eta_{c_{i},i} \cdot \left\| x - w_{i}^{(k)} \right\|$$
 (2)

Note that α_k is the learning rate s.t.:

$$\alpha_{k+1} \le \alpha_k \tag{3}$$

$$\sum_{k=0}^{\infty} \alpha_k = \infty \tag{4}$$

$$\sum_{k=0}^{\infty} \alpha_k^2 \le \infty \tag{5}$$

Training the model: Step 2

Note that $\eta_{c_i,i}$ is a neighborhood function, designed to:

- **①** Achieve a maximum when $||I_i I_j|| = 0$
- 2 $\eta_{c_i,i} \to 0$ as $||I_i I_j|| \to \infty$

The most common is Gaussian neighborhood:

$$\eta_{c_i,i} = \exp\left[-\frac{\|I_i - I_{c_i}\|}{2\sigma_k^2}\right] \tag{6}$$

Error metrics

Most common is quantization error: Let $c = \arg\min_i \|x - w_i\|$. The quantization error is then:

$$E_Q = \sum_i \|x_i - w_c\| \tag{7}$$

The topographic error preserves the underlying topology of the data defined as:

$$E_T = \frac{1}{|D|} \sum_{x \in D} te(x) \tag{8}$$

where:

$$te(x) = \begin{cases} 1 & c_1 \text{ and } c_2 \text{ are neighbors} \\ 0 & \text{else} \end{cases}$$
 (9)

The dataset

We look at ride-share pickups (Uber and Lyft) for the city of Chicago in the year 20202.

We collate the data by census tracts, and merge the data with demographics (median income) and built-environment characteristics (percentage of zero car ownerships, distance to nearest transit) from the EPA smart locations dataset.

The variables

Our variables are as follows:

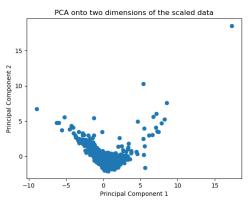
Table 1 Data description

Category	Variables	Unit	
Trip Characteristics	Number of Pickups	Number	
	Trip Duration	Seconds	
	Trip Length	Miles	
Socio- demographic Characteristics	Median Income	\$	
Built Environment	Population Density	People/Acre	
	Employment Density	Jobs/Acre	
	Land-use Mix	-	
	Percentage of zero-car ownership	Percentage	
	Distance to nearest transit-stop	Meters	

Preliminary analysis

Previous work by the author suggests that much can be gained by doing a segmentation analysis of the dataset.

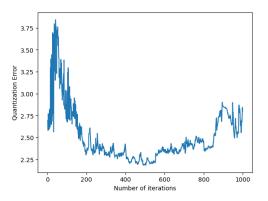
A principal component analysis of the scaled data shows that there exists an eigenvalue in one direction wit both components accounting for $\approx 50\%$ of the variance



The SOM

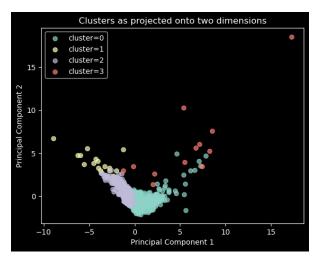
Taking a cue from previoous work we do create a 2×2 lattice.

Quantization errors across iteration counts shows 600 iterations to be optimal



The Clustering

We get a clustering as such:



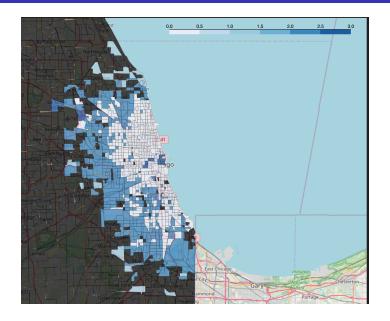
The Clusters I

Cluster	MedIncome	PopDensity	EmpDensity	LUDiversity	% 0 Car	
0	\$85.9k	38.18	10.2	0.82	24%	
1	\$149k	10.27	10.46	3.17	10%	
2	\$73k	18.32	3.41	1.01	14%	
3	\$164k	31.01	258.6	45.5	19%	

The Clusters II

Cluster	Median Income	Trip Seconds	Trip Miles
0	\$85.9k	1000.3	5.8
1	\$149	1961	7.5
2	\$73	1249	8.5
3	\$164	951	6.14

The map



The Clusters III

The full table:

	Pickups	MedianIncome	TotalPopulation	Population_Density	Employment_Density	Percent_Zero_Car_Ownership	LandUse_Diversity	Distance_from_transit	Trip_Miles	Trip_Seconds
cluster										
0	31765.885615	85900.493934	3385.093588	38.185717	10.308518	0.244521	0.824956	233.538478	5.797611	1000.290215
1	297.263158	149221.315789	4601.578947	10.272762	10.465472		3.175389	457.476149	17.542535	1961.039958
2	2929.275261	73009.703833	4206.780488	18.320666	3.423521	0.141682	1.018148	362.257844	8.466476	1249.391233
3	406730.166667	164795.250000	4237.083333		258.614703	0.192708	45.003452	208.357014	6.146520	951.360888

The takeaways

Key takeaways:

- People from richer neighborhoods take shorter Uber trips
- 2 Employment density is a better predictor than population density for the number of pickups
- Percentage of zero car ownership correlates with more pickups.

Future work

Possible future work:

- Could we do a detailed SHAP analysis of the factors predicting pickups, i.e. is it the case that median income of tracts can be a good predictor?
- 2 Could we do a time series analysis and see a seasonality decrease around March 2020.

Bibliography

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