

# Progress Report

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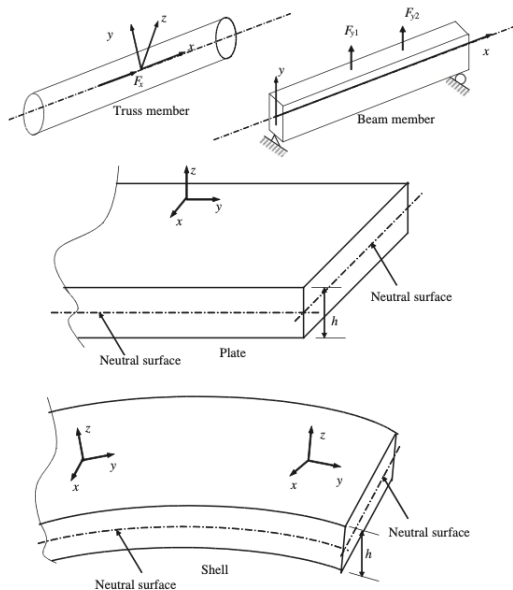
# What to Solve

We seek to solve dynamic equilibrium equations. The formulation from Liu and Quek assumes among other things:

- ① *Linear Elastic* Deformation grows proportionally with external force.
- ② *Isotropic* Material property is direction independent.

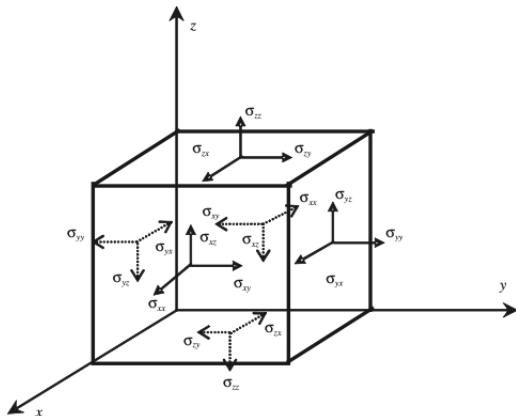
We distinguish between four kinds of objects: beams, trusses, plates and shells.

# What to Solve



# What to Solve

Taking a queue from Liu and Quek, we start off by defining DEE for an idealized infinitesimal, linearly elastic, isotropic material.



Observe that because of equilibrium  $\sigma_{xy} = \sigma_{yx}$ ;  $\sigma_{xz} = \sigma_{zx}$ ;  $\sigma_{yz} = \sigma_{zy}$   
 Which give us the stress tensors:  $\sigma^T = \{\sigma_{xx}, \sigma_{yy}, \sigma_{zz}, \sigma_{yz}, \sigma_{xz}, \sigma_{xy}\}$

# What to Solve

We also get six strain components  $\epsilon^T = \{\epsilon_{xx}, \epsilon_{yy}, \epsilon_{zz}, \gamma_{yz}, \gamma_{xz}, \gamma_{xy}\}$  Where:

$$\epsilon_{xx} = \frac{\partial u}{\partial x}; \quad \epsilon_{yy} = \frac{\partial v}{\partial y}; \quad \epsilon_{zz} = \frac{\partial w}{\partial z};$$

$$\gamma_{xy} = 2\epsilon_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x};$$

$$\gamma_{xz} = 2\epsilon_{xz} = \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x};$$

$$\gamma_{yz} = 2\epsilon_{yz} = \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y};$$

# What to Solve

Provided  $\mathbf{U} = \begin{pmatrix} u \\ v \\ w \end{pmatrix}$  the displacement matrix we get the system  $\epsilon = \mathbf{L}\mathbf{U}$

Where the differential operator is:  $\mathbf{L} = \begin{pmatrix} \frac{\partial}{\partial x} & 0 & 0 \\ 0 & \frac{\partial}{\partial y} & 0 \\ 0 & 0 & \frac{\partial}{\partial z} \\ 0 & \frac{\partial}{\partial z} & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} & 0 & \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} & \frac{\partial}{\partial x} & 0 \end{pmatrix}$