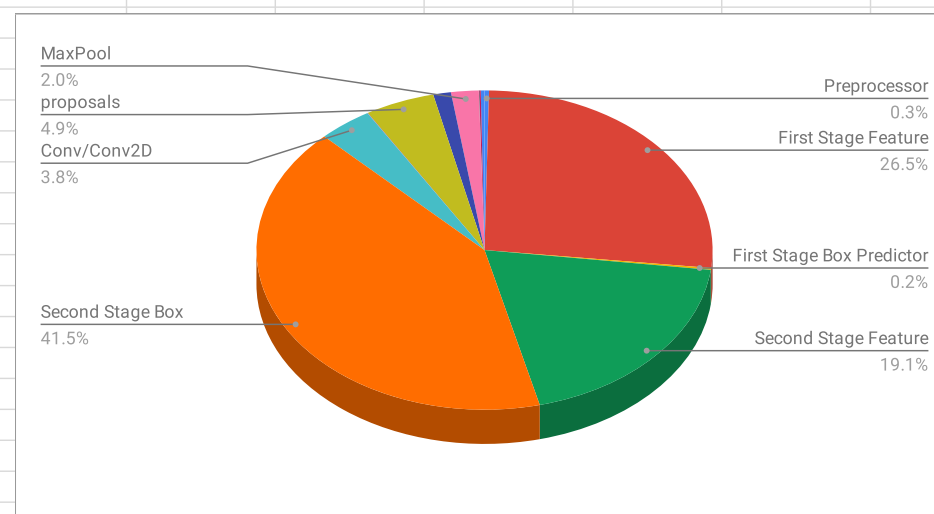
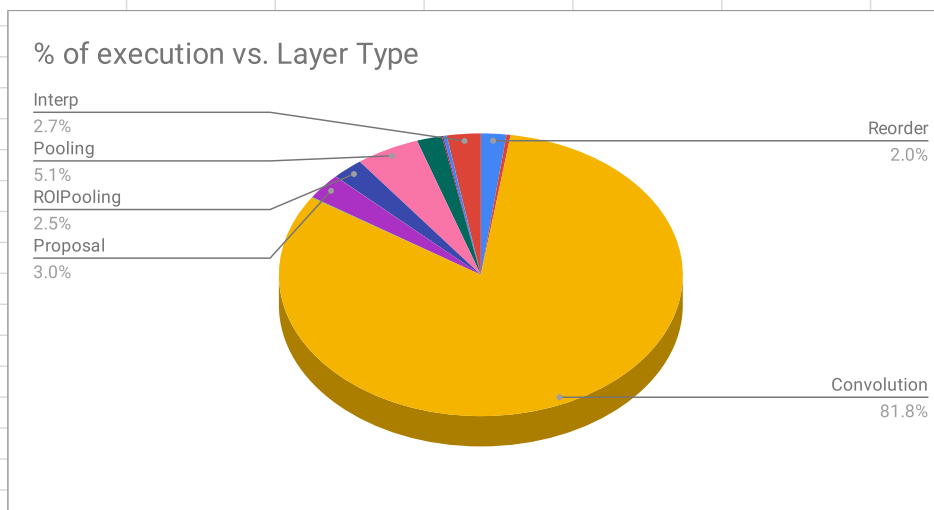


Mask-RCNN-OpenVino-InceptionV2_FP32_CPU_i9

FP32 CPU – Execution division by layer function		
Layer Name	Execution time(micro seconds)	% of execution
Preprocessor	604	0.32%
First Stage Feature Extractor	50573	26.47%
First Stage Box Predictor	367	0.19%
Second Stage Feature Extractor	36530	19.12%
Second Stage Box Predictor	79262	41.49%
Conv/Conv2D	7290	3.82%
predictions/Reshape/Softmax	53	0.03%
proposals	9438	4.94%
CropAndResize	2400	1.26%
MaxPool	3748	1.96%
reshape	48	0.03%
ScaleShift/scale_locs	205	0.11%
detection_output	509	0.27%
Total	191027	100.00%

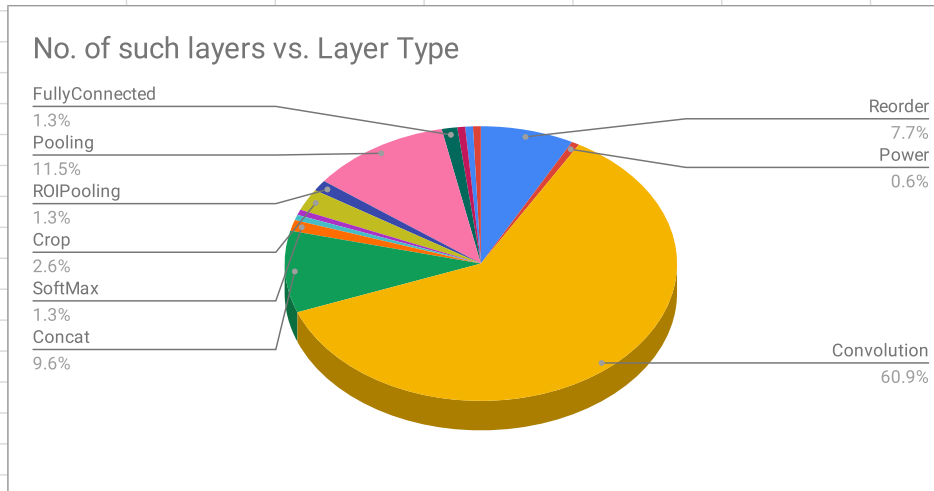


FP32 CPU – Execution division by layer type		
Layer Type	Execution time(micro seconds)	% of execution
Reorder	3685	2.03%
Power	604	0.33%
Convolution	148687	81.82%
Concat	88	0.05%
SoftMax	39	0.02%
Permute	34	0.02%
Proposal	5373	2.96%
Crop	24	0.01%
ROI Pooling	4581	2.52%
Pooling	9303	5.12%
Fully Connected	3670	2.02%
Scale Shift	205	0.11%
Detection Output	509	0.28%
Interp	4922	2.71%
Total	181724	100.00%



Total execution time in both the above tables should come out to be same, there is a small difference between two values because we've neglected some layers with negligible execution time.

Layer Type	No. of such layers	Average execution time per layer
Reorder	12	307.0833333
Power	1	604
Convolution	95	1565.126316
Concat	15	5.866666667
SoftMax	2	19.5
Permute	1	34
Proposal	1	5373
Crop	4	6
ROI Pooling	2	2290.5
Pooling	18	516.8333333
Fully Connected	2	1835
Scale Shift	1	205
Detection Output	1	509
Interp	1	4922
Total	156	1164.897436



Observations

Around 82% of time is spend on convolution

Execution time of single convolution is also comparatively higher, and larger no. of them makes it a bottleneck.

If we look at the layers functionality-wise, most time is spent on first stage feature extraction, second stage feature extraction and box prediction.

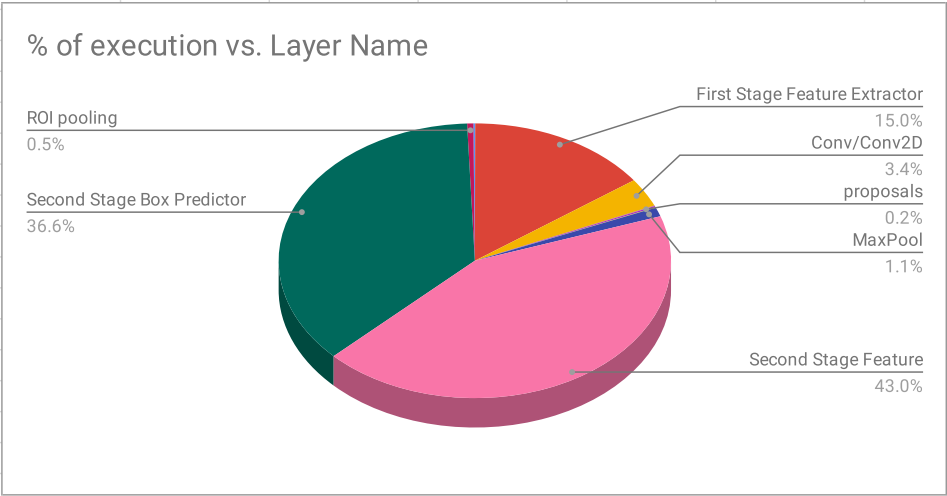
Proposal

We can try to optimize the convolution layer functionality, that will decrease total inference time significantly, because it is the most used layer.

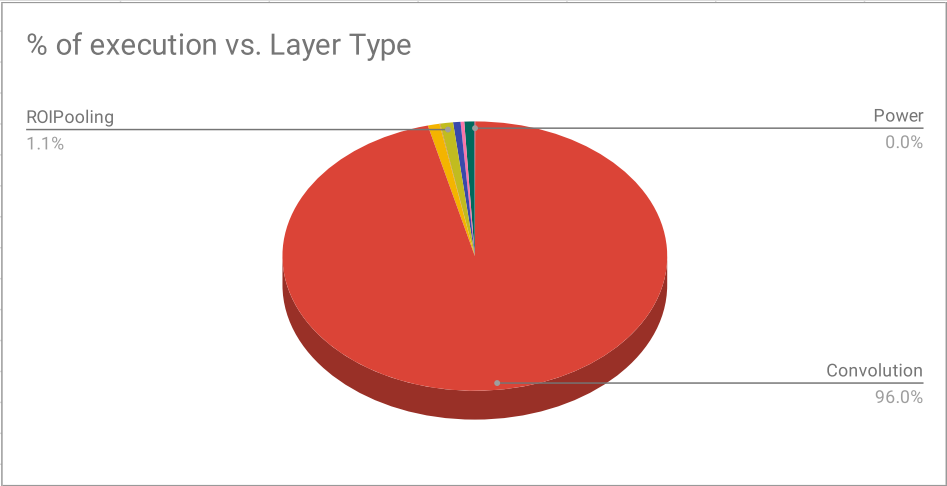
Additionally, if we can study and optimize first and second stage feature extraction and box prediction, it will further improve the inference time.

Mask-RCNN-OpenVino-InceptionV2_FP16_NCS_1

FP16 NCS1 – Execution division by layer function		
Layer Name	Execution time(micro seconds)	% of execution
Preprocessor	2451	0.03%
First Stage Feature Extractor	1073609	15.01%
Conv/Conv2D	239974	3.35%
Conv/Relu	1267	0.02%
First Stage Box Predctor	3733	0.05%
predictions/Reshape	401	0.01%
proposals	11904	0.17%
crop	3272	0.05%
MaxPool	76208	1.07%
Second Stage Feature Extractor	3079136	43.03%
Second Stage Box Predictor	2617991	36.59%
ROI pooling	36487	0.51%
masks	8560	0.12%
Total	7154993	100.00%

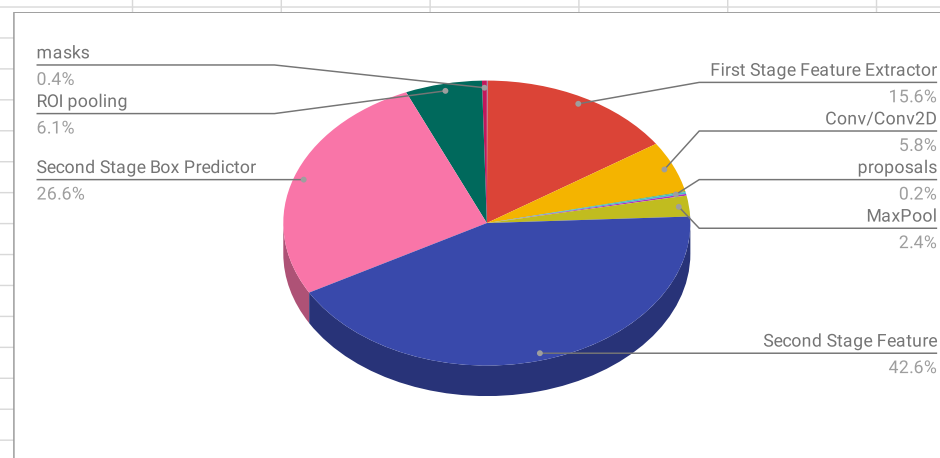


FP16 NCS1 – Execution division by layer type		
Layer Type	Execution time(micro seconds)	% of execution
Power	2451	0.03%
Convolution	6750290	94.43%
ReLU	69441	0.97%
Clamp	1267	0.02%
Proposal	2766	0.04%
Permute	91	0.00%
Reshape	256	0.00%
ROI Pooling	75533	1.06%
Pooling	43792	0.61%
Concat	21809	0.31%
Fully Connected	58348	0.82%
Crop	3272	0.05%
Total	7148641	100.00%

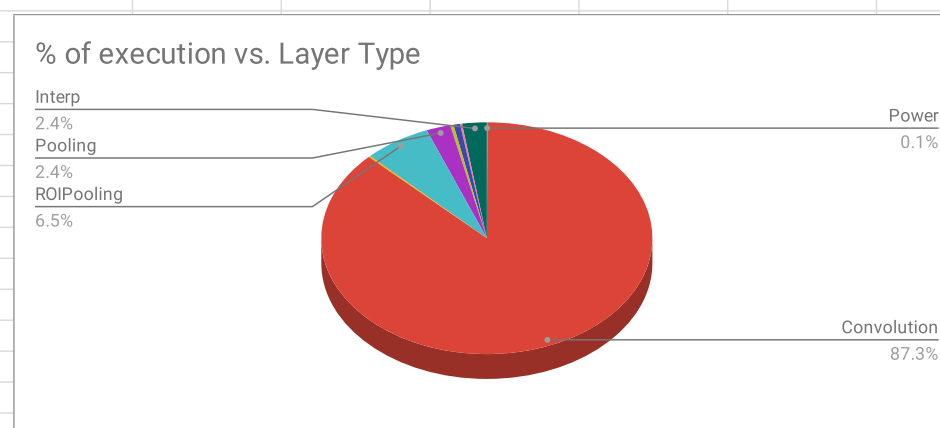


Mask-RCNN-OpenVino-InceptionV2_FP16_NCS_2

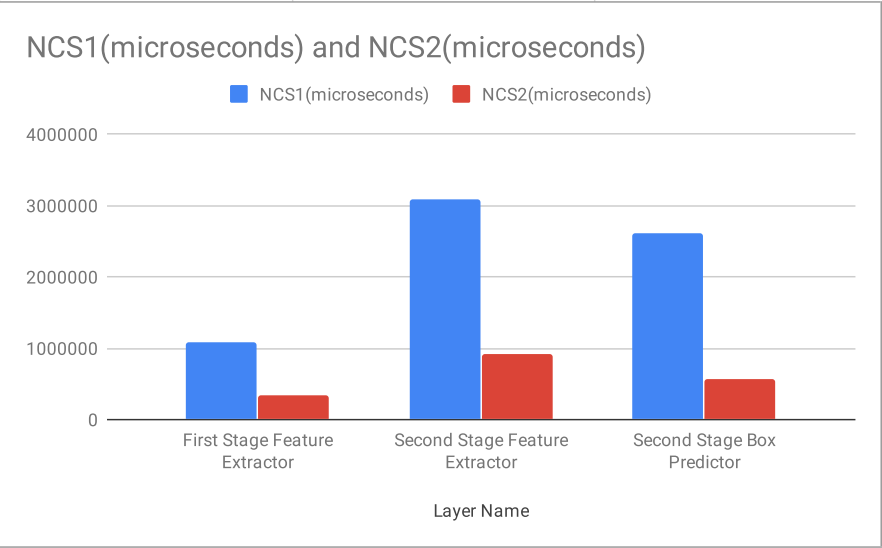
FP16 NCS2 – Execution division by layer function		
Layer Name	Execution time(micro seconds)	% of execution
Preprocessor	1279	0.06%
First Stage Feature Extractor	333049	15.56%
Conv/Conv2D	124213	5.80%
First Stage Box Predictor	1470	0.07%
predictions/Reshape	286	0.01%
proposals	4625	0.22%
crop	3994	0.19%
MaxPool	50490	2.36%
Second Stage Feature Extractor	912231	42.62%
Second Stage Box Predictor	569822	26.62%
ROI pooling	130707	6.11%
masks	8189	0.38%
Total	2140355	100.00%



FP16 NCS2 – Execution division by layer type		
Layer Type	Execution time(micro seconds)	% of execution
Power	1279	0.06%
Convolution	1747345	87.30%
Proposal	3354	0.17%
Permute	74	0.00%
Reshape	260	0.01%
ROI Pooling	130707	6.53%
Pooling	47323	2.36%
Concat	6416	0.32%
Fully Connected	12722	0.64%
Crop	3994	0.20%
Interp	48045	2.40%
Total	2001519	100.00%



Comparison between most time consuming layers on NCS1 and NCS2		
Layer Name	NCS1(microseconds)	NCS2(microseconds)
First Stage Feature Extractor	1073609	333049
Second Stage Feature Extractor	3079136	912231
Second Stage Box Predictor	2617991	569822



Observations

Here we can see that NCS2 is considerably faster than NCS1. But convolution is taking maximum time on all 3 devices.