

Basic Python Programming

[Session 1] Lab session

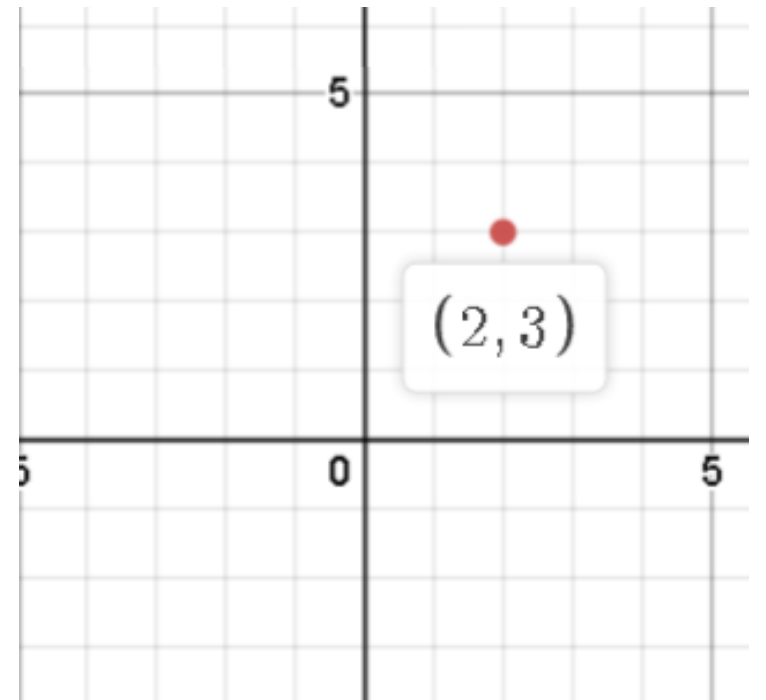
Contents

- **Class: Dot**
- **Class: Car**

Class: Dot

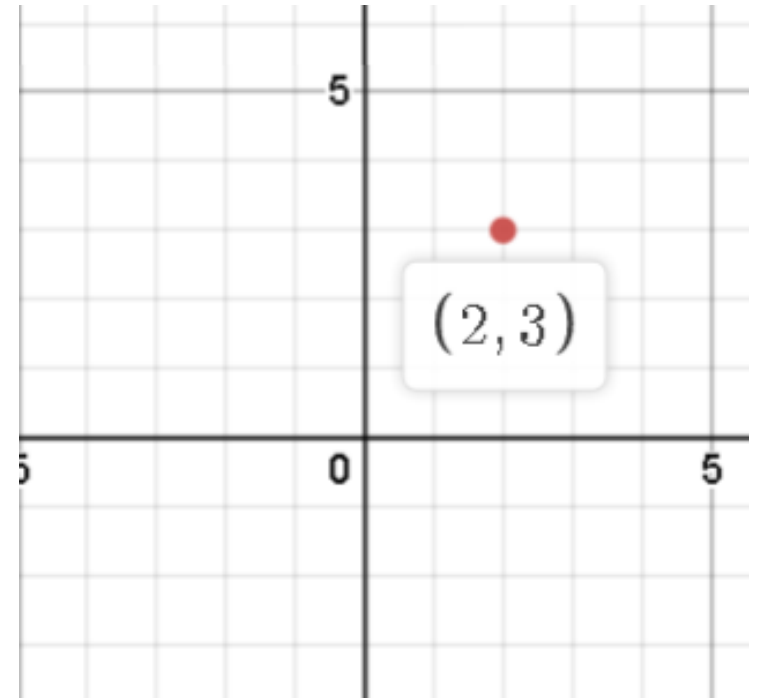
Dot [1]

- We will implement “Dot”
- dot?



Dot [2]


- Basically, Dot contains two data
 - x and y
- Okay, that's all for member variables
 - And then?
 - Define methods!



Review: Methods [1]

- Note that, every method should be like...

```
class A:  
    def some_method(self, param1, param2):  
        pass
```



Review: Methods [2]

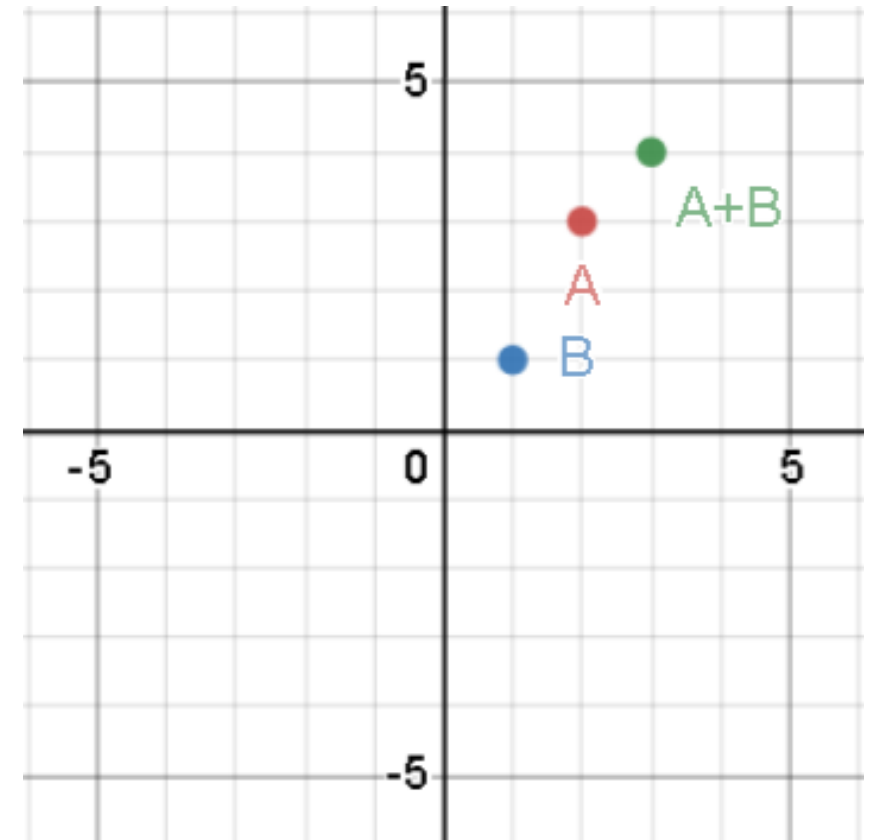
- You can access the member variable inside method, by using self!

```
1 class Student:
2     def __init__(self, my_name):
3         self.name = my_name
4
5     def get_name(self):
6         return self.name
7
8 john = Student("John")
9 print(john.get_name())
```

C:\Users\user\Documents\GitHub\EunSeong-Park.github.io\cont
John

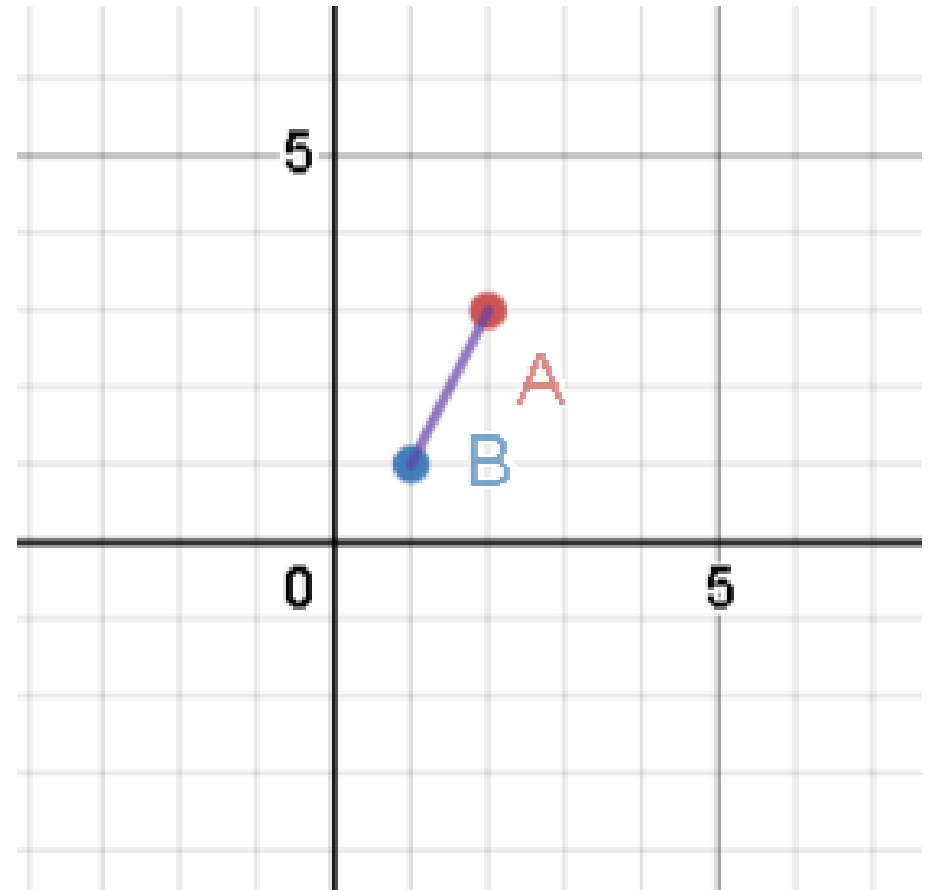
Dot: Methods [1]

- **dot_add, dot_sub** method adds / subtracts each coordinate
 - Example: $(2, 3) + (1, 1) = (3, 4)$



Dot: Methods [2]

- `dot_dist` returns the distance between two points
 - in this case, $\sqrt{5}$.



Dot: Methods [3]

- Other methods are defined in the skeleton code.
 - You have to modify this

```
1  # skeleton
2  import math
3
4  class Dot:
5      def __init__(self, x_input, y_input):
6          pass
7      def dot_get_x(self):
8          # return x (number)
9          pass
10     def dot_get_y(self):
11         # return y (number)
12         pass
13     def dot_add(self, other):
14         # return (x, y) = (x1 + x2, y1 + y2) (Dot)
15         pass
16     def dot_sub(self, other):
17         # return (x, y) = (x1 - x2, y1 - y2) (Dot)
18         pass
19     def dot_dist_origin(self):
20         # return the distance from the origin (0,0) (number)
21         pass
```

Let's start!

- Use the skeleton, dot.py

Class: Car

Car

- **A car can do**
 - drive (as long as the fuel remains)
 - show the its status:
 - fuel (L)
 - total distance (km)
 - etc.
- **Cars have their own features:**
 - car name
 - mileage (km/L)
 - max fuel (L)

Car: Member Variables

```
class Car:
    def __init__(self, name, mileage, max_fuel):
        self.name = name
        self.mileage = mileage
        self.max_fuel = max_fuel
        self.fuel = self.max_fuel
        self.dist = 0
```

Car: Methods [1]

- **Brrr(self, km): drive X km**
 - The car should consume the fuel, as you drive
 - If the fuel is not enough, it cannot go
 - After that, show the current state
- **gas_station(self): Full the fuel**
 - It's free!
 - After that, show the current state

Car: Methods [2]

- **status(self): show the current status**
 - warn if the fuel is too low

```
Car name: BMW  
Mileage: 16km/L  
Fuel: 25.0L / 50L  
Distance: 400km
```

```
Car name: BMW  
Mileage: 16km/L  
Fuel: 0.0625L / 50L  
Distance: 800549km  
WARNING: remaining fuel is too low
```


Let's start!

- Use the skeleton, `car.py`

Thank you