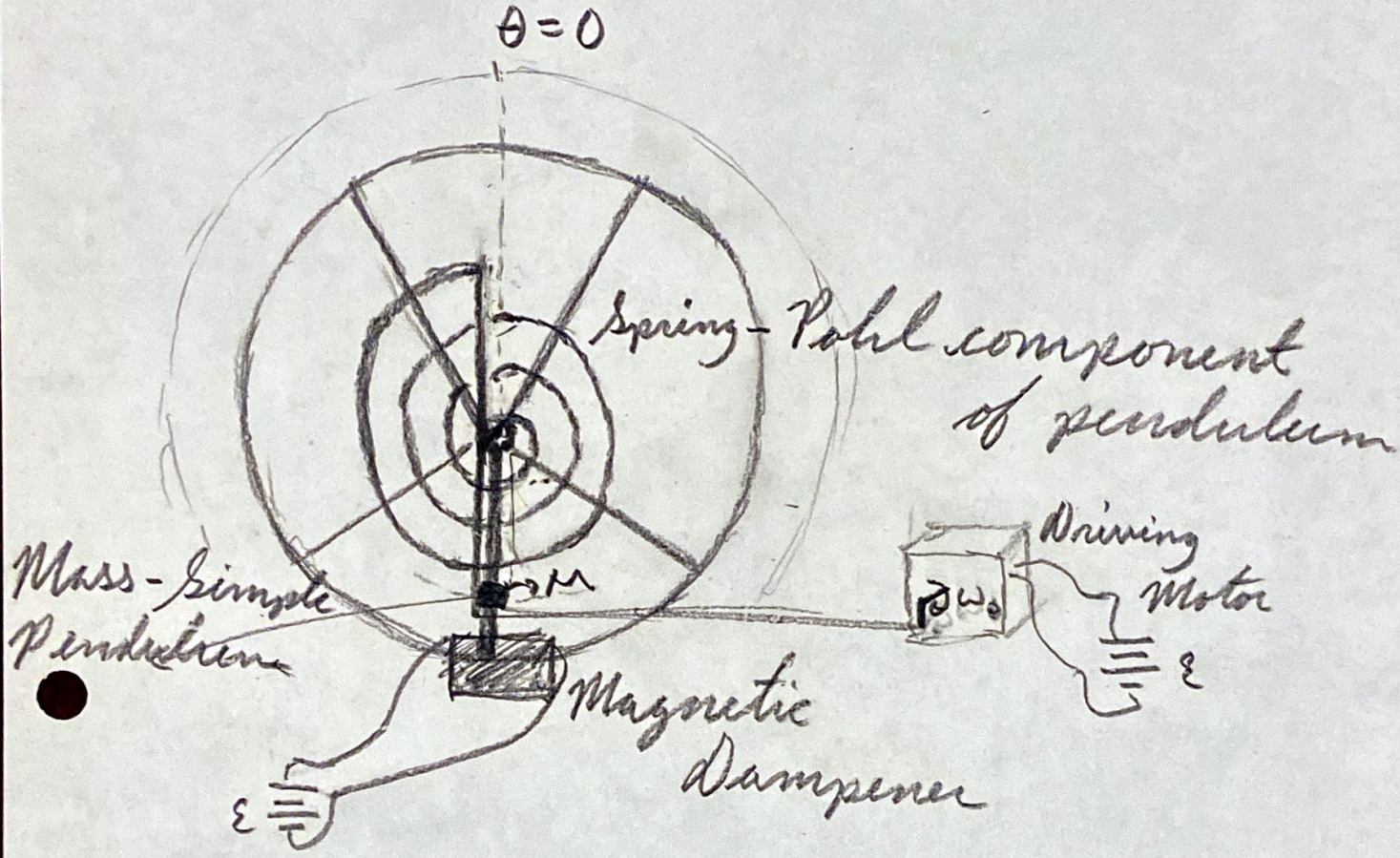
θ = 0
Spring-Pohl component of pendulum
Driving Motor
Mass-Simple Pendulum
M
ω₀
ε
Magnetic Dampener
ε