Liam Keeley ENWT Chapter 4 Summary August 16, 2022

4.1 Chapter 4 begins by introducing the notion of a continuous transformation between coordinate systems. Such transformations are built using a mapping T that transforms the original independent variable and mappings Q^{μ} which transform the original dependent variables:

$$\begin{split} t \to t' = & T(t, q^\mu, \epsilon) \\ q^\mu \to q^{\mu\prime} = & Q^\mu(t, q^\nu, \epsilon) \end{split}$$

Where epsilon is a a parameter which can be continuously varied.

In general, a functional is covariant under a transformation. That is, if Γ is the old functional, under some transformation, the new functional Γ' is:

$$\Gamma' = \int_{a}^{b} L(t', q^{\mu\prime}(t'), \frac{dq^{\mu\prime}(t')}{dt'})dt'$$

And the form of the Lagrangian remains the same. We can define an **infinitesimal** transformation of any transformation by expanding the original transformation in a Taylor Series about $\epsilon = 0$:

$$t' = t + \epsilon \left(\frac{dT}{d\epsilon}\right)_0 + \dots$$
$$q^{\mu \prime} = q^{\mu} + \epsilon \left(\frac{dQ^{\mu}}{d\epsilon}\right)_0 + \dots$$

And we can further define $\tau \equiv (\frac{dT}{d\epsilon})_0$ and $\zeta \equiv (\frac{dQ^{\mu}}{d\epsilon})_0$. These τ and ζ are know as **generators** of the transformation.

A set of continuously parameterized transformations, if the set contains and identity, and each element has an inverse, forms a **Lie group**. Finally, the definition of invariance is given as:

Invariance: The functional:

$$\Gamma = \int_{a}^{b} Ldt$$

is invariant under the infintesimal transformation:

$$t' = t + t + \dots$$

 $q^{\mu \prime} = q^{\mu} + \zeta^{\mu} + \dots$

If and only if $\Gamma' - \Gamma \sim \epsilon^s$

Or equivently, the functional is invariant if:

$$L'\frac{dt'}{dt} - L \sim \epsilon^s$$

4.2 Section 4.2 gives the Invariance Identity. That is:

Invariance Identity The functional:

$$\Gamma = \int_{a}^{b} Ldt$$

is invariant under the infintesimal transformation:

$$t' = t + t + \dots$$
$$a^{\mu \prime} = q^{\mu} + \zeta^{\mu} + \dots$$

if and only if the following identity holds:

$$\frac{\partial L}{\partial a^{\mu}} \zeta^{\mu} + p_{\mu} \dot{\zeta}^{\mu} + \frac{\partial L}{\partial t} \tau - H \dot{\tau} = 0$$

The proof of this starts by differentiating the definition of of invariance given above and proceeding from there. The following form is equivalent:

$$-(\zeta^{\mu}-q^{\dot{\mu}}\tau)\left[\frac{\partial L}{\partial q^{m}u}-\frac{d}{dt}\frac{\partial L}{\partial \dot{q}^{\dot{\mu}}}\right]=\frac{d}{dt}\left[p_{\mu}\zeta^{\mu}-H\tau\right]$$

4.3 Because the funtional:

$$\Gamma = \int_{a}^{b} Ldt$$

is unchanged by adding $\frac{dS}{dt}$ as long as S(b) = S(a) (the term will be lost integration), so in the definition of invariance, this term must be accounted for. The invariance identity can the be stated in its **divergence form** as:

$$\frac{\partial L}{\partial q^{\mu}} \zeta^{\mu} + p_{\mu} \dot{\zeta}^{\mu} + \frac{\partial L}{\partial t} \tau - H \dot{\tau} - \frac{dF}{dt} = 0$$