

YuMi: IRB 14000 Agenda

- Differentiated value proposition
- Overview and vision
- Main features
- Payload
- Working range
- Performance and accuracy
- Main dimensions
- Easy integration
- Outline manipulator

- Table mounting
- IP protection
- ESD protection
- Controller
- Customer benefits
- Key applications and segments
- Summary



Overview Differentiated value proposition



No barriers, no cages, no zones, YuMi is the first truly collaborative robot solution.



Overview and vision

- The target is to make automation technically and economically feasible for small part assembly.
- The solution shall also be suitable for pre-processing, assembly and packaging of all 3C product and other small devices, e.g. digital cameras, toys, watches, ABB low voltage products.
- The automated cells will co-exist with manual assembly cells and interaction between manual and automated cells must be smooth and safe.
- The robot automation should in principle perform the same work as a skilled assembly worker.
- The robot automation shall be easy to adapt for new conditions and tasks.



Overview and vision Demand from all industries

Target Industry (Consumer)

- Small parts assembly
- 3C
- Consumer products
- Toy Industry
- Watch industry

Market Demand

- Cycle time performance
- Safe by design
- ESD compliance
- Work close with humans
- Easy to depoly/program

Market Demand (continued)

- IP 30
- Accuracy and cost efficiency
- Size of human torso
- Portable

Most common feedback

- Fencing and safety are a big part of the cell cost
- Must be able to assemble same parts in fast and accurate manner whilst been safe
- Need to be able to deploy and program



Overview and vision Target growth markets







Small Parts Assembly

- Collaborative Assembly
- Camera-based inspection and assembly
- Accurate and fast assembly
- Testing and packaging

Consumer Products

- Collaborative Assembly (Plastic parts etc.)
- Packaging of small goods
- Multifunction hand for add components

Toy Industry

- Collaborative Assembly (toys)
- Use of feeding and vision options



Overview and vision Filling a gap



Small IRBs	IRB 14000
 Our market in the Small Parts Assembly, has reached great potentials Good market reputation Good performance in terms of accuracy and robustness One major drawback – working close to humans and collaboration Aim of IRB 14000 is to fill this gap 	 Goal is to provide a solution to small parts assembly while providing a cost competitive offering like Inherent safety Flexible feeding parts management Vision-Guided Assembly Best in class accuracy Speed effective assembly



Overview and vision Leading the competition



- More compact than the competitors
- More precise
- Equipped with an enclosed controller
- Universal parts feeding system
- High-end camera part location
- State of the art motion control
- First safe robot by design

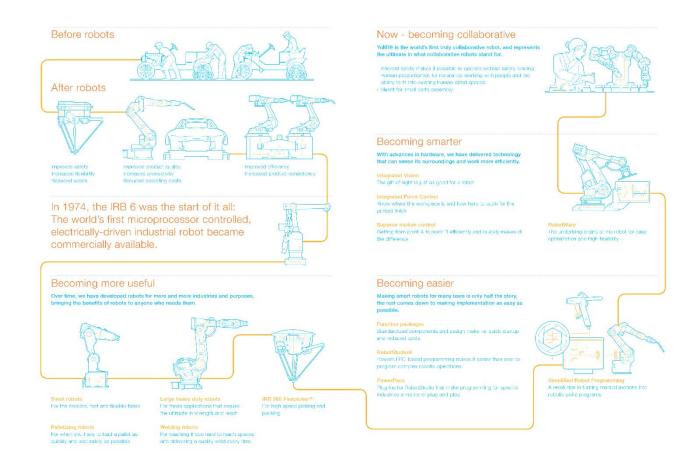


Overview Current portfolio





Overview and vision New era in our portfolio





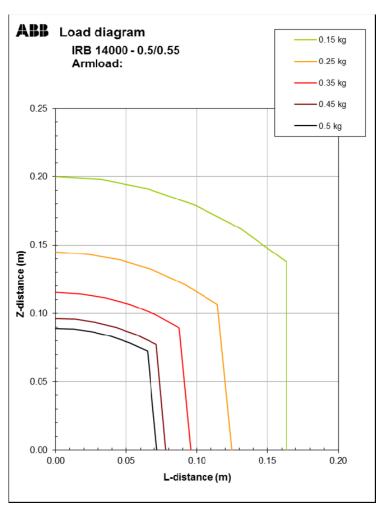
Main features

	IRB 14000 – 0.5/0.5
Payload	0.5 kg per arm
Reach	559 mm
Accuracy	0.02 mm
Footprint	399 mm * 497 mm
Customer interface	Foot interface
Weight	38 kg
Mounting position	Table
Temperature	5 C – 40 C deg
IP Protection	IP 30
Clean room / food grade	No



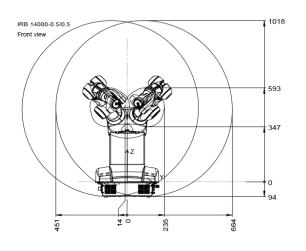
Payload IRB 14000 0.5/0.55

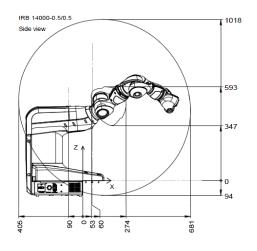


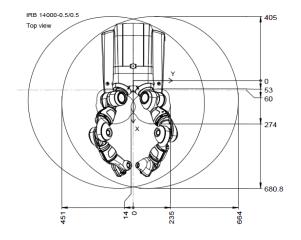




Working range IRB 14000 0.5/0.55



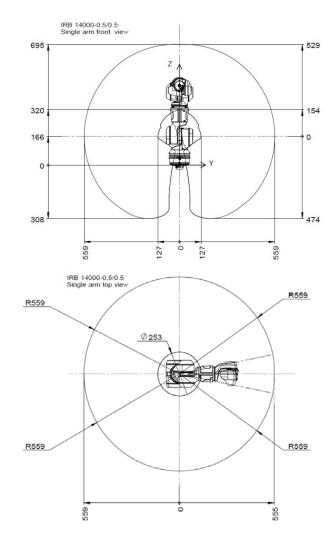


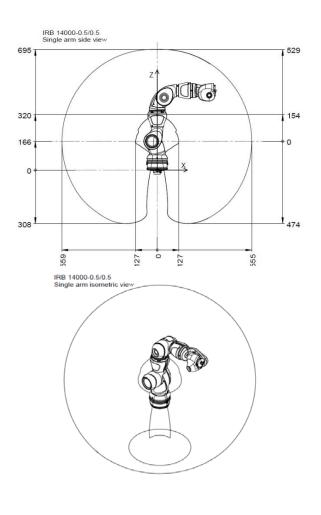






Working range: Single arm IRB 14000 0.5/0.5







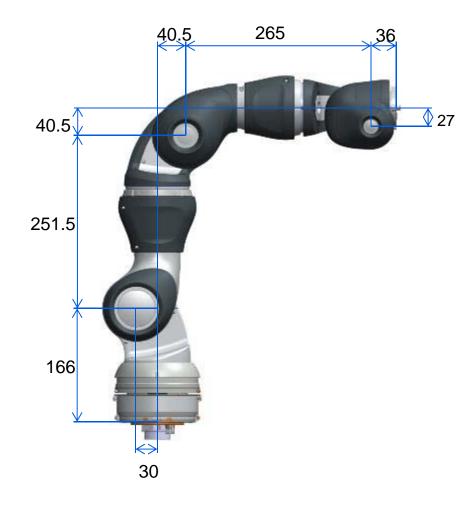
Working range Maximum velocity

	Motion Range	Max. Velocity
Axis 1 Rotation	+168.5° to -168.5°	180 °/s
Axis 2 Arm	+43.5° to -143.5°	180 °/s
Axis 7 Rotation	+168.5° to -168.5°	180 °/s
Axis 3 Arm	+80° to -123.5°	180 °/s
Axis 4 Wrist	+290° to -290 °	400 °/s
Axis 5 Bend	+138° to -88°	400 °/s
Axis 6 Turn	+229° to -229 °	400 °/s



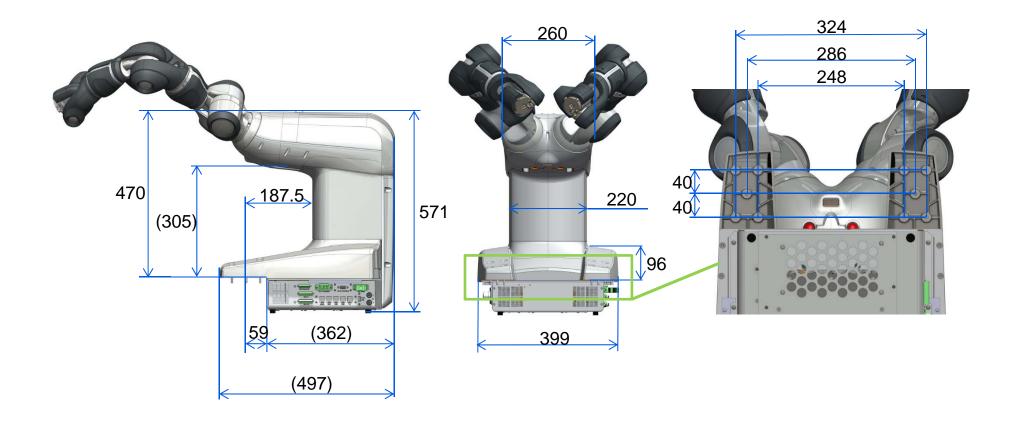
Main dimensions IRB 14000 0.5/0.5





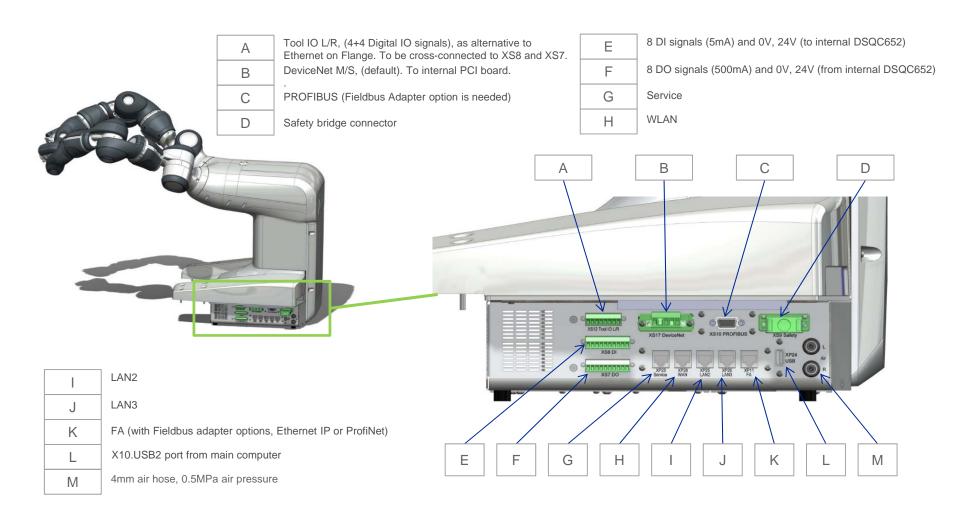


Main dimensions IRB 14000 0.5/0.5





Easy integration I/O: Customer interfaces



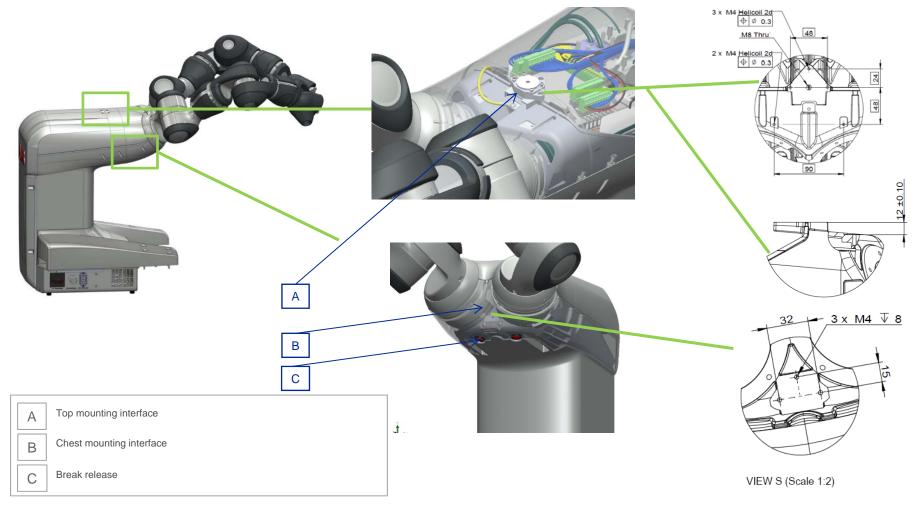


Easy integration Customer interfaces



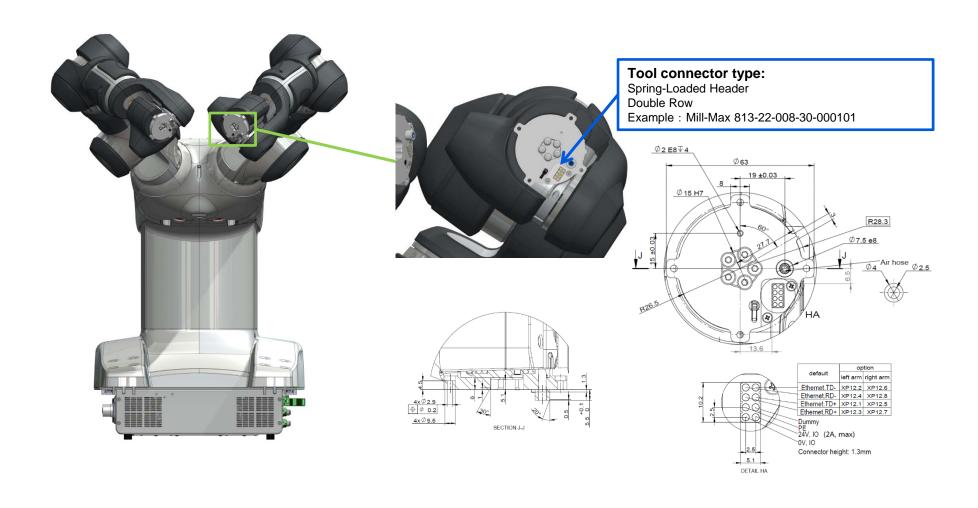


Easy integration I/O: Customer interfaces





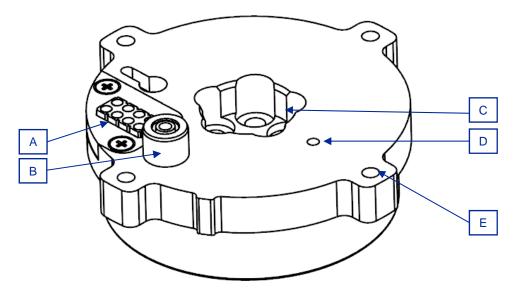
Easy integration I/O: Customer interfaces





Easy integration Mounting interfaces





A 8 pad Millmax connector for 24V and Ethernet or IO

7.5e8 and 4.4F10 for air

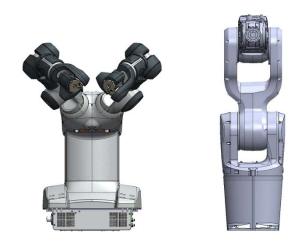
15H7 for alignment

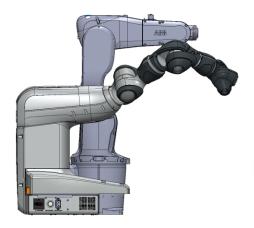
2E8 pin hole for alignment

4 x 2.9 thru holes for M2.5 screws



IRB 14000 0.5/0.55 vs IRB 1200-7/0.7 Outline manipulator









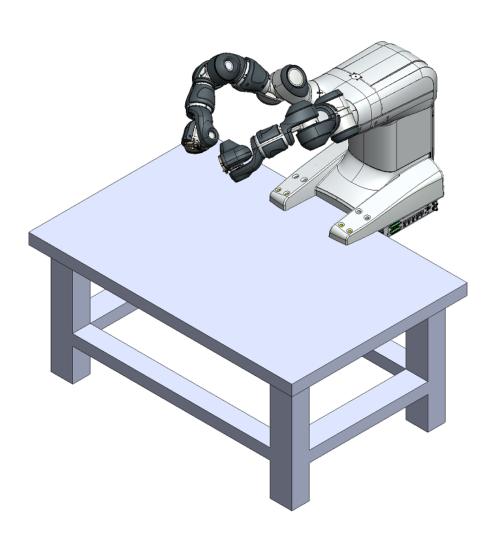
Front view

Side view

Top view



YuMi: IRB 14000 Table mounting





IP protection





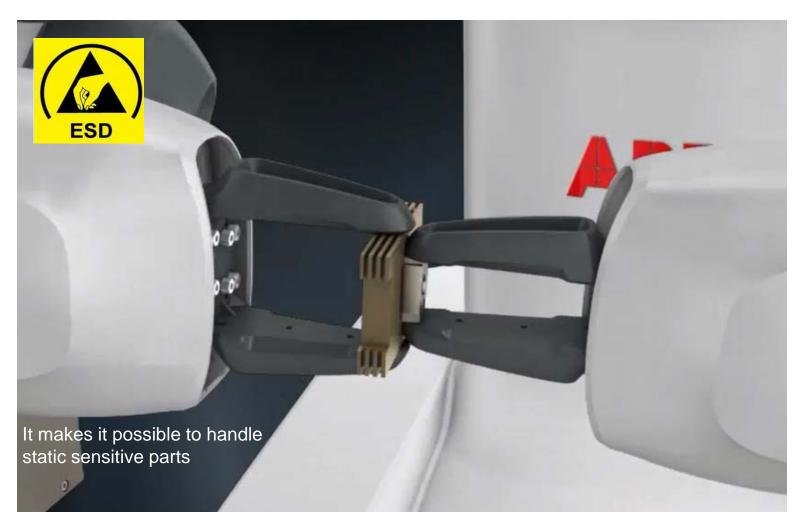


IP 30 (Standard)

It is sufficient for assembly



ESD protection





YuMi: IRB 14000 Controller



- Embedded controller based on IRC5
- Portable (38kg)
- External connectors
- Built-in 8 in /8 out





- Padded arms Including internal wiring and air
- Integral controller New in ABB portfolio
- Light construction –
 Makes the robot portable
- Ease-of-use— Lead Through Programing
- Enclosed design –
 Lower maintenance
- Wide range of communications options – easy to interface

- High speed 1500mm- ROI is increased
- Dual arm Multi-tasking
- Integrated vision Built in to product
- ESD compliance Can work with open electronics
- Safety certified Certified by an independent body
- Integrated hand Easy to integrate





Padded arms

- Adds to safety of operators if there is an unlikely contact during operation
- The robot can be run faster due to added protection
- Faster robot means the ROI will be greater





Integral controller

- Saves working space
- Better cell layout
- Equipment can be placed closer to, or around, robot without interference
- Robot is more streamlined and easy to relocate
- No floor cables or control cables





Lightweight construction

- Makes the robot portable
- Added to safety of the robot
- Smaller frame to mount the robot







Ease-of-use

- Lead-Through Programming makes the programming easy
- Integrated vision can pick unsorted parts
- Tablet programming can be wireless saving the need for wires
- Standard IRC5 rapid as other ABB robots





Enclosed design, which allows all wiring and air to go through the inside of the robot

- Reduced maintenance
- Less risk of cable and air hose damaged
- Can be used in confined spaces
- Easy to keep clean
- No risk of dust collecting on cables







Wide range of communications options

- No problem to connect other devices
- Not locked into one option
- Pick your standard so you do not have to train your staff

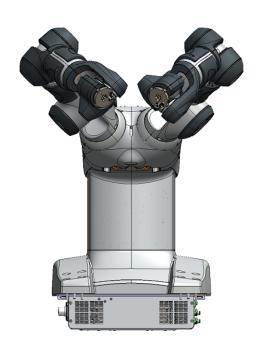




Best in class 1500 mm/sec collaboration speed

- Higher output, increases productivity
- Speed and safety at the same time
- Cutting-edge design standards







Dual arm

- Possible to achieve contact force assembly between arms
- Can process two tasks at the same time
- Operation similar to a human assembling





Integrated vision

- Cameras embedded in gripper
- Integrated hands makes it possible to use the hand for vison guided
- Can be used for simple inspection





ESD compliance

- No problems with static discharge
- Perfect for electronic assembly
- No need to test as we have certified the robot



FUNCTIONAL SAFETY



Safety certified

- No need to certify the robot
- Can be included in your risk assessment of the cell
- Independent body has certified the robot
- PL b Cat b





Integrated hand

- No need to design your own hand
- Multi-option hand with five options
- Integrated communications and air
- Servo
- Vacuum
- Camera



- Applications
 - Be suitable for
 - Small Parts Assembly
 - Collaborative Assembly
 - Accurate and fast assembly
 - Testing and packaging
 - Be not suitable for
 - Paint
 - Food grade
 - Clean room

Segments

- Electronics assembly
 - Collaborative Assembly
 - Packaging of small goods
 - Multi-functional hand for odd sized components
- Toy industry
 - Collaborative Assembly
 - (plastics)
 - Use of feeding and vision options



Key applications and segments Assembly



Small Parts Assembly

- IRB 14000 is the perfect alternative/complementary for IRB 120 or IRB 1200 in small parts assembly
- Safe collaborative assembly
- Precise 0.02 repeatability for small tasks





Vision Guided-Assembly

- Vision included in hands as package
- Vision can also be connected to robot for external devices like flex feeders
- This makes it possible to have less jigging and move to a more flexible cell design





Small Parts Assembly using the FlexFeeder™s and ABB gripper

 Gripper and FlexFeeders make it possible to have a complete solution from part handling to assembly



 Odd sorted parts can be placed in FlexFeeders and presented to the robot in a two dimensional plane







Small Parts Material Handing

- After the assembly process is complete the robot can place the finished product in box ready for shipment
- YuMi working side-by-side handing finished parts to be packed



Summary



Safe and collaborative

- No cages needed
- Padded arms and light weight design
- Speed limited

Increased ROI

fast accurate assembly, lower maintenance costs

Ease-of-integration

- Wide range of communications interfaces
- Integrated hand equipped with vision
- Integrated controller
- Light weight and portable

Ease-of-use

Lead-Through Programming



Power and productivity for a better world™

