Baian (Andrew) Chen

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Education

Massachusetts Institute of Technology

2016 - 2019 (expected)

Candidate for B.S. in Computer Science

GPA: 5.0/5.0

- Membership on Student Advisory Group for Engineering
- Undergraduate Teaching Assistantship in Introduction to Inference

Hong Kong University

2015 - 2016

Previous candidate for B.Eng. in Computing and Data Analysis with Minor in Math

GPA: 3.96/4.3

- HKU-Cambridge Engineering Joint Scheme
- Dean's Honors List

Experience

Tencent Games, Quantum/LightSpeed Studio, Research and Development

Intern. 2017

• Designed and Built a machine-learning development interface for gaming AI.

Shenzhen

• Built a deep-reinforcement learning based gaming AI prototype.

JetBrains Research, Mobile Robot Algorithms Laboratory, Researcher

Intern, 2017

• Built a Robot OS package constructing and testing framework.

St. Petersburg

• Work accepted by IEEE FRUCT Conference (2017) as oral presentation.

Projects

Task-Oriented Optics Flow Utilization

Vision Group, MIT CSAIL, 2016 – 2017

- Designed and built optics flow based convolutional neural network pyramids designated for video interpolation, denoising and super-resolution. Optimized Torch core package to reduce more than 75% GPU memory usage in practice. Supervised by *Prof. William T. Freeman*.
- Work submitted to CVPR Conference (2018).

Project InFORCE

Tangible Media Group, MIT Media Lab, 2016 – 2017

• Developed software layer for tangible human-computer interface. Supervised by *Prof. Hiroshi Ishii*.

Places Challenge

Advances in Computer Vision, MIT, 2016

• Developed deep-learning based scene categorization algorithm. Instructed by *Prof. Antonio Torralba*.

Quantum Controllability

QIFT Group, Oxford-HKU, 2016

- Researched on controllability of quantum unitary. Supervised by *Prof. Giulio Chiribella*.
- Work accepted by MIT-Harvard SPSUR Conference (2016).

Selected Independent Projects

- Designed and Developed a Robot Behavior Inference package on Robot OS for JetBrains Research and taught MIT IAP class *Introduction to Robot OS*. (2016 2017)
- Developed 2D to 3D simple-world recovery algorithm as a final conference entry to Microsoft Research AI Challenge. Sourced by Libraries.io open-source platform. (2016)

Skills

Software and Machine Learning:

• Python, Java, Lua, C++, Shell, Matlab, MySQL. Linux, Windows and OSX development environment. Torch, Tensorflow, Pytorch.

Communication:

• Chinese (native), English (fluent), Russian (limited), Korean (limited), Cantonese (limited).