



# NAO Documentation / User Manual

**Human-Robot Interaction** 

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"Our mission is to create and showcase meaningful and exciting human-to-robot interaction using the Aldebaran NAO robots recently required by CWU." – AriGato Robotics

## **CONTENTS** Section 1: Introduction to the NAO Robot 1.1 What is NAO?......X 1.2 Who made NAO?.....X 1.4 References.....X Section 2: NAO's Capabilities 2.1 Initial (Pre-Built) Capabilities.....X 2.2 Verbal Responses (Q&A)......X 2.3 Internet-Based Requests & Responses......X 2.4 Facial Detection & Recognition Responses......X 2.5 Basic Movement Options......X 2.6 Advanced Movement Options.....X Section 3: Creating Your Own NAO Modules 3.1 Basics of Choregraphe......X 3.2 Using the NAOqi Framework......X 3.3 Creating Your First Module.....X 3.4 Integrating Your Module onto NAO......X Section 4: Help 4.1 General FAQs......X

4.2 Troubleshooting......X

#### SECTION 1: INTRODUCTION TO THE NAO ROBOT

#### 1.1 WHAT IS NAO?

#### 1.2 WHO MADE NAO?

#### 1.3 DEFINITIONS, ACRONYMS, & ABBREVIATIONS

#### 1.4 REFERENCES

#### **SECTION 2: NAO'S CAPABILITIES**

#### 2.1 INITIAL (PRE-BUILT) CAPABILITIES

The original capabilities of the NAO are put on the robot by subscribing to the Aldebaran "Basic Channel." Official documentation on this channel lists and describes its capabilities. Below is a list of some of the phrases NAO can respond to in the documentation, most of which are available in English, French, and Japanese Language settings.

- "How are you?"
- "Can you say goodbye?"
- "What can you do?"
- "Tell me all you can do."
- "How do I install an application?"
- "How do I start an application?"
- "What did I say?"
- "Can you repeat please?"
- "What is your IP address?"
- "Are you connected to Internet?"
- "What languages so you speak?
- "Speak French."
- "Can you speak French?"
- "Speak Japanese."
- "Speak Chinese"
- "Can you speak Chinese"

<sup>&</sup>lt;sup>1</sup> http://doc.aldebaran.com/2-1/nao/basic\_channel\_conversation.html

- "Speak softer"
- "Speak louder"
- "Can you stand up?"
- "Can you sit down?"
- "Crouch."
- "Lay down"
- "Lay down on your back"
- "Lay down on your belly."
- "Stop Looking at me"
- "What is your name?"
- "Introduce yourself"
- "How tall are you?"
- "How much do you weigh?"
- 2.2 VERBAL RESPONSES (Q&A)
- 2.3 INTERNET-BASED REQUESTS & RESPONSES
- 2.4 FACIAL DETECTION & RECOGNITION RESPONSES
- 2.5 BASIC MOVEMENT OPTIONS
- 2.6 ADVANCED MOVEMENT OPTIONS
- **SECTION 3: CREATING YOUR OWN NAO MODULES**
- 3.1 BASICS OF CHOREGRAPHE
- 3.2 USING THE NAOQI FRAMEWORK
- 3.3 CREATING YOUR FIRST MODULE

### 3.4 INTEGRATING YOUR MODULE ONTO NAO

**SECTION 4: HELP** 

4.1 GENERAL FAQS

4.2 TROUBLESHOOTING