

Geometric properties

Embedding

Definition 1. Let $N = (Q, g)$ be a n -dimension Riemannian manifold on position parameter space with such inner product g that the map $\cdot \mapsto \frac{1}{k} \cdot e^1 \in P \rightarrow P^*$ is an isometric embedding to $(n + 1)$ -Euclidean manifold.

Remark 1. It have been proved that there is no isometric embedding from H^n to E^{n+1} . Hence, this section is based on a faulty assumption and would not provide a useful information.

Lemma 1. *Position parameter θ^i is associated to the following vector in position vector space.*

$$\frac{\partial}{\partial \theta^i} = \begin{pmatrix} -k \tan_k^* \theta^i p^j \\ k \frac{1}{\tan_k \theta^i} p^{i+1} \\ 0 \end{pmatrix} \frac{\partial}{\partial p^j}$$

Proof of lemma 1.

$$\begin{aligned} \frac{\partial}{\partial \theta^i} &= \frac{\partial p^j}{\partial \theta^i} \frac{\partial}{\partial p^j} \\ &= \frac{\partial}{\partial \theta^i} \left[\frac{1}{k} \begin{pmatrix} \prod_{l \in \{1..n\}} \cos_k \theta^l \\ \sin_k \theta^{j-1} \prod_{l \in \{j..n\}} \cos_k \theta^l \\ \sin_k \theta^n \end{pmatrix} \right] \frac{\partial}{\partial p^j} \quad ?? \\ &= \frac{1}{k} \frac{\partial}{\partial \theta^i} \left[\begin{pmatrix} \prod_{l \in \{1..n\}} \cos_k \theta^l \\ \sin_k \theta^{j-1} \prod_{l \in \{j..n\}} \cos_k \theta^l \\ \sin_k \theta^n \end{pmatrix} \right] \frac{\partial}{\partial p^j} \\ &= \frac{1}{k} \left[\begin{pmatrix} -k \sin_k^* \theta^i \prod_{l \in \{1..n\} / \{i\}} \cos_k \theta^l \\ -k \sin_k^* \theta^i \sin_k \theta^{j-1} \prod_{l \in \{j..n\} / \{i\}} \cos_k \theta^l \\ k \cos_k \theta^i \prod_{l \in \{i+1..n\}} \cos_k \theta^l \\ 0 \end{pmatrix} \right] \frac{\partial}{\partial p^j} \quad ?? \end{aligned}$$

$$\begin{aligned}
&= \begin{pmatrix} -\tan_k^* \theta^i \prod_{l \in \{1..n\}} \cos_k \theta^l \\ -\tan_k^* \theta^i \sin_k \theta^{j-1} \prod_{l \in \{j..n\}} \cos_k \theta^l \\ \frac{1}{\tan_k \theta^i} \prod_{l \in \{i+1..n\}} \cos_k \theta^l \\ 0 \end{pmatrix} \frac{\partial}{\partial p^j} \\
&= \begin{pmatrix} -k \tan_k^* \theta^i p^j \\ k \frac{1}{\tan_k \theta^i} p^{i+1} \\ 0 \end{pmatrix} \frac{\partial}{\partial p^j} \quad ??
\end{aligned}$$

□

Lemma 2. *The metric tensor of N is*

$$g_{ij} = \begin{cases} (1 - \operatorname{sgn} k) \tan_k^2(\theta^a) \prod_{1 \leq j} \cos_k^2 \theta^j + \prod_{a < j} \cos_k^2 \theta^j & \text{if } i = j, \\ 0 & \text{otherwise.} \end{cases}$$

Proof of lemma 2.

$$\begin{aligned}
g_{ab} \left[\frac{\partial}{\partial \theta^i} \right] &= \sum_{l,m=1}^{n+1} \frac{\partial p^l}{\partial \theta^a} g_{lm} \left[\frac{\partial}{\partial p^i} \right] \frac{\partial p^m}{\partial \theta^b} \\
&= \sum_{l=1}^{n+1} \frac{\partial p^l}{\partial \theta^a} \frac{\partial p^l}{\partial \theta^b}
\end{aligned}$$

If $a < b$,

$$\begin{aligned}
g_{ab} &= \begin{bmatrix} -k \tan_k^*(\theta^a) p^j \\ k \frac{1}{\tan_k(\theta^a)} p^{a+1} \\ 0 \end{bmatrix} \cdot \begin{bmatrix} -k \tan_k^*(\theta^b) p^j \\ k \frac{1}{\tan_k(\theta^b)} p^{b+1} \\ 0 \end{bmatrix} \\
&= \sum k^2 \tan_k^*(\theta^a) \tan_k^*(\theta^b) p^{j^2} - k^2 \frac{\tan_k^*(\theta^b)}{\tan_k(\theta^a)} p^{a+1^2} \\
&= \tan_k(\theta^b) \tan_k(\theta^a) \prod_{a \leq j \leq n+1} \cos_k^2 \theta^j \left(\prod_{1 \leq j < a} \cos_k^2 \theta^j + \sum \sin_k^2 \theta^i \prod_{i < j < a} \cos_k^2 \theta^j - \operatorname{sgn} k \right) \\
&= \tan_k(\theta^b) \tan_k(\theta^a) \prod_{a \leq j \leq n+1} \cos_k^2 \theta^j \left(\prod_{1 \leq j < a} \cos_k^2 \theta^j + \operatorname{sgn} k \left(1 - \prod_{1 \leq j < a} \cos_k^2 \theta^j \right) - \operatorname{sgn} k \right) \\
g_{ab} &= 0.
\end{aligned}$$

If $a > b$, $g_{ab} = g_{ba} = 0$.

If $a = b$,

$$\begin{aligned}
g_{aa} &= \begin{pmatrix} -k \tan_k^* \theta^a p^j \\ k \frac{1}{\tan_k \theta^a} p^{a+1} \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -k \tan_k^* \theta^a p^j \\ k \frac{1}{\tan_k \theta^a} p^{a+1} \\ 0 \end{pmatrix} \\
&= \sum_{j=1}^a \left(k p^j \tan_k^* \theta^a \right)^2 + \left(k p^{a+1} \cot_k \theta^a \right)^2 \\
&= \sum_{j=1}^a \left(k p^j \tan_k \theta^a \right)^2 + \left(k p^{a+1} \cot_k \theta^a \right)^2 \\
&= \sin_k^2(\theta^a) \prod_{a < j} \cos_k^2 \theta^j \left(\prod_{1 \leq j < a} \cos_k^2 \theta^j + \sum_{1 \leq i < a} \sin_k^2 \theta^i \prod_{i < j < a} \cos_k^2 \theta^j + \cot_k^2(\theta^a) \right) \\
&= \sin_k^2(\theta^a) \prod_{a < j} \cos_k^2 \theta^j \left(\prod_{1 \leq j < a} \cos_k^2 \theta^j + \sum_{1 \leq i < a} \sin_k^2 \theta^i \prod_{i < j < a} \cos_k^2 \theta^j + \cot_k^2(\theta^a) \right) \\
&= \sin_k^2(\theta^a) \prod_{a < j} \cos_k^2 \theta^j \left(\prod_{1 \leq j < a} \cos_k^2 \theta^j - \operatorname{sgn} k \prod_{1 \leq j < a} \cos_k^2 \theta^j + \operatorname{sgn} k \prod_{1 \leq j < a} \cos_k^2 \theta^j + \sum_{1 \leq i < a} \sin_k^2 \theta^i \prod_{i < j < a} \cos_k^2 \theta^j \right) \\
&= \sin_k^2(\theta^a) \prod_{a < j} \cos_k^2 \theta^j \left(\prod_{1 \leq j < a} \cos_k^2 \theta^j - \operatorname{sgn} k \prod_{1 \leq j < a} \cos_k^2 \theta^j + \operatorname{sgn} k + \cot_k^2(\theta^a) \right) \\
&= \sin_k^2(\theta^a) \prod_{a < j} \cos_k^2 \theta^j \left(\prod_{1 \leq j < a} \cos_k^2 \theta^j - \operatorname{sgn} k \prod_{1 \leq j < a} \cos_k^2 \theta^j + \operatorname{sgn} k + \csc_k^2(\theta^a - \operatorname{sgn} k) \right) \\
&= \sin_k^2(\theta^a) \prod_{a < j} \cos_k^2 \theta^j \left((1 - \operatorname{sgn} k) \prod_{1 \leq j < a} \cos_k^2 \theta^j + \csc_k^2(\theta^a) \right) \\
&= (1 - \operatorname{sgn} k) \tan_k^2(\theta^a) \prod_j \cos_k^2 \theta^j + \prod_{a < j} \cos_k^2 \theta^j
\end{aligned}$$

□

Curvature

Curvature (Method I)

This method may be easier to generalize to Model II where each direction can have partially independent curvature (or even Model III where extrinsic curvature become a thing). But it may be challenging to define Gauss map properly.

Lemma 3. *Given a position parameter θ , the tangent vector in position vector space*

can be calculated as follows

$$\nu(p) = \begin{cases} \begin{bmatrix} kp^1 \\ +kp^i \end{bmatrix} & k > 0 \\ \begin{bmatrix} 1 \\ 0 \end{bmatrix} & k = 0 . \\ \frac{1}{\sqrt{-1+2(kp^1)^2}} \begin{bmatrix} kp^1 \\ -kp^i \end{bmatrix} & k < 0 \end{cases}$$

Proof of lemma 3. From ??????,

$$p \in P \iff \begin{cases} \sum_i p^{i^2} = k^{-2} & k > 0, \\ p^1 = k^{-1} & k \rightarrow 0, \\ p^{1^2} - \sum_{1 < i} p^{i^2} = k^{-2} \wedge p^1 > 0 & k < 0. \end{cases}$$

Let

$$F(p) = \begin{cases} \sum_i p^{i^2} - k^{-2} & k > 0, \\ p^1 - k^{-1} & k \rightarrow 0, \\ p^{1^2} - \sum_{1 < i} p^{i^2} - k^{-2} & k < 0. \end{cases}$$

$$n = l \nabla F(p)$$

$$= l \begin{cases} \nabla \sum_i p^{i^2} - k^{-2} & k > 0, \\ \nabla p^1 - k^{-1} & k \rightarrow 0, \\ \nabla p^{1^2} - \sum_{1 < i} p^{i^2} - k^{-2} & k < 0. \end{cases}$$

$$= l \begin{cases} \begin{pmatrix} 2p^i \end{pmatrix} & k > 0, \\ \begin{pmatrix} 1 \\ 0 \end{pmatrix} & k \rightarrow 0, \\ \begin{pmatrix} -2p^1 \\ 2p^i \end{pmatrix} & k < 0. \end{cases}$$

$$\begin{aligned}
\hat{n} &= \pm \begin{cases} \frac{1}{\|p\|} \begin{pmatrix} p^i \\ 0 \end{pmatrix} & k > 0, \\ \begin{pmatrix} 1 \\ 0 \end{pmatrix} & k \rightarrow 0, \\ \frac{1}{\|p\|} \begin{pmatrix} -p^1 \\ p^i \end{pmatrix} & k < 0. \end{cases} \\
&= \pm \begin{cases} \frac{1}{k^{-1}} \begin{pmatrix} p^i \\ 0 \end{pmatrix} & k > 0, \\ \begin{pmatrix} 1 \\ 0 \end{pmatrix} & k \rightarrow 0, \\ \frac{1}{\sqrt{-1+2(kp^1)^2}} \begin{pmatrix} -p^1 \\ p^i \end{pmatrix} & k < 0. \end{cases} \\
\nu = \hat{n} &:= \begin{cases} \begin{pmatrix} kp^i \\ 1 \\ 0 \end{pmatrix} & k > 0, \\ \begin{pmatrix} 1 \\ 0 \end{pmatrix} & k \rightarrow 0, \\ \frac{1}{\sqrt{-1+2(kp^1)^2}} \begin{pmatrix} p^1 \\ -p^i \end{pmatrix} & k < 0. \end{cases}
\end{aligned}$$

□

Lemma 4.

$$L(p) = \begin{cases} -kI & k > 0, \\ 0 & k \rightarrow 0, \\ \frac{1}{\|p\|} \left(\frac{1}{\|p\|^2} pp^T \text{diag}(-1, 1, \dots, 1) - I \right) & k < 0. \end{cases}$$

Proof of lemma 4.

$$\begin{aligned}
\frac{\partial}{\partial p^j} \frac{1}{\|p\|} &= \frac{\partial}{\partial \|p\|} \frac{1}{\|p\|} \frac{\partial}{\partial p^j} \|p\| \\
&= -\frac{1}{\|p\|^2} \frac{\partial}{\partial p^j} \sqrt{\sum_i p^{i2}} \\
&= -\frac{1}{\|p\|^2} \frac{\partial}{\partial \sum_i p^{i2}} \sqrt{\sum_i p^{i2}} \frac{\partial}{\partial p^j} \sum_i p^{i2}
\end{aligned}$$

$$\begin{aligned}
&= -\frac{1}{\|p\|^2} \frac{1}{2\sqrt{\sum_i p^{i^2}}} 2p^j \\
&= -\frac{1}{\|p\|^2} \frac{1}{2\|p\|} 2p^j \\
&= -\frac{p^j}{\|p\|^3}
\end{aligned}$$

From ??,

$$\begin{aligned}
L(p) &= -(D\nu \circ (Df)^{-1})(p) \\
&= -(D\nu)(p) \\
&= -\left(\frac{\partial}{\partial p^j} \nu^i \Big|_p\right)_{i,j} \\
(L(p))_{i,j} &= \begin{cases} -\frac{\partial}{\partial p^j} k p^i & k > 0, \\ -\frac{\partial}{\partial p^j} 1 & k \rightarrow 0 \text{ and } i = 1, \\ -\frac{\partial}{\partial p^j} 0 & k \rightarrow 0 \text{ and } i \neq 1, \\ -\frac{\partial}{\partial p^j} \left(\frac{1}{\|p\|} p^1\right) & k < 0 \text{ and } i = 1, \\ -\frac{\partial}{\partial p^j} \left(-\frac{1}{\|p\|} p^i\right) & k < 0 \text{ and } i \neq 1, \end{cases} \\
&= \begin{cases} -k & k > 0 \text{ and } i = j, \\ 0 & k > 0 \text{ and } i \neq j, \\ 0 & k \rightarrow 0, \\ -\left(\frac{1}{\|p\|} \frac{\partial}{\partial p^j} p^1 + p^1 \frac{\partial}{\partial p^j} \frac{1}{\|p\|}\right) & k < 0 \text{ and } i = 1, \\ \left(\frac{1}{\|p\|} \frac{\partial}{\partial p^j} p^i + p^i \frac{\partial}{\partial p^j} \frac{1}{\|p\|}\right) & k < 0 \text{ and } i \neq 1, \end{cases}
\end{aligned}$$

$$= \begin{cases} -k & k > 0 \text{ and } i = j, \\ 0 & k > 0 \text{ and } i \neq j, \\ 0 & k \rightarrow 0, \\ -\frac{1}{\|p\|} + \frac{p^{12}}{\|p\|^3} & k < 0 \text{ and } i = j = 1, \\ \frac{p^1 p^j}{\|p\|^3} & k < 0 \text{ and } j \neq i = 1, \\ \frac{1}{\|p\|} - \frac{p^{i2}}{\|p\|^3} & k < 0 \text{ and } i = j \neq 1, \\ -\frac{p^i p^j}{\|p\|^3} & k < 0, i \neq j \text{ and } i \neq 1, \end{cases}$$

For $k > 0$, $L(p) = -kI$.

For $k \rightarrow 0$, $L(p) = 0$.

For $k < 0$, $L(p) = \frac{1}{\|p\|} \left(\frac{1}{\|p\|^2} pp^T \text{diag}(-1, 1, \dots, 1) - I \right)$. □

Lemma 5.

Proof of lemma 5. The proof is left as an exercise to the other author.

For $k > 0$,

$$\begin{aligned} 0 &= \det L(p) - \lambda I \\ &= \det -kI - \lambda I \\ &= \det (-k - \lambda)I \\ &= (-k - \lambda)^{n+1} \det I \\ &= (-k - \lambda)^{n+1} \\ \lambda &\in \{-k, \dots, -k\} \end{aligned}$$

For $k < 0$,

$$\begin{aligned} 0 &= \det L(p) - \lambda I \\ &= \det \frac{1}{\|p\|} \left(\frac{1}{\|p\|^2} pp^T \text{diag}(-1, 1, \dots, 1) - I \right) - \lambda I \\ &= \det \frac{1}{\|p\|} \left(\frac{1}{\|p\|^2} pp^T \text{diag}(-1, 1, \dots, 1) - I \right) - \left(\lambda' - \frac{1}{\|p\|} \right) I \quad \lambda' := \lambda + \frac{1}{\|p\|} \\ &= \det \frac{1}{\|p\|^3} pp^T \text{diag}(-1, 1, \dots, 1) - \frac{1}{\|p\|} I - \left(\lambda' - \frac{1}{\|p\|} \right) I \end{aligned}$$

$$\begin{aligned}
&= \det \frac{1}{\|p\|^3} pp^T \text{diag}(-1, 1, \dots, 1) - \lambda' I \\
&= \det \frac{1}{\|p\|^3} pp^T \text{diag}(-1, 1, \dots, 1) - \frac{1}{\|p\|^3} \lambda'' I & \lambda'' &:= \|p\|^3 \lambda' \\
&= \frac{1}{\|p\|^{3(n+1)}} \det pp^T \text{diag}(-1, 1, \dots, 1) - \lambda'' I \\
&= \det pp^T \text{diag}(-1, 1, \dots, 1) - \lambda'' I \\
&= \lambda''^n \left(\lambda'' + p^{12} - \sum_{i \neq 1} p^{i2} \right) \\
0 &= \lambda''^n \left(\lambda'' + \frac{1}{k} \right) \\
\lambda'' &\in \left\{ -\frac{1}{k}, 0, \dots, 0 \right\} \\
\lambda' &\in \left\{ -\frac{1}{k \|p\|^3}, 0, \dots, 0 \right\} \\
\lambda &\in \left\{ -\frac{1}{k \|p\|^3} - \frac{1}{\|p\|}, -\frac{1}{\|p\|}, \dots, -\frac{1}{\|p\|} \right\} \\
&= \left\{ -\frac{1 + \|p\|^2}{k \|p\|^3}, -\frac{1}{\|p\|}, \dots, -\frac{1}{\|p\|} \right\} \\
&= \left\{ -\frac{2k^2 p^{12}}{k \|p\|^3}, -\frac{1}{\|p\|}, \dots, -\frac{1}{\|p\|} \right\} \\
&= \left\{ -\frac{2k p^{12}}{\|p\|^3}, -\frac{1}{\|p\|}, \dots, -\frac{1}{\|p\|} \right\} \\
&= \left\{ k^2 \|p\| \frac{-2p^{12}}{k \|p\|^4}, -\frac{1}{\|p\|}, \dots, -\frac{1}{\|p\|} \right\} \\
&= \left\{ k^2 \|p\| \frac{-2p^{12}}{k \|p\|^4}, -\frac{1}{\|p\|}, \dots, -\frac{1}{\|p\|} \right\}
\end{aligned}$$

□

Curvature (Method II)

This method may be easier to be done (despite the fact that it never finished). But it raises problems when trying to generalize e.g. dealing with extrinsic curvature (which may be introduced in Model III if not to mess with other basis geometries).

Lemma 6.

Lemma 7.

*Curvature (Conclusion)***Lemma 8.**

CurvatureParameter. It can be seen that $\sec(p) = \kappa = \text{sgn}(k)k^2$. Hence, when provided κ , k can be determined and used to evaluate the model.

DRAFT