Deep learning episode 2 Computer vision applications







Image recognition



"Dog"

Image recognition



"Gray wall"

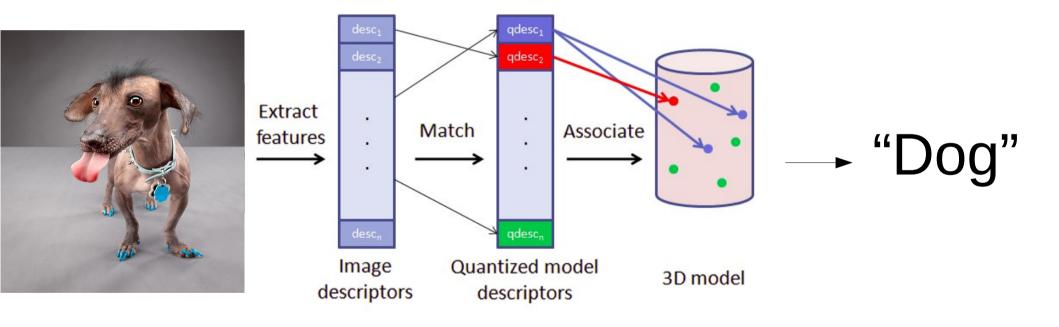
"Dog tongue"

"Dog"

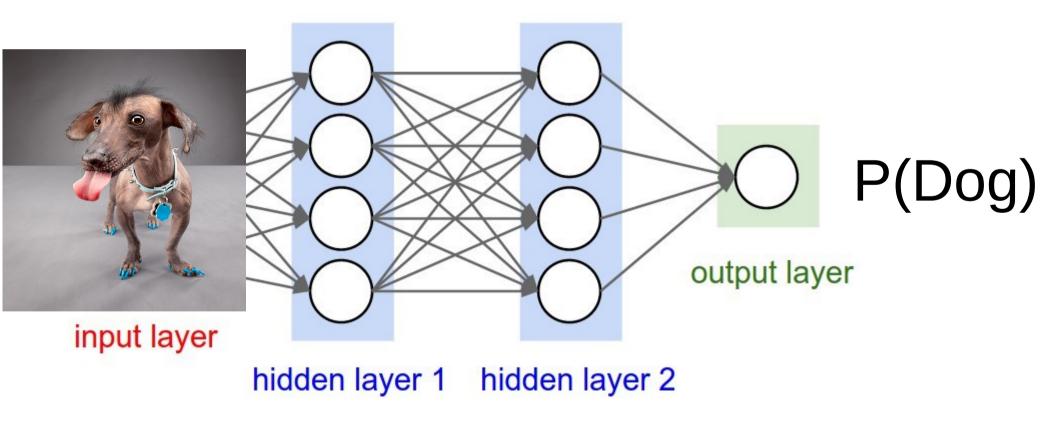
<a particular kind of dog>

"Animal sadism"

Classical approach



NN approach



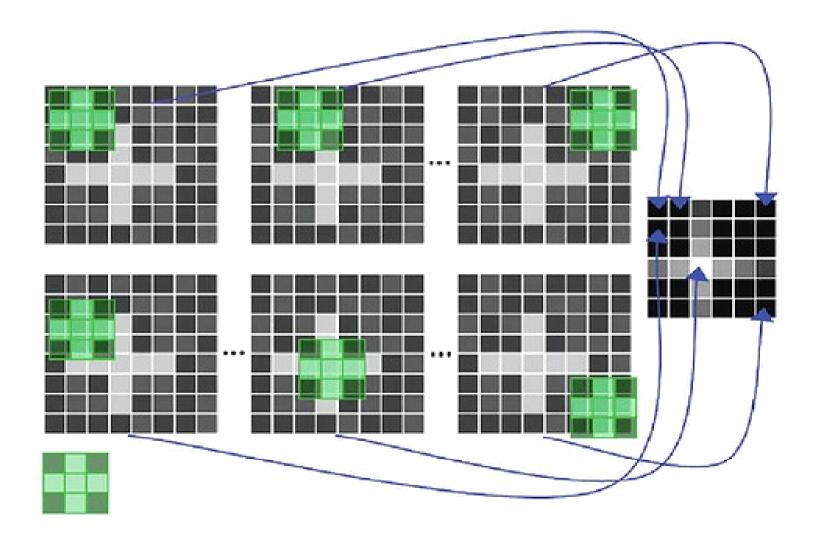
What features could NN learn this way?

Problem

Should we require, say, "Dog ear" feature

- Linear combination can only select dog ear at a one (or a few) positions.
- Need to learn independent features for each position
- Next layer needs to react on "dog ear 0,0 or dog ear 0,1 or ... or dog ear 255,255"
- Introduce a lot of parameters and risk overfitting.

Idea: force all these "dog ear" features to use **exactly same weights**, shifting weight matrix each time.



Idea: apply same filter to all patches

5x5

1 _{×1}	1,0	1,	0	0
0,×0	1 _{×1}	1,0	1	0
0 _{×1}	O _{×0}	1 _{×1}	1	1
0	0	1	1	0
0	1	1	0	0

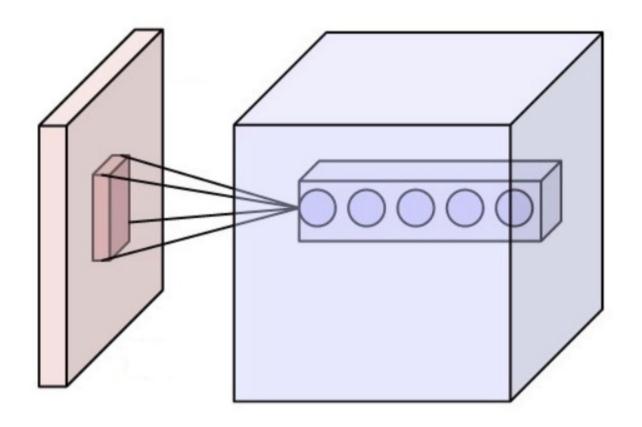
Image

3x3 (5-3+1)

4	

Convolved Feature

Intuition: how cat-like is this square?



Intuition: how cat-like is this square?

Input image



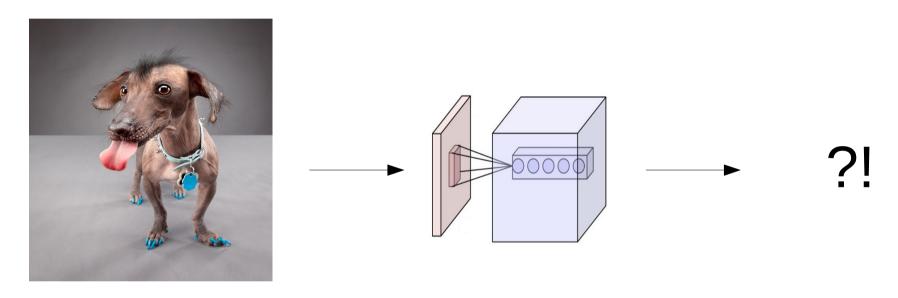
Convolution Kernel

$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

Feature map



Intuition: how edge-like is this square?



Filters: 100x(3x5x5)

Image : 3 (RGB) x 100 px x 100 px

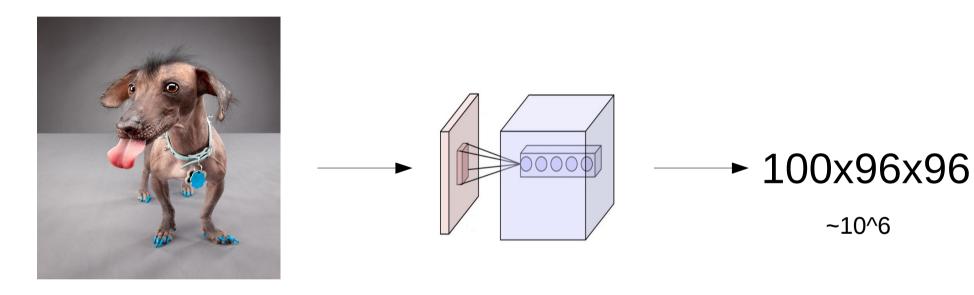
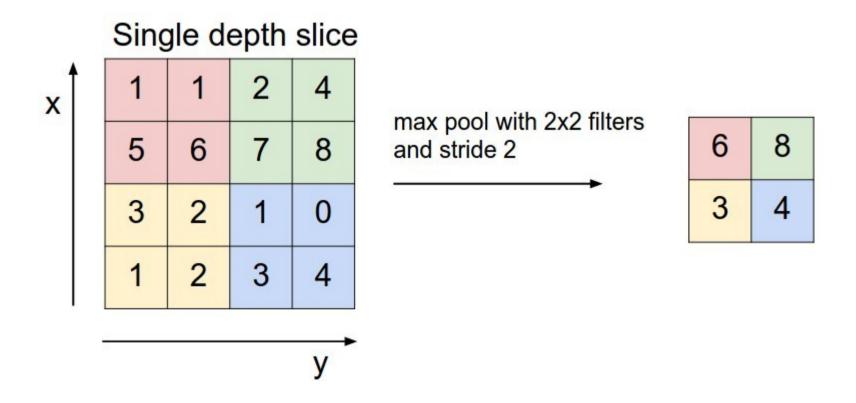


Image: 3 (RGB) x 100 px x 100 px

Filters: 100x(3x5x5)

Somewhat too many!

Pooling



Intuition: What is the max catlikelihood over this area?

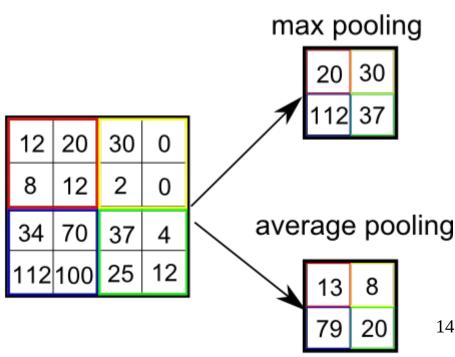
Pooling

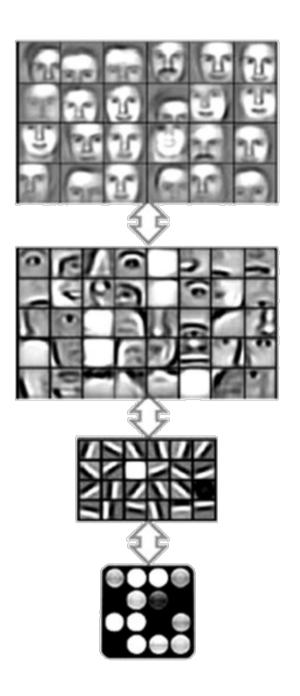
Motivation:

- Reduce layer size by a factor
- Make NN less sensitive to small image shifts

Popular types:

- Max
- Mean(average)





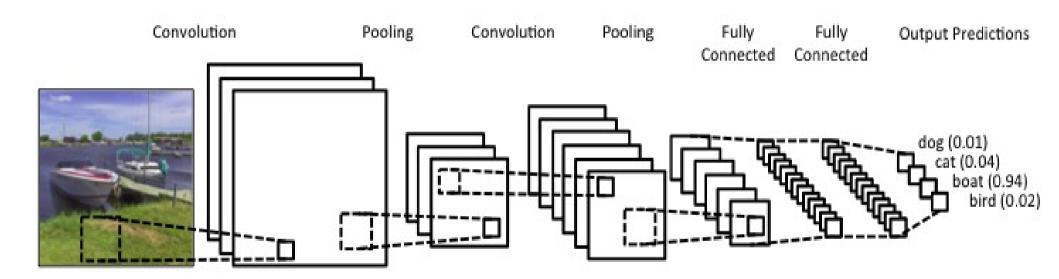
Discrete Choices

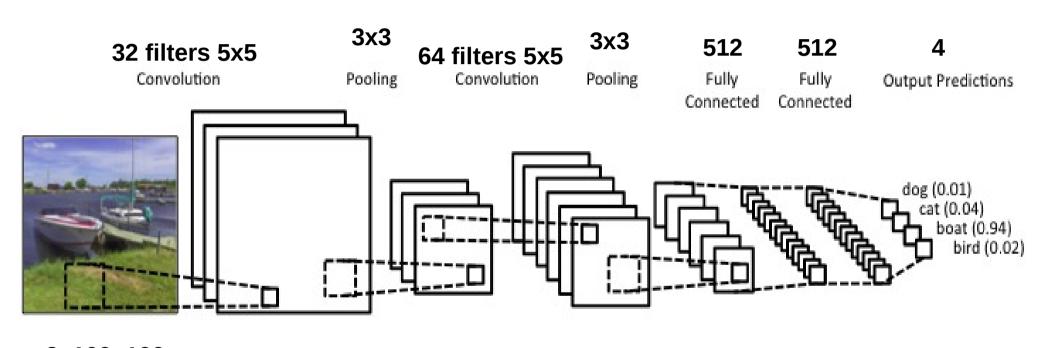
:

Layer 2 Features

Layer 1 Features

Original Data

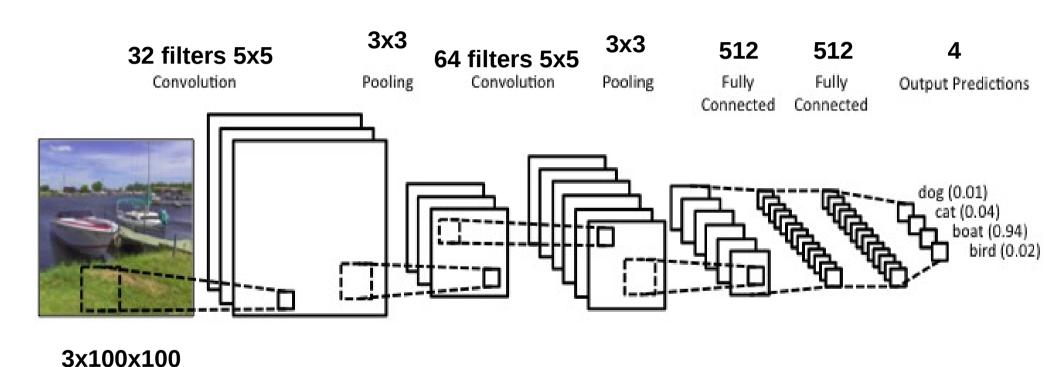




3x100x100

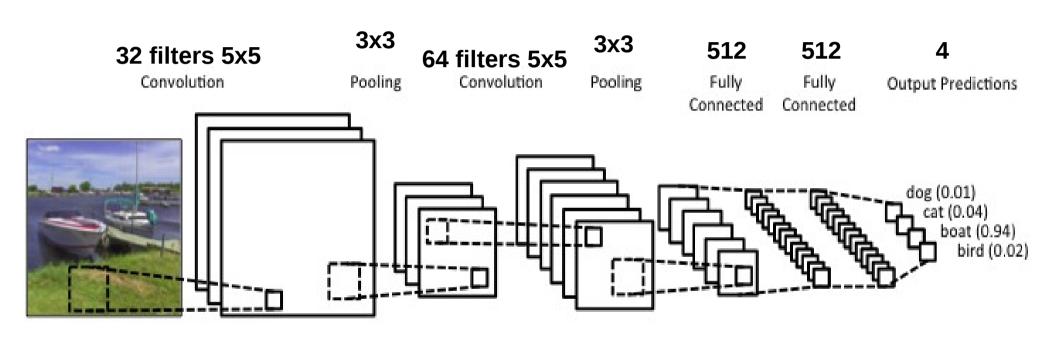
Quiz:

1) What is the blob size after second pooling



Quiz:

2) How many image pixels does **one cell** after **second convolution** depend on?

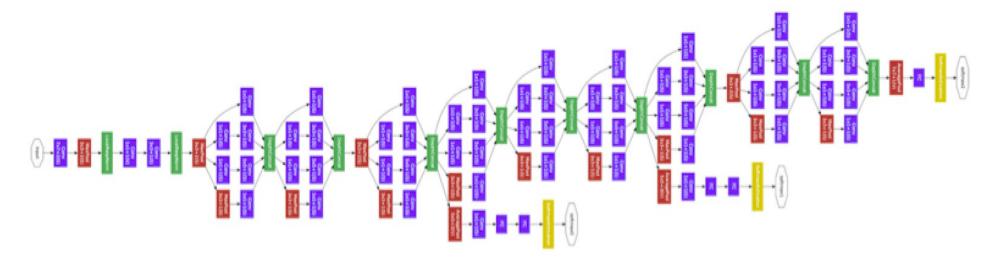


3x100x100

Quiz:

- 3) Which layer is hardest to compute?
- 4) Which layer has most independent parameters?

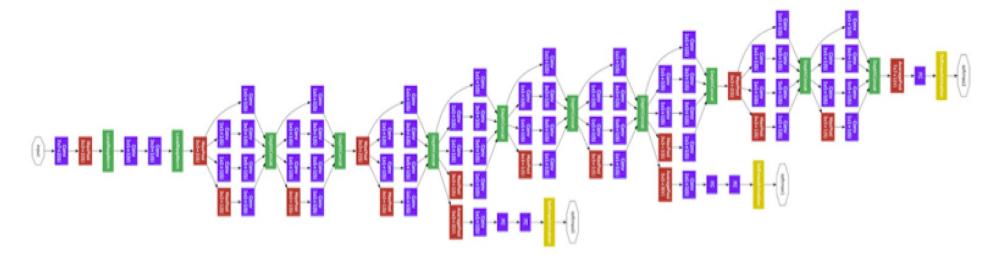
Inception-GoogleNet

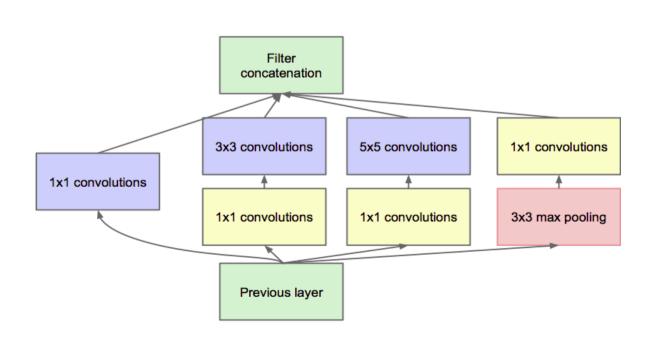




It is not a moon. It is a space station (c)

Inception-GoogleNet





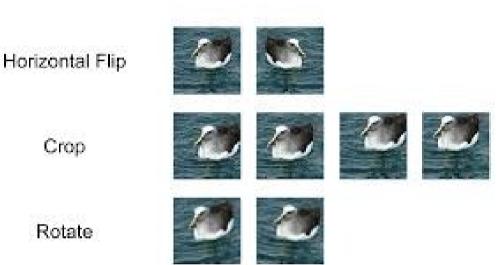


Data augmentation

Crop

Rotate

- Idea: we can get N times more data by tweaking images.
- If you rotate a cat 15 degrees, it's still a cat.
- Rotate, crop, zoom, flip horizontally, add noize, etc.
- Sound data: add background noizes



Problem:

- Consider a neuron in any layer beyond first
- At each iteration we tune it's weights towards better loss function
- But we also tune it's inputs. Some of them become larger, some – smaller
- Now the neuron needs to be re-tuned for it's new inputs

TL;DR:

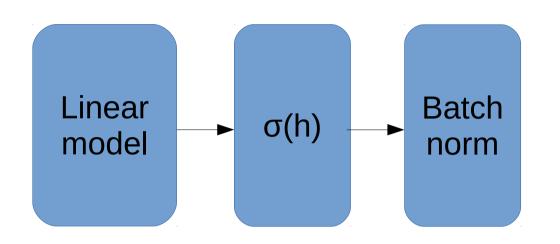
- It's usually a good idea to normalize linear model inputs
 - Every data science lecturer, ever

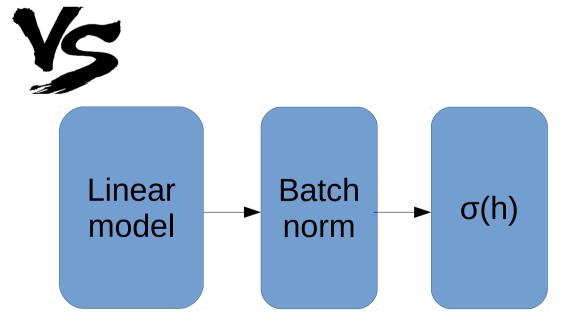
Idea:

 We normalize activation of a hidden layer (zero mean unit variance)

$$\hat{x}^k = \frac{x^k - E[x^k]}{\sqrt{Var[x^k]}}$$

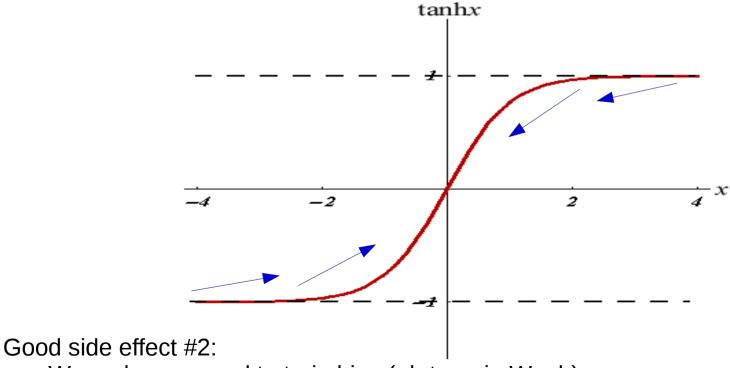
Now all neurons have ~same output range





Good side effect #1:

Vanishing gradient less a problem for sigmoid-like nonlinearities



We no longer need to train bias (+b term in Wx+b)

Other CV applications

to be covered in 3 weeks

Bounding box regression

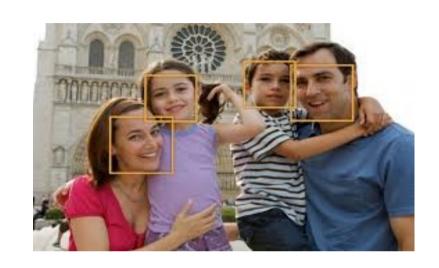
Predict object bounding box

(x0,y0,w,h)

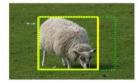
or several bounding boxes for multiple objects.

Applications examples:

- Face detection @ cameras
- Surveillance cameras
- Self-driving cars



IM:"005194" Conf=0.835223



IM:"004522" Conf=0.799045



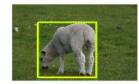
IM:"002306" Conf=0.789123



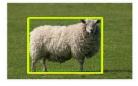
IM:"003538" Conf=0.829488



IM: "001064" Conf=0.797061



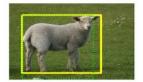
IM:"001956" Conf=0.788438



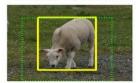
IM:"002810" Conf=0.801748



IM:"000819" Conf=0.794456



IM:"004285" Conf=0.782058



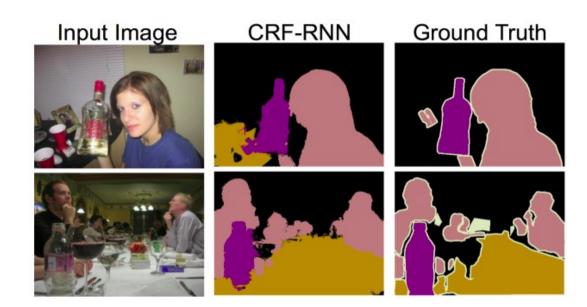
Segmentation

Predict class for each pixel

(fully-convolutional networks)

Applications examples:

- Moar surveillance
- Brain scan labeling
- Map labeling



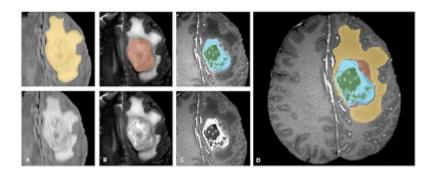
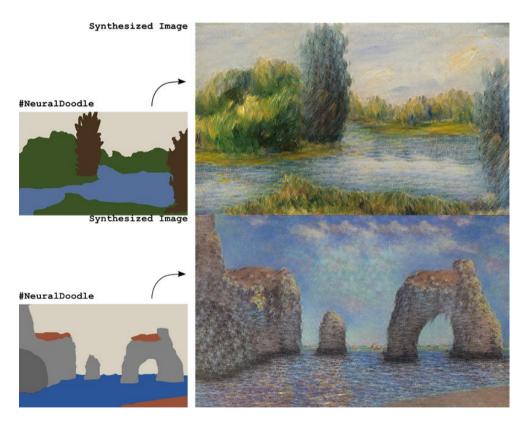


Image generation/transformation

- Generation: Given a set of reference images, learn to generate new images, resembling those you were given.
- Transformation: Given a set of reference images, learn to convert other images into ones resembling the reference set.



Neural Doodle (D. Ulyanov et al.)

Image tagging Image captioning Image retrieval Image encoding Image morphing Image encoding Image upscaling Object tracking on video Video processing Video interpolation

Fine-tuning **Adversarial Networks** Variational Autoencoders Knowledge transfer Domain adaptation Online learning **Explaining predictions** Soft targets Scene reconstruction 3D object retrieval Classifier optimization

Nuff

Let's code some neural networks!