Deep learning episode 12 Bayesian methods in DL









What is probability?



What is probability?

What does it mean if P(event) = 0.25?

How evaluate P(coin lands heads)?

A coin was flipped 2 times Heads both times P(heads) = ?





Frequentist Vs Bayesian

- Probability is objective nondeterminism
- There is no prior, there's data
- Hypothesis testing
- Quantum Physics
- Trust Regions
- Maximum Likelihode Estimate

- Probability is subjective ignorance
- Through prior I gain strength
- Regularization
- Structured learning
- Posterior distributions
- Maximum a-posteriori



Bayes theorem

Conditional probability

Probability of **a** given **b**

$$P(a|b) = \frac{P(ab)}{P(b)}$$

Bayes theorem

$$P(a|b) = \frac{P(ab)}{P(b)} = \frac{P(b|a) \cdot P(a)}{P(b)}$$

Bayes theorem

Conditional probability

Probability of **a** given **b**

$$P(a|b) = \frac{P(ab)}{P(b)}$$

Bayes theorem

Prem
$$P(ab) = P(b|a) \cdot P(a)$$

$$P(a|b) = \frac{P(ab)}{P(b)} = \frac{P(b|a) \cdot P(a)}{P(b)}$$

Marginalization

$$P(b) = \int_{a} P(b|a) \cdot P(a) da = E_{a \sim P(a)} P(b|a)$$

$$P(a|b) = \frac{P(b|a) \cdot P(a)}{P(b)} = \frac{P(b|a) \cdot P(a)}{\int P(b|a) \cdot P(a) da}$$

- Binary classification
- Data: X (objects) Y(answers)
- Model:

What parameters does logreg have?

- Binary classification
- Data: X (objects) Y(answers)
- Model:

$$\theta = [w_{\theta}, b_{\theta}]$$

How do we estimate $P(y|x,\theta)$?

- Binary classification
- Data: X (objects) Y(answers)
- Model:

$$\theta = [w_{\theta}, b_{\theta}]$$

$$P(y|x, \theta) = \sigma(w_{\theta} \cdot x + b_{\theta})$$

$$P(\bar{y}|x, \theta) = 1 - \sigma(w_{\theta} \cdot x + b_{\theta})$$

- Binary classification
- Data: X (objects) Y(answers)
- Model:

$$\theta = [w_{\theta}, b_{\theta}]$$

$$P(y|x, \theta) = \sigma(w_{\theta} \cdot x + b_{\theta})$$

$$P(\bar{y}|x, \theta) = 1 - \sigma(w_{\theta} \cdot x + b_{\theta})$$

Objective:

$$\theta' = \underset{\theta}{argmax} P(\theta|X,Y)$$

Frequentist Vs Bayesian



Objective:

$$\theta' = \underset{\theta}{argmax} P(\theta|X,Y)$$

$$P(\theta|X,Y) = \frac{P(X,Y|\theta) \cdot P(\theta)}{P(X,Y)}$$

Objective:

$$\begin{aligned} \theta' &= \underset{\theta}{\operatorname{argmax}} P\left(\theta|X,Y\right) \\ &P(Y|X,\theta) \cdot P(X|\theta) \\ P(\theta|X,Y) &= \frac{P(X,Y|\theta) \cdot P(\theta)}{P(X,Y)} \sim P(Y|X,\theta) \cdot P(\theta) \\ &\underset{\text{const(θ)}}{\operatorname{const(θ)}} \end{aligned}$$

Objective:

$$\theta' = \underset{\theta}{argmax} P(\theta|X,Y) = \underset{\theta}{argmax} P(Y|X,\theta) \cdot P(\theta)$$

Likelihood:

$$P(Y|X,\theta) = \prod_{i} P(y_{i}|x_{i},\theta)$$

Result:

$$\underset{\theta}{argmax} \prod_{i} P(y_{i}|x_{i},\theta) \cdot P(\theta)$$

Product of many <1 terms, Computationally unstable

Quiz: can we optimize something more stable?

Objective:

$$\theta' = \underset{\theta}{argmax} P(\theta|X,Y) = \underset{\theta}{argmax} P(Y|X,\theta) \cdot P(\theta)$$

$$arg_{\theta}^{max} \log \left[\prod_{i} P(y_{i}|x_{i},\theta) \cdot P(\theta) \right]$$

$$\underset{\theta}{argmax} \sum_{i} \log P(y_i|x_i,\theta) + \log P(\theta)$$

• Model:

$$P(y_i|x_i,\theta) = \inf_{if} y_i = 1, \sigma(w_{\theta} \cdot x + b_{\theta})$$
$$if y_i = 0, 1 - \sigma(w_{\theta} \cdot x + b_{\theta})$$

Model:

$$P(y_i|x_i,\theta) = \inf_{if} y_i = 1, \sigma(w_{\theta} \cdot x + b_{\theta})$$
$$if y_i = 0, 1 - \sigma(w_{\theta} \cdot x + b_{\theta})$$

$$\log P(y_i|x_i,\theta) = \inf_{if} y_i = 1, \log \sigma(w_\theta \cdot x + b_\theta)$$

$$if y_i = 0, \log(1 - \sigma(w_\theta \cdot x + b_\theta))$$

Replace if with multiplication

$$y_i \cdot \log \sigma(w_\theta \cdot x + b_\theta) + (1 - y_i) \cdot \log(1 - \sigma(w_\theta \cdot x + b_\theta))$$

Model:

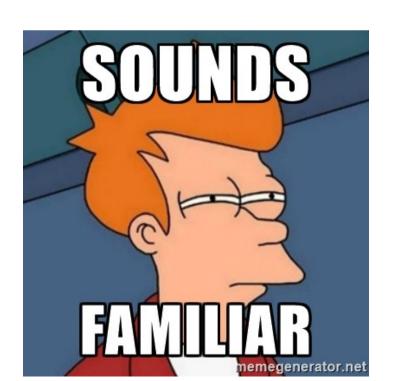
$$P(y_i|x_i,\theta) = if y_i = 1, \sigma(w_\theta \cdot x + b_\theta)$$

$$if y_i = 0, 1 - \sigma(w_\theta \cdot x + b_\theta)$$

$$\underset{\theta}{\operatorname{argmax}} \sum_{i} \log P(y_{i}|x_{i},\theta) + \log P(\theta)$$

- Assume uniform prior (const)
- Replace max(a) by min(-a)

$$-\sum_{i} P(y_{i}|x_{i},\theta) = y_{i} \cdot \sigma(w_{\theta} \cdot x + b_{\theta}) + (1 - y_{i}) \cdot (1 - \sigma(w_{\theta} \cdot x + b_{\theta}))$$



- Information about weights before observation
- Which of these weights you'd prefer?

First set of weights:

-0.554, 2.726, 0.999, 2.573, -0.694, 0.323, -1.903, -0.070

Second set of weights:

154016218671.074, 133023030621.400, 72847832520.938, 130909237163.079, -134435263422.709, 72550546946.769, 121468470400.514, -55724178429.301

Weights should be small,

$$P(0.1) > P(10^5)$$

Which distributions support that?

Weights should be small,

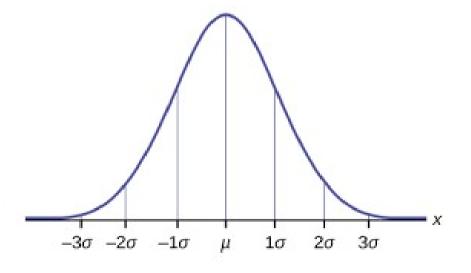
$$P(0.1) > P(10^5)$$

- Which distributions support that?
- Actually, all kinds of distributions, but we'll name a few...

Weights should be small,

$$P(0.1) > P(10^5)$$

- Which distributions support that?
- Normal



$$P(\theta) = \frac{1}{\sigma \cdot \sqrt{2\pi}} \cdot e^{\frac{-(\theta - \mu)^2}{\sigma^2}}$$

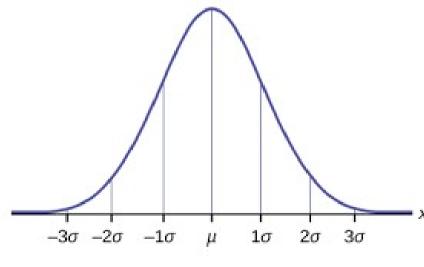
• Assumuing mean = 0

$$\log P(\theta) \sim \frac{-\theta^2}{\sigma^2}$$

Weights should be small,

$$P(0.1) > P(10^5)$$

- Which distributions support that?
- Normal

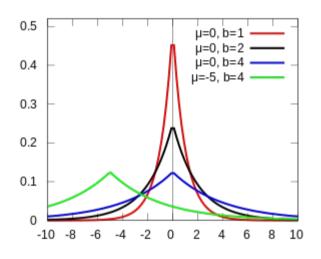


$$argmax \left[P(Y|X,\theta) + \frac{-1}{\sigma^2} \sum_{j} \theta_{j}^{2} \right]$$

$$\underset{\sigma}{argmin} \left[-P(Y|X,\theta) + \frac{1}{\sigma^2} \sum_{j} \theta_{j}^{2} \right]$$

Moar

Laplacian prior



$$P(\theta) = \frac{1}{2b} \cdot e^{\frac{-|\theta-\mu|}{b}}$$

• Guess the final term for loss...:)

Other: exponential for ensembling, mixtures, etc.

Linear regression

- Regression
- Predict P(y|x) with a gaussian
 - mean = wx+b
 - variance = 1

$$P(y_i|x,\theta) = \frac{1}{\sqrt{2\pi}} \cdot e^{-(y_i - [w_\theta \cdot x_i + b_\theta])^2}$$

$$\log P(y_i|x,\theta) = what ?$$

Linear regression

- Regression
- Predict P(y|x) with a gaussian
 - mean = wx+b
 - variance = 1

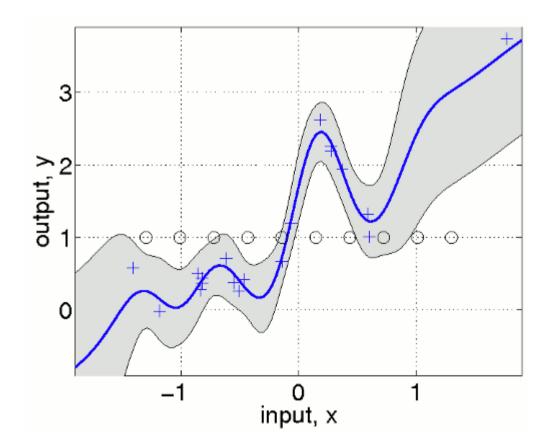
$$P(y_i|x,\theta) = \frac{1}{\sqrt{2\pi}} \cdot e^{-(y_i - [w_\theta \cdot x_i + b_\theta])^2}$$

$$\log P(Y|X,\theta) \sim -\sum_{i} (y_{i} - [w_{\theta} \cdot x_{i} + b_{\theta}])^{2}$$

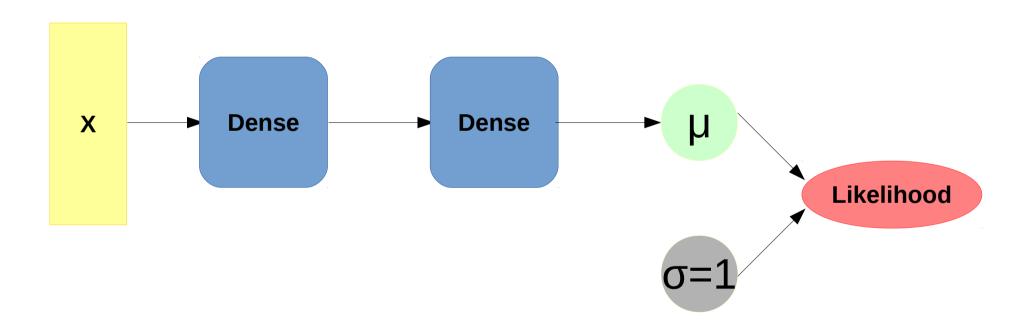
Hence, MSE

Why do we need certainty?

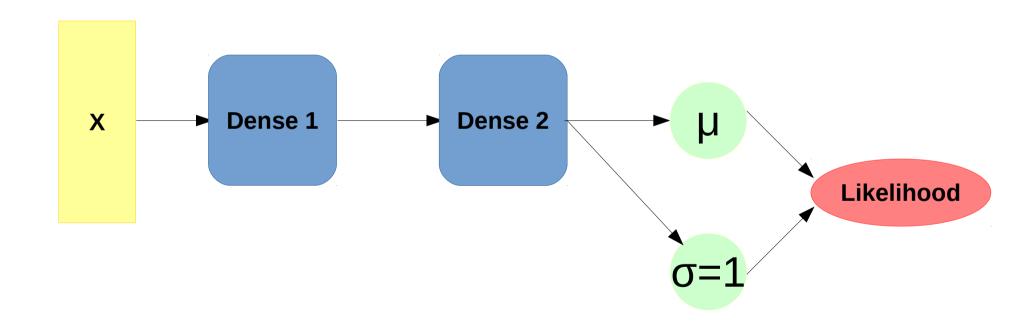
- To which extent do we trust our model?
- Sampling from generative models



• Before:

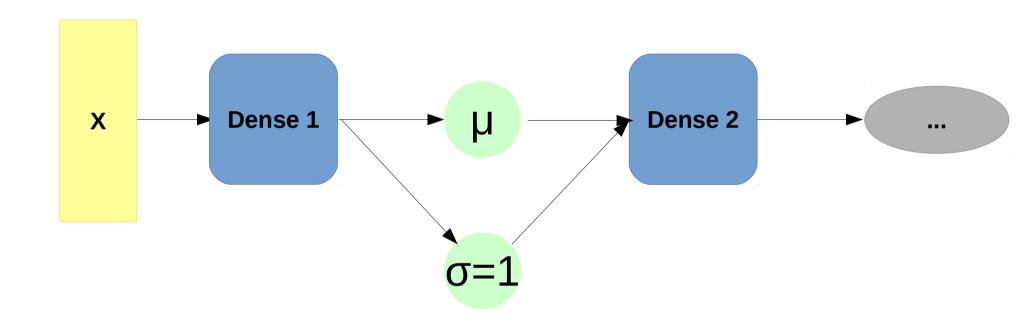


• After:



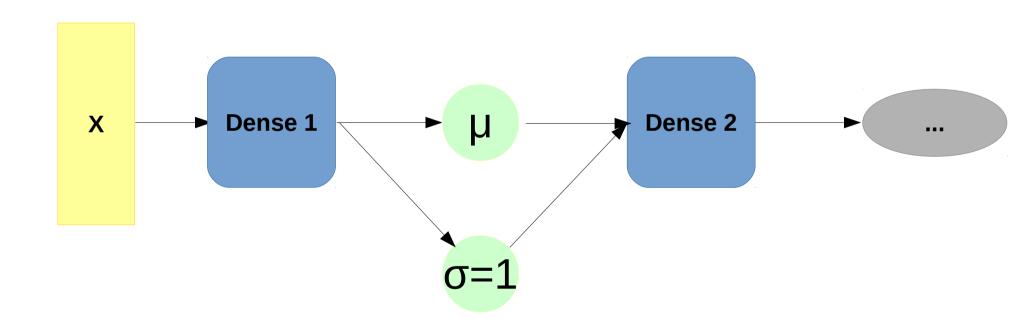
• Sigma = how certain are you?

Distribution on activations:



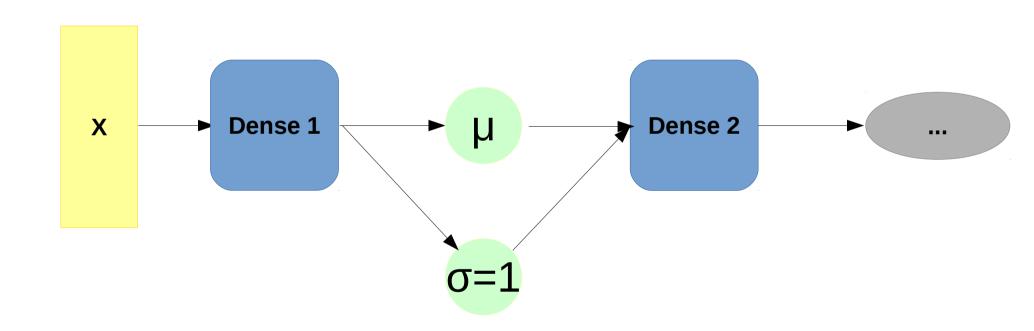
How do we train that thing?

Distribution on activations:



$$\log P(y|x,\theta) = E_{a \sim \mu(x), \sigma(x)} dense 2(a)$$

Distribution on activations:



$$\log P(y|x,\theta) = E_{a \sim \mu(x),\sigma(x)} dense 2(a)$$
weights

Reparameterization trick

• Idea:

Replace parameterized distribution with some expression over noise

$$N(\mu,\sigma)=\mu+\sigma\cdot N(0,1)$$

$$\frac{\delta[\mu + \sigma \cdot N(0,1)]}{\delta\mu, \delta\sigma} is okay$$

Works with many(but not all) distributions

How to train?

Reparameterization trick:

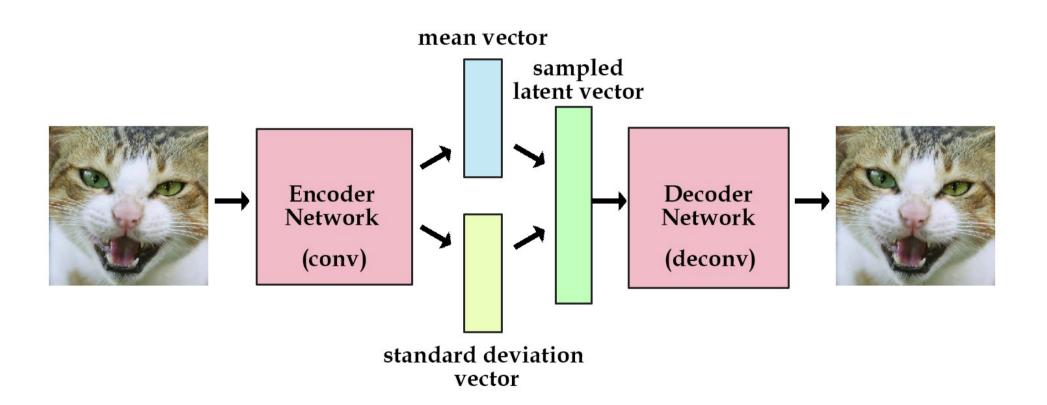
Was:

$$\log P(y|x,\theta) = E_{a \sim \mu(x),\sigma(x)} dense 2(a)$$

Now:

$$\log P(y|x,\theta) = E_{\xi \sim N(0,1)} dense 2 \left(\mu(x) + \sigma(x) \cdot \xi\right)$$

Seminar announcement



Seminar announcement

