

Research project report: Modelling MAPK/ERK pathway using Ordinary Differential Equations

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Abstract text

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Preface text

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1. Abstract

The MAPK/ERK pathway serves a key role in determining fate of a cell from extracellular inputs. Different cell fates are linked to a dynamics of the final node in the cascade, ERK kinases. To understand how different dynamic patterns of their behavior arise, we attempt to mechanistically model the simplified version of this pathway using Ordinary Differential Equations. Using data from a fibroblast cell transfected with optoRTK constructs and stimulated with various patterns of light, we attempted to estimate model parameters based on these experiments and use cross-validation techniques to check for generalization. Resulting fits had problems with achieving several performance metrics that would signify an optimal solution.

2. Introduction

TODO

3. Methods

3.1. Ordinary Differential Equations

Ordinary differential equations is a mathematical framework for describing the change of one variable (dependant variable, here Y) over another variable (independent variable, here X). Its simplest formulation is an expression that equates some mathematical expression to a derivative of our variable in question over the independent variable.

$$\frac{dY}{dX} = \dots \quad (1)$$

A solution to a differential equation is usually understood as obtaining a $Y(X)$ form, also called an *general solution*. General solutions can be obtained using an analytical solving process, the difficulty of which is heavily dependant on the specific problem being solved. An often encountered problem with analytical solution approach is a problem that contains complex, nonlinearly coupled equations, which do not yield easily to this method. An alternative approach to solving a system that has these characteristics is a numerical one. This method relies on a provided initial conditions and a ΔX -step resolution to simulate a single trajectory within an ODE system by evaluating the equations sequentially at a consecutive ΔX -steps away from the provided starting point. This method, while providing a weaker form of solution, can deal with harder problems, including those that describe complex, nonlinear systems.

3.2. Modeling & Simulation pipeline

Model definition was done in symbolic form using python and SymPy (TODO: reference them). A constructed model consists of a set of differential equations and current parameters. An interactive environment for simulating behavior of such models was constructed using marimo notebooks.

4. Results

5. Discussion

6. Conclusions

7. Future work

8. Supplementary material

Bibliography