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Notiztitel

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# K-Means-Clustering

Step 1: Determine the number of clusters  $k$ .

Step 2: Random choice of  $k$  different vectors  $\underline{v}_1, \underline{v}_2, \dots, \underline{v}_k$  and set these equal to the initial cluster centers  $\underline{u}_1, \underline{u}_2, \dots, \underline{u}_k$

Step 3: Choose a vector  $y(h)$  and calculate distance between  $y(h)$  and vectors  $\underline{u}_1, \dots, \underline{u}_k$ . Assign  $y(h)$  to cluster  $u^*$  with minimum distance and store  $y(h)$  in a list  $L_{u^*}$  for this cluster.

Step 4: Set  $h = h + 1$  and go back to Step 3, until all vectors have been processed. The  $k$  lists  $L_1 - L_k$  remain.

Step 5: Calculate new reference vectors  $\underline{L}_1 \sim \underline{L}_K$  for each cluster by calculating the mean vector for each list.

Step 6: Set  $h=0$  and go back to step 3 to start a new iteration. Altogether, 20-50 iterations are carried out.

Labelling of reference vectors

$\underline{L}_1 \dots \underline{L}_R$  according to the

available classes

- Collect a class-labeled data-
- perform another k-means base iteration with these vectors and assign corresponding lists  $\underline{L}_1 \dots \underline{L}_R$

Compute matrix  $P$  :

$$P = \begin{bmatrix} P(\underline{u}_1 / \Omega_1) & \dots & P(\underline{u}_k / \Omega_1) \\ P(\underline{u}_1 / \Omega_2) & & P(\underline{u}_k / \Omega_2) \\ \vdots & & \vdots \\ P(\underline{u}_1 / \Omega_n) & \dots & P(\underline{u}_k / \Omega_n) \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{\substack{\text{max} \\ \Omega_n}} \qquad \qquad \qquad \underbrace{\hspace{10em}}_{\substack{\text{max} \\ \Omega_n}}$

# Advantages:

- not chosen arbitrarily but by self-organizing principles
- they serve well for application of the KNN classification procedure
- they could be modified for other procedures, e.g. NN classification

## 3.2.3.2 Determination of parameters for decision functions

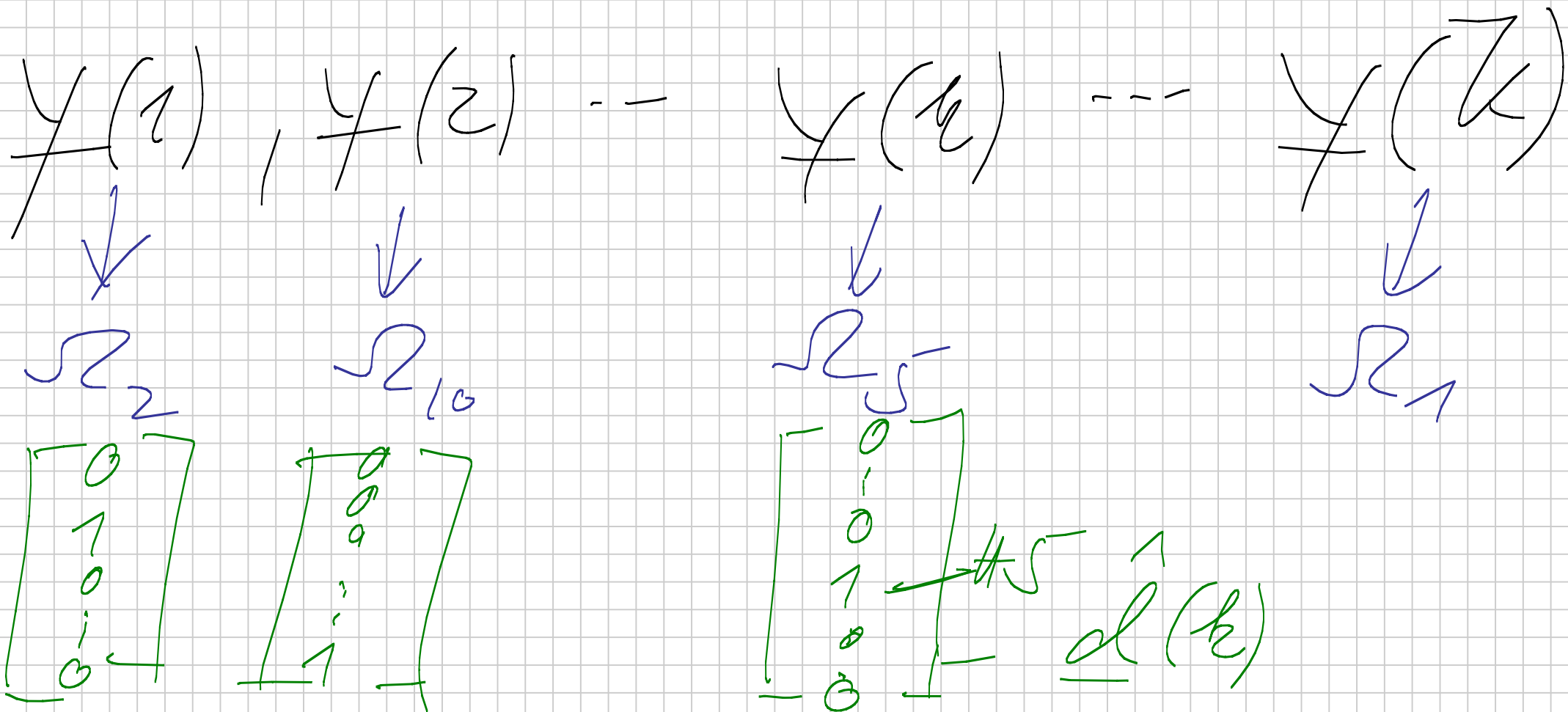
Recall procedure for decision functions:

$$\begin{bmatrix} \underline{L}_1^T \\ \underline{L}_2^T \\ \vdots \\ \underline{L}_M^T \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} = \begin{bmatrix} d_1 \\ \vdots \\ d_M \end{bmatrix} \rightarrow \text{MAX}$$

$\underline{W} \quad \underline{y} \quad = \quad \underline{d}$

parameters      unknown vector      decisions

Data collection:





Classification rule for training vector

$$y(k) : \underline{d}(k) = W \cdot y(k)$$

Classification error for  $k$ -th vector

$$y(k) : E(k) = \frac{1}{2} \sum_{i=1}^n \left[ \overline{d_i(k)} - d_i(k) \right]^2$$

For all presentations  
(entire data collection) :

$$E = \frac{1}{N} \sum_{h=1}^N E(h) = \frac{1}{2} \sum_{h=1}^N \left[ \sum_{i=1}^N d_i(h) - d_h(h) \right]$$

with  $d_i(h) = \sum_{j=1}^N w_{ij} y_j(h)$

Derivative of error  $E$  with respect to a weight  $w_{ij}$ :

$$\frac{\partial \mathcal{E}}{\partial \mathbf{z}_{ij}} = - \sum_{k=1}^K \left[ \overrightarrow{d_i(k)} - \overleftarrow{d_i(k)} \right] \frac{\partial d_i(k)}{\partial \mathbf{z}_{ij}}$$

$$= 0$$

$$= y_j(k)$$

$$\rightarrow \sum_{k=1}^K \left[ \overrightarrow{d_i(k)} - \overleftarrow{d_i(k)} \right] \cdot y_j(k) = 0$$

$$\sum_{k=1}^K \overrightarrow{d_i(k)} \cdot y_j(k) = \sum_{k=1}^K \overleftarrow{d_i(k)} \cdot y_j(k)$$

inserting  $\alpha_j(u)$  results in to

$$\frac{1}{K} \sum_{h=1}^K \alpha_h(u) \cdot y_j(h) = \frac{1}{K} \left[ \sum_{h=1}^K \alpha_h \cdot y_h(h) \right] \cdot y_j(h)$$

$$= \sum_{h=1}^K \alpha_h \cdot \frac{1}{K} \sum_{h=1}^K y_h(h) \cdot y_j(h)$$

$\Rightarrow$  On left side  $= X_{ij} = E\{d_{ij} \cdot y_j\}$

Right side

$$C_{hj} = E\{y_h \cdot y_j\}$$

$$\Rightarrow \cancel{K} \cdot X_{ij} = \cancel{K} \cdot \sum_{h=1}^N K_{ih} \cdot C_{hj}$$

Rewrite this equation in matrix notation:

notation:

$$X = W \cdot C$$

With  $X = E \left\{ \underline{d} \cdot \underline{y}^T \right\} = \frac{1}{K} \sum_{k=1}^K \underline{d}(k) \cdot \underline{y}^T(k)$

$$C = E \left\{ \underline{y} \cdot \underline{y}^T \right\} \stackrel{k=1}{=} \frac{1}{K} \sum_{k=1}^K \underline{y}(k) \cdot \underline{y}_k^T$$

$\Rightarrow h = X^T C^{-1}$

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