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Notiztitel

17.10.2008

Transformations of LDA

Generally : $\underline{X}' = \Phi \underline{X}$

What is the impact of such a transformation to matrices C_a and C_b ?

- class centers :

$$\underline{\mu}_h' = \phi' \cdot \underline{\mu}_h$$

- overall center : $\underline{\mu}' = \phi' \cdot \underline{\mu}$

- class - covariances :

$$C_h' = \phi' \cdot C_h \cdot \phi^T$$

Therefore, we can now easily derive the formulas for the matrices C_a'

and C_b' :

$$C_a' = E \{ C_h' \} = E \{ \phi \cdot C_h \cdot \phi^T \}$$

$$= \phi \cdot E \{ C_h \} \cdot \phi^T = \phi \cdot C_a \cdot \phi^T$$

$$\underbrace{\hspace{10em}}_{C_a}$$

$$C_b' = E \left\{ \left(\underline{m}_h' - \underline{m}' \right) \cdot \left(\underline{m}_h' - \underline{m}' \right)^T \right\}$$

$$= E \left\{ \phi (\underline{u}_h - \underline{u}) \cdot (\underline{u}_h - \underline{u})^T \phi^T \right\}$$

$$= \phi \underbrace{E \left\{ (\underline{u}_h - \underline{u}) \cdot (\underline{u}_h - \underline{u})^T \right\}}_{C_G} \phi^T$$

$$\Rightarrow C_G' = \phi \cdot C_G \cdot \phi^T$$

For the first transformation, we want to achieve the fact that

the new matrix C_a' should be transformed into the identity matrix I .

Because for orthogonal transformations, we have:

$$\begin{aligned}\phi \cdot I \cdot \phi^T &= \phi \cdot \phi^T \\ &= \phi \cdot \phi^{-1} = I\end{aligned}$$

Such a transformation can be realized with the following transformation matrix:

$$\Phi_a = L_a^{-1/2} U_a$$

Contains the
Eigenvalues of C_a
in diagonal form

Contains the
Eigenvectors of
 C_a

⇒ Now, the new matrix C_a' will be:

$$C_a' = \Phi_a C_a \Phi_a^T$$

$$= \begin{pmatrix} \Lambda_a^{-1/2} & U_a \end{pmatrix} \cdot C_a \begin{pmatrix} \Lambda_a^{-1/2} & U_a \end{pmatrix}^T$$

$$= \Lambda_a^{-1/2} U_a \cdot C_a \cdot U_a^T (\Lambda_a^{-1/2})^T$$

$$= \Lambda_a^{-1/2} \cdot \Lambda_a \cdot (\Lambda_a^{-1/2})^T = I$$

Now, we look for the 2nd transformation:

$$1) \quad X' = \Phi_a \cdot X$$

$$2) \quad X'' = \Phi_b \cdot X'$$

With $\Phi_b = U_b$

With U_b as matrix of the Eigen-
vectors derived from matrix C_b^1 .

For the matrix C_b'' we get then:

$$\begin{aligned} C_b'' &= \Phi_b \cdot C_b^1 \cdot \Phi_b^T \\ &= U_b \cdot C_b^1 \cdot U_b^T = \Lambda_b^1 \end{aligned}$$

Matrix of Eigenvalues
of matrix C_0

Summarization of LDA procedure :

- 1) Calculate matrices C_a and C_b from pattern vector $x(h)$, $h = 1, \dots, K$
- 2) Calculate the Eigenvalues and

Eigenvectors from matrix C_a .
Calculate the transformation
matrix $\phi_a = I_a^{-1/2} \cdot U_a$

3) Calculate matrix C_b' according

$$C_b' = \phi_a \cdot C_b \cdot \phi_a^T$$

4) Calculate Eigenvectors of C_b' ,

build matrix U_b from these
Eigenvectors, and set $\Phi_b = U_b$

5) Calculate the overall trans-
formation matrix =

$$\Phi = \Phi_b \cdot \Phi_a$$

\Rightarrow Now, all vectors a_i be

transformed according to

$$\underline{X''(h)} = \Phi \cdot \underline{X(h)}$$

resulting into a new vector space,
with "better" vectors $\underline{X''}$, having
the following features:

- average covariance matrix: $\underline{C_a''} = \underline{I}$

- Scattering matrix $G_b'' = I_b'$

3. Pattern Classification

major notations:

$X(b)$: original vectors

b : running index

$\mathbf{y}(h)$ = pre-processed vectors
(optimized, dimension N)

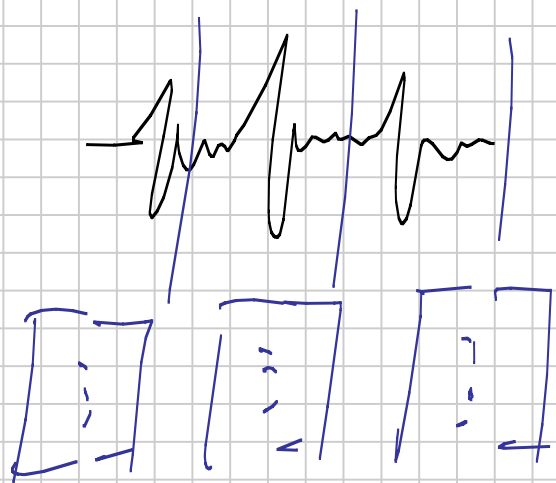
$$\Omega = \{\Omega_1, \Omega_2, \dots, \Omega_M\}$$

$\Rightarrow M$ different pattern classes

Distinction between numerical and
syntactical classification:

Example: speed recognition

Load 1



/a/s/o/

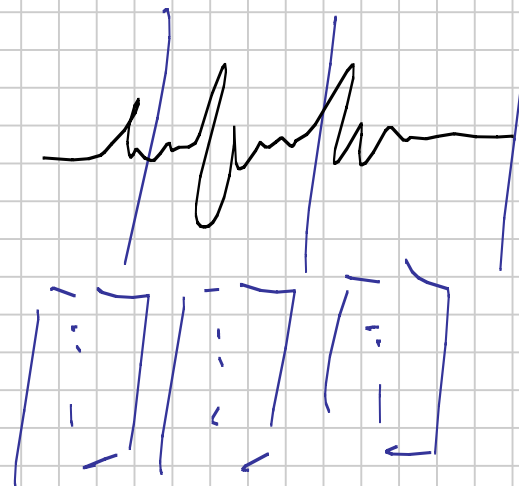
heuristic



Comparison

syntactical
(symbolic)
Comparison

Load 2

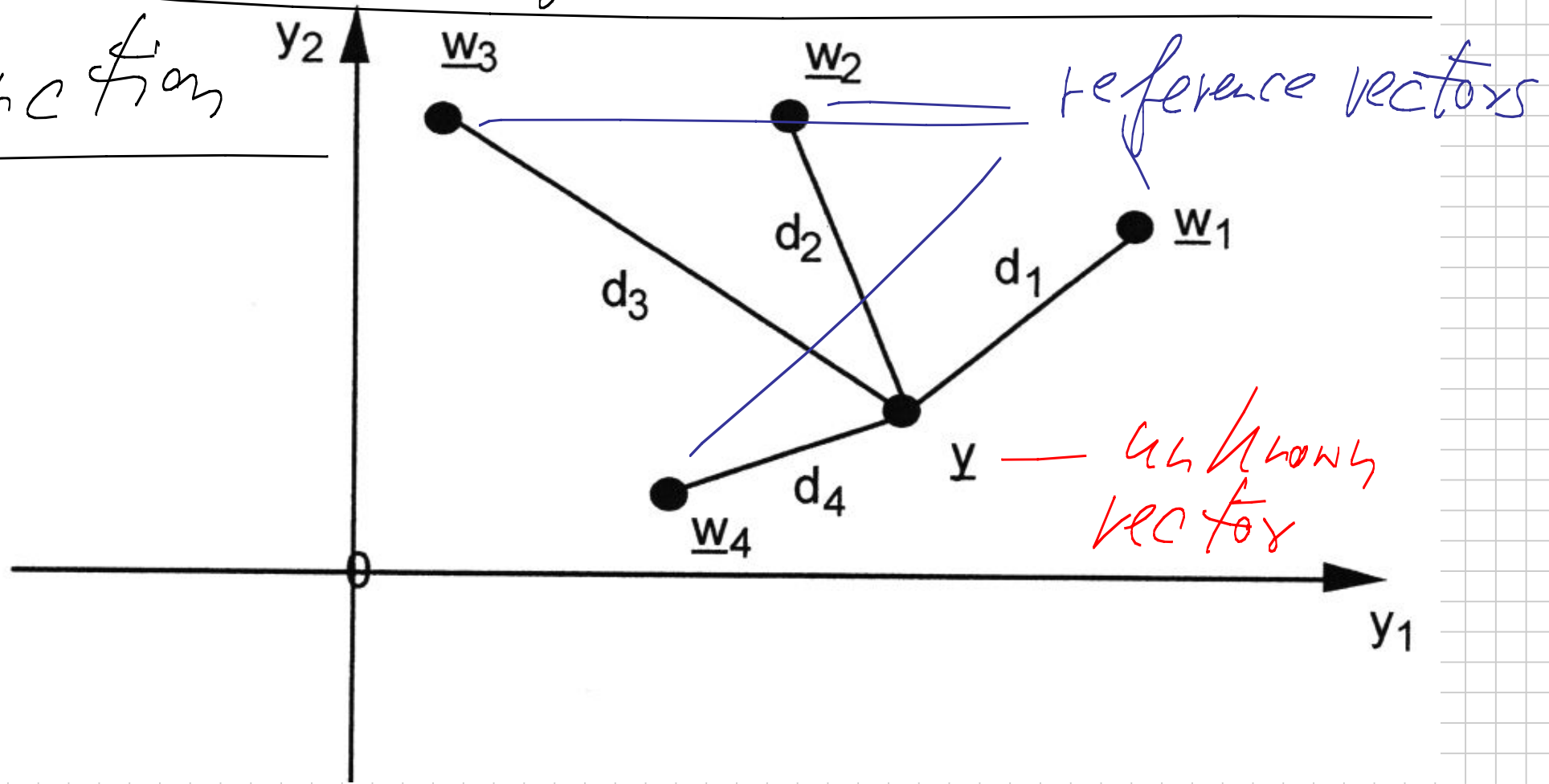


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3.2 Numerical Classification methods

3.2.1 Classification with distance

function



⇒ find similarity measures
between y and reference vectors
 \underline{w}_m

3.2.1.1 Distance measures

⇒ most insightful approach:
Euclidean distance between
 y and \underline{w}_m

$$d(\underline{X}, \underline{Y}) = \sqrt{\sum_{i=1}^N (\underline{X}_i - \underline{Y}_i)^2}$$

or an equivalent distance
measure

$$d(\underline{X}, \underline{Y}) = \sum_{i=1}^N (\underline{X}_i - \underline{Y}_i)^2$$

$$= (\underline{X} - \underline{Y})^T \cdot (\underline{X} - \underline{Y})$$

possible alternatives:

$$d(\underline{x}, \underline{y}) = \sum_{i=1}^N |x_i - y_i|$$

(Manhattan distance)

(city block distance)

another possibility:

$$d(\underline{x}, \underline{y}) = \sum_{i=1}^N (x_i - y_i)^2$$