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Moves

Rotate

1. Rotation more accurate than seconds and degree.
2. The motor for this robot is good, but connection with tire is not very smooth, and also the motor cannot calculate resistance.

I think this robot need more input or sensors to help it. The hardware for this robot is very powerful; it can run fast and stop immediately, and calculate the rotation for run is accurate without any resistance.

Maybe this robot too old, because it will pause when run to next step, and also don’t support a lot of logic things.

I believe this robot can do lot of things, we just start play it, so a lot functions don’t use it, and those kinds of functions may can improve accuracy.