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import numpy as np
from scipy.integrate import quad
import matplotlib.pyplot as plt
def Exp(x):
    return np.exp(x)
def Sin(x):
   return np.sin(x)
def integrand(x, f, i):
   return f(x) * np.power(x, i)
def interpolate(func, n):
    x1 = np.arange(0, n+1)
   x2 = (np.arange(0, n+1)).reshape(-1, 1)
   A = 1/(x1 + x2 + 1)
   b = np.array([quad(integrand, 0, 1, args=(func, i))[0] for i in range(n+1)])
    cis = np.linalg.solve(A, b)
   return cis
def pnOutput(coff, inputx):
   pw = np.arange(coff.shape[0])
    mid = np.power(inputx.reshape(-1, 1), pw)
    return mid @ coff
def getOutput(func, n, funcName="GroundTruth", savefig=False):
    coff = interpolate(func, n)
    inputx = np.arange(0, 10, 0.2)
    outputy = pnOutput(coff, inputx)
    groundTruth = func(inputx)
    error = np.abs(groundTruth - outputy)
    errorNorm = np.linalg.norm(error)
   plt.plot(inputx, outputy, label=f"approximation order {n}", color="red")
   plt.plot(inputx, groundTruth, label=f"{funcName}", color="blue")
   plt.title(f"n = {n}, error = {errorNorm}")
   plt.legend()
   if savefig:
        plt.savefig(f"hw6q2 {funcName} order{n}.jpg")
   plt.show()
def getError(func, n):
   coff = interpolate(func, n)
    inputx = np.arange(0, 1, 0.02)
    outputy = pnOutput(coff, inputx)
    groundTruth = func(inputx)
    error = np.abs(groundTruth - outputy)
   errorNorm = np.linalg.norm(error)
    # plt.plot(inputx, outputy, label=f"approximation order {n}", color="red")
    # plt.plot(inputx, groundTruth, label=f"groundTruth", color="blue")
    # plt.title(f"n = {n}, error = {errorNorm}")
    # plt.legend()
    # plt.show()
    return errorNorm
def hw6q2():
    n = np.arange(30)
    sinError = np.array([getError(Sin, i) for i in n])
    expError = np.array([getError(Exp, i) for i in n])
    plt.plot(n, sinError, label = "SinError", color="red")
   plt.plot(n, expError, label = "ExpError", color="blue")
    plt.legend()
   plt.xlabel("Order")
   plt.ylabel("Error")
   plt.title("Error Map")
   plt.savefig("hw6q2.jpg")
```

plt.show()

hw6q2()