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# O PyTorch

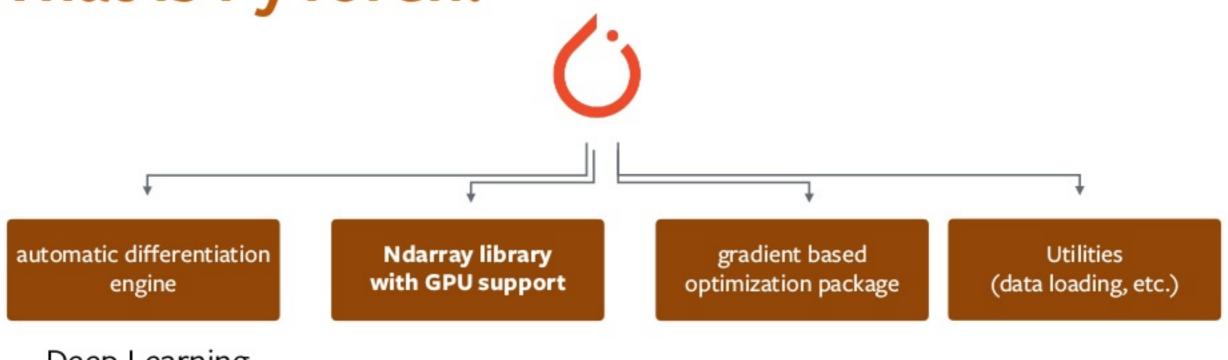
an ecosystem for deep learning

Soumith Chintala

Facebook Al



## What is PyTorch?



Deep Learning

Reinforcement Learning

Numpy-alternative



## ndarray library

- •np.ndarray <-> torch.Tensor
- •200+ operations, similar to numpy
- very fast acceleration on NVIDIA GPUs



```
# -*- coding: utf-8 -*-
import numpy as np
# N is batch size; D_in is input dimension;
# H is hidden dimension; D out is output dimension.
N, D_in, H, D_out = 64, 1000, 100, 10
# Create random input and output data
x = np.random.randn(N, D in)
y = np.random.randn(N, D out)
# Randomly initialize weights
w1 = np.random.randn(D_in, H)
                                             Numpy
w2 = np.random,randn(H, D out)
learning rate = 1e-6
for t in range (500):
    # Forward pass: compute predicted y
    h = x.dot(w1)
    h relu = np.maximum(h, 0)
   y pred = h relu.dot(w2)
    # Compute and print loss
    loss = np.square(y_pred - y).sum()
    print(t, loss)
    # Backprop to compute gradients of w1 and w2 with respect to loss
    grad\ y\ pred = 2.0\ *\ (y\ pred - y)
    grad_w2 = h_relu.T.dot(grad_y_pred)
    grad_h_relu = grad_y_pred.dot(w2.T)
    grad_h = grad_h_relu.copy()
    grad_h[h < 0] = 0
    grad w1 = x.T.dot(grad h)
    # Update weights
    w1 -= learning rate * grad w1
    w2 -= learning rate * grad w2
```

```
import torch
dtype = torch.FloatTensor
# dtype = torch.cuda.FloatTensor # Uncomment this to run on GPU
# N is batch size; D in is input dimension;
# H is hidden dimension; D out is output dimension.
N, D_in, H, D_out = 64, 1000, 100, 10
# Create random input and output data
x = torch.randn(N, D_in).type(dtype)
y = torch.randn(N, D_out).type(dtype)
                                              PyTorch
# Randomly initialize weights
w1 = torch, randn(D_in, H), type(dtype)
w2 = torch.randn(H, D_out).type(dtype)
learning rate = 1e-6
for t in range (500):
    # Forward pass: compute predicted y
    h = x.mm(w1)
   h_relu = h.clamp(min=0)
   y_pred = h_relu, mm(w2)
    # Compute and print loss
    loss = (y_pred - y).pow(2).sum()
    print(t, loss)
    # Backprop to compute gradients of w1 and w2 with respect to loss
    grad_y_pred = 2.0 * (y_pred - y)
    grad_w2 = h_relu.t().mm(grad_y_pred)
    grad h relu = grad y pred.mm(w2.t())
    grad_h = grad_h_relu.clone()
    grad h[h < 0] = 0
    grad w1 = x.t().mm(grad h)
    # Update weights using gradient descent
    w1 -= learning rate * grad w1
    w2 -= learning_rate * grad_w2
```

Tensors are similar to numpy's ndarrays, with the addition being that Tensors can also be used on a GPU to accelerate computing.

```
from __future__ import print_function
import torch
```

Construct a 5x3 matrix, uninitialized:

```
x = torch.Tensor(5, 3)
print(x)
```

#### Out:

```
1.00000e-25 *
0.4136 0.0000 0.0000
0.0000 1.6519 0.0000
1.6518 0.0000 1.6519
0.0000 1.6518 0.0000
1.6520 0.0000 1.6519
[torch,FloatTensor of size 5x3]
```



Construct a randomly initialized matrix

```
x = torch.rand(5, 3)
print(x)

Out:
0.2598  0.7231  0.8534
  0.3928  0.1244  0.5110
  0.5476  0.2700  0.5856
  0.7288  0.9455  0.8749
  0.6663  0.8230  0.2713
[torch.FloatTensor of size 5x3]
```

#### Get its size

```
print(x.size())

Out: torch.Size([5, 3])
```



You can use standard numpy-like indexing with all bells and whistles!

```
print(x[:, 1])

Out:
0.7231
0.1244
0.2700
0.9455
0.8230
[torch.FloatTensor of size 5]
```



```
y = torch.rand(5, 3)
print(x + y)
```

#### Out:

```
0.7931 1.1872 1.6143

1.1946 0.4669 0.9639

0.7576 0.8136 1.1897

0.7431 1.8579 1.3400

0.8188 1.1041 0.8914

[torch.FloatTensor of size 5x3]
```



Out:

[ 1. 1. 1. 1. 1.]

#### Converting torch Tensor to numpy Array

```
a = torch.ones(5)
 print(a)
Out:
      [torch.FloatTensor of size 5]
 b = a.numpy()
 print(b)
```



#### Converting torch Tensor to numpy Array

```
a = torch.ones(5)
print(a)
```

#### Out:

```
Zero memory-copy

very efficient

[torch.FloatTensor of size 5]
```

```
b = a.numpy()
print(b)
```

```
Out:
```

```
[ 1. 1. 1. 1. 1.]
```



See how the numpy array changed in value.

```
a.add_(1)
print(a)
print(b)
```

```
Out: 2 2 2 2 2 2 2 2 [torch.FloatTensor of size 5] [ 2. 2. 2. 2. 2.]
```



#### Converting numpy Array to torch Tensor

See how changing the np array changed the torch Tensor automatically

```
import numpy as np
a = np.ones(5)
b = torch.from_numpy(a)
np.add(a, 1, out=a)
print(a)
print(b)
```

```
Out: [ 2. 2. 2. 2. 2.]

2
2
2
2
[torch.DoubleTensor of size 5]
```

All the Tensors on the CPU except a CharTensor support converting to NumPy and back.



#### **Seamless GPU Tensors**

#### **CUDA Tensors** %

Tensors can be moved onto GPU using the .cuda function.

```
# let us run this cell only if CUDA is available
if torch.cuda.is_available():
    x = x.cuda()
    y = y.cuda()
    x + y
```



#### **Neural Networks**

```
class Net(nn.Module):
         def __init__(self):
             super(Net, self).__init__()
             self.conv1 = nn.Conv2d(1, 10, kernel_size=5)
 4
             self.conv2 = nn.Conv2d(10, 20, kernel_size=5)
 6
             self.conv2_drop = nn.Dropout2d()
             self.fc1 = nn.Linear(320, 50)
 8
             self.fc2 = nn.Linear(50, 10)
 9
10
        def forward(self, x):
11
             x = F.relu(F.max_pool2d(self.conv1(x), 2))
12
             x = F.relu(F.max_pool2d(self.conv2_drop(self.conv2(x)), 2))
13
             x = x.view(-1, 320)
            x = F.relu(self.fc1(x))
14
             x = F.dropout(x, training=self.training)
15
            x = self.fc2(x)
16
17
             return F.log_softmax(x)
18
    model = Net()
19
    input = Variable(torch.randn(10, 20))
20
    output = model(input)
```

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13
             x = x.view(-1, 320)
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15
             x = F.dropout(x, training=self.training)
16
             x = self.fc2(x)
             return F.log_softmax(x)
17
18
    model = Net()
19
     input = Variable(torch.randn(10, 20))
    output = model(input)
```

### Optimization package

SGD, Adagrad, RMSProp, LBFGS, etc.

```
net = Net()
optimizer = torch.optim.SGD(net.parameters(), lr=0.01, momentum=0.9)

for input, target in dataset:
    optimizer.zero_grad()
    output = model(input)
    loss = F.cross_entropy(output, target)
    loss.backward()
    optimizer.step()
```

### **Distributed PyTorch**

- MPI style distributed communication
- Broadcast Tensors to other nodes
- Reduce Tensors among nodes
  - for example: sum gradients among all nodes



#### **Distributed Data Parallel**

```
for epoch in range(max_epochs):
    for data, target in enumerate(training_data):
        output = model(data)
        loss = F.nll_loss(output, target)
        loss.backward()
        optimizer.step()
```



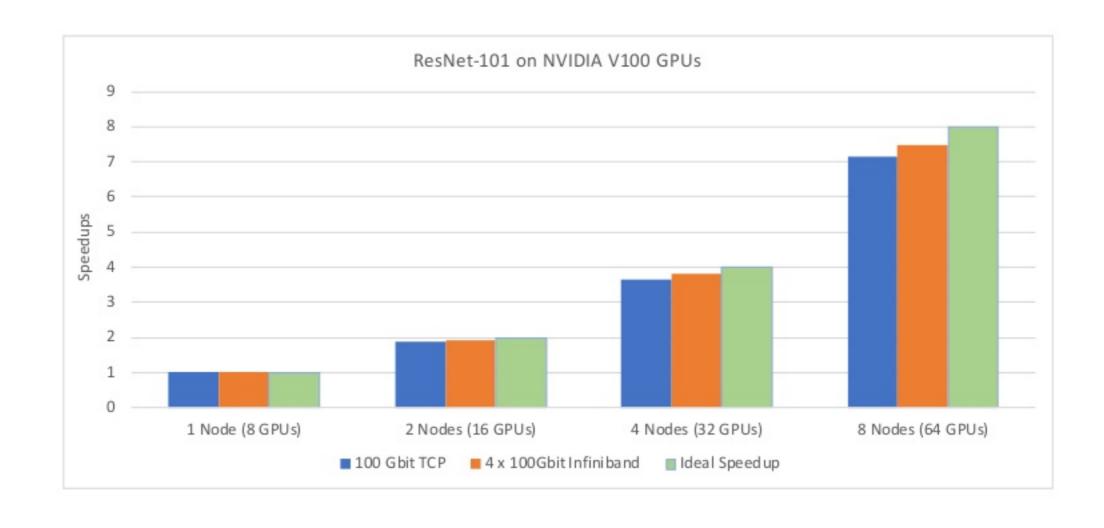
#### **Distributed Data Parallel**

```
for epoch in range(max_epochs):
    for data, target in enumerate(training_data):
        output = model(data)
        model = nn.DistributedDataParallel(model)
        loss = F.nll_loss(output, target)
        loss.backward()
        optimizer.step()
```





#### Distributed Training Performance - ResNet101



#### Use via DataBricks MLFlow

- mlflow.pytorch
  - saves and loads models
- More resources:
- https://docs.databricks.com/spark/latest/mllib/mlflow-pytorch.html
- https://www.mlflow.org/docs/latest/models.html



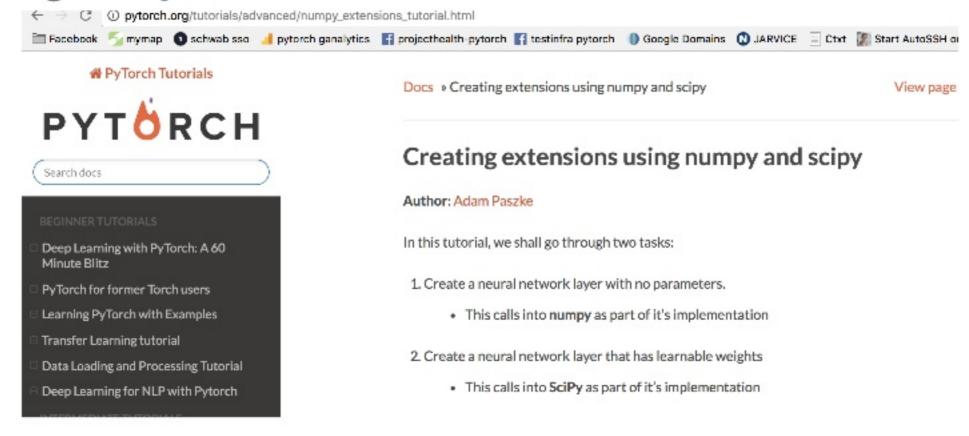
Use the entire Python ecosystem at your will



- Use the entire Python ecosystem at your will
- Including SciPy, Scikit-Learn, etc.



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· A shared model-zoo:

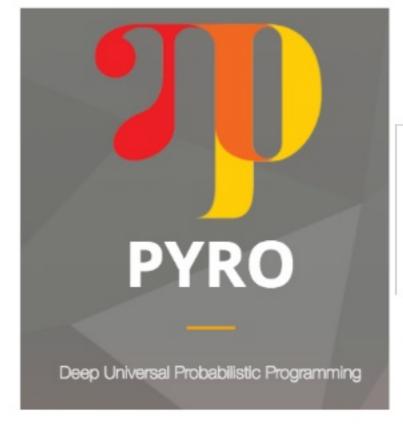
We provide pre-trained models for the ResNet variants and AlexNet, using the PyTorch

```
torch.utils.model_zoo .These can constructed by passing pretrained=True:
```

```
import torchvision.models as models
resnet18 = models.resnet18(pretrained=True)
alexnet = models.alexnet(pretrained=True)
```



Probabilistic Programming





github.com/probtorch/probtorch

http://pyro.ai/



#### Gaussian Processes

#### GPyTorch (Alpha Relase)

build passing

GPyTorch is a Gaussian Process library, implemented using PyTorch. It is designed for creating flexible and modular Gaussian Process models with ease, so that you don't have to be an expert to use GPs.

This package is currently under development, and is likely to change. Some things you can do right now:

- Simple GP regression (example here)
- Simple GP classification (example here)
- · Multitask GP regression (example here)
- . Scalable GP regression using kernel interpolation (example here)
- Scalable GP classification using kernel interpolation (example here)
- Deep kernel learning (example here)
- And (more!)



#### Machine Translation

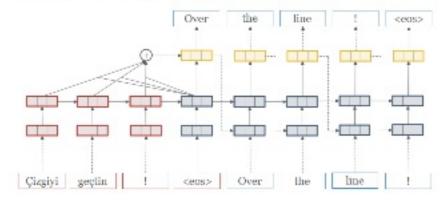
#### OpenNMT-py: Open-Source Neural Machine Translation

build pessing

This is a Pytorch port of OpenNMT, an open-source (MLT) neural machine translation system. It is designed to be research triangly to try out new ideas in translation, summary, image-to-text, morphology, and many other domains.

Codebase is relatively stable, but Pylorch is still evolving. We currently recommend torking it you need to have stable code

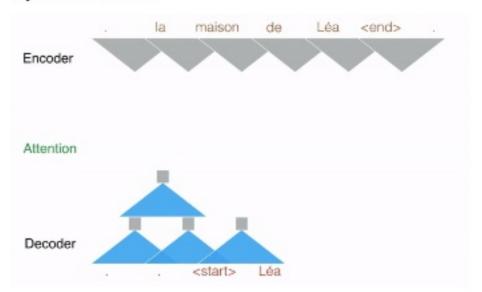
OpenNMT-py is run as a collaborative open-source project. It is maintained by Sasha Rush (Cambridge, MA), Ben Peters (Searbrücken), and Jianyu Zhan (Shenzhen). The original code was written by Adam Lerer (NYC). We love contributions. Please consult the Issues page for any Contributions Welcome tagged post.



https://github.com/OpenNMT/OpenNMT-py

FAIR Sequence-to-Sequence Toolkit (PyTorch)

This is a PyTorch version of fairseq, a sequence-to-sequence learning toolkit from Facebook AI Research. The original authors of this reimplementation are (in no particular order) Sergey Edunov, Myle Ott, and Sam Gross. The toolkit implements the fully convolutional model described in Convolutional Sequence to Sequence Learning and features multi-GPU training on a single machine as well as fast beam search generation on both CPU and GPU. We provide pre-trained models for English to French and English to German translation.

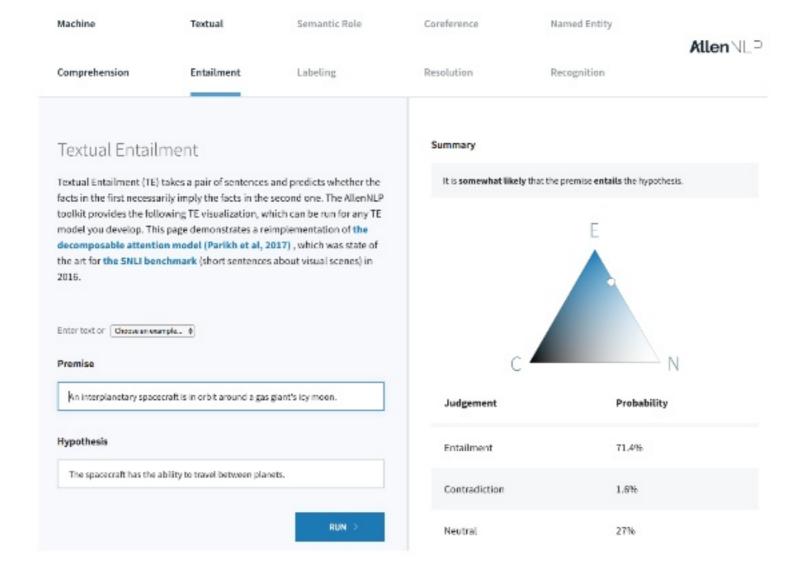


https://github.com/facebookresearch/fairseq-py



#### •AllenNLP

#### http://allennlp.org/





- AllenNLP http://allennlp.org/
- State-of-the-art models for comprehension, Q&A, various other NLP tasks



AllenNLP

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#### Passage

used in any situation and for any purpose, but today many are used in dangerous environments (including bomb detection and de-activation), manufacturing processes, or where humans cannot survive. Robots can take on any form but some are made to resemble humans in appearance. This is said to help in the acceptance of a robot in certain replicative behaviors usually performed by people. Such robots attempt to replicate walking, lifting, speech, cognition, and basically anything a human can do.

#### Question

What do robots that resemble humans attempt to do?



- AllenNLP
- State-of-the-art m various other NLP

http://allennlp.org/

#### Answer

replicate walking, lifting, speech, cognition

, Q&A,

#### Passage Context

Robotics is an interdisciplinary branch of engineering and science that includes mechanical engineering, electrical engineering, computer science, and others. Robotics deals with the design, construction, operation, and use of robots, as well as computer systems for their control, sensory feedback, and information processing. These technologies are used to develop machines that can substitute for humans. Robots can be used in any situation and for any purpose, but today many are used in dangerous environments (including bomb detection and de-activation), manufacturing processes, or where humans cannot survive. Robots can take on any form but some are made to resemble humans in appearance. This is said to help in the acceptance of a robot in certain replicative behaviors usually performed by people. Such robots attempt to replicate walking, lifting, speech, cognition, and basically anything a human can do.



• High-level library on PyTorch: <a href="http://docs.fast.ai">http://docs.fast.ai</a>



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- Read more at http://www.fast.ai/2018/10/02/fastai-ai/



state-of-the-art models in few lines



- state-of-the-art models in few lines
- fine-tune on your own data



- state-of-the-art models in few lines
- fine-tune on your own data

#### Near State-of-the-art Image Classifiers

```
data = data_from_imagefolder(Path('data/dogscats'),
         ds_tfms=get_transforms(), tfms=imagenet_norm, size=224)
learn = ConvLearner(data, tvm.resnet34, metrics=accuracy)
learn.fit_one_cycle(6)
learn.unfreeze()
learn.fit_one_cycle(4, slice(1e-5,3e-4))
```



- state-of-the-art models in few lines
- fine-tune on your own data

#### Models and Transforms for Tabular Data

class TabularModel

```
TabularModel ( emb_szs : ListSizes , n_cont : int , out_sz : int ,
layers : Collection [ int ] , ps : Collection [ float ] = None , emb_drop : float = 0.0 ,
y_range : OptRange = None , use_bn : bool = True ) :: Module [source]
```



#### With **v** from































