

viRUs

Team Reference Document

20/12/2015

CONTENTS

1.	Code Templates	2	4.8.	Hashing	18
1.1.	Basic Configuration	2	5.	Mathematics	18
1.2.	C++ Header	2	5.1.	Fraction	18
1.3.	Java Template	2	5.2.	Big Integer	19
2.	Data Structures	2	5.3.	Binomial Coefficients	20
2.1.	Union-Find	2	5.4.	Euclidean algorithm	21
2.2.	Segment Tree	2	5.5.	Trial Division Primality Testing	21
2.3.	Fenwick Tree	3	5.6.	Miller-Rabin Primality Test	21
2.4.	Matrix	3	5.7.	Pollard's ρ algorithm	21
2.5.	AVL Tree	4	5.8.	Sieve of Eratosthenes	21
2.6.	Cartesian Tree	5	5.9.	Divisor Sieve	21
2.7.	Heap	6	5.10.	Modular Exponentiation	22
2.8.	Dancing Links	6	5.11.	Modular Multiplicative Inverse	22
2.9.	Misof Tree	6	5.12.	Primitive Root	22
2.10.	k -d Tree	7	5.13.	Chinese Remainder Theorem	22
2.11.	Sqrt Decomposition	8	5.14.	Linear Congruence Solver	22
2.12.	Monotonic Queue	8	5.15.	Tonelli-Shanks algorithm	22
2.13.	Convex Hull Trick	8	5.16.	Numeric Integration	22
3.	Graphs	8	5.17.	Fast Fourier Transform	22
3.1.	Single-Source Shortest Paths	8	5.18.	Number-Theoretic Transform	23
3.2.	All-Pairs Shortest Paths	9	5.19.	Tridiagonal Matrix Algorithm	23
3.3.	Strongly Connected Components	9	5.20.	Mertens Function	24
3.4.	Cut Points and Bridges	10	5.21.	Summatory Phi	24
3.5.	Minimum Spanning Tree	10	5.22.	Numbers and Sequences	24
3.6.	Topological Sort	10	6.	Geometry	24
3.7.	Euler Path	10	6.1.	Primitives	24
3.8.	Bipartite Matching	11	6.2.	Lines	24
3.9.	Maximum Flow	11	6.3.	Circles	25
3.10.	Minimum Cost Maximum Flow	12	6.4.	Polygon	25
3.11.	All Pairs Maximum Flow	14	6.5.	Convex Hull	25
3.12.	Heavy-Light Decomposition	14	6.6.	Line Segment Intersection	26
3.13.	Centroid Decomposition	15	6.7.	Great-Circle Distance	26
3.14.	Least Common Ancestors, Binary Jumping	15	6.8.	Triangle Circumcenter	26
3.15.	Tarjan's Off-line Lowest Common Ancestors Algorithm	15	6.9.	Closest Pair of Points	26
3.16.	Maximum Density Subgraph	15	6.10.	3D Primitives	26
3.17.	Maximum Weighted Independent Set in a Bipartite Graph	16	6.11.	Polygon Centroid	27
4.	Strings	16	6.12.	Rotating Calipers	27
4.1.	The Knuth-Morris-Pratt algorithm	16	6.13.	Formulas	28
4.2.	The Z algorithm	16	7.	Other Algorithms	28
4.3.	Trie	16	7.1.	2SAT	28
4.4.	Suffix Array	17	7.2.	Stable Marriage	28
4.5.	Aho-Corasick Algorithm	17	7.3.	Algorithm X	28
4.6.	eerTree	17	7.4.	n th Permutation	29
4.7.	Suffix Automaton	18	7.5.	Cycle-Finding	29
			7.6.	Dates	29
			7.7.	Simulated Annealing	30
			7.8.	Fast Input Reading	30
			7.9.	128-bit Integer	30
			7.10.	Bit Hacks	30
			7.11.	The Twelfefold Way	31
			8.	Useful Information	32

Reykjavík University2

9.	Misc	32
9.1.	Debugging Tips	32
9.2.	Solution Ideas	32
10.	Formulas	33
10.1.	Markov Chains	33
10.2.	Burnside’s Lemma	33
10.3.	Bézout’s identity	33
10.4.	Misc	33
	Practice Contest Checklist	34

1. CODE TEMPLATES

1.1. Basic Configuration.

1.1.1. .bashrc.

```
xset r rate 150 100-----// dd
set -o vi-----// f4
-----// 08
function check {-----// f6
---IFS=-----// 17
---s=""-----// 22
---cat $1 | while read l; do-----// 81
-----s="$s$(echo $l | sed 's/\s//g')\n"-----// d0
-----h=$(echo -ne "$s" | md5sum)-----// 27
-----echo "${h:0:2} $l"-----// 1b
---done-----// aa
}-----// a7
# setxkbmap -option caps:escape dvorak is-----// 18
# setxkbmap en_US-----// 97
alias c='cd'-----// 7e
alias l='ls -lh'-----// 36
alias la='ls -lah'-----// 7c
```

ProTip™: setxkbmap dvorak on qwerty: o.yqtxmal ekrpat

1.1.2. .vimrc.

```
set nosp et sw=4 ts=4 sts=4 si cindent hi=1000 nu ru noeb showcmd showmode-----// bb
syn on | colorscheme slate-----// e5
```

1.2. C++ Header. A C++ header.

```
#include <bits/stdc++.h>-----// 84
using namespace std;-----// 16
template <class T> int size(const T &x) { return x.size(); }-----// 5f
#define rep(i,a,b) for (__typeof(a) i=(a); i<(b); ++i)-----// 6c
#define iter(it,c) for (__typeof((c).begin()) it = (c).begin(); it != (c).end(); ++it)
typedef pair<int, int> ii;-----// 44
typedef vector<int> vi;-----// 9d
typedef vector<ii> vii;-----// eb
typedef long long ll;-----// 47
const int INF = ~(1<<31); // 2147483647-----// 10
-----// b2
const double EPS = 1e-9;-----// d5
const double pi = acos(-1);-----// 67
typedef unsigned long long ull;-----// ff
typedef vector<vi> vvi;-----// 4b
typedef vector<vii> vvii;-----// 36
template <class T> T smod(T a, T b) { return (a % b + b) % b; }-----// ea
```

1.3. Java Template. A Java template.

```
import java.util.*;-----// 37
import java.math.*;-----// 89
import java.io.*;-----// 28
-----// a3
public class Main {-----// 17
```

```
----public static void main(String[] args) throws Exception {-----// 02
-----Scanner in = new Scanner(System.in);-----// ef
-----PrintWriter out = new PrintWriter(System.out, false);-----// 62
-----// code-----// e6
-----out.flush();-----// 56
----}-----// 79
}-----// 00
```

2. DATA STRUCTURES

2.1. Union-Find. An implementation of the Union-Find disjoint sets data structure.

```
struct union_find {-----// 42
---vi p; union_find(int n) : p(n, -1) { }-----// 28
---int find(int x) { return p[x] < 0 ? x : p[x] = find(p[x]); }-----// ba
---bool unite(int x, int y) {-----// 6c
---int xp = find(x), yp = find(y);-----// 64
---if (xp == yp) return false;-----// 0b
---if (p[xp] > p[yp]) swap(xp,yp);-----// 78
---p[xp] += p[yp], p[yp] = xp;-----// 88
---return true; }-----// 1f
---int size(int x){ return -p[find(x)]; } }-----// b9
```

2.2. Segment Tree. An implementation of a Segment Tree.

```
#ifdef SEG_MIN-----// 03
const int ID = INF;-----// 56
int f(int a, int b) { return min(a, b); }-----// 4f
#else-----// 0e
const int ID = 0;-----// 3e
int f(int a, int b) { return a + b; }-----// dd
#endif-----// 16
struct segment_tree {-----// ab
---int n; vi data, lazy;-----// dd
---segment_tree() {}-----// 93
---segment_tree(const vi &arr) : n(size(arr)), data(4*n), lazy(4*n,INF) {-----// f1
---mk(arr, 0, n-1, 0); }-----// e9
---int mk(const vi &arr, int l, int r, int i) {-----// 12
---if (l == r) return data[i] = arr[l];-----// 5b
---int m = (l + r) / 2;-----// de
---return data[i] = f(mk(arr, l, m, 2*i+1), mk(arr, m+1, r, 2*i+2)); }-----// 0a
---int query(int a, int b) { return q(a, b, 0, n-1, 0); }-----// f6
---int q(int a, int b, int l, int r, int i) {-----// 22
---propagate(l, r, i);-----// 12
---if (r < a || b < l) return ID;-----// c7
---if (a <= l && r <= b) return data[i];-----// ce
---int m = (l + r) / 2;-----// 7a
---return f(q(a, b, l, m, 2*i+1), q(a, b, m+1, r, 2*i+2)); }-----// 5c
---void update(int i, int v) { u(i, v, 0, n-1, 0); }-----// 90
---int u(int i, int v, int l, int r, int j) {-----// 02
---propagate(l, r, j);-----// ae
---if (r < i || i < l) return data[j];-----// 92
---if (l == i && r == i) return data[j] = v;-----// 4a
---int m = (l + r) / 2;-----// cb
```

```

-----return data[j] = f(u(i, v, l, m, 2*j+1), u(i, v, m+1, r, 2*j+2)); }-----// 34
---void range_update(int a, int b, int v) { ru(a, b, v, 0, n-1, 0); }-----// 71
---int ru(int a, int b, int v, int l, int r, int i) {-----// e0
-----propagate(l, r, i);-----// 19
-----if (l > r) return ID;-----// cc
-----if (r < a || b < l) return data[i];-----// d9
-----if (a <= l && r <= b) return (lazy[i] = v) * (r - l + 1) + data[i];-----// 06
-----int m = (l + r) / 2;-----// cc
-----return data[i] = f(ru(a, b, v, l, m, 2*i+1),-----// cc
-----ru(a, b, v, m+1, r, 2*i+2));-----// 2b
-----}-----// 0b
---void propagate(int l, int r, int i) {-----// a7
-----if (l > r || lazy[i] == INF) return;-----// 5f
-----data[i] += lazy[i] * (r - l + 1);-----// 44
-----if (l < r) {-----// 28
-----if (lazy[2*i+1] == INF) lazy[2*i+1] = lazy[i];-----// 4e
-----else lazy[2*i+1] += lazy[i];-----// 1e
-----if (lazy[2*i+2] == INF) lazy[2*i+2] = lazy[i];-----// de
-----else lazy[2*i+2] += lazy[i];-----// 74
-----}-----// 1f
-----lazy[i] = INF;-----// f8
---}-----// 41
};-----// ae

```

2.2.1. Persistent Segment Tree.

```

int segcnt = 0;-----// cf
struct segment {-----// 68
---int l, r, lid, rid, sum;-----// fc
} segs[2000000];-----// dd
int build(int l, int r) {-----// 2b
---if (l > r) return -1;-----// 4e
---int id = segcnt++;-----// a8
---segs[id].l = l;-----// 90
---segs[id].r = r;-----// 19
---if (l == r) segs[id].lid = -1, segs[id].rid = -1;-----// ee
---else {-----// fe
-----int m = (l + r) / 2;-----// 14
-----segs[id].lid = build(l, m);-----// e3
-----segs[id].rid = build(m + 1, r); }-----// 69
---segs[id].sum = 0;-----// 21
---return id; }-----// c5
int update(int idx, int v, int id) {-----// b8
---if (id == -1) return -1;-----// bb
---if (idx < segs[id].l || idx > segs[id].r) return id;-----// fb
---int nid = segcnt++;-----// b3
---segs[nid].l = segs[id].l;-----// 78
---segs[nid].r = segs[id].r;-----// ca
---segs[nid].lid = update(idx, v, segs[id].lid);-----// 92
---segs[nid].rid = update(idx, v, segs[id].rid);-----// 06
---segs[nid].sum = segs[id].sum + v;-----// 1a
---return nid; }-----// e6

```

```

int query(int id, int l, int r) {-----// a2
---if (r < segs[id].l || segs[id].r < l) return 0;-----// 17
---if (l <= segs[id].l && segs[id].r <= r) return segs[id].sum;-----// ad
---return query(segs[id].lid, l, r) + query(segs[id].rid, l, r); }-----// ee

```

2.3. **Fenwick Tree.** A Fenwick Tree is a data structure that represents an array of n numbers. It supports adjusting the i -th element in $O(\log n)$ time, and computing the sum of numbers in the range $i..j$ in $O(\log n)$ time. It only needs $O(n)$ space.

```

struct fenwick_tree {-----// 98
---int n; vi data;-----// d3
---fenwick_tree(int _n) : n(_n), data(vi(n)) { }-----// db
---void update(int at, int by) {-----// 76
-----while (at < n) data[at] += by, at |= at + 1; }-----// fb
---int query(int at) {-----// 71
---int res = 0;-----// c3
-----while (at >= 0) res += data[at], at = (at & (at + 1)) - 1;-----// 37
-----return res; }-----// e4
---int rsq(int a, int b) { return query(b) - query(a - 1); }-----// be
};-----// 57
struct fenwick_tree_sq {-----// d4
---int n; fenwick_tree x1, x0;-----// 18
---fenwick_tree_sq(int _n) : n(_n), x1(fenwick_tree(n)),-----// 2e
---x0(fenwick_tree(n)) { }-----// 7c
---// insert f(y) = my + c if x <= y-----// 17
---void update(int x, int m, int c) { x1.update(x, m); x0.update(x, c); }-----// 45
---int query(int x) { return x*x1.query(x) + x0.query(x); }-----// 73
};-----// 13
void range_update(fenwick_tree_sq &s, int a, int b, int k) {-----// 89
---s.update(a, k, k * (1 - a)); s.update(b+1, -k, k * b); }-----// 7f
int range_query(fenwick_tree_sq &s, int a, int b) {-----// 15
---return s.query(b) - s.query(a-1); }-----// f3

```

2.4. Matrix.

A Matrix class.

```

template <class K> bool eq(K a, K b) { return a == b; }-----// 2a
template <> bool eq<double>(double a, double b) { return abs(a - b) < EPS; }-----// a7
template <class T> struct matrix {-----// 0a
---int rows, cols, cnt; vector<T> data;-----// a1
---inline T& at(int i, int j) { return data[i * cols + j]; }-----// 5c
---matrix(int r, int c) : rows(r), cols(c), cnt(r * c) {-----// 56
-----data.assign(cnt, T(0)); }-----// e3
---matrix(const matrix& other) : rows(other.rows), cols(other.cols),-----// b5
---cnt(other.cnt), data(other.data) { }-----// c1
---T& operator()(int i, int j) { return at(i, j); }-----// 29
---matrix<T> operator +(const matrix& other) {-----// 33
-----matrix<T> res(*this); rep(i,0,cnt) res.data[i] += other.data[i];-----// f8
-----return res; }-----// 09
---matrix<T> operator -(const matrix& other) {-----// 91
-----matrix<T> res(*this); rep(i,0,cnt) res.data[i] -= other.data[i];-----// 7b
-----return res; }-----// 9a
---matrix<T> operator *(T other) {-----// 99
-----matrix<T> res(*this); rep(i,0,cnt) res.data[i] *= other;-----// 05
-----return res; }-----// 8c

```

```

----matrix<T> operator *(const matrix& other) {-----// 31
-----matrix<T> res(rows, other.cols);-----// 4c
-----rep(i,0,rows) rep(j,0,other.cols) rep(k,0,cols)-----// ae
-----res(i, j) += at(i, k) * other.data[k * other.cols + j];-----// 17
-----return res; }-----// 65
---matrix<T> pow(int p) {-----// 53
---matrix<T> res(rows, cols), sq(*this);-----// 87
---rep(i,0,rows) res(i, i) = T(1);-----// 9d
---while (p) {-----// 79
---if (p & 1) res = res * sq;-----// 62
---p >>= 1;-----// 79
---if (p) sq = sq * sq;-----// 35
---} return res; }-----// 22
---matrix<T> rref(T &det, int &rank) {-----// 2a
---matrix<T> mat(*this); det = T(1), rank = max(rows, cols);-----// 7a
---for (int r = 0, c = 0; c < cols; c++) {-----// 8e
---int k = r;-----// 5b
---while (k < rows && eq<T>(mat(k, c), T(0))) k++;-----// 3e
---if (k >= rows) { rank--; continue; }-----// 1a
---if (k != r) {-----// c4
---det *= T(-1);-----// 55
---rep(i,0,cols)-----// e1
---swap(mat.at(k, i), mat.at(r, i));-----// 7d
---} det *= mat(r, r);-----// b6
---T d = mat(r,c);-----// 66
---rep(i,0,cols) mat(r, i) /= d;-----// d1
---rep(i,0,rows) {-----// f6
---T m = mat(i, c);-----// 05
---if (i != r && !eq<T>(m, T(0)))-----// 1a
---rep(j,0,cols) mat(i, j) -= m * mat(r, j);-----// 7b
---} r++;-----// c5
---} return mat; }-----// b3
---matrix<T> transpose() {-----// 59
---matrix<T> res(cols, rows);-----// 5b
---rep(i,0,rows) rep(j,0,cols) res(j, i) = at(i, j);-----// 92
---return res; } }-----// df

```

2.5. **AVL Tree.** A fast, easily augmentable, balanced binary search tree.

```

#define AVL_MULTISSET 0-----// b5
-----// 61
template <class T>-----// 22
struct avl_tree {-----// 30
---struct node {-----// 8f
---T item; node *p, *l, *r;-----// a9
---int size, height;-----// 47
---node(const T &item, node *_p = NULL) : item(_item), p(_p),-----// ed
---l(NULL), r(NULL), size(1), height(0) { } }-----// 27
---avl_tree() : root(NULL) { }-----// b4
---node *root;-----// 4e
---inline int sz(node *n) const { return n ? n->size : 0; }-----// 4f
---inline int height(node *n) const { return n ? n->height : -1; }-----// d2

```

```

inline bool left_heavy(node *n) const {-----// 8e
return n && height(n->l) > height(n->r); }-----// dc
inline bool right_heavy(node *n) const {-----// 14
return n && height(n->r) > height(n->l); }-----// 24
inline bool too_heavy(node *n) const {-----// c4
return n && abs(height(n->l) - height(n->r)) > 1; }-----// 10
void delete_tree(node *n) {-----// 47
if (n) { delete_tree(n->l), delete_tree(n->r); delete n; } }-----// e2
node*& parent_leg(node *n) {-----// f6
if (!n->p) return root;-----// f4
if (n->p->l == n) return n->p->l;-----// 98
if (n->p->r == n) return n->p->r;-----// 68
assert(false); }-----// 0f
void augment(node *n) {-----// d2
if (!n) return;-----// b8
n->size = 1 + sz(n->l) + sz(n->r);-----// 26
n->height = 1 + max(height(n->l), height(n->r)); }-----// f0
#define rotate(l, r) \
node *l = n->l; \
l->p = n->p; \
parent_leg(n) = l; \
n->l = l->r; \
if (l->r) l->r->p = n; \
l->r = n, n->p = l; \
augment(n), augment(l)
void left_rotate(node *n) { rotate(r, l); }-----// a8
void right_rotate(node *n) { rotate(l, r); }-----// b5
void fix(node *n) {-----// be
while (n) { augment(n);-----// fb
if (too_heavy(n)) {-----// b5
if (left_heavy(n) && right_heavy(n->l)) left_rotate(n->l);-----// a3
else if (right_heavy(n) && left_heavy(n->r))-----// 76
right_rotate(n->r);-----// 12
if (left_heavy(n)) right_rotate(n);-----// 8a
else left_rotate(n);-----// 2e
n = n->p; } }-----// f5
n = n->p; } }-----// 86
inline int size() const { return sz(root); }-----// 15
node* find(const T &item) const {-----// 8f
node *cur = root;-----// 37
while (cur) {-----// a4
if (cur->item < item) cur = cur->r;-----// 8b
else if (item < cur->item) cur = cur->l;-----// 38
else break; }-----// ae
return cur; }-----// b7
node* insert(const T &item) {-----// 5f
node *prev = NULL, **cur = &root;-----// f7
while (*cur) {-----// 82
prev = *cur;-----// 1c
if ((*cur->item < item) cur = &((*cur->r);-----// 54

```

```

// b5
// e4
// 58
// 89
// 65
// 03
// be
// 2b
// 2a
// fa
// 7d
// ca
// c8
// 52
// 9a
// 91
// 83
// 4b
// f4
// 85
// a6
// 9c
// bb
// e3
// 18
// 4c
// f3
// 38
// a0
// 36
// 0e
// 64
// 88
// 92
// 05
// 90
// 42
// e3
// 9f
// e3
// f6
// 83
// 29
// c4
// 02
// 80
// 18
// b5
// 08
// 69
// d2
#endif
}
node *n = new node(item, prev);
*cur = n, fix(n); return n; }
void erase(const T &item) { erase(find(item)); }
void erase(node *n, bool free = true) {
    if (!n) return;
    if (!n->l && n->r) parent_leg(n) = n->r, n->r->p = n->p;
    else if (n->l && !n->r) parent_leg(n) = n->l, n->l->p = n->p;
    else if (n->l && n->r) {
        node *s = successor(n);
        erase(s, false);
        s->p = n->p, s->l = n->l, s->r = n->r;
        if (n->l) n->l->p = s;
        if (n->r) n->r->p = s;
        parent_leg(n) = s, fix(s);
        return;
    } else parent_leg(n) = NULL;
    fix(n->p), n->p = n->l = n->r = NULL;
    if (free) delete n; }
node* successor(node *n) const {
    if (!n) return NULL;
    if (n->r) return nth(0, n->r);
    node *p = n->p;
    while (p && p->r == n) n = p, p = p->p;
    return p; }
node* predecessor(node *n) const {
    if (!n) return NULL;
    if (n->l) return nth(n->l->size-1, n->l);
    node *p = n->p;
    while (p && p->l == n) n = p, p = p->p;
    return p; }
node* nth(int n, node *cur = NULL) const {
    if (!cur) cur = root;
    while (cur) {
        if (n < sz(cur->l)) cur = cur->l;
        else if (n > sz(cur->l)) n -= sz(cur->l) + 1, cur = cur->r;
        else break;
    } return cur; }
int count_less(node *cur) {
    int sum = sz(cur->l);
    while (cur) {
        if (cur->p && cur->p->r == cur) sum += 1 + sz(cur->p->l);
        cur = cur->p;
    } return sum; }
void clear() { delete_tree(root), root = NULL; } }

```

Also a very simple wrapper over the AVL tree that implements a map interface.

```

// 01
// dc
// 58
// 78
// 89
// ba
// 17
// 95
// 3e
// 2d
// 0b
// 41
// 2e
#include "avl_tree.cpp"
template <class K, class V> struct avl_map {
    struct node {
        K key; V value;
        node(K k, V v) : key(k), value(v) { }
        bool operator <(const node &other) const { return key < other.key; } };
    avl_tree<node> tree;
    V& operator [] (K key) {
        typename avl_tree<node>::node *n = tree.find(node(key, V(0)));
        if (!n) n = tree.insert(node(key, V(0)));
        return n->item.value;
    }
};

```

2.6. Cartesian Tree.

```

// 36
// e5
// 4d
// 19
// 42
// 1d
// 1d
// fd
// 0a
// b4
// 4d
// e0
// b7
// 74
// 46
// 3c
// f0
// be
// c0
// b4
// 51
// 32
// da
// 0b
// ae
// 78
// 2f
// ca
// 0d
// 4d
// 7b
// 7c
// 48
// 22
// a3
struct node {
    int x, y, sz;
    node *l, *r;
    node(int _x, int _y) : x(_x), y(_y), sz(1), l(NULL), r(NULL) { } };
int tsize(node* t) { return t ? t->sz : 0; }
void augment(node *t) { t->sz = 1 + tsize(t->l) + tsize(t->r); }
pair<node*, node*> split(node *t, int x) {
    if (!t) return make_pair((node*)NULL, (node*)NULL);
    if (t->x < x) {
        pair<node*, node*> res = split(t->r, x);
        t->r = res.first; augment(t);
        return make_pair(t, res.second); }
    pair<node*, node*> res = split(t->l, x);
    t->l = res.second; augment(t);
    return make_pair(res.first, t); }
node* merge(node *l, node *r) {
    if (!l) return r; if (!r) return l;
    if (l->y > r->y) { l->r = merge(l->r, r); augment(l); return l; }
    r->l = merge(l, r->l); augment(r); return r; }
node* find(node *t, int x) {
    while (t) {
        if (x < t->x) t = t->l;
        else if (t->x < x) t = t->r;
        else return t; }
    return NULL; }
node* insert(node *t, int x, int y) {
    if (find(t, x) != NULL) return t;
    pair<node*, node*> res = split(t, x);
    return merge(res.first, merge(new node(x, y), res.second)); }
node* erase(node *t, int x) {
    if (!t) return NULL;
    if (t->x < x) t->r = erase(t->r, x);
    else if (x < t->x) t->l = erase(t->l, x);
    else { node *old = t; t = merge(t->l, t->r); delete old; }
    if (t) augment(t); return t; }

```

```
int kth(node *t, int k) {-----// b3
---if (k < tsize(t->l)) return kth(t->l, k);-----// 64
---else if (k == tsize(t->l)) return t->x;-----// 97
---else return kth(t->r, k - tsize(t->l) - 1); }-----// f0
```

2.7. **Heap.** An implementation of a binary heap.

```
#define RESIZE-----// d0
#define SWP(x,y) tmp = x, x = y, y = tmp-----// fb
struct default_int_cmp {-----// 8d
---default_int_cmp() { }-----// 35
---bool operator()(const int &a, const int &b) { return a < b; } }-----// e9
template <class Compare = default_int_cmp> struct heap {-----// 42
---int len, count, *q, *loc, tmp;-----// 07
---Compare _cmp;-----// a5
---inline bool cmp(int i, int j) { return _cmp(q[i], q[j]); }-----// e2
---inline void swp(int i, int j) {-----// 3b
---    SWP(q[i], q[j]), SWP(loc[q[i]], loc[q[j]]); }-----// bd
---void swim(int i) {-----// b5
---    while (i > 0) {-----// 70
---        int p = (i - 1) / 2;-----// b8
---        if (!cmp(i, p)) break;-----// 2f
---        swp(i, p), i = p; } }-----// 20
---void sink(int i) {-----// 40
---    while (true) {-----// 07
---        int l = 2*i + 1, r = l + 1;-----// 85
---        if (l >= count) break;-----// d9
---        int m = r >= count || cmp(l, r) ? l : r;-----// db
---        if (!cmp(m, i)) break;-----// 4e
---        swp(m, i), i = m; } }-----// 36
---heap(int init_len = 128) : count(0), len(init_len), _cmp(Compare()) {-----// 05
---    q = new int[len], loc = new int[len];-----// bc
---    memset(loc, 255, len << 2); }-----// 45
---~heap() { delete[] q; delete[] loc; }-----// 23
---void push(int n, bool fix = true) {-----// b8
---    if (len == count || n >= len) {-----// dc
---        #ifdef RESIZE-----// 0a
---        int newlen = 2 * len;-----// 85
---        while (n >= newlen) newlen *= 2;-----// 54
---        int *newq = new int[newlen], *newloc = new int[newlen];-----// 9f
---        rep(i,0,len) newq[i] = q[i], newloc[i] = loc[i];-----// 53
---        memset(newloc + len, 255, (newlen - len) << 2);-----// a6
---        delete[] q, delete[] loc;-----// 7a
---        loc = newloc, q = newq, len = newlen;-----// 80
---    #else-----// 82
---    assert(false);-----// 46
---    #endif-----// 5c
---    }-----// 34
---    assert(loc[n] == -1);-----// 71
---    loc[n] = count, q[count++] = n;-----// 98
---    if (fix) swim(count-1); }-----// 70
---void pop(bool fix = true) {-----// 2e
```

```
-----assert(count > 0);-----// 7b
-----loc[q[0]] = -1, q[0] = q[--count], loc[q[0]] = 0;-----// 71
-----if (fix) sink(0);-----// 80
-----}-----// b2
---int top() { assert(count > 0); return q[0]; }-----// d9
---void heapify() { for (int i = count - 1; i > 0; i--)-----// 77
---    if (cmp(i, (i - 1) / 2)) swp(i, (i - 1) / 2); }-----// cc
---void update_key(int n) {-----// 86
---    assert(loc[n] != -1, swim(loc[n]), sink(loc[n])); }-----// d9
---bool empty() { return count == 0; }-----// 77
---int size() { return count; }-----// 74
---void clear() { count = 0, memset(loc, 255, len << 2); } }-----// 99
```

2.8. **Dancing Links.** An implementation of Donald Knuth’s Dancing Links data structure. A linked list supporting deletion and restoration of elements.

```
template <class T>-----// 82
struct dancing_links {-----// 9e
---struct node {-----// 62
---    T item;-----// dd
---    node *l, *r;-----// 32
---    node(const T &item, node *_l = NULL, node *_r = NULL)-----// 6d
---        : item(_item), l(_l), r(_r) {-----// 6d
---        if (l) l->r = this;-----// 97
---        if (r) r->l = this;-----// 81
---    }-----// 2d
---};-----// d3
---node *front, *back;-----// aa
---dancing_links() { front = back = NULL; }-----// 72
---node *push_back(const T &item) {-----// 83
---    back = new node(item, back, NULL);-----// c4
---    if (!front) front = back;-----// d2
---    return back;-----// c0
---}-----// a9
---node *push_front(const T &item) {-----// 4a
---    front = new node(item, NULL, front);-----// 47
---    if (!back) back = front;-----// 10
---    return front;-----// cf
---}-----// b6
---void erase(node *n) {-----// a0
---    if (!n->l) front = n->r; else n->l->r = n->r;-----// ab
---    if (!n->r) back = n->l; else n->r->l = n->l;-----// 1b
---}-----// 7b
---void restore(node *n) {-----// 82
---    if (!n->l) front = n; else n->l->r = n;-----// a5
---    if (!n->r) back = n; else n->r->l = n;-----// 9d
---}-----// eb
};-----// 5e
```

2.9. **Misof Tree.** A simple tree data structure for inserting, erasing, and querying the *n*th largest element.

```
#define BITS 15-----// 7b
struct misof_tree {-----// fe
```



```
int cnt[BITS][1<<BITS];-----// aa
misof_tree() { memset(cnt, 0, sizeof(cnt)); }-----// b0
void insert(int x) { for (int i = 0; i < BITS; cnt[i++][x]++, x >= 1); }-----// 5a
void erase(int x) { for (int i = 0; i < BITS; cnt[i++][x]--, x >= 1); }-----// 49
int nth(int n) {-----// 8a
    int res = 0;-----// a4
    for (int i = BITS-1; i >= 0; i--)-----// 99
        if (cnt[i][res <= 1] <= n) n -= cnt[i][res], res |= 1;-----// f4
    return res;-----// 3a
};-----// b5
};-----// 0a
```

2.10. *k*-d Tree. A *k*-dimensional tree supporting fast construction, adding points, and nearest neighbor queries. NOTE: Not completely stable, occasionally segfaults.

```
#define INC(c) ((c) == K - 1 ? 0 : (c) + 1)-----// 77
template <int K> struct kd_tree {-----// 93
    struct pt {-----// 99
        double coord[K];-----// 31
        pt() {}-----// 96
        pt(double c[K]) { rep(i,0,K) coord[i] = c[i]; }-----// 37
        double dist(const pt &other) const {-----// 16
            double sum = 0.0;-----// 0c
            rep(i,0,K) sum += pow(coord[i] - other.coord[i], 2.0);-----// f3
            return sqrt(sum); } }-----// 68
    struct cmp {-----// 8c
        int c;-----// fa
        cmp(int _c) : c(_c) {}-----// 28
        bool operator()(const pt &a, const pt &b) {-----// 8e
            for (int i = 0, cc; i <= K; i++) {-----// 24
                cc = i == 0 ? c : i - 1;-----// ae
                if (abs(a.coord[cc] - b.coord[cc]) > EPS)-----// ad
                    return a.coord[cc] < b.coord[cc];-----// ed
            }-----// 5d
            return false; } }-----// a4
    struct bb {-----// f1
        pt from, to;-----// 26
        bb(pt _from, pt _to) : from(_from), to(_to) {}-----// 9c
        double dist(const pt &p) {-----// 74
            double sum = 0.0;-----// 48
            rep(i,0,K) {-----// d2
                if (p.coord[i] < from.coord[i])-----// ff
                    sum += pow(from.coord[i] - p.coord[i], 2.0);-----// 07
                else if (p.coord[i] > to.coord[i])-----// 50
                    sum += pow(p.coord[i] - to.coord[i], 2.0);-----// 45
            }-----// e8
            return sqrt(sum); }-----// df
        bb bound(double l, int c, bool left) {-----// 67
            pt nf(from.coord), nt(to.coord);-----// af
            if (left) nt.coord[c] = min(nt.coord[c], l);-----// 48
            else nf.coord[c] = max(nf.coord[c], l);-----// 14
            return bb(nf, nt); } }-----// 97
```

```
struct node {-----// 7f
    pt p; node *_l, *_r;-----// 2c
    node(pt _p, node *_l, node *_r) : p(_p), l(_l), r(_r) { } }-----// 84
node *root;-----// 62
// kd_tree() : root(NULL) { }-----// 50
kd_tree(vector<pt> pts) { root = construct(pts, 0, size(pts) - 1, 0); }-----// 8a
node* construct(vector<pt> &pts, int from, int to, int c) {-----// 8d
    if (from > to) return NULL;-----// 21
    int mid = from + (to - from) / 2;-----// b3
    nth_element(pts.begin() + from, pts.begin() + mid,-----// 56
        pts.begin() + to + 1, cmp(c));-----// a5
    return new node(pts[mid], construct(pts, from, mid - 1, INC(c)),-----// 39
        construct(pts, mid + 1, to, INC(c))); }-----// 3a
bool contains(const pt &p) { return _con(p, root, 0); }-----// 59
bool _con(const pt &p, node *n, int c) {-----// 70
    if (!n) return false;-----// b4
    if (cmp(c)(p, n->p)) return _con(p, n->l, INC(c));-----// 2b
    if (cmp(c)(n->p, p)) return _con(p, n->r, INC(c));-----// ec
    return true; }-----// b5
void insert(const pt &p) { _ins(p, root, 0); }-----// 09
void _ins(const pt &p, node* &n, int c) {-----// 40
    if (!n) n = new node(p, NULL, NULL);-----// 98
    else if (cmp(c)(p, n->p)) _ins(p, n->l, INC(c));-----// ed
    else if (cmp(c)(n->p, p)) _ins(p, n->r, INC(c)); }-----// 91
void clear() { _clr(root); root = NULL; }-----// dd
void _clr(node *n) { if (n) _clr(n->l), _clr(n->r), delete n; }-----// 17
pt nearest_neighbour(const pt &p, bool allow_same=true) {-----// 0f
    assert(root);-----// 47
    double mn = INFINITY, cs[K];-----// 0d
    rep(i,0,K) cs[i] = -INFINITY;-----// 56
    pt from(cs);-----// f0
    rep(i,0,K) cs[i] = INFINITY;-----// 8c
    pt to(cs);-----// ad
    return _nn(p, root, bb(from, to), mn, 0, allow_same).first;-----// f6
}-----// 79
pair<pt, bool> _nn(-----// a1
    const pt &p, node *n, bb b, double &mn, int c, bool same) {-----// a6
    if (!n || b.dist(p) > mn) return make_pair(pt(), false);-----// e4
    bool found = same || p.dist(n->p) > EPS, l1 = true, l2 = false;-----// 59
    pt resp = n->p;-----// 92
    if (found) mn = min(mn, p.dist(resp));-----// 67
    node *n1 = n->l, *n2 = n->r;-----// b3
    rep(i,0,2) {-----// af
        if (i == 1 || cmp(c)(n->p, p)) swap(n1, n2), swap(l1, l2);-----// 1f
        pair<pt, bool> res =-----// a4
            _nn(p, n1, b.bound(n->p.coord[c], c, l1), mn, INC(c), same);-----// a8
        if (res.second && (!found || p.dist(res.first) < p.dist(resp)))-----// cd
            resp = res.first, found = true;-----// 15
    }-----// 24
    return make_pair(resp, found); } }-----// c5
```


2.11. **Sqrt Decomposition.** Design principle that supports many operations in amortized \sqrt{n} per operation.

```
struct segment {-----// b2
---vi arr;-----// 8c
---segment(vi _arr) : arr(_arr) { } };-----// 11
vector<segment> T;-----// a1
int K;-----// dc
void rebuild() {-----// 17
---int cnt = 0;-----// 14
---rep(i,0,size(T))-----// b1
---cnt += size(T[i].arr);-----// d1
---K = static_cast<int>(ceil(sqrt(cnt)) + 1e-9);-----// 4c
---vi arr(cnt);-----// 14
---for (int i = 0, at = 0; i < size(T); i++)-----// 79
---rep(j,0,size(T[i].arr))-----// a4
---arr[at++] = T[i].arr[j];-----// f7
---T.clear();-----// 4c
---for (int i = 0; i < cnt; i += K)-----// 79
---T.push_back(segment(vi(arr.begin()+i, arr.begin()+min(i+K, cnt))));-----// f0
}-----// 03
int split(int at) {-----// 71
---int i = 0;-----// 8a
---while (i < size(T) && at >= size(T[i].arr))-----// 6c
---at -= size(T[i].arr), i++;-----// 9a
---if (i >= size(T)) return size(T);-----// 83
---if (at == 0) return i;-----// 49
---T.insert(T.begin() + i + 1, segment(vi(T[i].arr.begin() + at, T[i].arr.end())));-----// af
---T[i] = segment(vi(T[i].arr.begin(), T[i].arr.begin() + at));-----// af
---return i + 1;-----// ac
}-----// ea
void insert(int at, int v) {-----// 5f
---vi arr; arr.push_back(v);-----// 6a
---T.insert(T.begin() + split(at), segment(arr));-----// 67
}-----// cc
void erase(int at) {-----// be
---int i = split(at); split(at + 1);-----// da
---T.erase(T.begin() + i);-----// 6b
}-----// 4b
```

2.12. **Monotonic Queue.** A queue that supports querying for the minimum element. Useful for sliding window algorithms.

```
struct min_stack {-----// d8
---stack<int> S, M;-----// fe
---void push(int x) {-----// 20
---S.push(x);-----// e2
---M.push(M.empty() ? x : min(M.top(), x)); }-----// 92
---int top() { return S.top(); }-----// f1
---int mn() { return M.top(); }-----// 02
---void pop() { S.pop(); M.pop(); }-----// fd
---bool empty() { return S.empty(); }-----// d2
};-----// 74
```

```
struct min_queue {-----// b4
---min_stack inp, outp;-----// 3d
---void push(int x) { inp.push(x); }-----// 6b
---void fix() {-----// 5d
---if (outp.empty()) while (!inp.empty())-----// 3b
---outp.push(inp.top(), inp.pop());-----// 8e
---}-----// 3f
---int top() { fix(); return outp.top(); }-----// dc
---int mn() {-----// 39
---if (inp.empty()) return outp.mn();-----// 01
---if (outp.empty()) return inp.mn();-----// 90
---return min(inp.mn(), outp.mn()); }-----// 97
---void pop() { fix(); outp.pop(); }-----// 4f
---bool empty() { return inp.empty() && outp.empty(); }-----// 65
};-----// 60
```

2.13. **Convex Hull Trick.**

```
struct convex_hull_trick {-----// 16
---vector<pair<double,double> > h;-----// b4
---double intersect(int i) {-----// 9b
---return (h[i+1].second-h[i].second)/(h[i].first-h[i+1].first); }-----// b9
---void add(double m, double b) {-----// a4
---h.push_back(make_pair(m,b));-----// f9
---while (size(h) >= 3) {-----// f6
---int n = size(h);-----// d8
---if (intersect(n-3) < intersect(n-2)) break;-----// 07
---swap(h[n-2], h[n-1]);-----// bf
---h.pop_back(); } }-----// 4b
---double get_min(double x) {-----// b0
---int lo = 0, hi = size(h) - 2, res = -1;-----// 5b
---while (lo <= hi) {-----// 24
---int mid = lo + (hi - lo) / 2;-----// 5a
---if (intersect(mid) <= x) res = mid, lo = mid + 1;-----// 1d
---else hi = mid - 1; } }-----// b6
---return h[res+1].first * x + h[res+1].second; } };
```

3. GRAPHS

3.1. **Single-Source Shortest Paths.**

3.1.1. *Dijkstra’s algorithm.* An implementation of Dijkstra’s algorithm. It runs in $\Theta(|E| \log |V|)$ time.

```
int *dist, *dad;-----// 46
struct cmp {-----// a5
---bool operator()(int a, int b) {-----// bb
---return dist[a] != dist[b] ? dist[a] < dist[b] : a < b; }-----// e6
};-----// 41
pair<int*, int*> dijkstra(int n, int s, vii *adj) {-----// 53
---dist = new int[n];-----// 84
---dad = new int[n];-----// 05
---rep(i,0,n) dist[i] = INF, dad[i] = -1;-----// 80
---set<int, cmp> pq;-----// 98
---dist[s] = 0, pq.insert(s);-----// 1f
---while (!pq.empty()) {-----// 47
```

```
-----int cur = *pq.begin(); pq.erase(pq.begin());-----// 58
-----rep(i,0,size(adj[cur])) {-----// a6
-----int nxt = adj[cur][i].first,-----// a4
-----ndist = dist[cur] + adj[cur][i].second;-----// 3a
-----if (ndist < dist[nxt]) pq.erase(nxt),-----// 2d
-----dist[nxt] = ndist, dad[nxt] = cur, pq.insert(nxt);-----// eb
-----}-----// d2
-----}-----// df
---return pair<int*, int*>(dist, dad);-----// e3
}-----// 9b
```

3.1.2. *Bellman-Ford algorithm.* The Bellman-Ford algorithm solves the single-source shortest paths problem in $O(|V||E|)$ time. It is slower than Dijkstra’s algorithm, but it works on graphs with negative edges and has the ability to detect negative cycles, neither of which Dijkstra’s algorithm can do.

```
int* bellman_ford(int n, int s, vii* adj, bool& has_negative_cycle) {-----// cf
---has_negative_cycle = false;-----// 47
---int* dist = new int[n];-----// 7f
---rep(i,0,n) dist[i] = i == s ? 0 : INF;-----// df
---rep(i,0,n-1) rep(j,0,n) if (dist[j] != INF)-----// 4d
---rep(k,0,size(adj[j]))-----// 88
---dist[adj[j][k].first] = min(dist[adj[j][k].first],-----// e1
---dist[j] + adj[j][k].second);-----// 18
---rep(j,0,n) rep(k,0,size(adj[j]))-----// f8
---if (dist[j] + adj[j][k].second < dist[adj[j][k].first])-----// 37
---has_negative_cycle = true;-----// f1
---return dist;-----// 78
}-----// a9
```

3.1.3. *IDA* algorithm.*

```
int n, cur[100], pos;-----// 48
int calch() {-----// 88
---int h = 0;-----// 4a
---rep(i,0,n) if (cur[i] != 0) h += abs(i - cur[i]);-----// 9b
---return h;-----// c6
}-----// c8
int dfs(int d, int g, int prev) {-----// 12
---int h = calch();-----// 5d
---if (g + h > d) return g + h;-----// 15
---if (h == 0) return 0;-----// ff
---int mn = INF;-----// 7e
---rep(di,-2,3) {-----// 0d
-----if (di == 0) continue;-----// 0a
-----int nxt = pos + di;-----// 76
-----if (nxt == prev) continue;-----// 39
-----if (0 <= nxt && nxt < n) {-----// 68
-----swap(cur[pos], cur[nxt]);-----// 35
-----swap(pos,nxt);-----// 64
-----mn = min(mn, dfs(d, g+1, nxt));-----// 22
-----swap(pos,nxt);-----// 84
-----swap(cur[pos], cur[nxt]);-----// 3b
-----}-----// 46
```

```
-----if (mn == 0) break;-----// 8f
-----}-----// d3
---return mn;-----// da
}-----// f8
int idastar() {-----// 22
---rep(i,0,n) if (cur[i] == 0) pos = i;-----// 6b
---int d = calch();-----// 38
---while (true) {-----// 18
---int nd = dfs(d, 0, -1);-----// 42
---if (nd == 0 || nd == INF) return d;-----// b5
---d = nd;-----// f7
---}-----// f9
}-----// 82
```

3.2. All-Pairs Shortest Paths.

3.2.1. *Floyd-Warshall algorithm.* The Floyd-Warshall algorithm solves the all-pairs shortest paths problem in $O(|V|^3)$ time.

```
void floyd_warshall(int** arr, int n) {-----// 21
---rep(k,0,n) rep(i,0,n) rep(j,0,n)-----// af
---if (arr[i][k] != INF && arr[k][j] != INF)-----// 84
---arr[i][j] = min(arr[i][j], arr[i][k] + arr[k][j]);-----// 39
}-----// bf
```

3.3. Strongly Connected Components.

3.3.1. *Kosaraju’s algorithm.* Kosaraju’s algorithm finds strongly connected components of a directed graph in $O(|V| + |E|)$ time.

```
#include "../data-structures/union_find.cpp"-----// 5e
-----// 11
vector<bool> visited;-----// 66
vi order;-----// 9b
-----// a5
void scc_dfs(const vvi &adj, int u) {-----// a1
---int v; visited[u] = true;-----// e3
---rep(i,0,size(adj[u]))-----// 2d
---if (!visited[v = adj[u][i]]) scc_dfs(adj, v);-----// a2
---order.push_back(u);-----// 02
}-----// 53
-----// 63
pair<union_find, vi> scc(const vvi &adj) {-----// c2
---int n = size(adj), u, v;-----// f8
---order.clear();-----// 20
---union_find uf(n);-----// a8
---vi dag;-----// 61
---vvi rev(n);-----// c5
---rep(i,0,n) rep(j,0,size(adj[i])) rev[adj[i][j]].push_back(i);-----// 7e
---visited.resize(n, fill(visited.begin(), visited.end(), false));-----// 80
---rep(i,0,n) if (!visited[i]) scc_dfs(rev, i);-----// 4e
---fill(visited.begin(), visited.end(), false);-----// 59
---stack<int> S;-----// bb
---for (int i = n-1; i >= 0; i--) {-----// 96
---if (visited[order[i]]) continue;-----// db
```

```
-----S.push(order[i]), dag.push_back(order[i]);-----// 68
-----while (!S.empty()) {-----// 9e
-----visited[u = S.top()] = true, S.pop(), uf.unite(u, order[i]);-----// b3
-----rep(j,0,size(adj[u])) if (!visited[v = adj[u][j]]) S.push(v);-----// 1b
-----}-----// 61
-----}-----// 57
-----return pair<union_find, vi>(uf, dag);-----// 2b
}-----// 92
```

3.4. Cut Points and Bridges.

```
#define MAXN 5000-----// f7
int low[MAXN], num[MAXN], curnum;-----// d7
void dfs(const vvi &adj, vi &cp, vii &bri, int u, int p) {-----// 22
---low[u] = num[u] = curnum++;-----// a3
---int cnt = 0; bool found = false;-----// 97
---rep(i,0,size(adj[u])) {-----// ae
-----int v = adj[u][i];-----// 56
-----if (num[v] == -1) {-----// 3b
-----dfs(adj, cp, bri, v, u);-----// ba
-----low[u] = min(low[u], low[v]);-----// be
-----cnt++;-----// e0
-----found = found || low[v] >= num[u];-----// 30
-----if (low[v] > num[u]) bri.push_back(ii(u, v));-----// bf
-----} else if (p != v) low[u] = min(low[u], num[v]); }-----// 76
---if (found && (p != -1 || cnt > 1)) cp.push_back(u); }-----// 3e
pair<vi,vii> cut_points_and_bridges(const vvi &adj) {-----// 76
---int n = size(adj);-----// c8
---vi cp; vii bri;-----// fb
---memset(num, -1, n << 2);-----// 45
---curnum = 0;-----// 07
---rep(i,0,n) if (num[i] == -1) dfs(adj, cp, bri, i, -1);-----// 7e
---return make_pair(cp, bri); }-----// 4c
```

3.5. Minimum Spanning Tree.

3.5.1. Kruskal’s algorithm.

```
#include "../data-structures/union_find.cpp"-----// 5e
-----// 11
// n is the number of vertices-----// 18
// edges is a list of edges of the form (weight, (a, b))-----// c6
// the edges in the minimum spanning tree are returned on the same form-----// 4d
vector<pair<int, ii> > mst(int n, vector<pair<int, ii> > edges) {-----// a7
---union_find uf(n);-----// 04
---sort(edges.begin(), edges.end());-----// 51
---vector<pair<int, ii> > res;-----// 71
---rep(i,0,size(edges))-----// 97
-----if (uf.find(edges[i].second.first) !=
-----uf.find(edges[i].second.second)) {-----// bd
-----res.push_back(edges[i]);-----// 85
-----uf.unite(edges[i].second.first, edges[i].second.second);-----// d3
-----}-----// 6c
-----// 37
```

```
-----return res;-----// cb
}-----// 50
```

3.6. Topological Sort.

3.6.1. Modified Depth-First Search.

```
void tsort_dfs(int cur, char* color, const vvi& adj, stack<int>& res,-----// ca
-----bool& has_cycle) {-----// a8
---color[cur] = 1;-----// 5b
---rep(i,0,size(adj[cur])) {-----// c4
-----int nxt = adj[cur][i];-----// c1
-----if (color[nxt] == 0)-----// dd
-----tsort_dfs(nxt, color, adj, res, has_cycle);-----// 12
-----else if (color[nxt] == 1)-----// 78
-----has_cycle = true;-----// c8
-----if (has_cycle) return;-----// 87
-----}-----// 57
---color[cur] = 2;-----// 61
---res.push(cur);-----// 7e
}-----// c8
-----// 5e
vi tsort(int n, vvi adj, bool& has_cycle) {-----// 7f
---has_cycle = false;-----// 38
---stack<int> S;-----// 4f
---vi res;-----// a4
---char* color = new char[n];-----// ba
---memset(color, 0, n);-----// 95
---rep(i,0,n) {-----// 6e
-----if (!color[i]) {-----// f5
-----tsort_dfs(i, color, adj, S, has_cycle);-----// 71
-----if (has_cycle) return res;-----// 14
-----}-----// fe
-----}-----// 5e
---while (!S.empty()) res.push_back(S.top()), S.pop();-----// 28
---return res;-----// 2b
}-----// c0
```

3.7. Euler Path. Finds an euler path (or circuit) in a directed graph, or reports that none exist.

```
#define MAXV 1000-----// 2f
#define MAXE 5000-----// 87
vi adj[MAXV];-----// ff
int n, m, indeg[MAXV], outdeg[MAXV], res[MAXE + 1];-----// 49
ii start_end() {-----// 30
---int start = -1, end = -1, any = 0, c = 0;-----// 74
---rep(i,0,n) {-----// 20
-----if (outdeg[i] > 0) any = i;-----// 63
-----if (indeg[i] + 1 == outdeg[i]) start = i, c++;-----// 5a
-----else if (indeg[i] == outdeg[i] + 1) end = i, c++;-----// 13
-----else if (indeg[i] != outdeg[i]) return ii(-1,-1);-----// c1
-----}-----// ed
---if ((start == -1) != (end == -1) || (c != 2 && c != 0)) return ii(-1,-1);-----// 54
---if (start == -1) start = end = any;-----// 5e
```

```

-   if(dist(v) < dist(-1)) {- // f1
-       iter(u, adj[v]) if(dist(R[*u]) == INF) // 9b
-       dist(R[*u]) = dist(v) + 1, q[r++] = R[*u]; // 79
-   } // b8
- } // 0d
- return dist(-1) != INF; // 43
- } // 2c
bool dfs(int v) {- // 26
- if(v != -1) {- // d8
-     iter(u, adj[v]) // 99
-     if(dist(R[*u]) == dist(v) + 1) // 74
-     if(dfs(R[*u])) {- // 40
-         R[*u] = v, L[v] = *u; // 47
-         return true; // a2
-     } // 17
-     dist(v) = INF; // 62
-     return false; // 3c
- } // 3d
- return true; // ae
- } // 0f
void add_edge(int i, int j) { adj[i].push_back(j); } // 92
int maximum_matching() {- // a2
-     int matching = 0; // 71
-     memset(L, -1, sizeof(int) * N); // 72
-     memset(R, -1, sizeof(int) * M); // bf
-     while(bfs()) rep(i,0,N) // 3e
-         matching += L[i] == -1 && dfs(i); // 1d
-     return matching; // ec
- } // 8b
}; // b7

```

3.9. Maximum Flow.

3.9.1. *Dinic's algorithm.* An implementation of Dinic's algorithm that runs in $O(|V|^2|E|)$. It computes the maximum flow of a flow network.

```
#define MAXV 2000-----// ba
int q[MAXV], d[MAXV];-----// e6
struct flow_network {-----// 12
    struct edge {-----// 1e
        int v, cap, nxt;-----// ab
        edge() { }-----// 38
        edge(int _v, int _cap, int _nxt) : v(_v), cap(_cap), nxt(_nxt) { }-----// bc
    };-----// 6e
    int n, ecnt, *head, *curh;-----// 46
    vector<edge> e, e_store;-----// 1f
    flow_network(int n, int m = -1) : n(_n), ecnt(0) {-----// d3
        e.reserve(2 * (m == -1 ? n : m));-----// 24
        head = new int[n], curh = new int[n];-----// 6b
        memset(head, -1, n * sizeof(int));-----// 56
    }-----// 77
    void destroy() { delete[] head; delete[] curh; }-----// f6
    void reset() { e = e_store; }-----// 87
```

```

----void destroy() { delete[] head; delete[] curh; }-----// f6
----void reset() { e = e_store; }-----// 87

```

```
void add_edge(int u, int v, int uv, int vu = 0) {
    e.push_back(edge(v, uv, head[u])); head[u] = ecnt++;
    e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;
}

int augment(int v, int t, int f) {
    if (v == t) return f;
    for (int &i = curh[v], ret; i != -1; i = e[i].nxt)
        if (e[i].cap > 0 && d[e[i].v] + 1 == d[v])
            if ((ret = augment(e[i].v, t, min(f, e[i].cap))) > 0)
                return (e[i].cap -= ret, e[i^1].cap += ret, ret);
    return 0;
}

int max_flow(int s, int t, bool res = true) {
    if(s == t) return 0;
    e_store = e;
    int f = 0, x, l, r;
    while (true) {
        memset(d, -1, n * sizeof(int));
        l = r = 0, d[q[r++] = t] = 0;
        while (l < r)
            for (int v = q[l++], i = head[v]; i != -1; i = e[i].nxt)
                if (e[i^1].cap > 0 && d[e[i].v] == -1)
                    d[q[r++] = e[i].v] = d[v]+1;
            if (d[s] == -1) break;
            memcpy(curh, head, n * sizeof(int));
            while ((x = augment(s, t, INF)) != 0) f += x;
        if (res) reset();
    }
    return f;
};

3.9.2. Edmonds Karp's algorithm. An implementation of Edmonds Karp's algorithm that runs in
O(|V||E|^2). It computes the maximum flow of a flow network.

#define MAXV 2000
int q[MAXV], d[MAXV], p[MAXV];
struct flow_network {
    struct edge {
        int v, cap, nxt;
        edge(int _v, int _cap, int _nxt) : v(_v), cap(_cap), nxt(_nxt) {}
    };
    int n, ecnt, *head;
    vector<edge> e, e_store;
    flow_network(int _n, int m = -1) : n(_n), ecnt(0) {
        e.reserve(2 * (m == -1 ? n : m));
        memset(head = new int[n], -1, n << 2);
    }
    void destroy() { delete[] head; }
    void reset() { e = e_store; }
    void add_edge(int u, int v, int uv, int vu=0) {
        e.push_back(edge(v, uv, head[u])); head[u] = ecnt++;
        e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;
    }
};

e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;
}

int max_flow(int s, int t, bool res = true) {
    if (s == t) return 0;
    e_store = e;
    int f = 0, l, r, v;
    while (true) {
        memset(d, -1, n << 2);
        memset(p, -1, n << 2);
        l = r = 0, d[q[r++] = s] = 0;
        while (l < r)
            for (int u = q[l++], i = head[u]; i != -1; i = e[i].nxt)
                if (e[i].cap > 0 &&
                    (d[v = e[i].v] == -1 || d[u] + 1 < d[v]))
                    d[v] = d[u] + 1, p[q[r++] = v] = i;
            if (p[t] == -1) break;
            int x = INF, at = p[t];
            while (at != -1) x = min(x, e[at].cap), at = p[e[at^1].v];
            at = p[t], f += x;
            while (at != -1)
                e[at].cap -= x, e[at^1].cap += x, at = p[e[at^1].v];
        if (res) reset();
        return f;
    }
};

3.10. Minimum Cost Maximum Flow. An implementation of Edmonds Karp's algorithm, modi-
fied to find shortest path to augment each time (instead of just any path). It computes the maximum
flow of a flow network, and when there are multiple maximum flows, finds the maximum flow with
minimum cost. Running time is O(|V|^2|E| log |V|). NOTE: Doesn't work on negative weights!
```

```
#define MAXV 2000
int d[MAXV], p[MAXV], pot[MAXV];
struct cmp {
    bool operator()(int i, int j) {
        return d[i] == d[j] ? i < j : d[i] < d[j];
    }
};

struct flow_network {
    struct edge {
        int v, cap, cost, nxt;
        edge(int _v, int _cap, int _cost, int _nxt) : v(_v), cap(_cap), cost(_cost), nxt(_nxt) {}
    };
    int n, ecnt, *head;
    vector<edge> e, e_store;
    flow_network(int _n, int m = -1) : n(_n), ecnt(0) {
        e.reserve(2 * (m == -1 ? n : m));
        memset(head = new int[n], -1, n << 2);
    }
    void destroy() { delete[] head; }
    void reset() { e = e_store; }
    void add_edge(int u, int v, int uv, int vu=0) {
        e.push_back(edge(v, uv, head[u])); head[u] = ecnt++;
        e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;
    }
};

e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;
}

int max_flow(int s, int t, bool res = true) {
    if (s == t) return 0;
    e_store = e;
    int f = 0, x, l, r, v;
    while (true) {
        memset(d, -1, n << 2);
        memset(p, -1, n << 2);
        l = r = 0, d[q[r++] = s] = 0;
        while (l < r)
            for (int u = q[l++], i = head[u]; i != -1; i = e[i].nxt)
                if (e[i].cap > 0 &&
                    (d[v = e[i].v] == -1 || d[u] + 1 < d[v]))
                    d[v] = d[u] + 1, p[q[r++] = v] = i;
            if (p[t] == -1) break;
            int x = INF, at = p[t];
            while (at != -1) x = min(x, e[at].cap), at = p[e[at^1].v];
            at = p[t], f += x;
            while (at != -1)
                e[at].cap -= x, e[at^1].cap += x, at = p[e[at^1].v];
        if (res) reset();
        return f;
    }
};

3.10. Minimum Cost Maximum Flow. An implementation of Edmonds Karp's algorithm, modi-
fied to find shortest path to augment each time (instead of just any path). It computes the maximum
flow of a flow network, and when there are multiple maximum flows, finds the maximum flow with
minimum cost. Running time is O(|V|^2|E| log |V|). NOTE: Doesn't work on negative weights!
```

```
void reset() { e = e_store; } // 88
void add_edge(int u, int v, int cost, int uv, int vu=0) { // b4
    e.push_back(edge(v, uv, cost, head[u])); head[u] = ecnt++; // 43
    e.push_back(edge(u, vu, -cost, head[v])); head[v] = ecnt++; // 53
} // 16
ii min_cost_max_flow(int s, int t, bool res = true) { // 6d
    if (s == t) return ii(0, 0); // 34
    e_store = e; // 70
    memset(pot, 0, n << 2); // 24
    int f = 0, c = 0, v; // d4
    while (true) { // 29
        memset(d, -1, n << 2); // fd
        memset(p, -1, n << 2); // b7
        set<int, cmp> q; // d8
        q.insert(s); d[s] = 0; // 1d
        while (!q.empty()) { // 04
            int u = *q.begin(); // dd
            q.erase(q.begin()); // 20
            for (int i = head[u]; i != -1; i = e[i].nxt) { // 02
                if (e[i].cap == 0) continue; // 1c
                int cd = d[u] + e[i].cost + pot[u] - pot[v = e[i].v]; // 1d
                if (d[v] == -1 || cd < d[v]) { // d2
                    if (q.find(v) != q.end()) q.erase(q.find(v)); // e2
                    d[v] = cd; p[v] = i; // f7
                    q.insert(v); // 74
                } // 6c
            } // 1b
        } // da
        if (p[t] == -1) break; // 09
        int x = INF, at = p[t]; // e8
        while (at != -1) x = min(x, e[at].cap), at = p[e[at^1].v]; // 32
        at = p[t], f += x; // 43
        while (at != -1) // 53
            e[at].cap -= x, e[at^1].cap += x, at = p[e[at^1].v]; // 95
        c += x * (d[t] + pot[t] - pot[s]); // 44
        rep(i,0,n) if (p[i] != -1) pot[i] += d[i]; // 86
    } // 4e
    if (res) reset(); // d7
    return ii(f, c); // 9f
} // 4c
}; // ec
```

A second implementation that is slower but works on negative weights.

```
struct flow_network { // 81
    struct mcmf_edge { // f6
        int u, v; // e1
        ll w, c; // b4
        mcmf_edge* rev; // 9d
        mcmf_edge(int _u, int _v, ll _w, ll _c, mcmf_edge* _rev = NULL) { // ea
            u = _u; v = _v; w = _w; c = _c; rev = _rev; // 83
        } // 02
    }; // b9
    int n; // b4
    vector<pair<int, pair<ll, ll> > > adj; // 72
    flow_network(int _n) { // 55
        n = _n; // fa
        adj = new vector<pair<int, pair<ll, ll> > >[n]; // bb
    } // bd
    void add_edge(int u, int v, ll cost, ll cap) { // 79
        adj[u].push_back(make_pair(v, make_pair(cap, cost))); // c8
    } // ed
    pair<ll,ll> min_cost_max_flow(int s, int t) { // ea
        vector<mcmf_edge*> g = new vector<mcmf_edge*>[n]; // ce
        for (int i = 0; i < n; i++) { // 57
            for (int j = 0; j < size(adj[i]); j++) { // 37
                mcmf_edge *cur = new mcmf_edge(i, adj[i][j].first, // 21
                    adj[i][j].second.first, adj[i][j].second.second), // 56
                    *rev = new mcmf_edge(adj[i][j].first, i, 0, // 48
                        adj[i][j].second.second, cur); // b1
                cur->rev = rev; // ef
                g[i].push_back(cur); // 1d
                g[adj[i][j].first].push_back(rev); // 05
            } // ba
        } // 83
        ll flow = 0, cost = 0; // 68
        mcmf_edge** back = new mcmf_edge*[n]; // e5
        ll* dist = new ll[n]; // 50
        while (true) { // 65
            for (int i = 0; i < n; i++) back[i] = NULL, dist[i] = INF; // d0
            dist[s] = 0; // 5e
            for (int i = 0; i < n - 1; i++) // be
                for (int j = 0; j < n; j++) // 6e
                    if (dist[j] != INF) // e3
                        for (int k = 0; k < size(g[j]); k++) // 85
                            if (g[j][k]->w > 0 && dist[j] + g[j][k]->c < // 7f
                                dist[g[j][k]->v]) { // 6d
                                dist[g[j][k]->v] = dist[j] + g[j][k]->c; // cf
                                back[g[j][k]->v] = g[j][k]; // 3d
                            } // f3
            mcmf_edge* cure = back[t]; // b4
            if (cure == NULL) break; // ab
            ll cap = INF; // 7a
            while (true) { // ad
                cap = min(cap, cure->w); // c3
                if (cure->u == s) break; // 82
                cure = back[cure->u]; // 45
            } // 91
            assert(cap > 0 && cap < INF); // ae
            cure = back[t]; // b9
            while (true) { // 2a
                cost += cap * cure->c; // f8
                cure->w -= cap; // d1
                cure->rev->w += cap; // cf
            }
        }
    }
};
```


Reykjavík University15

```
-----if (cure->u == s) break;-----// 8c
-----cure = back[cure->u];-----// 60
-----}-----// 09
-----flow += cap;-----// f2
-----}-----// be
-----// instead of deleting g, we could also-----// e0
-----// use it to get info about the actual flow-----// 6c
-----for (int i = 0; i < n; i++)-----// eb
-----for (int j = 0; j < size(g[i]); j++)-----// 82
-----delete g[i][j];-----// 06
-----delete[] g;-----// 23
-----delete[] back;-----// 5a
-----delete[] dist;-----// b9
-----return make_pair(flow, cost);-----// ec
-----}-----// ad
};-----// bf
```

3.11. All Pairs Maximum Flow.

3.11.1. *Gomory-Hu Tree*. An implementation of the Gomory-Hu Tree. The spanning tree is constructed using Gusfield’s algorithm in $O(|V|^2)$ plus $|V| - 1$ times the time it takes to calculate the maximum flow. If Dinic’s algorithm is used to calculate the max flow, the running time is $O(|V|^3|E|)$. NOTE: Not sure if it works correctly with disconnected graphs.

```
#include "dinic.cpp"-----// 58
-----// 25
bool same[MAXV];-----// 59
pair<vii, vvi> construct_gh_tree(flow_network &g) {-----// 77
---int n = g.n, v;-----// 5d
---vii par(n, ii(0, 0)); vvi cap(n, vi(n, -1));-----// 49
---rep(s,1,n) {-----// 9e
-----int l = 0, r = 0;-----// 08
-----par[s].second = g.max_flow(s, par[s].first, false);-----// 54
-----memset(d, 0, n * sizeof(int));-----// c8
-----memset(same, 0, n * sizeof(bool));-----// c9
-----d[q[r++] = s] = 1;-----// dd
-----while (l < r) {-----// 45
-----same[v = q[l++]] = true;-----// c5
-----for (int i = g.head[v]; i != -1; i = g.e[i].nxt)-----// 66
-----if (g.e[i].cap > 0 && d[g.e[i].v] == 0)-----// 21
-----d[q[r++] = g.e[i].v] = 1;-----// dd
-----}-----// 44
-----rep(i,s+1,n)-----// 71
-----if (par[i].first == par[s].first && same[i]) par[i].first = s;-----// 97
-----g.reset();-----// d8
-----}-----// 93
---rep(i,0,n) {-----// 14
-----int mn = INF, cur = i;-----// 59
-----while (true) {-----// b8
-----cap[cur][i] = mn;-----// 8d
-----if (cur == 0) break;-----// fb
-----mn = min(mn, par[cur].second), cur = par[cur].first;-----// 4d
-----}-----// aa
```

3.12. Heavy-Light Decomposition.

```
#include "../data-structures/segment_tree.cpp"-----// 16
struct HLD {-----// 25
---int n, curhead, curloc;-----// d9
---vi sz, head, parent, loc;-----// 81
---vvi adj; segment_tree values;-----// 13
---HLD(int _n) : n(_n), sz(n, 1), head(n), parent(n, -1), loc(n), adj(n) {-----// 1c
---vi tmp(n, ID); values = segment_tree(tmp); }-----// f0
---void add_edge(int u, int v) { adj[u].push_back(v), adj[v].push_back(u); }-----// 77
---void update_cost(int u, int v, int c) {-----// 7b
-----if (parent[v] == u) swap(u, v); assert(parent[u] == v);-----// db
-----values.update(loc[u], c); }-----// 50
---int csz(int u) {-----// 7c
---rep(i,0,size(adj[u])) if (adj[u][i] != parent[u])-----// a5
---sz[u] += csz(adj[parent[adj[u][i]] = u][i]);-----// c2
---return sz[u]; }-----// 75
---void part(int u) {-----// c3
---head[u] = curhead; loc[u] = curloc++;-----// 63
---int best = -1;-----// 27
---rep(i,0,size(adj[u]))-----// 49
---if (adj[u][i] != parent[u] && (best == -1 || sz[adj[u][i]] > sz[best]))-----// 26
---best = adj[u][i];-----// c4
---if (best != -1) part(best);-----// 92
---rep(i,0,size(adj[u]))-----// 92
---if (adj[u][i] != parent[u] && adj[u][i] != best)-----// e8
---part(curhead = adj[u][i]); }-----// 88
---void build(int r = 0) { curloc = 0, csz(curhead = r), part(r); }-----// 78
---int lca(int u, int v) {-----// 74
---vi uat, vat; int res = -1;-----// 43
---while (u != -1) uat.push_back(u), u = parent[head[u]];-----// 51
---while (v != -1) vat.push_back(v), v = parent[head[v]];-----// 6d
---u = size(uat) - 1, v = size(vat) - 1;-----// 8a
---while (u >= 0 && v >= 0 && head[uat[u]] == head[vat[v]])-----// ae
---res = (loc[uat[u]] < loc[vat[v]] ? uat[u] : vat[v]), u--, v--;-----// a2
---return res; }-----// 91
---int query_upto(int u, int v) { int res = ID;-----// 72
---while (head[u] != head[v])-----// 69
---res = f(res, values.query(loc[head[u]], loc[u])),-----// a4
---u = parent[head[u]];-----// 8c
---return f(res, values.query(loc[v] + 1, loc[u])); }-----// ea
```



```
----int query(int u, int v) { int l = lca(u, v);-----// 53
-----return f(query_upto(u, l), query_upto(v, l)); } }-----// 5b

3.13. Centroid Decomposition.

#define MAXV 100100-----// 86
#define LGMAXV 20-----// aa
int jmp[MAXV][LGMAXV],-----// 6d
---path[MAXV][LGMAXV],-----// 9d
---sz[MAXV], seph[MAXV],-----// cf
---shortest[MAXV];-----// 6b
struct centroid_decomposition {-----// 99
---int n; vvi adj;-----// e9
---centroid_decomposition(int _n) : n(_n), adj(n) { }-----// 46
---void add_edge(int a, int b) { adj[a].push_back(b), adj[b].push_back(a); }-----// bc
---int dfs(int u, int p) {-----// 8f
-----sz[u] = 1;-----// c8
-----rep(i,0,size(adj[u])) if (adj[u][i] != p) sz[u] += dfs(adj[u][i], u);-----// 78
-----return sz[u]; }-----// f4
---void makepaths(int sep, int u, int p, int len) {-----// 84
-----jmp[u][seph[sep]] = sep, path[u][seph[sep]] = len;-----// d9
---int bad = -1;-----// af
-----rep(i,0,size(adj[u])) {-----// f4
-----if (adj[u][i] == p) bad = i;-----// cf
-----else makepaths(sep, adj[u][i], u, len + 1);-----// f2
-----}-----// 8a
-----if (p == sep) swap(adj[u][bad], adj[u].back()), adj[u].pop_back(); }-----// 07
---void separate(int h=0, int u=0) {-----// 03
---dfs(u,-1); int sep = u;-----// b5
---down: iter(nxt,adj[sep])-----// 04
---if (sz[*nxt] < sz[sep] && sz[*nxt] > sz[u]/2) {-----// db
---sep = *nxt; goto down; }-----// 1a
-----seph[sep] = h, makepaths(sep, sep, -1, 0);-----// ed
-----rep(i,0,size(adj[sep])) separate(h+1, adj[sep][i]); }-----// 90
---void paint(int u) {-----// bd
---rep(h,0,seph[u]+1)-----// c5
---shortest[jmp[u][h]] = min(shortest[jmp[u][h]], path[u][h]); }-----// 11
---int closest(int u) {-----// 91
---int mn = INF/2;-----// fe
---rep(h,0,seph[u]+1) mn = min(mn, path[u][h] + shortest[jmp[u][h]]);-----// 3e
---return mn; } }-----// 13
```

3.14. Least Common Ancestors, Binary Jumping.

```
struct node {-----// 36
---node *p, *jmp[20];-----// 24
---int depth;-----// 10
---node(node *_p = NULL) : p(_p) {-----// 78
-----depth = p ? 1 + p->depth : 0;-----// 3b
-----memset(jmp, 0, sizeof(jmp));-----// 64
-----jmp[0] = p;-----// 64
-----for (int i = 1; (1<<i) <= depth; i++)-----// a8
-----jmp[i] = jmp[i-1]->jmp[i-1]; } }-----// 3b
node* st[100000];-----// 65
```

```
node* lca(node *a, node *b) {-----// 29
---if (!a || !b) return NULL;-----// cd
---if (a->depth < b->depth) swap(a,b);-----// fe
---for (int j = 19; j >= 0; j--)-----// b3
---while (a->depth - (1<<j) >= b->depth) a = a->jmp[j];-----// c0
---if (a == b) return a;-----// 08
---for (int j = 19; j >= 0; j--)-----// 11
---while (a->depth >= (1<<j) && a->jmp[j] != b->jmp[j])-----// f0
---a = a->jmp[j], b = b->jmp[j];-----// d0
---return a->p; }-----// c5
```

3.15. Tarjan's Off-line Lowest Common Ancestors Algorithm.

```
#include "../data-structures/union_find.cpp"-----// 5e
struct tarjan_olca {-----// 87
---int *ancestor;-----// 39
---vi *adj, answers;-----// dd
---vii *queries;-----// 66
---bool *colored;-----// 97
---union_find uf;-----// 70
---tarjan_olca(int n, vi *_adj) : adj(_adj), uf(n) {-----// 78
-----colored = new bool[n];-----// 8d
-----ancestor = new int[n];-----// f2
-----queries = new vii[n];-----// 3e
-----memset(colored, 0, n);-----// 6e
-----}-----// 6b
---void query(int x, int y) {-----// d3
-----queries[x].push_back(ii(y, size(answers)));-----// a0
-----queries[y].push_back(ii(x, size(answers)));-----// 14
-----answers.push_back(-1);-----// ca
-----}-----// 6b
---void process(int u) {-----// 85
---ancestor[u] = u;-----// 1a
---rep(i,0,size(adj[u])) {-----// ce
---int v = adj[u][i];-----// dd
---process(v);-----// e8
---uf.unite(u,v);-----// 55
---ancestor[uf.find(u)] = u;-----// 1d
-----}-----// 57
---colored[u] = true;-----// b9
---rep(i,0,size(queries[u])) {-----// d7
---int v = queries[u][i].first;-----// 89
---if (colored[v]) {-----// cb
---answers[queries[u][i].second] = ancestor[uf.find(v)];-----// 63
---}-----// d0
-----}-----// 40
-----}-----// a9
};-----// 1e
```

3.16. Maximum Density Subgraph. Given (weighted) undirected graph G . Binary search density. If g is current density, construct flow network: (S, u, m) , $(u, T, m + 2g - d_u)$, $(u, v, 1)$, where m is a large constant (larger than sum of edge weights). Run floating-point max-flow. If minimum cut has empty S -component, then maximum density is smaller than g , otherwise it's larger. Distance between

valid densities is at least $1/(n(n-1))$. Edge case when density is 0. This also works for weighted graphs by replacing d_u be the weighted degree, and doing more iterations (if weights are not integers).

3.17. Maximum Weighted Independent Set in a Bipartite Graph. This is the same as the minimum weighted vertex cover. Solve this by constructing a flow network with edges $(S,u,w(u))$ for $u \in L$, $(v,T,w(v))$ for $v \in R$ and (u,v,∞) for $(u,v) \in E$. The minimum S,T -cut is the answer. Vertices adjacent to a cut edge are in the vertex cover.

4. STRINGS

4.1. The Knuth-Morris-Pratt algorithm. An implementation of the Knuth-Morris-Pratt algorithm. Runs in $O(n+m)$ time, where n and m are the lengths of the string and the pattern.

```
int* compute_pi(const string &t) {-----// a2
---int m = t.size();-----// 8b
---int *pit = new int[m + 1];-----// 8e
---if (0 <= m) pit[0] = 0;-----// 42
---if (1 <= m) pit[1] = 0;-----// 34
---rep(i,2,m+1) {-----// 0f
---    for (int j = pit[i - 1]; ; j = pit[j]) {-----// b5
---        if (t[j] == t[i - 1]) { pit[i] = j + 1; break; }-----// 21
---        if (j == 0) { pit[i] = 0; break; }-----// 95
---    }-----// c9
---}-----// eb
---return pit; }-----// e8
int string_match(const string &s, const string &t) {-----// 9e
---int n = s.size(), m = t.size();-----// 92
---int *pit = compute_pi(t);-----// 72
---for (int i = 0, j = 0; i < n; ) {-----// 27
---    if (s[i] == t[j]) {-----// 73
---        i++; j++;-----// 7e
---        if (j == m) {-----// de
---            return i - m;-----// e9
---            // or j = pit[j];-----// ce
---        }-----// 85
---    }-----// 35
---    else if (j > 0) j = pit[j];-----// 43
---    else i++; }-----// b8
---delete[] pit; return -1; }-----// e3
```

4.2. The Z algorithm. Given a string S , $Z_i(S)$ is the longest substring of S starting at i that is also a prefix of S . The Z algorithm computes these Z values in $O(n)$ time, where $n = |S|$. Z values can, for example, be used to find all occurrences of a pattern P in a string T in linear time. This is accomplished by computing Z values of $S = TP$, and looking for all i such that $Z_i \geq |T|$.

```
int* z_values(const string &s) {-----// 4d
---int n = size(s);-----// 97
---int* z = new int[n];-----// c4
---int l = 0, r = 0;-----// 1c
---z[0] = n;-----// 98
---rep(i,1,n) {-----// b2
---    z[i] = 0;-----// 4c
---    if (i > r) {-----// 6d
---        l = r = i;-----// 24
---        while (r < n && s[r - l] == s[r]) r++;-----// 68
```

```
-----z[i] = r - l; r--;-----// 07
---    } else if (z[i - l] < r - i + 1) z[i] = z[i - l];-----// 6f
---    else {-----// a8
---        l = i;-----// 55
---        while (r < n && s[r - l] == s[r]) r++;-----// 2c
---        z[i] = r - l; r--; } }-----// 13
---    return z;-----// 78
}-----// 16
```

4.3. Trie. A Trie class.

```
template <class T>-----// 82
struct trie {-----// 4a
---    struct node {-----// 39
---        map<T, node*> children;-----// 82
---        int prefixes, words;-----// ff
---        node() { prefixes = words = 0; } } ;-----// 16
---    node* root;-----// 97
---    trie() : root(new node()) { }-----// d2
---    template <class I>-----// 2f
---    void insert(I begin, I end) {-----// 3b
---        node* cur = root;-----// ae
---        while (true) {-----// 03
---            cur->prefixes++;-----// 6c
---            if (begin == end) { cur->words++; break; }-----// df
---            else {-----// 51
---                T head = *begin;-----// 8f
---                typename map<T, node*>::const_iterator it;-----// ff
---                it = cur->children.find(head);-----// 57
---                if (it == cur->children.end()) {-----// f7
---                    pair<T, node*> nw(head, new node());-----// 66
---                    it = cur->children.insert(nw).first;-----// c5
---                    } begin++, cur = it->second; } } }-----// 68
---    template<class I>-----// 51
---    int countMatches(I begin, I end) {-----// 84
---        node* cur = root;-----// 88
---        while (true) {-----// 5b
---            if (begin == end) return cur->words;-----// 61
---            else {-----// c1
---                T head = *begin;-----// 75
---                typename map<T, node*>::const_iterator it;-----// 00
---                it = cur->children.find(head);-----// c6
---                if (it == cur->children.end()) return 0;-----// 06
---                begin++, cur = it->second; } } }-----// 85
---    template<class I>-----// e7
---    int countPrefixes(I begin, I end) {-----// 7d
---        node* cur = root;-----// c6
---        while (true) {-----// ac
---            if (begin == end) return cur->prefixes;-----// 33
---            else {-----// 85
---                T head = *begin;-----// 0e
---                typename map<T, node*>::const_iterator it;-----// 6e
```

```
-----it = cur->children.find(head);-----// 40
-----if (it == cur->children.end()) return 0;-----// 18
-----begin++, cur = it->second; } } } ;-----// 7a
```

4.4. **Suffix Array.** An $O(n \log^2 n)$ construction of a Suffix Tree.

```
struct entry { ii nr; int p; };-----// f9
bool operator <(const entry &a, const entry &b) { return a.nr < b.nr; }-----// 77
struct suffix_array {-----// 87
----string s; int n; vvi P; vector<entry> L; vi idx;-----// b6
----suffix_array(string _s) : s(_s), n(size(s)) {-----// a3
-----L = vector<entry>(n), P.push_back(vi(n)), idx = vi(n);-----// 12
-----rep(i,0,n) P[0][i] = s[i];-----// 5c
-----for (int stp = 1, cnt = 1; cnt >> 1 < n; stp++, cnt <= 1) {-----// 86
-----P.push_back(vi(n));-----// 53
-----rep(i,0,n)-----// 6f
-----L[L[i].p = i].nr = ii(P[stp - 1][i],-----// e2
-----i + cnt < n ? P[stp - 1][i + cnt] : -1);-----// 43
-----sort(L.begin(), L.end());-----// 5f
-----rep(i,0,n)-----// a8
-----P[stp][L[i].p] = i > 0 &&-----// 3a
-----L[i].nr == L[i - 1].nr ? P[stp][L[i - 1].p] : i;-----// 55
-----}-----// 8b
-----rep(i,0,n) idx[P[size(P) - 1][i]] = i;-----// 17
-----}-----// d9
----int lcp(int x, int y) {-----// 71
----int res = 0;-----// d6
----if (x == y) return n - x;-----// bc
----for (int k = size(P) - 1; k >= 0 && x < n && y < n; k--)-----// fe
----if (P[k][x] == P[k][y]) x += 1 << k, y += 1 << k, res += 1 << k;-----// b7
----return res;-----// bc
----}-----// f1
};-----// f6
```

4.5. **Aho-Corasick Algorithm.** An implementation of the Aho-Corasick algorithm. Constructs a state machine from a set of keywords which can be used to search a string for any of the keywords.

```
struct aho_corasick {-----// 78
----struct out_node {-----// 3e
----string keyword; out_node *next;-----// f0
----out_node(string k, out_node *n) : keyword(k), next(n) { }-----// 26
----};-----// b9
----struct go_node {-----// 40
----map<char, go_node*> next;-----// 6b
----out_node *out; go_node *fail;-----// 3e
----go_node() { out = NULL; fail = NULL; }-----// 0f
----};-----// c0
----go_node *go;-----// b8
----aho_corasick(vector<string> keywords) {-----// 4b
----go = new go_node();-----// 77
----iter(k, keywords) {-----// f2
----go_node *cur = go;-----// a2
----iter(c, *k)-----// 6e
----cur = cur->next.find(*c) != cur->next.end() ? cur->next[*c] :-----// 97
```

```
----- (cur->next[*c] = new go_node());-----// af
-----cur->out = new out_node(*k, cur->out);-----// 3f
-----}-----// eb
----queue<go_node*> q;-----// 2c
----iter(a, go->next) q.push(a->second);-----// db
----while (!q.empty()) {-----// 07
----go_node *r = q.front(); q.pop();-----// e0
----iter(a, r->next) {-----// 18
----go_node *s = a->second;-----// 55
----q.push(s);-----// b5
----go_node *st = r->fail;-----// 53
----while (st && st->next.find(a->first) == st->next.end())-----// 0e
----st = st->fail;-----// b3
----if (!st) st = go;-----// 0b
----s->fail = st->next[a->first];-----// c1
----if (s->fail) {-----// 98
----else {-----// 5b
----out_node* out = s->out;-----// b8
----while (out->next) out = out->next;-----// b4
----out->next = s->fail->out;-----// 62
----}-----// a6
----}-----// 81
----}-----// 55
----}-----// bf
----}-----// de
----vector<string> search(string s) {-----// c4
----vector<string> res;-----// 79
----go_node *cur = go;-----// 85
----iter(c, s) {-----// 57
----while (cur && cur->next.find(*c) == cur->next.end())-----// df
----cur = cur->fail;-----// b1
----if (!cur) cur = go;-----// 92
----cur = cur->next[*c];-----// 97
----if (!cur) cur = go;-----// 01
----for (out_node *out = cur->out; out; out = out->next)-----// d7
----res.push_back(out->keyword);-----// 7c
----}-----// 56
----return res;-----// 6b
----}-----// 3e
};-----// de
```

4.6. **eerTree.** Constructs an eerTree in $O(n)$, one character at a time.

```
#define MAXN 100100-----// 29
#define SIGMA 26-----// e2
#define BASE 'a'-----// a1
char *s = new char[MAXN];-----// db
struct state {-----// 33
----int len, link, to[SIGMA];-----// 24
} *st = new state[MAXN+2];-----// 57
struct eertree {-----// 78
```

```
int last, sz, n;-----// ba
eertree() : last(1), sz(2), n(0) {-----// 83
    st[0].len = st[0].link = -1;-----// 3f
    st[1].len = st[1].link = 0; }-----// 34
int extend() {-----// c2
    char c = s[n++]; int p = last;-----// 25
    while (n - st[p].len - 2 < 0 || c != s[n - st[p].len - 2]) p = st[p].link;
    if (!st[p].to[c-BASE]) {-----// 82
        int q = last = sz++;-----// 42
        st[p].to[c-BASE] = q;-----// fc
        st[q].len = st[p].len + 2;-----// c5
        do { p = st[p].link;-----// 04
        } while (p != -1 && (n < st[p].len + 2 || c != s[n - st[p].len - 2]));
        if (p == -1) st[q].link = 1;-----// 77
        else st[q].link = st[p].to[c-BASE];-----// 6a
        return 1; }-----// 29
    last = st[p].to[c-BASE];-----// 42
    return 0; } };;-----// ec
```

4.7. **Suffix Automaton.** Minimum automata that accepts all suffixes of a string with $O(n)$ construction. The automata itself is a DAG therefore suitable for DP, examples are counting unique substrings, occurrences of substrings and suffix.

```
// TODO: Add longest common subsring-----// 0e
const int MAXL = 100000;-----// 31
struct suffix_automaton {-----// e0
    vi len, link, occur, cnt;-----// 78
    vector<map<char,int>> next;-----// 90
    vector<bool> isclone;-----// 7b
    ll *occuratleast;-----// f2
    int sz, last;-----// 7d
    string s;-----// f2
    suffix_automaton() : len(MAXL*2), link(MAXL*2), occur(MAXL*2), next(MAXL*2),
    isclone(MAXL*2) { clear(); }-----// a3
    void clear(){ sz = 1; last = len[0] = 0; link[0] = -1; next[0].clear();-----// aa
    isclone[0] = false; }-----// 26
    bool issubstr(string other){-----// 3b
        for(int i = 0, cur = 0; i < size(other); ++i){-----// 7f
            if(cur == -1) return false; cur = next[cur][other[i]]; }-----// 54
        return true; }-----// 1a
    void extend(char c){ int cur = sz++; len[cur] = len[last] + 1;-----// 1d
    next[cur].clear(); isclone[cur] = false; int p = last;-----// a9
    for(; p != -1 && !next[p].count(c); p = link[p]){ next[p][c] = cur; }-----// 6f
    if(p == -1){ link[cur] = 0; }-----// 18
    else{ int q = next[p][c];-----// 34
        if(len[p] + 1 == len[q]){ link[cur] = q; }-----// 4d
        else { int clone = sz++; isclone[clone] = true;-----// 57
            len[clone] = len[p] + 1;-----// 8c
            link[clone] = link[q]; next[clone] = next[q];-----// 76
            for(; p != -1 && next[p].count(c) && next[p][c] == q; p = link[p]){
                next[p][c] = clone; }-----// 32
            link[q] = link[cur] = clone;-----// 73
```

```
    } } last = cur; }-----// b9
    void count(){-----// e7
        cnt=vi(sz, -1); stack<ii> S; S.push(ii(0,0));map<char,int>::iterator i;-----// 56
        while(!S.empty()){-----// 4c
            ii cur = S.top(); S.pop();-----// 67
            if(cur.second){-----// 78
                for(i = next[cur.first].begin(); i != next[cur.first].end();++i){
                    cnt[cur.first] += cnt[(*i).second]; } }-----// da
                else if(cnt[cur.first] == -1){-----// 99
                    cnt[cur.first] = 1; S.push(ii(cur.first, 1));-----// bd
                    for(i = next[cur.first].begin(); i != next[cur.first].end();++i){
                        S.push(ii((*i).second, 0)); } } } }-----// 61
string lexicok(ll k){-----// 8b
    int st = 0; string res; map<char,int>::iterator i;-----// cf
    while(k){ for(i = next[st].begin(); i != next[st].end(); ++i){-----// 69
        if(k <= cnt[(*i).second]){ st = (*i).second;-----// ec
            res.push_back((*i).first); k--; break; }-----// 63
        } else { k -= cnt[(*i).second]; } } }-----// ee
    return res; }-----// 0b
    void countoccur(){-----// ad
        for(int i = 0; i < sz; ++i){ occur[i] = 1 - isclone[i]; }-----// 1b
        vii states(sz);-----// dc
        for(int i = 0; i < sz; ++i){ states[i] = ii(len[i],i); }-----// 97
        sort(states.begin(), states.end());-----// 8d
        for(int i = size(states)-1; i >= 0; --i){ int v = states[i].second;-----// a4
            if(link[v] != -1) { occur[link[v]] += occur[v]; } } }-----// cc
};-----// 32
-----// 56
```

4.8. **Hashing.** Modulus should be a large prime. Can also use multiple instances with different moduli to minimize chance of collision.

```
struct hasher { int b = 311, m; vi h, p;-----// 61
    hasher(string s, int _m) : m(_m), h(size(s)+1), p(size(s)+1) {-----// f6
        p[0] = 1; h[0] = 0;-----// d3
        rep(i,0,size(s)) p[i+1] = ((ll)p[i] * b % m;-----// 8a
        rep(i,0,size(s)) h[i+1] = ((ll)h[i] * b + s[i]) % m; }-----// 10
    int hash(int l, int r) {-----// b2
        return (h[r+1] + m - (ll)h[l] * p[r-l+1] % m) % m; } };;-----// 26
```

5. MATHEMATICS

5.1. **Fraction.** A fraction (rational number) class. Note that numbers are stored in lowest common terms.

```
template <class T> struct fraction {-----// 27
    T gcd(T a, T b) { return b == T(0) ? a : gcd(b, a % b); }-----// fe
    T n, d;-----// 6a
    fraction(T n_, T d_) {-----// b0
        assert(d_ != 0);-----// 8c
        n = n_, d = d_;-----// ad
        if (d < T(0)) n = -n, d = -d;-----// bc
        T g = gcd(abs(n), abs(d));-----// 95
        n /= g, d /= g; }-----// 53
```

```
---fraction(T n_) : n(n_), d(1) {}-----// ec
---fraction(const fraction<T>& other) : n(other.n), d(other.d) {}-----// a6
---fraction<T> operator +(const fraction<T>& other) const {-----// 24
-----return fraction<T>(n * other.d + other.n * d, d * other.d);}-----// d1
---fraction<T> operator -(const fraction<T>& other) const {-----// 89
-----return fraction<T>(n * other.d - other.n * d, d * other.d);}-----// bf
---fraction<T> operator *(const fraction<T>& other) const {-----// 10
-----return fraction<T>(n * other.n, d * other.d); }-----// b4
---fraction<T> operator /(const fraction<T>& other) const {-----// 33
-----return fraction<T>(n * other.d, d * other.n); }-----// bc
---bool operator <(const fraction<T>& other) const {-----// e8
-----return n * other.d < other.n * d; }-----// cc
---bool operator <=(const fraction<T>& other) const {-----// 89
-----return !(other < *this); }-----// 90
---bool operator >(const fraction<T>& other) const {-----// e7
-----return other < *this; }-----// 24
---bool operator >=(const fraction<T>& other) const {-----// 94
-----return !(*this < other); }-----// 18
---bool operator ==(const fraction<T>& other) const {-----// b8
-----return n == other.n && d == other.d; }-----// 6f
---bool operator !=(const fraction<T>& other) const {-----// 5d
-----return !(*this == other); } }-----// 8f
```

5.2. Big Integer. A big integer class.

```
struct intx {-----// cf
---intx() { normalize(1); }-----// 6c
---intx(string n) { init(n); }-----// b9
---intx(int n) { stringstream ss; ss << n; init(ss.str()); }-----// 36
---intx(const intx& other) : sign(other.sign), data(other.data) {}-----// 3b
---int sign;-----// 26
---vector<unsigned int> data;-----// 19
---static const int dcnt = 9;-----// 12
---static const unsigned int radix = 1000000000U;-----// f0
---int size() const { return data.size(); }-----// 29
---void init(string n) {-----// 13
---intx res; res.data.clear();-----// 4e
-----if (n.empty()) n = "0";-----// 99
-----if (n[0] == '-') res.sign = -1, n = n.substr(1);-----// 3b
-----for (int i = n.size() - 1; i >= 0; i -= intx::dcnt) {-----// e7
-----unsigned int digit = 0;-----// 98
-----for (int j = intx::dcnt - 1; j >= 0; j--) {-----// 72
-----int idx = i - j;-----// cd
-----if (idx < 0) continue;-----// 52
-----digit = digit * 10 + (n[idx] - '0');-----// 1f
-----}-----// c0
-----res.data.push_back(digit);-----// 07
-----}-----// fb
---data = res.data;-----// 7d
---normalize(res.sign);-----// 76
---}-----// 6e
---intx& normalize(int nsign) {-----// 3b
-----if (data.empty()) data.push_back(0);-----// fa
-----for (int i = data.size() - 1; i > 0 && data[i] == 0; i--)-----// 27
-----data.erase(data.begin() + i);-----// 67
-----sign = data.size() == 1 && data[0] == 0 ? 1 : nsign;-----// ff
-----return *this;-----// 40
-----}-----// ac
---friend ostream& operator <<(ostream& outs, const intx& n) {-----// 0d
-----if (n.sign < 0) outs << '-';-----// c0
-----bool first = true;-----// 33
-----for (int i = n.size() - 1; i >= 0; i--) {-----// 63
-----if (first) outs << n.data[i], first = false;-----// 33
-----else {-----// 1f
-----unsigned int cur = n.data[i];-----// 0f
-----stringstream ss; ss << cur;-----// 8c
-----string s = ss.str();-----// 64
-----int len = s.size();-----// 0d
-----while (len < intx::dcnt) outs << '0', len++;-----// 0a
-----outs << s;-----// 97
-----}-----// f7
-----}-----// e9
-----return outs;-----// cf
-----}-----// b9
---string to_string() const { stringstream ss; ss << *this; return ss.str(); }// fc
---bool operator <(const intx& b) const {-----// 21
-----if (sign != b.sign) return sign < b.sign;-----// cf
-----if (size() != b.size())-----// 4d
-----return sign == 1 ? size() < b.size() : size() > b.size();-----// 4d
-----for (int i = size() - 1; i >= 0; i--) if (data[i] != b.data[i])-----// 35
-----return sign == 1 ? data[i] < b.data[i] : data[i] > b.data[i];-----// 27
-----return false;-----// ca
-----}-----// 32
---intx operator -() const { intx res(*this); res.sign *= -1; return res; }// 9d
---friend intx abs(const intx &n) { return n < 0 ? -n : n; }-----// 02
---intx operator +(const intx& b) const {-----// f8
-----if (sign > 0 && b.sign < 0) return *this - (-b);-----// 36
-----if (sign < 0 && b.sign > 0) return b - (-*this);-----// 70
-----if (sign < 0 && b.sign < 0) return -((-*this) + (-b));-----// 59
---intx c; c.data.clear();-----// 18
---unsigned long long carry = 0;-----// 5c
---for (int i = 0; i < size() || i < b.size() || carry; i++) {-----// e3
---carry += (i < size() ? data[i] : 0ULL) +-----// 91
---(i < b.size() ? b.data[i] : 0ULL);-----// 0c
---c.data.push_back(carry % intx::radix);-----// 86
---carry /= intx::radix;-----// fd
---}-----// 50
---return c.normalize(sign);-----// 20
---}-----// 70
---intx operator -(const intx& b) const {-----// 53
---if (sign > 0 && b.sign < 0) return *this + (-b);-----// 8f
---if (sign < 0 && b.sign > 0) return -(-*this + b);-----// 1b
---if (sign < 0 && b.sign < 0) return (-b) - (-*this);-----// a1
```



```
-----if (*this < b) return -(b - *this);-----// 36 #include "intx.cpp"-----// 83
-----intx c; c.data.clear();-----// 6b #include "fft.cpp"-----// 13
-----long long borrow = 0;-----// f8
-----rep(i,0,size()) {-----// a7 intx fastmul(const intx &an, const intx &bn) {-----// ab
-----    borrow = data[i] - borrow - (i < b.size() ? b.data[i] : 0ULL);-----// a5 ----string as = an.to_string(), bs = bn.to_string();-----// 32
-----    c.data.push_back(borrow < 0 ? intx::radix + borrow : borrow);-----// 9b ----int n = size(as), m = size(bs), l = 1,-----// dc
-----    borrow = borrow < 0 ? 1 : 0;-----// fb ----len = 5, radix = 100000,-----// 4f
-----}-----// dd ----*a = new int[n], alen = 0,-----// b8
-----return c.normalize(sign);-----// 5c ----*b = new int[m], blen = 0;-----// 0a
-----}-----// 5e ----memset(a, 0, n <= 2);-----// 1d
-----intx operator *(const intx& b) const {-----// b3 ----memset(b, 0, m <= 2);-----// 01
-----intx c; c.data.assign(size() + b.size() + 1, 0);-----// 3a ----for (int i = n - 1; i >= 0; i -= len, alen++)-----// 6e
-----rep(i,0,size()) {-----// 0f ----    for (int j = min(len - 1, i); j >= 0; j--)-----// 43
-----    long long carry = 0;-----// 15 ----        a[alen] = a[alen] * 10 + as[i - j] - '0';-----// 14
-----    for (int j = 0; j < b.size() || carry; j++) {-----// 95 ----    for (int i = m - 1; i >= 0; i -= len, blen++)-----// b6
-----        if (j < b.size()) carry += (long long)data[i] * b.data[j];-----// 6d ----        for (int j = min(len - 1, i); j >= 0; j--)-----// ae
-----        carry += c.data[i + j];-----// c6 ----            b[blen] = b[blen] * 10 + bs[i - j] - '0';-----// 9b
-----        c.data[i + j] = carry % intx::radix;-----// a8 ----    while (l < 2*max(alen,blen)) l <= 1;-----// 51
-----        carry /= intx::radix;-----// dc ----    cpx *A = new cpx[l], *B = new cpx[l];-----// 0d
-----    }-----// e3 ----    rep(i,0,l) A[i] = cpx(i < alen ? a[i] : 0, 0);-----// ff
-----}-----// f0 ----    rep(i,0,l) B[i] = cpx(i < blen ? b[i] : 0, 0);-----// 7f
-----return c.normalize(sign * b.sign);-----// 09 ----    fft(A, l); fft(B, l);-----// 77
-----}-----// a7 ----    rep(i,0,l) A[i] *= B[i];-----// 1c
-----friend pair<intx,intx> divmod(const intx& n, const intx& d) {-----// 40 ----    fft(A, l, true);-----// ec
-----assert(!(d.size() == 1 && d.data[0] == 0));-----// 42 ----    ull *data = new ull[l];-----// f1
-----intx q, r; q.data.assign(n.size(), 0);-----// 5e ----    rep(i,0,l) data[i] = (ull)(round(real(A[i])));-----// e2
-----for (int i = n.size() - 1; i >= 0; i--) {-----// 52 ----    rep(i,0,l-1)-----// c8
-----    r.data.insert(r.data.begin(), 0);-----// cb ----        if (data[i] >= (unsigned int)(radix)) {-----// 03
-----    r = r + n.data[i];-----// ea ----            data[i+1] += data[i] / radix;-----// 48
-----    long long k = 0;-----// dd ----            data[i] %= radix;-----// 94
-----    if (d.size() < r.size())-----// 4d ----        }-----// 47
-----        k = (long long)intx::radix * r.data[d.size()];-----// d2 ----    int stop = l-1;-----// 92
-----    if (d.size() - 1 < r.size()) k += r.data[d.size() - 1];-----// af ----    while (stop > 0 && data[stop] == 0) stop--;-----// 5b
-----    k /= d.data.back();-----// 85 ----    stringstream ss;-----// a6
-----    r = r - abs(d) * k;-----// 3b ----    ss << data[stop];-----// f3
-----    // if (r < 0) for (ll t = 1LL << 62; t >= 1; t >= 1) {-----// 0e ----    for (int i = stop - 1; i >= 0; i--)-----// 7b
-----    //---- intx dd = abs(d) * t;-----// 9d ----        ss << setfill('0') << setw(len) << data[i];-----// 41
-----    //---- while (r + dd < 0) r = r + dd, k -= t; }-----// a1 ----    delete[] A; delete[] B;-----// dd
-----    while (r < 0) r = r + abs(d), k--;-----// cb ----    delete[] a; delete[] b;-----// 77
-----    q.data[i] = k;-----// 1a ----    delete[] data;-----// 5e
-----}-----// 3c ----    return intx(ss.str());-----// 88
-----return pair<intx, intx>(q.normalize(n.sign * d.sign), r);-----// 9e }-----// d8
-----}-----// a7
-----intx operator /(const intx& d) const {-----// 22
-----    return divmod(*this,d).first; }-----// c3
-----intx operator %(const intx& d) const {-----// 32
-----    return divmod(*this,d).second * sign; }-----// 0c
};-----// 64
```

5.2.1. Fast Multiplication. Fast multiplication for the big integer using Fast Fourier Transform.

5.3. Binomial Coefficients. The binomial coefficient $\binom{n}{k} = \frac{n!}{k!(n-k)!}$ is the number of ways to choose k items out of a total of n items. Also contains an implementation of Lucas' theorem for computing the answer modulo a prime p .

```
int nck(int n, int k) {-----// f6
----if (n < k) return 0;-----// 55
----k = min(k, n - k);-----// bd
----int res = 1;-----// e6
----rep(i,1,k+1) res = res * (n - (k - i)) / i;-----// 4d
```

```
--return res;-----// 1f
}-----// 6c
int nck(int n, int k, int p) {-----// cf
--int res = 1;-----// 5c
--while (n || k) {-----// e2
-----res *= nck(n % p, k % p);-----// cc
-----res %= p, n /= p, k /= p;-----// 0a
--}-----// d9
--return res;-----// 30
}-----// 0a
```

5.4. **Euclidean algorithm.** The Euclidean algorithm computes the greatest common divisor of two integers a, b .

```
int gcd(int a, int b) { return b == 0 ? a : gcd(b, a % b); }-----// d9

The extended Euclidean algorithm computes the greatest common divisor  $d$  of two integers  $a, b$  and also finds two integers  $x, y$  such that  $a \times x + b \times y = d$ .

int egcd(int a, int b, int& x, int& y) {-----// 85
--if (b == 0) { x = 1; y = 0; return a; }-----// 7b
--else {-----// 00
--int d = egcd(b, a % b, x, y);-----// 34
--x -= a / b * y;-----// 4a
--swap(x, y);-----// 26
--return d;-----// db
--}-----// 9e
}-----// 40
```

5.5. **Trial Division Primality Testing.** An optimized trial division to check whether an integer is prime.

```
bool is_prime(int n) {-----// 6c
--if (n < 2) return false;-----// c9
--if (n < 4) return true;-----// d9
--if (n % 2 == 0 || n % 3 == 0) return false;-----// 0f
--if (n < 25) return true;-----// ef
--for (int i = 5; i*i <= n; i += 6)-----// 38
--if (n % i == 0 || n % (i + 2) == 0) return false;-----// 69
--return true; }-----// b1
```

5.6. **Miller-Rabin Primality Test.** The Miller-Rabin probabilistic primality test.

```
#include "mod_pow.cpp"-----// c7
bool is_probable_prime(ll n, int k) {-----// be
--if (~n & 1) return n == 2;-----// d1
--if (n <= 3) return n == 3;-----// 39
--int s = 0; ll d = n - 1;-----// 37
--while (~d & 1) d >>= 1, s++;-----// 35
--while (k--) {-----// c8
-----ll a = (n - 3) * rand() / RAND_MAX + 2;-----// 06
-----ll x = mod_pow(a, d, n);-----// 64
-----if (x == 1 || x == n - 1) continue;-----// 9b
-----bool ok = false;-----// 03
-----rep(i,0,s-1) {-----// 13
-----x = (x * x) % n;-----// 90
-----if (x == 1) return false;-----// 5c
```

```
-----if (x == n - 1) { ok = true; break; }-----// a1
-----}-----// 3a
-----if (!ok) return false;-----// 37
--} return true; }-----// fe
```

5.7. **Pollard’s ρ algorithm.**

```
// public static int[] seeds = new int[] {2,3,5,7,11,13,1031};-----// 1d
// public static BigInteger rho(BigInteger n, BigInteger seed) {-----// 03
//---- int i = 0,-----// 00
//----- k = 2;-----// 79
//---- BigInteger x = seed,-----// cc
//-----y = seed;-----// 31
//---- while (i < 1000000) {-----// 10
//----- i++;-----// 8c
//----- x = (x.multiply(x).add(n).subtract(BigInteger.ONE)).mod(n);-----// 74
//----- BigInteger d = y.subtract(x).abs().gcd(n);-----// ce
//----- if (!d.equals(BigInteger.ONE) && !d.equals(n)) {-----// b9
//----- return d;-----// 3b
//----- }-----// 7c
//----- if (i == k) {-----// 2c
//----- y = x;-----// 89
//----- k = k*2;-----// 1d
//----- }-----// 10
//---- }-----// 96
//---- return BigInteger.ONE;-----// 62
// }-----// d7
```

5.8. **Sieve of Eratosthenes.** An optimized implementation of Eratosthenes’ Sieve.

```
vi prime_sieve(int n) {-----// 40
--int mx = (n - 3) >> 1, sq, v, i = -1;-----// 27
--vi primes;-----// 8f
--bool* prime = new bool[mx + 1];-----// ef
--memset(prime, 1, mx + 1);-----// 28
--if (n >= 2) primes.push_back(2);-----// f4
--while (++i <= mx) if (prime[i]) {-----// 73
-----primes.push_back(v = (i << 1) + 3);-----// be
-----if ((sq = i * ((i << 1) + 6) + 3) > mx) break;-----// 2d
-----for (int j = sq; j <= mx; j += v) prime[j] = false; }-----// 2e
--while (++i <= mx) if (prime[i]) primes.push_back((i << 1) + 3);-----// 29
--delete[] prime; // can be used for O(1) lookup-----// 36
--return primes; }-----// 72
```

5.9. **Divisor Sieve.** A $O(n)$ prime sieve. Computes the smallest divisor of any number up to n .

```
vi divisor_sieve(int n) {-----// 7f
--vi minimalDiv(n+1, 2), primes;-----// 37
--if(n>=2) primes.push_back(2);-----// 27
--minimalDiv[0] = 0;-----// 02
--for(int k=1;k<=n;k+=2) minimalDiv[k] = k;-----// e6
--for(int k=3;k<=n;k+=2) {-----// 5d
--if(minimalDiv[k] == k) primes.push_back(k);-----// 75
--rep(i, 1, size(primes))-----// 49
--if(primes[i] > minimalDiv[k] || primes[i]*k > n) break;-----// 53
```



```
-----else minimalDiv[primes[i]*k] = primes[i];-----// 90
-----}------// 9d
-----return primes; }-----// 93
-----// a8
```

5.10. **Modular Exponentiation.** A function to perform fast modular exponentiation.

```
template <class T>-----// 82
T mod_pow(T b, T e, T m) {-----// aa
---T res = T(1);-----// 85
---while (e) {-----// b7
-----if (e & T(1)) res = smod(res * b, m);-----// 6d
-----b = smod(b * b, m), e >>= T(1); }-----// 12
---return res;-----// c6
}-----// 30
```

5.11. **Modular Multiplicative Inverse.** A function to find a modular multiplicative inverse. Alternatively use mod_pow(a,m-2,m) when m is prime.

```
#include "egcd.cpp"-----// 55
-----// e8
int mod_inv(int a, int m) {-----// 49
---int x, y, d = egcd(a, m, x, y);-----// 3e
---if (d != 1) return -1;-----// 20
---return x < 0 ? x + m : x;-----// 3c
}-----// 69
```

5.12. **Primitive Root.**

```
#include "mod_pow.cpp"-----// c7
ll primitive_root(ll m) {-----// 8a
---vector<ll> div;-----// f2
---for (ll i = 1; i*i <= m-1; i++) {-----// ca
-----if ((m-1) % i == 0) {-----// 85
-----if (i < m) div.push_back(i);-----// fd
-----if (m/i < m) div.push_back(m/i); } }-----// f2
---rep(x,2,m) {-----// 57
-----bool ok = true;-----// 17
-----iter(it,div) if (mod_pow<ll>(x, *it, m) == 1) { ok = false; break; }-----// 2f
-----if (ok) return x; }-----// 5d
---return -1; }-----// 23
```

5.13. **Chinese Remainder Theorem.** An implementation of the Chinese Remainder Theorem.

```
#include "egcd.cpp"-----// 55
int crt(const vi& as, const vi& ns) {-----// c3
---int cnt = size(as), N = 1, x = 0, r, s, l;-----// 55
---rep(i,0,cnt) N *= ns[i];-----// b1
---rep(i,0,cnt) egcd(ns[i], l = N/ns[i], r, s), x += as[i] * s * l;-----// 21
---return smod(x, N); }-----// d3
```

5.14. **Linear Congruence Solver.** A function that returns all solutions to $ax \equiv b \pmod n$, modulo n .

```
#include "egcd.cpp"-----// 55
vi linear_congruence(int a, int b, int n) {-----// c8
---int x, y, d = egcd(a, n, x, y);-----// 7a
---vi res;-----// f5
```

```
---if (b % d != 0) return res;-----// 30
---int x0 = smod(b / d * x, n);-----// cb
---rep(k,0,d) res.push_back(smod(x0 + k * n / d, n));-----// 17
---return res;-----// 90
}-----// 66
```

5.15. **Tonelli-Shanks algorithm.** Given prime p and integer $1 \leq n < p$, returns the square root r of n modulo p . There is also another solution given by $-r$ modulo p .

```
#include "mod_pow.cpp"-----// c7
ll legendre(ll a, ll p) {-----// 27
---if (a % p == 0) return 0;-----// 29
---if (p == 2) return 1;-----// 9a
---return mod_pow(a, (p-1)/2, p) == 1 ? 1 : -1; }-----// 65
ll tonelli_shanks(ll n, ll p) {-----// e0
---assert(legendre(n,p) == 1);-----// 46
---if (p == 2) return 1;-----// 2d
---ll s = 0, q = p-1, z = 2;-----// 66
---while (~q & 1) s++, q >>= 1;-----// a7
---if (s == 1) return mod_pow(n, (p+1)/4, p);-----// a7
---while (legendre(z,p) != -1) z++;-----// 25
---ll c = mod_pow(z, q, p),-----// 65
---r = mod_pow(n, (q+1)/2, p),-----// b5
---t = mod_pow(n, q, p),-----// 5c
---m = s;-----// 01
---while (t != 1) {-----// 44
-----ll i = 1, ts = (ll)t*t % p;-----// 55
-----while (ts != 1) i++, ts = ((ll)ts * ts) % p;-----// 16
-----ll b = mod_pow(c, 1LL<<(m-i-1), p);-----// 6c
-----r = (ll)r * b % p;-----// 4f
-----t = (ll)t * b % p * b % p;-----// 78
-----c = (ll)b * b % p;-----// 31
-----m = i; }-----// b2
---return r; }-----// 48
```

5.16. **Numeric Integration.** Numeric integration using Simpson's rule.

```
double integrate(double (*f)(double), double a, double b,-----// 76
---double delta = 1e-6) {-----// c0
---if (abs(a - b) < delta)-----// 38
---return (b-a)/8 *-----// 56
---(f(a) + 3*f((2*a+b)/3) + 3*f((a+2*b)/3) + f(b));-----// e1
---return integrate(f, a,-----// 64
---(a+b)/2, delta) + integrate(f, (a+b)/2, b, delta);-----// 0c
}-----// 4b
```

5.17. **Fast Fourier Transform.** The Cooley-Tukey algorithm for quickly computing the discrete Fourier transform. The fft function only supports powers of twos. The czt function implements the Chirp Z-transform and supports any size, but is slightly slower.

```
#include <complex>-----// 8e
typedef complex<long double> cpx;-----// 25
// NOTE: n must be a power of two-----// 14
void fft(cpx *x, int n, bool inv=false) {-----// 36
---for (int i = 0, j = 0; i < n; i++) {-----// f9
```

```
-----if (i < j) swap(x[i], x[j]);-----// 44
-----int m = n>>1;-----// 9c
-----while (1 <= m && m <= j) j -= m, m >>= 1;-----// fe
-----j += m;-----// 11
-----}-----// d0
----for (int mx = 1; mx < n; mx <= 1) {-----// 15
----cpx wp = exp(cpx(0, (inv ? -1 : 1) * pi / mx)), w = 1;-----// 79
----for (int m = 0; m < mx; m++, w *= wp) {-----// dc
----for (int i = m; i < n; i += mx << 1) {-----// 6a
----cpx t = x[i + mx] * w;-----// 12
----x[i + mx] = x[i] - t;-----// 73
----x[i] += t;-----// 0e
----}-----// 14
----}-----// a4
----}-----// bf
---if (inv) rep(i,0,n) x[i] /= cpx(n);-----// 16
}-----// 1c
void czt(cpx *x, int n, bool inv=false) {-----// c5
---int len = 2*n+1;-----// bc
---while (len & (len - 1)) len &= len - 1;-----// 65
---len <= 1;-----// 21
---cpx w = exp(-2.0L * pi / n * cpx(0,1)),-----// 45
---*c = new cpx[n], *a = new cpx[len],-----// 4e
---*b = new cpx[len];-----// 30
---rep(i,0,n) c[i] = pow(w, (inv ? -1.0 : 1.0)*i*i/2);-----// 9e
---rep(i,0,n) a[i] = x[i] * c[i], b[i] = 1.0L/c[i];-----// e9
---rep(i,0,n-1) b[len - n + i + 1] = 1.0L/c[n-i-1];-----// 9f
---fft(a, len); fft(b, len);-----// 63
---rep(i,0,len) a[i] *= b[i];-----// 58
---fft(a, len, true);-----// 2d
---rep(i,0,n) {-----// ff
---x[i] = c[i] * a[i];-----// 77
---if (inv) x[i] /= cpx(n);-----// b1
---}-----// 27
---delete[] a;-----// 0a
---delete[] b;-----// 5c
---delete[] c;-----// f8
}-----// c6
```

5.18. Number-Theoretic Transform.

```
#include "../mathematics/primitive_root.cpp"-----// 8c
int mod = 998244353, g = primitive_root(mod),-----// 9c
---ginv = mod_pow<ll>(g, mod-2, mod), inv2 = mod_pow<ll>(2, mod-2, mod);-----// 02
#define MAXN (1<<22)-----// b2
struct Num {-----// d1
---int x;-----// 5b
---Num(ll _x=0) { x = (_x%mod+mod)%mod; }-----// b5
---Num operator +(const Num &b) { return x + b.x; }-----// c5
---Num operator -(const Num &b) const { return x - b.x; }-----// eb
---Num operator *(const Num &b) const { return (ll)x * b.x; }-----// c1
---Num operator /(const Num &b) const { return (ll)x * b.inv().x; }-----// 86
```

```
---Num inv() const { return mod_pow<ll>((ll)x, mod-2, mod); }-----// ef
---Num pow(int p) const { return mod_pow<ll>((ll)x, p, mod); }-----// c5
} T1[MAXN], T2[MAXN];-----// 62
void ntt(Num x[], int n, bool inv = false) {-----// e1
---Num z = inv ? ginv : g;-----// 9e
---z = z.pow((mod - 1) / n);-----// 46
---for (ll i = 0, j = 0; i < n; i++) {-----// ea
---if (i < j) swap(x[i], x[j]);-----// d5
---ll k = n>>1;-----// e5
---while (1 <= k && k <= j) j -= k, k >>= 1;-----// 45
---j += k; }-----// 56
---for (int mx = 1, p = n/2; mx < n; mx <= 1, p >>= 1) {-----// 58
---Num wp = z.pow(p), w = 1;-----// b9
---for (int k = 0; k < mx; k++, w = w*wp) {-----// dc
---for (int i = k; i < n; i += mx << 1) {-----// b5
---Num t = x[i + mx] * w;-----// f9
---x[i + mx] = x[i] - t;-----// e9
---x[i] = x[i] + t; } } }-----// c0
---if (inv) {-----// f5
---Num ni = Num(n).inv();-----// c6
---rep(i,0,n) { x[i] = x[i] * ni; } } }-----// 9c
void inv(Num x[], Num y[], int l) {-----// 3b
---if (l == 1) { y[0] = x[0].inv(); return; }-----// 37
---inv(x, y, l>>1);-----// a1
---// NOTE: maybe l<<2 instead of l<<1-----// ec
---rep(i,l>>1,l<<1) T1[i] = y[i] = 0;-----// b8
---rep(i,0,l) T1[i] = x[i];-----// f9
---ntt(T1, l<<1); ntt(y, l<<1);-----// bd
---rep(i,0,l<<1) y[i] = y[i]*2 - T1[i] * y[i] * y[i];-----// 54
---ntt(y, l<<1, true); }-----// 6e
void sqrt(Num x[], Num y[], int l) {-----// 78
---if (l == 1) { assert(x[0].x == 1); y[0] = 1; return; }-----// a7
---sqrt(x, y, l>>1);-----// 40
---inv(y, T2, l>>1);-----// e4
---rep(i,l>>1,l<<1) T1[i] = T2[i] = 0;-----// eb
---rep(i,0,l) T1[i] = x[i];-----// 65
---ntt(T2, l<<1); ntt(T1, l<<1);-----// cb
---rep(i,0,l<<1) T2[i] = T1[i] * T2[i];-----// 9b
---ntt(T2, l<<1, true);-----// 77
---rep(i,0,l) y[i] = (y[i] + T2[i]) * inv2; }-----// 19
```

5.19. **Tridiagonal Matrix Algorithm.** Solves a tridiagonal system of linear equations $a_i x_{i-1} + b_i x_i + c_i x_{i+1} = d_i$ where $a_1 = c_n = 0$. Beware of numerical instability.

```
#define MAXN 5000-----// f7
long double A[MAXN], B[MAXN], C[MAXN], D[MAXN], X[MAXN];-----// d8
void solve(int n) {-----// 01
---C[0] /= B[0]; D[0] /= B[0];-----// 94
---rep(i,1,n-1) C[i] /= B[i] - A[i]*C[i-1];-----// 6b
---rep(i,1,n) D[i] = (D[i] - A[i] * D[i-1]) / (B[i] - A[i] * C[i-1]);-----// 33
---X[n-1] = D[n-1];-----// c7
---for (int i = n-2; i>=0; i--) X[i] = D[i] - C[i] * X[i+1]; }-----// ad
```

5.20. **Mertens Function.** Mertens function is $M(n) = \sum_{i=1}^n \mu(i)$. Let $L \approx (n \log \log n)^{2/3}$ and the algorithm runs in $O(n^{2/3})$.

```
#define L 9000000-----// 27
int mob[L], mer[L];-----// f1
unordered_map<ll,ll> mem;-----// 30
ll M(ll n) {-----// de
----if (n < L) return mer[n];-----// 1c
----if (mem.find(n) != mem.end()) return mem[n];-----// 79
----ll ans = 0, done = 1;-----// 48
----for (ll i = 2; i*i <= n; i++) ans += M(n/i), done = i;-----// 41
----for (ll i = 1; i*i <= n; i++) ans += mer[i] * (n/i - max(done, n/(i+1)));-----// 43
----return mer[n] = 1 - ans; }-----// c2
void sieve() {-----// b9
----for (int i = 1; i < L; i++) mer[i] = mob[i] = 1;-----// f7
----for (int i = 2; i < L; i++) {-----// 8e
-----if (mer[i]) {-----// 8b
-----mob[i] = -1;-----// e5
-----for (int j = i+i; j < L; j += i)-----// f0
-----mer[j] = 0, mob[j] = (j/i)%i == 0 ? 0 : -mob[j/i];-----// 26
-----}-----// aa
-----mer[i] = mob[i] + mer[i-1]; } }-----// 3b
```

5.21. **Summatory Phi.** The summatory phi function $\Phi(n) = \sum_{i=1}^n \phi(i)$. Let $L \approx (n \log \log n)^{2/3}$ and the algorithm runs in $O(n^{2/3})$.

```
#define N 10000000-----// e8
ll sp[N];-----// 90
unordered_map<ll,ll> mem;-----// 54
ll sumphi(ll n) {-----// 3a
----if (n < N) return sp[n];-----// de
----if (mem.find(n) != mem.end()) return mem[n];-----// 4c
----ll ans = 0, done = 1;-----// b2
----for (ll i = 2; i*i <= n; i++) ans += sumphi(n/i), done = i;-----// 0f
----for (ll i = 1; i*i <= n; i++) ans += sp[i] * (n/i - max(done, n/(i+1)));-----// 7b
----return mem[n] = n*(n+1)/2 - ans; }-----// 76
void sieve() {-----// fa
----for (int i = 1; i < N; i++) sp[i] = i;-----// 11
----for (int i = 2; i < N; i++) {-----// 9a
-----if (sp[i] == i) {-----// 81
-----sp[i] = i-1;-----// c7
-----for (int j = i+i; j < N; j += i) sp[j] -= sp[j] / i; }-----// ea
-----sp[i] += sp[i-1]; } }-----// 92
```

5.22. **Numbers and Sequences.** Some random prime numbers: 1031, 32771, 1048583, 33554467, 1073741827, 34359738421, 1099511627791, 35184372088891, 1125899906842679, 36028797018963971.

6. GEOMETRY

6.1. **Primitives.** Geometry primitives.

```
#define P(p) const point &p-----// 2e
#define L(p0, p1) P(p0), P(p1)-----// cf
#define C(p0, r) P(p0), double r-----// f1
#define PP(pp) pair<point,point> &pp-----// e5
```

```
typedef complex<double> point;-----// 6a
double dot(P(a), P(b)) { return real(conj(a) * b); }-----// d2
double cross(P(a), P(b)) { return imag(conj(a) * b); }-----// 8a
point rotate(P(p), double radians = pi / 2, P(about) = point(0,0)) {-----// 23
----return (p - about) * exp(point(0, radians)) + about; }-----// 25
point reflect(P(p), L(about1, about2)) {-----// 50
----point z = p - about1, w = about2 - about1;-----// 8b
----return conj(z / w) * w + about1; }-----// 83
point proj(P(u), P(v)) { return dot(u, v) / dot(u, u) * u; }-----// e7
point normalize(P(p), double k = 1.0) {-----// 5f
----return abs(p) == 0 ? point(0,0) : p / abs(p) * k; }-----// 4a
double ccw(P(a), P(b), P(c)) { return cross(b - a, c - b); }-----// 27
bool collinear(P(a), P(b), P(c)) { return abs(ccw(a, b, c)) < EPS; }-----// b3
double angle(P(a), P(b), P(c)) {-----// 61
----return acos(dot(b - a, c - b) / abs(b - a) / abs(c - b)); }-----// c7
double signed_angle(P(a), P(b), P(c)) {-----// 4a
----return asin(cross(b - a, c - b) / abs(b - a) / abs(c - b)); }-----// 40
double angle(P(p)) { return atan2(imag(p), real(p)); }-----// e6
point perp(P(p)) { return point(-imag(p), real(p)); }-----// d9
double progress(P(p), L(a, b)) {-----// b3
----if (abs(real(a) - real(b)) < EPS)-----// 5e
-----return (imag(p) - imag(a)) / (imag(b) - imag(a));-----// 5e
----else return (real(p) - real(a)) / (real(b) - real(a)); }-----// 31
```

6.2. **Lines.** Line related functions.

```
#include "primitives.cpp"-----// e0
bool collinear(L(a, b), L(p, q)) {-----// 7c
----return abs(ccw(a, b, p)) < EPS && abs(ccw(a, b, q)) < EPS; }-----// 55
bool parallel(L(a, b), L(p, q)) { return abs(cross(b - a, q - p)) < EPS; }-----// a6
point closest_point(L(a, b), P(c), bool segment = false) {-----// 71
----if (segment) {-----// ae
-----if (dot(b - a, c - b) > 0) return b;-----// f1
-----if (dot(a - b, c - a) > 0) return a;-----// de
-----}-----// 16
----double t = dot(c - a, b - a) / norm(b - a);-----// 36
----return a + t * (b - a);-----// a0
}-----// 82
double line_segment_distance(L(a,b), L(c,d)) {-----// 0b
----double x = INFINITY;-----// 97
----if (abs(a - b) < EPS && abs(c - d) < EPS) x = abs(a - c);-----// 9e
----else if (abs(a - b) < EPS) x = abs(a - closest_point(c, d, a, true));-----// c3
----else if (abs(c - d) < EPS) x = abs(c - closest_point(a, b, c, true));-----// 3d
----else if ((ccw(a, b, c) < 0) != (ccw(a, b, d) < 0) &&-----// 07
-----ccw(c, d, a) < 0) != (ccw(c, d, b) < 0)) x = 0;-----// 97
----else {-----// e3
-----x = min(x, abs(a - closest_point(c,d, a, true)));-----// 59
-----x = min(x, abs(b - closest_point(c,d, b, true)));-----// 76
-----x = min(x, abs(c - closest_point(a,b, c, true)));-----// 12
-----x = min(x, abs(d - closest_point(a,b, d, true)));-----// b8
-----}-----// d6
----return x;-----// b6
```

```
// 83
bool intersect(L(a, b), L(p, q), point &res, bool segment = false) { // d1
---// NOTE: check for parallel/collinear lines before calling this function---// c9
---point r = b - a, s = q - p; // 5a
---double c = cross(r, s), t = cross(p - a, s) / c, u = cross(p - a, r) / c; // 48
---if (segment && (t < 0-EPS || t > 1+EPS || u < 0-EPS || u > 1+EPS)) // dc
---return false; // df
---res = a + t * r; // ff
---return true; // 60
} // 44
```

6.3. Circles. Circle related functions.

```
#include "lines.cpp" // d3
int intersect(C(A, rA), C(B, rB), point & res1, point & res2) { // 52
---double d = abs(B - A); // 7a
---if ((rA + rB) < (d - EPS) || d < abs(rA - rB) - EPS) return 0; // 18
---double a = (rA*rA - rB*rB + d*d) / 2 / d, h = sqrt(rA*rA - a*a); // e5
---point v = normalize(B - A, a), u = normalize(rotate(B-A), h); // bd
---res1 = A + v + u, res2 = A + v - u; // e0
---if (abs(u) < EPS) return 1; return 2; // 09
} // dc
int intersect(L(A, B), C(0, r), point & res1, point & res2) { // f9
---double h = abs(0 - closest_point(A, B, 0)); // a7
---if (r < h - EPS) return 0; // 05
---point H = proj(0 - A, B - A) + A, v = normalize((B - A), sqrt(r*r - h*h)); // 40
---res1 = H + v; res2 = H - v; // 7e
---if (abs(v) < EPS) return 1; return 2; // 12
} // 5f
int tangent(P(A), C(0, r), point & res1, point & res2) { // 9d
---point v = 0 - A; double d = abs(v); // e9
---if (d < r - EPS) return 0; // 4a
---double alpha = asin(r / d), L = sqrt(d*d - r*r); // 36
---v = normalize(v, L); // b7
---res1 = A + rotate(v, alpha); res2 = A + rotate(v, -alpha); // 85
---if (abs(r - d) < EPS || abs(v) < EPS) return 1; // eb
---return 2; // ee
} // 63
void tangent_outer(point A, double rA, point B, double rB, PP(P), PP(Q)) { // d0
---if (rA - rB > EPS) { swap(rA, rB); swap(A, B); } // 60
---double theta = asin((rB - rA)/abs(A - B)); // ae
---point v = rotate(B - A, theta + pi/2), u = rotate(B - A, -(theta + pi/2)); // 10
---u = normalize(u, rA); // 0b
---P.first = A + normalize(v, rA); P.second = B + normalize(v, rB); // e5
---Q.first = A + normalize(u, rA); Q.second = B + normalize(u, rB); // 5f
} // c8
```

6.4. Polygon. Polygon primitives.

```
#include "primitives.cpp" // e0
typedef vector<point> polygon; // b3
double polygon_area_signed(polygon p) { // 31
---double area = 0; int cnt = size(p); // a2
---rep(i,1,cnt-1) area += cross(p[i] - p[0], p[i + 1] - p[0]); // 51
```

```
---return area / 2; } // 66
double polygon_area(polygon p) { return abs(polygon_area_signed(p)); } // a4
#define CHK(f,a,b,c) (f(a) < f(b) && f(b) <= f(c) && ccw(a,c,b) < 0) // 8f
int point_in_polygon(polygon p, point q) { // 5d
---int n = size(p); bool in = false; double d; // 69
---for (int i = 0, j = n - 1; i < n; j = i++) // f3
---if (collinear(p[i], q, p[j]) &&
---0 <= (d = progress(q, p[i], p[j])) && d <= 1) // 4b
---return 0; // b3
---for (int i = 0, j = n - 1; i < n; j = i++) // 67
---if (CHK(real, p[i], q, p[j]) || CHK(real, p[j], q, p[i])) // b4
---in = !in; // ff
---return in ? -1 : 1; } // ba
// pair<polygon, polygon> cut_polygon(const polygon &poly, point a, point b) { // 0d
//--- polygon left, right; // 0a
//--- point it(-100, -100); // 5b
//--- for (int i = 0, cnt = poly.size(); i < cnt; i++) { // 70
//--- int j = i == cnt-1 ? 0 : i + 1; // 02
//--- point p = poly[i], q = poly[j]; // 44
//--- if (ccw(a, b, p) <= 0) left.push_back(p); // 8d
//--- if (ccw(a, b, p) >= 0) right.push_back(p); // 43
//--- // myintersect = intersect where // ba
//--- // (a,b) is a line, (p,q) is a line segment // 7e
//--- if (myintersect(a, b, p, q, it)) // 6f
//--- left.push_back(it), right.push_back(it); // 8a
//--- } // e0
//--- return pair<polygon, polygon>(left, right); // 3d
// } // 07
```

6.5. Convex Hull. An algorithm that finds the Convex Hull of a set of points. NOTE: Doesn't work on some weird edge cases. (A small case that included three collinear lines would return the same point on both the upper and lower hull.)

```
#include "polygon.cpp" // 58
#define MAXN 1000 // 09
point hull[MAXN]; // 43
bool cmp(const point &a, const point &b) { // 32
---return abs(real(a) - real(b)) > EPS ? // 44
---real(a) < real(b) : imag(a) < imag(b); } // 40
int convex_hull(polygon p) { // cd
---int n = size(p), l = 0; // 67
---sort(p.begin(), p.end(), cmp); // 3d
---rep(i,0,n) { // e4
---if (i > 0 && p[i] == p[i - 1]) continue; // c7
---while (l >= 2 && ccw(hull[l - 2], hull[l - 1], p[i]) >= 0) l--; // 62
---hull[l++] = p[i]; // bd
---} // d2
---int r = l; // 30
---for (int i = n - 2; i >= 0; i--) { // 59
---if (p[i] == p[i + 1]) continue; // af
---while (r - l >= 1 && ccw(hull[r - 2], hull[r - 1], p[i]) >= 0) r--; // 4d
---hull[r++] = p[i]; // f5
```

```

}-----// f6
---return l == 1 ? 1 : r - 1;-----// a6
}-----// 6d
```

6.6. **Line Segment Intersection.** Computes the intersection between two line segments.

```

#include "lines.cpp"-----// d3
bool line_segment_intersect(L(a, b), L(c, d), point &A, point &B) {-----// f3
---if (abs(a - b) < EPS && abs(c - d) < EPS) {-----// 1c
-----A = B = a; return abs(a - d) < EPS; }-----// 8d
---else if (abs(a - b) < EPS) {-----// 42
-----A = B = a; double p = progress(a, c,d);-----// cd
-----return 0.0 <= p && p <= 1.0-----// 05
-----&& (abs(a - c) + abs(d - a) - abs(d - c)) < EPS; }-----// 22
---else if (abs(c - d) < EPS) {-----// c8
-----A = B = c; double p = progress(c, a,b);-----// 0c
-----return 0.0 <= p && p <= 1.0-----// a5
-----&& (abs(c - a) + abs(b - c) - abs(b - a)) < EPS; }-----// 72
---else if (collinear(a,b, c,d)) {-----// 68
-----double ap = progress(a, c,d), bp = progress(b, c,d);-----// 26
---if (ap > bp) swap(ap, bp);-----// 4a
---if (bp < 0.0 || ap > 1.0) return false;-----// 3e
-----A = c + max(ap, 0.0) * (d - c);-----// ab
-----B = c + min(bp, 1.0) * (d - c);-----// 70
-----return true; }-----// 05
---else if (parallel(a,b, c,d)) return false;-----// 6a
---else if (intersect(a,b, c,d, A, true)) {-----// 98
-----B = A; return true; }-----// c2
---return false;-----// 4a
}-----// 7b
```

6.7. **Great-Circle Distance.** Computes the distance between two points (given as latitude/longitude coordinates) on a sphere of radius r .

```

double gc_distance(double pLat, double pLong,-----// 7b
-----double qLat, double qLong, double r) {-----// a4
---pLat *= pi / 180; pLong *= pi / 180;-----// ee
---qLat *= pi / 180; qLong *= pi / 180;-----// 75
---return r * acos(cos(pLat) * cos(qLat) * cos(pLong - qLong) +-----// e3
-----sin(pLat) * sin(qLat));-----// 1e
}-----// 60
}-----// 3f
```

6.8. **Triangle Circumcenter.** Returns the unique point that is the same distance from all three points. It is also the center of the unique circle that goes through all three points.

```

#include "primitives.cpp"-----// e0
point circumcenter(point a, point b, point c) {-----// 76
---b -= a, c -= a;-----// 41
---return a + perp(b * norm(c) - c * norm(b)) / 2.0 / cross(b, c);-----// 7a
}-----// c3
```

6.9. **Closest Pair of Points.** A sweep line algorithm for computing the distance between the closest pair of points.

```

#include "primitives.cpp"-----// e0
-----// 85
struct cmpx { bool operator ()(const point &a, const point &b) {-----// 01
-----return abs(real(a) - real(b)) > EPS ?-----// e9
-----real(a) < real(b) : imag(a) < imag(b); } };-----// 53
struct cmpy { bool operator ()(const point &a, const point &b) {-----// 6f
---return abs(imag(a) - imag(b)) > EPS ?-----// 0b
-----imag(a) < imag(b) : real(a) < real(b); } };-----// a4
double closest_pair(vector<point> pts) {-----// f1
---sort(pts.begin(), pts.end(), cmpx());-----// 0c
---set<point, cmpy> cur;-----// bd
---set<point, cmpy>::const_iterator it, jt;-----// a6
---double mn = INFINITY;-----// f9
---for (int i = 0, l = 0; i < size(pts); i++) {-----// ac
-----while (real(pts[i]) - real(pts[l]) > mn) cur.erase(pts[l++]);-----// 8b
-----it = cur.lower_bound(point(-INFINITY, imag(pts[i]) - mn));-----// fc
-----jt = cur.upper_bound(point(INFINITY, imag(pts[i]) + mn));-----// 39
-----while (it != jt) mn = min(mn, abs(*it - pts[i])), it++;-----// 09
-----cur.insert(pts[i]); }-----// 82
---return mn; }-----// 4c
```

6.10. **3D Primitives.** Three-dimensional geometry primitives.

```

#define P(p) const point3d &p-----// a7
#define L(p0, p1) P(p0), P(p1)-----// 0f
#define PL(p0, p1, p2) P(p0), P(p1), P(p2)-----// 67
struct point3d {-----// 63
---double x, y, z;-----// e6
---point3d() : x(0), y(0), z(0) {}-----// af
---point3d(double _x, double _y, double _z) : x(_x), y(_y), z(_z) {}-----// fc
---point3d operator+(P(p)) const {-----// 17
-----return point3d(x + p.x, y + p.y, z + p.z); }-----// 8e
---point3d operator-(P(p)) const {-----// fb
-----return point3d(x - p.x, y - p.y, z - p.z); }-----// 83
---point3d operator-() const {-----// 89
-----return point3d(-x, -y, -z); }-----// d4
---point3d operator*(double k) const {-----// 4d
-----return point3d(x * k, y * k, z * k); }-----// fd
---point3d operator/(double k) const {-----// 95
-----return point3d(x / k, y / k, z / k); }-----// 58
---double operator%(P(p)) const {-----// d1
-----return x * p.x + y * p.y + z * p.z; }-----// 09
---point3d operator*(P(p)) const {-----// 4f
-----return point3d(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x); }-----// ed
---double length() const {-----// 3e
---return sqrt(*this % *this); }-----// 05
---double distTo(P(p)) const {-----// dd
---return (*this - p).length(); }-----// 57
---double distTo(P(A), P(B)) const {-----// bd
-----// A and B must be two different points-----// 4e
-----return ((*this - A) * (*this - B)).length() / A.distTo(B); }-----// 6e
---point3d normalize(double k = 1) const {-----// db
```



```
-----// length() must not return 0-----// 3c
--return (*this) * (k / length()); }-----// d4
--point3d getProjection(P(A), P(B)) const {-----// 86
--point3d v = B - A;-----// 64
--return A + v.normalize((v % (*this - A)) / v.length()); }-----// 53
--point3d rotate(P(normal)) const {-----// 55
-----// normal must have length 1 and be orthogonal to the vector-----// eb
--return (*this) * normal; }-----// 5c
--point3d rotate(double alpha, P(normal)) const {-----// 21
--return (*this) * cos(alpha) + rotate(normal) * sin(alpha); }-----// 82
--point3d rotatePoint(P(0), P(axe), double alpha) const{-----// 7a
--point3d Z = axe.normalize(axe % (*this - 0));-----// ba
--return 0 + Z + (*this - 0 - Z).rotate(alpha, 0); }-----// 38
--bool isZero() const {-----// 64
--return abs(x) < EPS && abs(y) < EPS && abs(z) < EPS; }-----// 15
--bool isOnLine(L(A, B)) const {-----// 30
--return ((A - *this) * (B - *this)).isZero(); }-----// 58
--bool isInSegment(L(A, B)) const {-----// f1
--return isOnLine(A, B) && ((A - *this) % (B - *this)) < EPS; }-----// d9
--bool isInSegmentStrictly(L(A, B)) const {-----// 0e
--return isOnLine(A, B) && ((A - *this) % (B - *this)) < -EPS; }-----// ba
--double getAngle() const {-----// 0f
--return atan2(y, x); }-----// 40
--double getAngle(P(u)) const {-----// d5
--return atan2((*this * u).length(), *this % u); }-----// 79
--bool isOnPlane(PL(A, B, C)) const {-----// 8e
--return abs((A - *this) * (B - *this) % (C - *this)) < EPS; } };;-----// 74
int line_line_intersect(L(A, B), L(C, D), point3d &O){-----// dc
--if (abs((B - A) * (C - A) % (D - A)) > EPS) return 0;-----// 6a
--if ((A - B) * (C - D)).length() < EPS)-----// 79
--return A.isOnLine(C, D) ? 2 : 0;-----// 09
--point3d normal = ((A - B) * (C - B)).normalize();-----// bc
--double s1 = (C - A) * (D - A) % normal;-----// 68
--0 = A + ((B - A) / (s1 + ((D - B) * (C - B) % normal))) * s1;-----// 56
--return 1; }-----// a7
int line_plane_intersect(L(A, B), PL(C, D, E), point3d &O) {-----// 09
--double V1 = (C - A) * (D - A) % (E - A);-----// c1
--double V2 = (D - B) * (C - B) % (E - B);-----// 29
--if (abs(V1 + V2) < EPS)-----// 81
--return A.isOnPlane(C, D, E) ? 2 : 0;-----// d5
--0 = A + ((B - A) / (V1 + V2)) * V1;-----// 38
--return 1; }-----// ce
bool plane_plane_intersect(P(A), P(nA), P(B), P(nB), point3d &P, point3d &Q) {--// 5a
--point3d n = nA * nB;-----// 49
--if (n.isZero()) return false;-----// 03
--point3d v = n * nA;-----// d7
--P = A + (n * nA) * ((B - A) % nB / (v % nB));-----// 1a
--Q = P + n;-----// 9c
--return true; }-----// 1a
```

6.11. Polygon Centroid.

```
#include "polygon.cpp"-----// 58
point polygon_centroid(polygon p) {-----// 79
--double cx = 0.0, cy = 0.0;-----// d5
--double mnx = 0.0, mny = 0.0;-----// 22
--int n = size(p);-----// 2d
--rep(i,0,n)-----// 08
--mnx = min(mnx, real(p[i]));-----// c6
--mny = min(mny, imag(p[i]));-----// 84
--rep(i,0,n)-----// 3f
--p[i] = point(real(p[i]) - mnx, imag(p[i]) - mny);-----// 49
--rep(i,0,n) {-----// 3c
--int j = (i + 1) % n;-----// 5b
--cx += (real(p[i]) + real(p[j])) * cross(p[i], p[j]);-----// 4f
--cy += (imag(p[i]) + imag(p[j])) * cross(p[i], p[j]); }-----// 4a
--return point(cx, cy) / 6.0 / polygon_area_signed(p) + point(mnx, mny); }--// a1

6.12. Rotating Calipers.

#include "lines.cpp"-----// d3
struct caliper {-----// 6b
--ii pt;-----// ff
--double angle;-----// 44
--caliper(ii _pt, double _angle) : pt(_pt), angle(_angle) { }-----// 94
--double angle_to(ii pt2) {-----// e8
--double x = angle - atan2(pt2.second - pt.second, pt2.first - pt.first);--// d4
--while (x >= pi) x -= 2*pi;-----// 5c
--while (x <= -pi) x += 2*pi;-----// 4f
--return x; }-----// 66
--void rotate(double by) {-----// 0d
--angle -= by;-----// a4
--while (angle < 0) angle += 2*pi;-----// 6e
--}-----// 38
--void move_to(ii pt2) { pt = pt2; }-----// 31
--double dist(const caliper &other) {-----// 2d
--point a(pt.first,pt.second),-----// fe
--b = a + exp(point(0,angle)) * 10.0,-----// ed
--c(other.pt.first, other.pt.second);-----// f7
--return abs(c - closest_point(a, b, c));-----// 9e
--} };;-----// ee
-----// 26
// int h = convex_hull(pts);-----// 06
// double mx = 0;-----// 05
// if (h > 1) {-----// 1b
//----int a = 0,-----// 89
//-----b = 0;-----// 71
//----rep(i,0,h) {-----// 41
//-----if (hull[i].first < hull[a].first)-----// 5b
//-----a = i;-----// 71
//-----if (hull[i].first > hull[b].first)-----// 67
//-----b = i;-----// 3e
//----}-----// b1
//----caliper A(hull[a], pi/2), B(hull[b], 3*pi/2);-----// 6f
```

```
//---- double done = 0;-----// ca
//---- while (true) {-----// 52
//----- mx = max(mx, abs(point(hull[a].first,hull[a].second)-----// b1
//----- - point(hull[b].first, hull[b].second));-----// 13
//----- double tha = A.angle_to(hull[(a+1)%h]),-----// 37
//----- thb = B.angle_to(hull[(b+1)%h]);-----// 9c
//----- if (tha <= thb) {-----// 09
//----- A.rotate(tha);-----// 8a
//----- B.rotate(tha);-----// 1a
//----- a = (a+1) % h;-----// 35
//----- A.move_to(hull[a]);-----// d2
//----- } else {-----// dd
//----- A.rotate(thb);-----// 73
//----- B.rotate(thb);-----// da
//----- b = (b+1) % h;-----// 9d
//----- B.move_to(hull[b]);-----// f7
//----- }-----// e1
//----- done += min(tha, thb);-----// 4e
//----- if (done > pi) {-----// 13
//----- break;-----// 07
//----- }-----// 15
//---- }-----// af
// }-----// 40
```

- 6.13. **Formulas.** Let $a = (a_x, a_y)$ and $b = (b_x, b_y)$ be two-dimensional vectors.
- $a \cdot b = |a||b| \cos \theta$, where θ is the angle between a and b .
 - $a \times b = |a||b| \sin \theta$, where θ is the signed angle between a and b .
 - $a \times b$ is equal to the area of the parallelogram with two of its sides formed by a and b . Half of that is the area of the triangle formed by a and b .
 - **Euler’s formula:** $V - E + F = 2$
 - Side lengths a, b, c can form a triangle iff. $a + b > c$, $b + c > a$ and $a + c > b$.
 - Sum of internal angles of a regular convex n -gon is $(n - 2)\pi$.

7. OTHER ALGORITHMS

7.1. **2SAT.** A fast 2SAT solver.

```
#include "../graph/scc.cpp"-----// c3
-----// 63
bool two_sat(int n, const vii& clauses, vi& all_truthy) {-----// f4
---all_truthy.clear();-----// 31
---vvi adj(2*n+1);-----// 7b
---rep(i,0,size(courses)) {-----// 76
-----adj[-clauses[i].first + n].push_back(courses[i].second + n);-----// eb
-----if (clauses[i].first != clauses[i].second)-----// bc
-----adj[-clauses[i].second + n].push_back(courses[i].first + n);-----// f0
---}-----// da
---pair<union_find, vi> res = scc(adj);-----// 00
---union_find scc = res.first;-----// 20
---vi dag = res.second;-----// ed
---vi truth(2*n+1, -1);-----// c7
---for (int i = 2*n; i >= 0; i--) {-----// 50
-----int cur = order[i] - n, p = scc.find(cur + n), o = scc.find(-cur + n);--// 4f
```

```
-----if (cur == 0) continue;-----// cd
-----if (p == o) return false;-----// d0
-----if (truth[p] == -1) truth[p] = 1;-----// d3
-----truth[cur + n] = truth[p];-----// 50
-----truth[o] = 1 - truth[p];-----// 8c
-----if (truth[p] == 1) all_truthy.push_back(cur);-----// 55
---}-----// c3
---return true;-----// eb
}-----// 6b
```

7.2. **Stable Marriage.** The Gale-Shapley algorithm for solving the stable marriage problem.

```
vi stable_marriage(int n, int** m, int** w) {-----// e4
---queue<int> q;-----// f6
---vi at(n, 0), eng(n, -1), res(n, -1); vvi inv(n, vi(n));-----// c3
---rep(i,0,n) rep(j,0,n) inv[i][w[i][j]] = j;-----// f1
---rep(i,0,n) q.push(i);-----// d8
---while (!q.empty()) {-----// 68
---int curm = q.front(); q.pop();-----// e2
---for (int &i = at[curm]; i < n; i++) {-----// 7e
-----int curw = m[curm][i];-----// 95
-----if (eng[curw] == -1) { }-----// f7
-----else if (inv[curw][curm] < inv[curw][eng[curw]])-----// d6
-----q.push(eng[curw]);-----// 2e
-----else continue;-----// 1d
---res[eng[curw] = curm] = curw, ++i; break;-----// a1
---}-----// c4
---}-----// 3d
---return res;-----// 42
}-----// bf
```

7.3. **Algorithm X.** An implementation of Knuth’s Algorithm X, using dancing links. Solves the Exact Cover problem.

```
bool handle_solution(vi rows) { return false; }-----// 63
struct exact_cover {-----// 95
---struct node {-----// 7e
-----node *l, *r, *u, *d, *p;-----// 19
-----int row, col, size;-----// ae
-----node(int _row, int _col) : row(_row), col(_col) {-----// c9
-----size = 0; l = r = u = d = p = NULL; }-----// c3
---};-----// c1
---int rows, cols, *sol;-----// 7b
---bool **arr;-----// e6
---node *head;-----// fe
---exact_cover(int _rows, int _cols) : rows(_rows), cols(_cols), head(NULL) {--// b6
-----arr = new bool*[rows];-----// cf
-----sol = new int[rows];-----// 5f
-----rep(i,0,rows)
-----arr[i] = new bool[cols], memset(arr[i], 0, cols);-----// dd
---}-----// 21
---void set_value(int row, int col, bool val = true) { arr[row][col] = val; }--// 9e
---void setup() {-----// a3
-----node ***ptr = new node**[rows + 1];-----// bd
```



```
-----rep(i,0,rows+1) {-----// 76
-----ptr[i] = new node*[cols];-----// eb
-----rep(j,0,cols)-----// cd
-----if (i == rows || arr[i][j]) ptr[i][j] = new node(i, j);-----// 16
-----else ptr[i][j] = NULL;-----// d2
-----}-----// ac
-----rep(i,0,rows+1) {-----// fc
-----rep(j,0,cols) {-----// 51
-----if (!ptr[i][j]) continue;-----// f7
-----int ni = i + 1, nj = j + 1;-----// 7a
-----while (true) {-----// fc
-----if (ni == rows + 1) ni = 0;-----// 4c
-----if (ni == rows || arr[ni][j]) break;-----// 8d
-----++ni;-----// 68
-----}-----// ad
-----ptr[i][j]->d = ptr[ni][j];-----// 84
-----ptr[ni][j]->u = ptr[i][j];-----// 66
-----while (true) {-----// 7f
-----if (nj == cols) nj = 0;-----// de
-----if (i == rows || arr[i][nj]) break;-----// 4c
-----++nj;-----// c5
-----}-----// 72
-----ptr[i][j]->r = ptr[i][nj];-----// 60
-----ptr[i][nj]->l = ptr[i][j];-----// 82
-----}-----// 0b
-----}-----// 16
-----head = new node(rows, -1);-----// 66
-----head->r = ptr[rows][0];-----// 3e
-----ptr[rows][0]->l = head;-----// 8c
-----head->l = ptr[rows][cols - 1];-----// 6a
-----ptr[rows][cols - 1]->r = head;-----// c1
-----rep(j,0,cols) {-----// 92
-----int cnt = -1;-----// d4
-----rep(i,0,rows+1)-----// bd
-----if (ptr[i][j]) cnt++, ptr[i][j]->p = ptr[rows][j];-----// f3
-----ptr[rows][j]->size = cnt;-----// c2
-----}-----// b9
-----rep(i,0,rows+1) delete[] ptr[i];-----// a5
-----delete[] ptr;-----// 72
-----}-----// 19
-----#define COVER(c, i, j) {-----// 91
-----c->r->l = c->l, c->l->r = c->r;-----// 82
-----for (node *i = c->d; i != c; i = i->d)-----// 62
-----for (node *j = i->r; j != i; j = j->r)-----// 26
-----j->d->u = j->u, j->u->d = j->d, j->p->size--;-----// c1
-----}-----// 89
-----#define UNCOVER(c, i, j) {-----// f0
-----for (node *i = c->u; i != c; i = i->u)-----// 7b
-----for (node *j = i->l; j != i; j = j->l)-----// 65
-----j->p->size++, j->d->u = j->u->d = j;-----// 0e
-----c->r->l = c->l->r = c;-----// 0e
-----}-----// 0e

bool search(int k = 0) {-----// f9
if (head == head->r) {-----// 75
vi res(k);-----// 90
rep(i,0,k) res[i] = sol[i];-----// 2a
sort(res.begin(), res.end());-----// 63
return handle_solution(res);-----// 11
}
node *c = head->r, *tmp = head->r;-----// a3
for ( ; tmp != head; tmp = tmp->r) if (tmp->size < c->size) c = tmp;-----// 41
if (c == c->d) return false;-----// 02
COVER(c, i, j);-----// f6
bool found = false;-----// 8d
for (node *r = c->d; !found && r != c; r = r->d) {-----// 78
sol[k] = r->row;-----// c0
for (node *j = r->r; j != r; j = j->r) { COVER(j->p, a, b); }-----// f9
found = search(k + 1);-----// fb
for (node *j = r->l; j != r; j = j->l) { UNCOVER(j->p, a, b); }-----// 87
}
UNCOVER(c, i, j);-----// a7
return found;-----// c0
}-----// d2
};-----// d7

7.4. nth Permutation. A very fast algorithm for computing the nth permutation of the list {0, 1, ..., k-1}.
vector<int> nth_permutation(int cnt, int n) {-----// 78
vector<int> idx(cnt), per(cnt), fac(cnt);-----// 9e
rep(i,0,cnt) idx[i] = i;-----// bc
rep(i,1,cnt+1) fac[i - 1] = n % i, n /= i;-----// 2b
for (int i = cnt - 1; i >= 0; i--)-----// f9
per[cnt - i - 1] = idx[fac[i]], idx.erase(idx.begin() + fac[i]);-----// ee
return per;-----// ab
}-----// 37

7.5. Cycle-Finding. An implementation of Floyd's Cycle-Finding algorithm.
ii find_cycle(int x0, int (*f)(int)) {-----// a5
int t = f(x0), h = f(t), mu = 0, lam = 1;-----// 8d
while (t != h) t = f(t), h = f(f(h));-----// 79
h = x0;-----// 04
while (t != h) t = f(t), h = f(h), mu++;-----// 9d
h = f(t);-----// 00
while (t != h) h = f(h), lam++;-----// 5e
return ii(mu, lam);-----// b4
}-----// 42

7.6. Dates. Functions to simplify date calculations.
int intToDay(int jd) { return jd % 7; }-----// 89
int dateToInt(int y, int m, int d) {-----// 96
return 1461 * (y + 4800 + (m - 14) / 12) / 4 +-----// a8
367 * (m - 2 - (m - 14) / 12 * 12) / 12 +-----// d1
3 * ((y + 4900 + (m - 14) / 12) / 100) / 4 +-----// be
d - 32075;-----// e0
}
```

```
}-----// fa
void intToDate(int jd, int &y, int &m, int &d) {-----// a1
----int x, n, i, j;-----// 00
----x = jd + 68569;-----// 11
----n = 4 * x / 146097;-----// 2f
----x -= (146097 * n + 3) / 4;-----// 58
----i = (4000 * (x + 1)) / 1461001;-----// 0d
----x -= 1461 * i / 4 - 31;-----// 09
----j = 80 * x / 2447;-----// 3d
----d = x - 2447 * j / 80;-----// eb
----x = j / 11;-----// b7
----m = j + 2 - 12 * x;-----// 82
----y = 100 * (n - 49) + i + x;-----// 70
}-----// af
```

7.7. **Simulated Annealing.** An example use of Simulated Annealing to find a permutation of length n that maximizes $\sum_{i=1}^{n-1} |p_i - p_{i+1}|$.

```
double curtime() { return static_cast<double>(clock()) / CLOCKS_PER_SEC; }-----// 9d
int simulated_annealing(int n, double seconds) {-----// 54
---default_random_engine rng;-----// 67
---uniform_real_distribution<double> randfloat(0.0, 1.0);-----// ed
---uniform_int_distribution<int> randint(0, n - 2);-----// bb
---// random initial solution-----// 01
---vi sol(n);-----// 1c
---rep(i,0,n) sol[i] = i + 1;-----// 33
---random_shuffle(sol.begin(), sol.end());-----// ea
---// initialize score-----// 28
---int score = 0;-----// 7d
---rep(i,1,n) score += abs(sol[i] - sol[i-1]);-----// 61
---int iters = 0;-----// 0b
---double T0 = 100.0, T1 = 0.001,-----// 5c
-----progress = 0, temp = T0,-----// 3a
-----starttime = curtime();-----// d6
---while (true) {-----// 46
----if (!(iters & ((1 << 4) - 1))) {-----// 5d
-----progress = (curtime() - starttime) / seconds;-----// 44
-----temp = T0 * pow(T1 / T0, progress);-----// a7
-----if (progress > 1.0) break; }-----// 8b
----// random mutation-----// eb
----int a = randint(rng);-----// c3
----// compute delta for mutation-----// 84
----int delta = 0;-----// 60
-----if (a > 0) delta += abs(sol[a+1] - sol[a-1]) - abs(sol[a] - sol[a-1]);-----// 94
-----if (a+2 < n) delta += abs(sol[a] - sol[a+2]) - abs(sol[a+1] - sol[a+2]);
----// maybe apply mutation-----// fb
----if (delta >= 0 || randfloat(rng) < exp(delta / temp)) {-----// 81
-----swap(sol[a], sol[a+1]);-----// b3
-----score += delta;-----// db
----// if (score >= target) return;-----// 4d
----}-----// 5c
```

```
-----iters++; }-----// 28
---return score; }-----// ba
```

7.8. **Fast Input Reading.** If input or output is huge, sometimes it is beneficial to optimize the input reading/output writing. This can be achieved by reading all input in at once (using fread), and then parsing it manually. Output can also be stored in an output buffer and then dumped once in the end (using fwrite). A simpler, but still effective, way to achieve speed is to use the following input reading method.

```
void readn(register int *n) {-----// dc
---int sign = 1;-----// 32
---register char c;-----// a5
---*n = 0;-----// 35
---while((c = getc_unlocked(stdin)) != '\n') {-----// f3
----switch(c) {-----// 0c
-----case '-': sign = -1; break;-----// 28
-----case ' ': goto hell;-----// fd
-----case '\n': goto hell;-----// 79
-----default: *n *= 10; *n += c - '0'; break;-----// c0
----}-----// 2d
hell:-----// c3
---*n *= sign;-----// ba
}-----// a0
}-----// 67
```

7.9. **128-bit Integer.** GCC has a 128-bit integer data type named `__int128`. Useful if doing multiplication of 64-bit integers, or something needing a little more than 64-bits to represent.

7.10. **Bit Hacks.**

```
int snoob(int x) {-----// 73
---int y = x & -x, z = x + y;-----// 12
---return z | ((x ^ z) >> 2) / y;-----// 97
}-----// 14
```

Catalan	$C_0 = 1, C_n = \frac{1}{n+1} \binom{2n}{n} = \sum_{i=0}^{n-1} C_i C_{n-i-1} = \frac{4n-2}{n+1} C_{n-1}$	
Stirling 1st kind	$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = 1, \begin{bmatrix} n \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ n \end{bmatrix} = 0, \begin{bmatrix} n \\ k \end{bmatrix} = (n-1) \begin{bmatrix} n-1 \\ k \end{bmatrix} + \begin{bmatrix} n-1 \\ k-1 \end{bmatrix}$	#perms of n objs with 1 obj fixed
Stirling 2nd kind	$\left\{ \begin{smallmatrix} n \\ 1 \end{smallmatrix} \right\} = \left\{ \begin{smallmatrix} n \\ n \end{smallmatrix} \right\} = 1, \left\{ \begin{smallmatrix} n \\ k \end{smallmatrix} \right\} = k \left\{ \begin{smallmatrix} n-1 \\ k \end{smallmatrix} \right\} + \left\{ \begin{smallmatrix} n-1 \\ k-1 \end{smallmatrix} \right\}$	#ways to partition n objs into k nonempty subsets
Euler	$\left\langle \begin{smallmatrix} n \\ 0 \end{smallmatrix} \right\rangle = \left\langle \begin{smallmatrix} n \\ n-1 \end{smallmatrix} \right\rangle = 1, \left\langle \begin{smallmatrix} n \\ k \end{smallmatrix} \right\rangle = (k+1) \left\langle \begin{smallmatrix} n-1 \\ k \end{smallmatrix} \right\rangle + (n-k) \left\langle \begin{smallmatrix} n-1 \\ k-1 \end{smallmatrix} \right\rangle$	#perms of n objs with k obj fixed
Euler 2nd Order	$\left\langle \begin{smallmatrix} n \\ k \end{smallmatrix} \right\rangle = (k+1) \left\langle \begin{smallmatrix} n-1 \\ k \end{smallmatrix} \right\rangle + (2n-k-1) \left\langle \begin{smallmatrix} n-1 \\ k-1 \end{smallmatrix} \right\rangle$	#perms of 1, 1, 2, 2, ..., n
Bell	$B_1 = 1, B_n = \sum_{k=0}^{n-1} B_k \binom{n-1}{k} = \sum_{k=0}^n \left\{ \begin{smallmatrix} n \\ k \end{smallmatrix} \right\}$	#partitions of $1..n$ (S)

#labeled rooted trees

#labeled unrooted trees

$\sum_{i=1}^n i^2 = n(n+1)(2n+1)/6$

$!n = n \times!(n-1) + (-1)^n$

$\sum_{i=1}^n \binom{n}{i} F_i = F_{2n}$

$\sum_{k=0}^n \binom{k}{m} = \binom{n+1}{m+1}$

$a \equiv b \pmod{x,y} \Rightarrow a \equiv b \pmod{\text{lcm}(x,y)}$

$ac \equiv bc \pmod{m} \Rightarrow a \equiv b \pmod{\frac{m}{\gcd(c,m)}}$

$p \text{ prime} \Leftrightarrow (p-1)! \equiv -1 \pmod{p}$

$\sigma_x(n) = \prod_{i=0}^r \frac{p_i^{(a_i+1)x}-1}{p_i^x-1}$

$\sum_{k=0}^m (-1)^k \binom{n}{k} = (-1)^m \binom{n-1}{m}$

$2^{\omega(n)} = O(\sqrt{n})$

$d = v_i t + \frac{1}{2} a t^2$

$v_f = v_i + a t$

$n^{\overline{n-1}}$

$n^{\overline{n-2}}$

$\sum_{i=1}^n i^3 = n^2(n+1)^2/4$

$!n = (n-1)!(n-1)+(n-2)!$

$\sum_i \binom{n-i}{i} = F_{n+1}$

$\sum_{d|n} \phi(d) = n$

$(\sum_{d|n} \sigma_0(d))^2 = \sum_{d|n} \sigma_0(d)^3$

$\gcd(n^a-1, n^b-1) = n^{\gcd(a,b)}-1$

$\sigma_0(n) = \prod_{i=0}^r (a_i+1)$

$\sum_{i=1}^n 2^{\omega(i)} = O(n \log n)$

$v_f^2 = v_i^2 + 2ad$

$d = \frac{v_i+v_f}{2} t$

7.11. **The Twelffold Way.** Putting n balls into k boxes.

Balls	same	distinct	same	distinct	
Boxes	same	same	distinct	distinct	Remarks
-	$p_k(n)$	$\sum_{i=0}^k \left\{ \begin{smallmatrix} n \\ i \end{smallmatrix} \right\}$	$\binom{n+k-1}{k-1}$	k^n	$p_k(n)$: #partitions of n into $\leq k$ positive parts
size ≥ 1	$p(n,k)$	$\left\{ \begin{smallmatrix} n \\ k \end{smallmatrix} \right\}$	$\binom{n-1}{k-1}$	$k! \left\{ \begin{smallmatrix} n \\ k \end{smallmatrix} \right\}$	$p(n,k)$: #partitions of n into k positive parts
size ≤ 1	$[n \leq k]$	$[n \leq k]$	$\binom{k}{n}$	$n! \binom{k}{n}$	$[cond]$: 1 if $cond = true$, else 0

8. USEFUL INFORMATION	* Knuth optimization	– Kirchoff’s matrix tree theorem
9. MISC	· $\text{dp}[i][j] = \min_{i < k < j} \{ \text{dp}[i][k] + \text{dp}[k][j] + C[i][j] \}$	– Prüfer sequences
9.1. Debugging Tips.	· $A[i][j - 1] \leq A[i][j] \leq A[i + 1][j]$	– Lovász Toggle
• Stack overflow? Recursive DFS on tree that is actually a long path?	· $O(n^3)$ to $O(n^2)$	– Look at the DFS tree (which has no cross-edges)
• Floating-point numbers	· sufficient: QI and $C[b][c] \leq C[a][d], a \leq b \leq c \leq d$	• Mathematics
– Getting NaN? Make sure <code>acos</code> etc. are not getting values out of their range (perhaps <code>1+eps</code>).	• Greedy	– Is the function multiplicative?
– Rounding negative numbers?	• Randomized	– Look for a pattern
– Outputting in scientific notation?	• Optimizations	– Permutations
• Wrong Answer?	– Use bitset (/64)	* Consider the cycles of the permutation
– Read the problem statement again!	– Switch order of loops (cache locality)	– Functions
– Are multiple test cases being handled correctly? Try repeating the same test case many times.	• Process queries offline	* Sum of piecewise-linear functions is a piecewise-linear function
– Integer overflow?	– Mo’s algorithm	* Sum of convex (concave) functions is convex (concave)
– Think very carefully about boundaries of all input parameters	• Square-root decomposition	– Modular arithmetic
– Try out possible edge cases:	• Precomputation	* Chinese Remainder Theorem
* $n = 0, n = -1, n = 1, n = 2^{31} - 1$ or $n = -2^{31}$	• Efficient simulation	* Linear Congruence
* List is empty, or contains a single element	– Mo’s algorithm	– Sieve
* n is even, n is odd	– Sqrt decomposition	– System of linear equations
* Graph is empty, or contains a single vertex	– Store 2^k jump pointers	– Values too big to represent?
* Graph is a multigraph (loops or multiple edges)	• Data structure techniques	* Compute using the logarithm
* Polygon is concave or non-simple	– Sqrt buckets	* Divide everything by some large value
– Is initial condition wrong for small cases?	– Store 2^k jump pointers	– Linear programming
– Are you sure the algorithm is correct?	– 2^k merging trick	* Is the dual problem easier to solve?
– Explain your solution to someone.	• Counting	• Logic
– Are you using any functions that you don’t completely understand? Maybe STL functions?	– Inclusion-exclusion principle	– 2-SAT
– Maybe you (or someone else) should rewrite the solution?	– Generating functions	– XOR-SAT (Gauss elimination or Bipartite matching)
• Run-Time Error?	• Graphs	• Meet in the middle
– Is it actually Memory Limit Exceeded?	– Can we model the problem as a graph?	• Only work with the smaller half ($\log(n)$)
9.2. Solution Ideas.	– Can we use any properties of the graph?	• Strings
• Dynamic Programming	– Strongly connected components	– Trie (maybe over something weird, like bits)
– Drop a parameter, recover from others	– Cycles (or odd cycles)	– Suffix array
– Swap answer and a parameter	– Bipartite (no odd cycles)	– Suffix automaton (+DP?)
– Parsing CFGs: CYK Algorithm	* Bipartite matching	– Aho-Corasick
– Optimizations	* Hall’s marriage theorem	– <code>eerTree</code>
* Convex hull optimization	* Stable Marriage	– Work with $S + S$
· $\text{dp}[i] = \min_{j < i} \{ \text{dp}[j] + b[j] \times a[i] \}$	– Cut vertex/bridge	• Hashing
· $b[j] \geq b[j + 1]$	– Biconnected components	• Euler tour, tree to array
· optionally $a[i] \leq a[i + 1]$	– Degrees of vertices (odd/even)	• Segment trees
· $O(n^2)$ to $O(n)$	– Trees	– Lazy propagation
* Divide and conquer optimization	* Heavy-light decomposition	– Persistent
· $\text{dp}[i][j] = \min_{k < j} \{ \text{dp}[i - 1][k] + C[k][j] \}$	* Centroid decomposition	– Implicit
· $A[i][j] \leq A[i][j + 1]$	* Least common ancestor	– Segment tree of X
· $O(kn^2)$ to $O(kn \log n)$	– Eulerian path/circuit	• Geometry
· sufficient: $C[a][c] + C[b][d] \leq C[a][d] + C[b][c], a \leq b \leq c \leq d$ (QI)	– Chinese postman problem	– Minkowski sum (of convex sets)
	– Topological sort	– Rotating calipers
	– (Min-Cost) Max Flow	– Sweep line (horizontally or vertically?)
	– Min Cut	– Sweep angle
	* Maximum Density Subgraph	– Convex hull
	– Huffman Coding	• Fix a parameter (possibly the answer).
	– Min-Cost Arborescence	• Are there few distinct values?
	– Steiner Tree	

- Binary search
- Sliding Window (+ Monotonic Queue)
- Computing a Convolution? Fast Fourier Transform
- Exact Cover (+ Algorithm X)
- Cycle-Finding
- What is the smallest set of values that identify the solution? The cycle structure of the permutation? The powers of primes in the factorization?
- Look at the complement problem
 - Minimize something instead of maximizing
- Immediately enforce necessary conditions. (All values greater than 0? Initialize them all to 1)
- Add large constant to negative numbers to make them positive
- Counting/Bucket sort

10. FORMULAS

- **Jacobi symbol:** $(\frac{a}{b}) = a^{(b-1)/2} \pmod{b}$
- **Heron’s formula:** A triangle with side lengths a, b, c has area $\sqrt{s(s-a)(s-b)(s-c)}$ where $s = \frac{a+b+c}{2}$.
- **Pick’s theorem:** A polygon on an integer grid containing i lattice points and having b lattice points on the boundary has area $i + \frac{b}{2} - 1$.
- **Euler’s totient:** The number of integers less than n that are coprime to n are $n \prod_{p|n} (1 - \frac{1}{p})$ where each p is a distinct prime factor of n .
- **König’s theorem:** In any bipartite graph $G = (L \cup R, E)$, the number of edges in a maximum matching is equal to the number of vertices in a minimum vertex cover. Let U be the set of unmatched vertices in L , and Z be the set of vertices that are either in U or are connected to U by an alternating path. Then $K = (L \setminus Z) \cup (R \cap Z)$ is the minimum vertex cover.
- A minumum Steiner tree for n vertices requires at most $n - 2$ additional Steiner vertices.
- The number of vertices of a graph is equal to its minimum vertex cover number plus the size of a maximum independent set.
- **Wilson’s theorem:** $(n - 1)! \equiv -1 \pmod{n}$ iff. n is prime
- **Lagrange polynomial** through points $(x_0, y_0), \dots, (x_k, y_k)$ is
$$L(x) = \sum_{j=0}^k y_j \prod_{\substack{0 \leq m \leq k \\ m \neq j}} \frac{x - x_m}{x_j - x_m}$$
- **Hook length formula:** If λ is a Young diagram and $h_\lambda(i, j)$ is the hook-length of cell (i, j) , then then the number of Young tableaux $d_\lambda = n! / \prod h_\lambda(i, j)$.
- **Möbius inversion formula:** If $f(n) = \sum_{d|n} g(d)$, then $g(n) = \sum_{d|n} \mu(d) f(n/d)$. If $f(n) = \sum_{m=1}^n g(\lfloor n/m \rfloor)$, then $g(n) = \sum_{m=1}^n \mu(m) f(\lfloor \frac{n}{m} \rfloor)$.

10.1. **Markov Chains.** A Markov Chain can be represented as a weighted directed graph of states, where the weight of an edge represents the probability of transitioning over that edge in one timestep. Let $P^{(m)} = (p_{ij}^{(m)})$ be the probability matrix of transitioning from state i to state j in m timesteps, and note that $P^{(1)}$

is the adjacency matrix of the graph. **Chapman-Kolmogorov:** $p_{ij}^{(m+n)} = \sum_k p_{ik}^{(m)} p_{kj}^{(n)}$. It follows that $P^{(m+n)} = P^{(m)} P^{(n)}$ and $P^{(m)} = P^m$. If $p^{(0)}$ is the initial probability distribution (a vector), then $p^{(0)} P^{(m)}$ is the probability distribution after m timesteps.

The return times of a state i is $R_i = \{m \mid p_{ii}^{(m)} > 0\}$, and i is *aperiodic* if $\gcd(R_i) = 1$. A MC is aperiodic if any of its ver-tices is aperiodic. A MC is *irreducible* if the corresponding graph is strongly connected.

A distribution π is stationary if $\pi P = \pi$. If MC is irreducible then $\pi_i = 1/\mathbb{E}[T_i]$, where T_i is the expected time between two visits at i . π_j/π_i is the expected number of visits at j in between two consecutive visits at i . A MC is *ergodic* if $\lim_{m \rightarrow \infty} p^{(0)} P^m = \pi$. A MC is ergodic iff. it is irreducible and aperiodic.

A MC for a random walk in an undirected weighted graph (unweighted graph can be made weighted by adding 1-weights) has $p_{uv} = w_{uv} / \sum_x w_{ux}$. If the graph is connected, then $\pi_u = \sum_x w_{ux} / \sum_v \sum_x w_{vx}$. Such a random walk is aperiodic iff. the graph is not bipartite.

An *absorbing* MC is of the form $P = \begin{pmatrix} Q & R \\ 0 & I_r \end{pmatrix}$. Let $N = \sum_{m=0}^\infty Q^m = (I_t - Q)^{-1}$. Then, if starting in state i , the expected number of steps till absorp-tion is the i -th entry in $N1$. If starting in state i , the probability of being absorbed in state j is the (i, j) -th entry of NR .

Many problems on MC can be formulated in terms of a system of recurrence relations, and then solved using Gaussian elimination.

10.2. **Burnside’s Lemma.** Let G be a finite group that acts on a set X . For each g in G let X^g denote the set of elements in X that are fixed by g . Then the number of orbits

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

10.3. **Bézout’s identity.** If (x, y) is any solution to $ax + by = d$ (e.g. found by the Extended Euclidean Algorithm), then all solu-tions are given by

$$\left(x + k \frac{b}{\gcd(a, b)}, y - k \frac{a}{\gcd(a, b)}\right)$$

10.4. **Misc.**

10.4.1. *Determinants and PM.*

$$\begin{aligned} \det(A) &= \sum_{\sigma \in S_n} \operatorname{sgn}(\sigma) \prod_{i=1}^n a_{i, \sigma(i)} \\ \operatorname{perm}(A) &= \sum_{\sigma \in S_n} \prod_{i=1}^n a_{i, \sigma(i)} \\ pf(A) &= \frac{1}{2^n n!} \sum_{\sigma \in S_{2n}} \operatorname{sgn}(\sigma) \prod_{i=1}^n a_{\sigma(2i-1), \sigma(2i)} \\ &= \sum_{M \in \operatorname{PM}(n)} \operatorname{sgn}(M) \prod_{(i, j) \in M} a_{i, j} \end{aligned}$$

10.4.2. *BEST Theorem.* Number of OST given by Kirchoff’s The-orem (remove r/c with root) $\# \operatorname{OST}(G, r) \cdot \prod_v (d_v - 1)!$

10.4.3. *Primitive Roots.* Only exists when n is $2, 4, p^k, 2p^k$, where p odd prime. Assume n prime. Number of primitive roots $\phi(\phi(n))$ Let g be primitive root. All primitive roots are of the form g^k where $k, \phi(p)$ are coprime. k -roots: $g^{i \cdot \phi(n)/k}$ for $0 \leq i < k$

10.4.4. *Sum of primes.* For any multiplicative f :

$$S(n, p) = S(n, p - 1) - f(p) \cdot (S(n/p, p - 1) - S(p - 1, p - 1))$$

10.4.5. *Floor.*

$$\begin{aligned} \lfloor \lfloor x/y \rfloor / z \rfloor &= \lfloor x/(yz) \rfloor \\ x \%_y y &= x - y \lfloor x/y \rfloor \end{aligned}$$

PRACTICE CONTEST CHECKLIST

- How many operations per second? Compare to local machine.
- What is the stack size?
- How to use printf/scanf with long long/long double?
- Is `__int128` available?
- Does MLE give RTE or MLE as a verdict? What about stack overflow?
- What is `RAND_MAX`?
- How does the judge handle extra spaces (or missing new-lines) in the output?
- Look at documentation for programming languages.
- Try different programming languages: C++ and Java.
- Try the submit script.
- Try local programs: `i?python[23]`, `factor`.
- Try submitting with `assert(false)` and `assert(false)`.
- Return-value from `main`.
- Look for directory with sample test cases.
- Remove this page from the notebook.