

viRUs

Team Reference Document

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1. CODE TEMPLATES

1.1. Basic Configuration. Vim and (Caps Lock = Escape) configuration.

```
o.yqtxmal ekrpat # setxkbmap dvorak for dvorak on qwerty
setxkbmap -option caps:escape
set -o vi
xset r rate 150 100
cat > ~/.vimrc
set nosp et sw=4 ts=4 sts=4 si cindent hi=1000 nu ru noeb showcmd showmode
syn on | colorscheme slate
```

1.2. C++ Header. A C++ header.

```
#include <bits/stdc++.h>-----// 84
using namespace std;-----// 16
template <class T> int size(const T &x) { return x.size(); }-----// 5f
#define rep(i,a,b) for (__typeof(a) i=(a); i<(b); ++i)-----// 6c
#define iter(it,c) for (__typeof((c).begin()) it = (c).begin(); it != (c).end(); ++it)
typedef pair<int, int> ii;-----// 44
typedef vector<int> vi;-----// 9d
typedef vector<ii> vii;-----// eb
typedef long long ll;-----// 47
const int INF = 2147483647;-----// db
-----// d8
const double EPS = 1e-9;-----// 18
const double pi = acos(-1);-----// ec
typedef unsigned long long ull;-----// 30
typedef vector<vi> vvi;-----// 92
typedef vector<vii> vvii;-----// fc
template <class T> T mod(T a, T b) { return (a % b + b) % b; }-----// 3f
```

1.3. Java Template. A Java template.

```
import java.util.*;-----// 37
import java.math.*;-----// 89
import java.io.*;-----// 28
-----// a3
public class Main {-----// 17
---public static void main(String[] args) throws Exception {-----// 02
-----Scanner in = new Scanner(System.in);-----// ef
-----PrintWriter out = new PrintWriter(System.out, false);-----// 62
-----// code-----// e6
-----out.flush();-----// 56
-----}-----// 79
}-----// 00
```

2. DATA STRUCTURES

2.1. Union-Find.

```
struct union_find {-----// 42
---vi p; union_find(int n) : p(n, -1) { }-----// 28
---int find(int x) { return p[x] < 0 ? x : p[x] = find(p[x]); }-----// ba
---bool unite(int x, int y) {-----// 6c
-----int xp = find(x), yp = find(y);-----// 64
-----if (xp == yp) return false;-----// 0b
```

```
-----if (p[xp] > p[yp]) swap(xp,yp);-----// 78
-----p[xp] += p[yp], p[yp] = xp;-----// 88
-----return true; }-----// 1f
----int size(int x) { return -p[find(x)]; } };-----// b9
```

2.2. Segment Tree.

```
#ifdef SEG_MIN-----// 03
const int ID = INF;-----// 56
int f(int a, int b) { return min(a, b); }-----// 4f
#else-----// 0e
const int ID = 0;-----// 3e
int f(int a, int b) { return a + b; }-----// dd
#endif-----// 16
struct segment_tree {-----// ab
---int n; vi data, lazy;-----// dd
---segment_tree() {}-----// 93
---segment_tree(const vi &arr) : n(size(arr)), data(4*n), lazy(4*n,INF) {-----// f1
---mk(arr, 0, n-1, 0); }-----// e9
---int mk(const vi &arr, int l, int r, int i) {-----// 12
---if (l == r) return data[i] = arr[l];-----// 5b
---int m = (l + r) / 2;-----// de
---return data[i] = f(mk(arr, l, m, 2*i+1), mk(arr, m+1, r, 2*i+2)); }-----// 0a
---int query(int a, int b) { return q(a, b, 0, n-1, 0); }-----// f6
---int q(int a, int b, int l, int r, int i) {-----// 22
---propagate(l, r, i);-----// 12
---if (r < a || b < l) return ID;-----// c7
---if (a <= l && r <= b) return data[i];-----// ce
---int m = (l + r) / 2;-----// 7a
---return f(q(a, b, l, m, 2*i+1), q(a, b, m+1, r, 2*i+2)); }-----// 5c
---void update(int i, int v) { u(i, v, 0, n-1, 0); }-----// 90
---int u(int i, int v, int l, int r, int j) {-----// 02
---propagate(l, r, j);-----// ae
---if (r < i || i < l) return data[j];-----// 92
---if (l == i && r == i) return data[j] = v;-----// 4a
---int m = (l + r) / 2;-----// cb
---return data[j] = f(u(i, v, l, m, 2*j+1), u(i, v, m+1, r, 2*j+2)); }-----// 34
---void range_update(int a, int b, int v) { ru(a, b, v, 0, n-1, 0); }-----// 71
---int ru(int a, int b, int v, int l, int r, int i) {-----// e0
---propagate(l, r, i);-----// 19
---if (l > r) return ID;-----// cc
---if (r < a || b < l) return data[i];-----// d9
---if (l == r) return data[i] += v;-----// 5f
---if (a <= l && r <= b) return (lazy[i] = v) * (r - l + 1) + data[i];-----// 76
---int m = (l + r) / 2;-----// e7
---return data[i] = f(ru(a, b, v, l, m, 2*i+1),-----// 0e
---ru(a, b, v, m+1, r, 2*i+2)); }-----// f2
---}-----// 47
---void propagate(int l, int r, int i) {-----// b5
---if (l > r || lazy[i] == INF) return;-----// 83
---data[i] += lazy[i] * (r - l + 1);-----// 99
---if (l < r) {-----// dd
```

```
-----if (lazy[2*i+1] == INF) lazy[2*i+1] = lazy[i];-----// ee };-----// 57
-----else lazy[2*i+1] += lazy[i];-----// 72 struct fenwick_tree_sq {-----// d4
-----if (lazy[2*i+2] == INF) lazy[2*i+2] = lazy[i];-----// dd ---int n; fenwick_tree x1, x0;-----// 18
-----else lazy[2*i+2] += lazy[i];-----// a4 ---fenwick_tree_sq(int _n) : n(_n), x1(fenwick_tree(n)),-----// 2e
-----}-----// e9 ---x0(fenwick_tree(n)) { }-----// 7c
-----lazy[i] = INF;-----// c4 ---// insert f(y) = my + c if x <= y-----// 17
-----}------// 2c ---void update(int x, int m, int c) { x1.update(x, m); x0.update(x, c); }-----// 45
};-----// 17 ---int query(int x) { return x*x1.query(x) + x0.query(x); }-----// 73
};-----// 13
```

2.2.1. Persistent Segment Tree.

```
int segcnt = 0;-----// cf
struct segment {-----// 68
----int l, r, lid, rid, sum;-----// fc
} segs[2000000];-----// dd
int build(int l, int r) {-----// 2b
----if (l > r) return -1;-----// 4e
----int id = segcnt++;-----// a8
----segs[id].l = l;-----// 90
----segs[id].r = r;-----// 19
----if (l == r) segs[id].lid = -1, segs[id].rid = -1;-----// ee
----else {-----// fe
-----int m = (l + r) / 2;-----// 14
-----segs[id].lid = build(l , m);-----// e3
-----segs[id].rid = build(m + 1, r); }-----// 69
----segs[id].sum = 0;-----// 21
----return id; }-----// c5
int update(int idx, int v, int id) {-----// b8
----if (id == -1) return -1;-----// bb
----if (idx < segs[id].l || idx > segs[id].r) return id;-----// fb
----int nid = segcnt++;-----// b3
----segs[nid].l = segs[id].l;-----// 78
----segs[nid].r = segs[id].r;-----// ca
----segs[nid].lid = update(idx, v, segs[id].lid);-----// 92
----segs[nid].rid = update(idx, v, segs[id].rid);-----// 06
----segs[nid].sum = segs[id].sum + v;-----// 1a
----return nid; }-----// e6
int query(int id, int l, int r) {-----// a2
----if (r < segs[id].l || segs[id].r < l) return 0;-----// 17
----if (l <= segs[id].l && segs[id].r <= r) return segs[id].sum;-----// ad
----return query(segs[id].lid, l, r) + query(segs[id].rid, l, r); }-----// ee
```

2.3. Fenwick Tree.

```
struct fenwick_tree {-----// 98
----int n; vi data;-----// d3
----fenwick_tree(int _n) : n(_n), data(vi(n)) { }-----// db
----void update(int at, int by) {-----// 76
-----while (at < n) data[at] += by, at |= at + 1; }-----// fb
----int query(int at) {-----// 71
----int res = 0;-----// c3
----while (at >= 0) res += data[at], at = (at & (at + 1)) - 1;-----// 37
----return res; }-----// e4
----int rsq(int a, int b) { return query(b) - query(a - 1); }-----// be
```

2.4. Matrix.

```
template <class K> bool eq(K a, K b) { return a == b; }-----// 2a
template <> bool eq<double>(double a, double b) { return abs(a - b) < EPS; }-----// a7
template <class T> struct matrix {-----// 0a
----int rows, cols, cnt; vector<T> data;-----// a1
----inline T& at(int i, int j) { return data[i * cols + j]; }-----// 5c
----matrix(int r, int c) : rows(r), cols(c), cnt(r * c) {-----// 56
-----data.assign(cnt, T(0)); }-----// e3
----matrix(const matrix& other) : rows(other.rows), cols(other.cols),-----// b5
-----cnt(other.cnt), data(other.data) { }-----// c1
----T& operator()(int i, int j) { return at(i, j); }-----// 29
----matrix<T> operator +(const matrix& other) {-----// 33
-----matrix<T> res(*this); rep(i,0,cnt) res.data[i] += other.data[i];-----// f8
-----return res; }-----// 09
----matrix<T> operator -(const matrix& other) {-----// 91
-----matrix<T> res(*this); rep(i,0,cnt) res.data[i] -= other.data[i];-----// 7b
-----return res; }-----// 9a
----matrix<T> operator *(T other) {-----// 99
-----matrix<T> res(*this); rep(i,0,cnt) res.data[i] *= other;-----// 05
-----return res; }-----// 8c
----matrix<T> operator *(const matrix& other) {-----// 31
-----matrix<T> res(rows, other.cols);-----// 4c
-----rep(i,0,rows) rep(j,0,other.cols) rep(k,0,cols)-----// ae
-----res(i, j) += at(i, k) * other.data[k * other.cols + j];-----// 17
-----return res; }-----// 65
----matrix<T> pow(int p) {-----// 53
-----matrix<T> res(rows, cols), sq(*this);-----// 87
-----rep(i,0,rows) res(i, i) = T(1);-----// 9d
-----while (p) {-----// 79
-----if (p & 1) res = res * sq;-----// 62
-----p >>= 1;-----// 79
-----if (p) sq = sq * sq;-----// 35
-----} return res; }-----// 22
----matrix<T> rref(T &det, int &rank) {-----// 2a
----matrix<T> mat(*this); det = T(1), rank = max(rows, cols);-----// 7a
----for (int r = 0, c = 0; c < cols; c++) {-----// 8e
----int k = r;-----// 5b
```

```

1  #define rotate(l, r) \
2  node *l = n->l; \
3  l->p = n->p; \
4  parent_leg(n) = l; \
5  n->l = l->r; \
6  if (l->r) l->r->p = n; \
7  l->r = n, n->p = l; \
8  augment(n), augment(l)
9
10 void left_rotate(node *n) { rotate(r, l); }
11 void right_rotate(node *n) { rotate(l, r); }
12 void fix(node *n) {
13     while (n) { augment(n);
14         if (too_heavy(n)) {
15             if (left_heavy(n) && right_heavy(n->l)) left_rotate(n->l);
16             else if (right_heavy(n) && left_heavy(n->r))
17                 right_rotate(n->r);
18             if (left_heavy(n)) right_rotate(n);
19             else left_rotate(n);
20

```

```
-----n = n->p; } }-----// 86
```

```

inline int size() const { return sz(root); } // 1f
---node* find(const T &item) const { // 8f
    node *cur = root; // 37
    while (cur) { // a4
        if (cur->item < item) cur = cur->r; // 8b
        else if (item < cur->item) cur = cur->l; // 38
        else break; } // ae
    return cur; } // b7
---node* insert(const T &item) { // 5f
    node *prev = NULL, **cur = &root; // f7
    while (*cur) { // 82
        prev = *cur; // 1c
        if ((*cur)->item < item) cur = &((*cur)->r); // 54
        else cur = &((*cur)->l); // e4
    } // 58
    else if (item < (*cur)->item) cur = &((*cur)->l); // 89
    else return *cur; // 65
} // 03
} // be
node *n = new node(item, prev); // 2b
*cur = n, fix(n); return n; } // 2a
void erase(const T &item) { erase(find(item)); } // fa
void erase(node *n, bool free = true) { // 7d
    if (!n) return; // ca
    if (!n->l && n->r) parent_leg(n) = n->r, n->r->p = n->p; // c8
    else if (n->l && !n->r) parent_leg(n) = n->l, n->l->p = n->p; // 52
    else if (n->l && n->r) { // 9a
        node *s = successor(n); // 91
        erase(s, false); // 83
    }
}

```

```
-----s->p = n->p, s->l = n->l, s->r = n->r;-----// 4b
-----if (n->l) n->l->p = s;-----// f4
-----if (n->r) n->r->p = s;-----// 85
-----parent_leg(n) = s, fix(s);-----// a6
-----return;-----// 9c
-----} else parent_leg(n) = NULL;-----// bb
-----fix(n->p), n->p = n->l = n->r = NULL;-----// e3
-----if (free) delete n; }-----// 18
---node* successor(node *n) const {-----// 4c
-----if (!n) return NULL;-----// f3
-----if (n->r) return nth(0, n->r);-----// 38
-----node *p = n->p;-----// a0
-----while (p && p->r == n) n = p, p = p->p;-----// 36
-----return p; }-----// 0e
---node* predecessor(node *n) const {-----// 64
-----if (!n) return NULL;-----// 88
-----if (n->l) return nth(n->l->size-1, n->l);-----// 92
-----node *p = n->p;-----// 05
-----while (p && p->l == n) n = p, p = p->p;-----// 90
-----return p; }-----// 42
---node* nth(int n, node *cur = NULL) const {-----// e3
-----if (!cur) cur = root;-----// 9f
-----while (cur) {-----// e3
-----if (n < sz(cur->l)) cur = cur->l;-----// f6
-----else if (n > sz(cur->l)) n -= sz(cur->l) + 1, cur = cur->r;-----// 83
-----else break;-----// 29
-----} return cur; }-----// c4
---int count_less(node *cur) {-----// 02
-----int sum = sz(cur->l);-----// 80
-----while (cur) {-----// 18
-----if (cur->p && cur->p->r == cur) sum += 1 + sz(cur->p->l);-----// b5
-----cur = cur->p;-----// 08
-----} return sum; }-----// 69
---void clear() { delete_tree(root), root = NULL; } };-----// d2
```

2.6. Heap.

```
#define RESIZE-----// d0
#define SWP(x,y) tmp = x, x = y, y = tmp-----// fb
struct default_int_cmp {-----// 8d
---default_int_cmp() { }-----// 35
---bool operator()(const int &a, const int &b) { return a < b; } };-----// e9
template <class Compare = default_int_cmp> struct heap {-----// 42
---int len, count, *q, *loc, tmp;-----// 07
---Compare _cmp;-----// a5
---inline bool cmp(int i, int j) { return _cmp(q[i], q[j]); }-----// e2
---inline void swp(int i, int j) {-----// 3b
-----SWP(q[i], q[j]), SWP(loc[q[i]], loc[q[j]]); }-----// bd
---void swim(int i) {-----// b5
-----while (i > 0) {-----// 70
-----int p = (i - 1) / 2;-----// b8
-----if (!cmp(i, p))break;-----// 2f
-----swp(i, p), i = p; } }-----// 20
---void sink(int i) {-----// 40
-----while (true) {-----// 07
-----int l = 2*i + 1, r = l + 1;-----// 85
-----if (l >= count) break;-----// d9
-----int m = r >= count || cmp(l, r) ? l : r;-----// db
-----if (!cmp(m, i)) break;-----// 4e
-----swp(m, i), i = m; } }-----// 36
---heap(int init_len = 128) : count(0), len(init_len), _cmp(Compare()) {-----// 05
---q = new int[len], loc = new int[len];-----// bc
---memset(loc, 255, len << 2); }-----// 45
---~heap() { delete[] q; delete[] loc; }-----// 23
---void push(int n, bool fix = true) {-----// b8
-----if (len == count || n >= len) {-----// dc
#ifdef RESIZE-----// 0a
-----int newlen = 2 * len;-----// 85
-----while (n >= newlen) newlen *= 2;-----// 54
-----int *newq = new int[newlen], *newloc = new int[newlen];-----// 9f
-----rep(i,0,len) newq[i] = q[i], newloc[i] = loc[i];-----// 53
-----memset(newloc + len, 255, (newlen - len) << 2);-----// a6
-----delete[] q, delete[] loc;-----// 7a
-----loc = newloc, q = newq, len = newlen;-----// 80
#else-----// 82
-----assert(false);-----// 46
#endif-----// 5c
-----}-----// 34
-----assert(loc[n] == -1);-----// 71
-----loc[n] = count, q[count++] = n;-----// 98
-----if (fix) swim(count-1); }-----// 70
---void pop(bool fix = true) {-----// 2e
---assert(count > 0);-----// 7b
---loc[q[0]] = -1, q[0] = q[--count], loc[q[0]] = 0;-----// 71
---if (fix) sink(0);-----// 80
---}-----// b2
---int top() { assert(count > 0); return q[0]; }-----// d9
---void heapify() { for (int i = count - 1; i > 0; i--)-----// 77
---if (cmp(i, (i - 1) / 2)) swp(i, (i - 1) / 2); }-----// cc
---void update_key(int n) {-----// 86
---assert(loc[n] != -1), swim(loc[n]), sink(loc[n]); }-----// d9
---bool empty() { return count == 0; }-----// 77
---int size() { return count; }-----// 74
---void clear() { count = 0, memset(loc, 255, len << 2); } };-----// 99
```

2.7. Dancing Links.

```
template <class T>-----// 82
struct dancing_links {-----// 9e
---struct node {-----// 62
---T item;-----// dd
---node *l, *r;-----// 32
---node(const T &item, node *_l = NULL, node *_r = NULL)-----// 6d
---: item(_item), l(_l), r(_r) {-----// 6d
```

```

-----if (l) l->r = this;-----// 97
-----if (r) r->l = this;-----// 81
-----}-----// 2d
};-----// d3
---node *front, *back;-----// aa
---dancing_links() { front = back = NULL; }-----// 72
---node *push_back(const T &item) {-----// 83
-----back = new node(item, back, NULL);-----// c4
-----if (!front) front = back;-----// d2
-----return back;-----// c0
-----}-----// a9
---node *push_front(const T &item) {-----// 4a
-----front = new node(item, NULL, front);-----// 47
-----if (!back) back = front;-----// 10
-----return front;-----// cf
-----}-----// b6
---void erase(node *n) {-----// a0
-----if (!n->l) front = n->r; else n->l->r = n->r;-----// ab
-----if (!n->r) back = n->l; else n->r->l = n->l;-----// 1b
-----}-----// 7b
---void restore(node *n) {-----// 82
-----if (!n->l) front = n; else n->l->r = n;-----// a5
-----if (!n->r) back = n; else n->r->l = n;-----// 9d
-----}-----// eb
};-----// 5e

```

## 2.8. Misof Tree.

```

#define BITS 15-----// 7b
struct misof_tree {-----// fe
---int cnt[BITS][1<<BITS];-----// aa
---misof_tree() { memset(cnt, 0, sizeof(cnt)); }-----// b0
---void insert(int x) { for (int i = 0; i < BITS; cnt[i++][x]++, x >= 1); }-----// 5a
---void erase(int x) { for (int i = 0; i < BITS; cnt[i++][x]--, x >= 1); }-----// 49
---int nth(int n) {-----// 8a
---int res = 0;-----// a4
---for (int i = BITS-1; i >= 0; i--)-----// 99
---if (cnt[i][res <= 1] <= n) n -= cnt[i][res], res |= 1;-----// f4
---return res;-----// 3a
---}-----// b5
};-----// 0a

```

## 2.9. k-d Tree.

```

#define INC(c) ((c) == K - 1 ? 0 : (c) + 1)-----// 77
template <int K> struct kd_tree {-----// 93
---struct pt {-----// 99
-----double coord[K];-----// 31
-----pt() {}-----// 96
-----pt(double c[K]) { rep(i,0,K) coord[i] = c[i]; }-----// 37
-----double dist(const pt &other) const {-----// 16
-----double sum = 0.0;-----// 0c
-----rep(i,0,K) sum += pow(coord[i] - other.coord[i], 2.0);-----// f3
-----return sqrt(sum); } }-----// 68

```

```

---struct cmp {-----// 8c
---int c;-----// fa
---cmp(int _c) : c(_c) {}-----// 28
---bool operator()(const pt &a, const pt &b) {-----// 8e
---for (int i = 0, cc; i <= K; i++) {-----// 24
---cc = i == 0 ? c : i - 1;-----// ae
---if (abs(a.coord[cc] - b.coord[cc]) > EPS)-----// ad
---return a.coord[cc] < b.coord[cc];-----// ed
---}-----// 5d
---return false; } }-----// a4
---struct bb {-----// f1
---pt from, to;-----// 26
---bb(pt _from, pt _to) : from(_from), to(_to) {}-----// 9c
---double dist(const pt &p) {-----// 74
---double sum = 0.0;-----// 48
---rep(i,0,K) {-----// d2
---if (p.coord[i] < from.coord[i])-----// ff
---sum += pow(from.coord[i] - p.coord[i], 2.0);-----// 07
---else if (p.coord[i] > to.coord[i])-----// 50
---sum += pow(p.coord[i] - to.coord[i], 2.0);-----// 45
---}-----// e8
---return sqrt(sum); }-----// df
---bb bound(double l, int c, bool left) {-----// 67
---pt nf(from.coord), nt(to.coord);-----// af
---if (left) nt.coord[c] = min(nt.coord[c], l);-----// 48
---else nf.coord[c] = max(nf.coord[c], l);-----// 14
---return bb(nf, nt); } }-----// 97
---struct node {-----// 7f
---pt p; node *l, *r;-----// 2c
---node(pt _p, node *_l, node *_r) : p(_p), l(_l), r(_r) { } }-----// 84
---node *root;-----// 62
---// kd_tree() : root(NULL) { }-----// 50
---kd_tree(vector<pt> pts) { root = construct(pts, 0, size(pts) - 1, 0); }-----// 8a
---node* construct(vector<pt> &pts, int from, int to, int c) {-----// 8d
---if (from > to) return NULL;-----// 21
---int mid = from + (to - from) / 2;-----// b3
---nth_element(pts.begin() + from, pts.begin() + mid,-----// 56
---pts.begin() + to + 1, cmp(c));-----// a5
---return new node(pts[mid], construct(pts, from, mid - 1, INC(c)),-----// 39
---construct(pts, mid + 1, to, INC(c))); }-----// 3a
---bool contains(const pt &p) { return _con(p, root, 0); }-----// 59
---bool _con(const pt &p, node *n, int c) {-----// 70
---if (!n) return false;-----// b4
---if (cmp(c)(p, n->p)) return _con(p, n->l, INC(c));-----// 2b
---if (cmp(c)(n->p, p)) return _con(p, n->r, INC(c));-----// ec
---return true; }-----// b5
---void insert(const pt &p) { _ins(p, root, 0); }-----// 09
---void _ins(const pt &p, node* &n, int c) {-----// 40
---if (!n) n = new node(p, NULL, NULL);-----// 98
---else if (cmp(c)(p, n->p)) _ins(p, n->l, INC(c));-----// ed
---else if (cmp(c)(n->p, p)) _ins(p, n->r, INC(c)); }-----// 91

```



```
---void clear() { _clr(root); root = NULL; }-----// dd
---void _clr(node *n) { if (n) _clr(n->l), _clr(n->r), delete n; }-----// 17
---pt nearest_neighbour(const pt &p, bool allow_same=true) {-----// 0f
-----assert(root);-----// 47
-----double mn = INFINITY, cs[K];-----// 0d
-----rep(i,0,K) cs[i] = -INFINITY;-----// 56
-----pt from(cs);-----// f0
-----rep(i,0,K) cs[i] = INFINITY;-----// 8c
-----pt to(cs);-----// ad
-----return _nn(p, root, bb(from, to), mn, 0, allow_same).first;-----// f6
}-----// 79
---pair<pt, bool> _nn(-----// a1
-----const pt &p, node *n, bb b, double &mn, int c, bool same) {-----// a6
-----if (!n || b.dist(p) > mn) return make_pair(pt(), false);-----// e4
-----bool found = same || p.dist(n->p) > EPS, l1 = true, l2 = false;-----// 59
-----pt resp = n->p;-----// 92
-----if (found) mn = min(mn, p.dist(resp));-----// 67
-----node *n1 = n->l, *n2 = n->r;-----// b3
-----rep(i,0,2) {-----// af
-----if (i == 1 || cmp(c)(n->p, p)) swap(n1, n2), swap(l1, l2);-----// 1f
-----pair<pt, bool> res =-----// a4
-----_nn(p, n1, b.bound(n->p.coord[c], c, l1), mn, INC(c), same);-----// a8
-----if (res.second && (!found || p.dist(res.first) < p.dist(resp)))-----// cd
-----resp = res.first, found = true;-----// 15
-----}-----// 24
-----return make_pair(resp, found); } }-----// c5
```

2.10. Sqrt Decomposition.

```
struct segment {-----// b2
---vi arr;-----// 8c
---segment(vi _arr) : arr(_arr) { } }-----// 11
vector<segment> T;-----// a1
int K;-----// dc
void rebuild() {-----// 17
---int cnt = 0;-----// 14
---rep(i,0,size(T))-----// b1
---cnt += size(T[i].arr);-----// d1
---K = static_cast<int>(ceil(sqrt(cnt)) + 1e-9);-----// 4c
---vi arr(cnt);-----// 14
---for (int i = 0, at = 0; i < size(T); i++)-----// 79
---rep(j,0,size(T[i].arr))-----// a4
---arr[at++] = T[i].arr[j];-----// f7
---T.clear();-----// 4c
---for (int i = 0; i < cnt; i += K)-----// 79
---T.push_back(segment(vi(arr.begin()+i, arr.begin()+min(i+K, cnt))));-----// f0
}-----// 03
int split(int at) {-----// 71
---int i = 0;-----// 8a
---while (i < size(T) && at >= size(T[i].arr))-----// 6c
---at -= size(T[i].arr), i++;-----// 9a
---if (i >= size(T)) return size(T);-----// 83
```

```
---if (at == 0) return i;-----// 49
---T.insert(T.begin() + i + 1, segment(vi(T[i].arr.begin() + at, T[i].arr.end())));
---T[i] = segment(vi(T[i].arr.begin(), T[i].arr.begin() + at));-----// af
---return i + 1;-----// ac
}-----// ea
void insert(int at, int v) {-----// 5f
---vi arr; arr.push_back(v);-----// 6a
---T.insert(T.begin() + split(at), segment(arr));-----// 67
}-----// cc
void erase(int at) {-----// be
---int i = split(at); split(at + 1);-----// da
---T.erase(T.begin() + i);-----// 6b
}-----// 4b
```

2.11. Monotonic Queue.

```
struct min_stack {-----// d8
---stack<int> S, M;-----// fe
---void push(int x) {-----// 20
---S.push(x);-----// e2
---M.push(M.empty() ? x : min(M.top(), x)); }-----// 92
---int top() { return S.top(); }-----// f1
---int mn() { return M.top(); }-----// 02
---void pop() { S.pop(); M.pop(); }-----// fd
---bool empty() { return S.empty(); }-----// d2
};-----// 74
struct min_queue {-----// b4
---min_stack inp, outp;-----// 3d
---void push(int x) { inp.push(x); }-----// 6b
---void fix() {-----// 5d
---if (outp.empty()) while (!inp.empty())
---outp.push(inp.top()), inp.pop();-----// 8e
---}-----// 3f
---int top() { fix(); return outp.top(); }-----// dc
---int mn() {-----// 39
---if (inp.empty()) return outp.mn();-----// 01
---if (outp.empty()) return inp.mn();-----// 90
---return min(inp.mn(), outp.mn()); }-----// 97
---void pop() { fix(); outp.pop(); }-----// 4f
---bool empty() { return inp.empty() && outp.empty(); }-----// 65
};-----// 60
```

2.12. Convex Hull Trick.

```
struct convex_hull_trick {-----// 16
---vector<pair<double,double> > h;-----// b4
---double intersect(int i) {-----// 9b
---return (h[i+1].second-h[i].second)/(h[i].first-h[i+1].first); }-----// b9
---void add(double m, double b) {-----// a4
---h.push_back(make_pair(m,b));-----// f9
---while (size(h) >= 3) {-----// f6
---int n = size(h);-----// d8
---if (intersect(n-3) < intersect(n-2)) break;-----// 07
---swap(h[n-2], h[n-1]);-----// bf
```

```
-----h.pop_back(); } }-----// 4b
---double get_min(double x) {-----// b0
-----int lo = 0, hi = size(h) - 2, res = -1;-----// 5b
-----while (lo <= hi) {-----// 24
-----int mid = lo + (hi - lo) / 2;-----// 5a
-----if (intersect(mid) <= x) res = mid, lo = mid + 1;-----// 1d
-----else hi = mid - 1; }-----// b6
-----return h[res+1].first * x + h[res+1].second; } }-----// 84
```

3. GRAPHS

3.1. Single-Source Shortest Paths.

3.1.1. Dijkstra’s algorithm.

```
int *dist, *dad;-----// 46
struct cmp {-----// a5
---bool operator()(int a, int b) {-----// bb
-----return dist[a] != dist[b] ? dist[a] < dist[b] : a < b; }-----// e6
};-----// 41
pair<int*, int*> dijkstra(int n, int s, vii *adj) {-----// 53
---dist = new int[n];-----// 84
---dad = new int[n];-----// 05
---rep(i,0,n) dist[i] = INF, dad[i] = -1;-----// 80
---set<int, cmp> pq;-----// 98
---dist[s] = 0, pq.insert(s);-----// 1f
---while (!pq.empty()) {-----// 47
-----int cur = *pq.begin(); pq.erase(pq.begin());-----// 58
-----rep(i,0,size(adj[cur])) {-----// a6
-----int nxt = adj[cur][i].first,-----// a4
-----ndist = dist[cur] + adj[cur][i].second;-----// 3a
-----if (ndist < dist[nxt]) pq.erase(nxt),-----// 2d
-----dist[nxt] = ndist, dad[nxt] = cur, pq.insert(nxt);-----// eb
-----}-----// d2
---}-----// df
---return pair<int*, int*>(dist, dad);-----// e3
}-----// 9b
```

3.1.2. Bellman-Ford algorithm.

```
int* bellman_ford(int n, int s, vii* adj, bool& has_negative_cycle) {-----// cf
---has_negative_cycle = false;-----// 47
---int* dist = new int[n];-----// 7f
---rep(i,0,n) dist[i] = i == s ? 0 : INF;-----// df
---rep(i,0,n-1) rep(j,0,n) if (dist[j] != INF)-----// 4d
-----rep(k,0,size(adj[j]))-----// 88
-----dist[adj[j][k].first] = min(dist[adj[j][k].first],-----// e1
-----dist[j] + adj[j][k].second);-----// 18
---rep(j,0,n) rep(k,0,size(adj[j]))-----// f8
---if (dist[j] + adj[j][k].second < dist[adj[j][k].first])-----// 37
---has_negative_cycle = true;-----// f1
---return dist;-----// 78
}-----// a9
```

3.1.3. IDA\* algorithm.

```
int n, cur[100], pos;-----// 48
int calch() {-----// 88
---int h = 0;-----// 4a
---rep(i,0,n) if (cur[i] != 0) h += abs(i - cur[i]);-----// 9b
---return h;-----// c6
}-----// c8
int dfs(int d, int g, int prev) {-----// 12
---int h = calch();-----// 5d
---if (g + h > d) return g + h;-----// 15
---if (h == 0) return 0;-----// ff
---int mn = INF;-----// 7e
---rep(di,-2,3) {-----// 0d
-----if (di == 0) continue;-----// 0a
-----int nxt = pos + di;-----// 76
-----if (nxt == prev) continue;-----// 39
-----if (0 <= nxt && nxt < n) {-----// 68
-----swap(cur[pos], cur[nxt]);-----// 35
-----swap(pos,nxt);-----// 64
-----mn = min(mn, dfs(d, g+1, nxt));-----// 22
-----swap(pos,nxt);-----// 84
-----swap(cur[pos], cur[nxt]);-----// 3b
-----}-----// 46
-----if (mn == 0) break;-----// 8f
---}-----// d3
---return mn;-----// da
}-----// f8
int idastar() {-----// 22
---rep(i,0,n) if (cur[i] == 0) pos = i;-----// 6b
---int d = calch();-----// 38
---while (true) {-----// 18
---int nd = dfs(d, 0, -1);-----// 42
---if (nd == 0 || nd == INF) return d;-----// b5
---d = nd;-----// f7
---}-----// f9
}-----// 82
```

3.2. Strongly Connected Components.

3.2.1. Kosaraju’s algorithm.

```
#include "../data-structures/union_find.cpp"-----// 5e
vector<bool> visited;-----// 66
vi order;-----// 9b
void scc_dfs(const vvi &adj, int u) {-----// a1
---int v; visited[u] = true;-----// e3
---rep(i,0,size(adj[u]))-----// 2d
---if (!visited[v = adj[u][i]]) scc_dfs(adj, v);-----// a2
---order.push_back(u);-----// 02
}-----// 53
-----// 63
```



```
pair<union_find, vi> scc(const vvi &adj) {-----// c2
---int n = size(adj), u, v;-----// f8
---order.clear();-----// 20
---union_find uf(n);-----// a8
---vi dag;-----// 61
---vvi rev(n);-----// c5
---rep(i,0,n) rep(j,0,size(adj[i])) rev[adj[i][j]].push_back(i);-----// 7e
---visited.resize(n), fill(visited.begin(), visited.end(), false);-----// 80
---rep(i,0,n) if (!visited[i]) scc_dfs(rev, i);-----// 4e
---fill(visited.begin(), visited.end(), false);-----// 59
---stack<int> S;-----// bb
---for (int i = n-1; i >= 0; i--) {-----// 96
-----if (visited[order[i]]) continue;-----// db
-----S.push(order[i]), dag.push_back(order[i]);-----// 68
-----while (!S.empty()) {-----// 9e
-----visited[u = S.top()] = true, S.pop(), uf.unite(u, order[i]);-----// b3
-----rep(j,0,size(adj[u])) if (!visited[v = adj[u][j]]) S.push(v);-----// 1b
-----}-----// 61
---}-----// 57
---return pair<union_find, vi>(uf, dag);-----// 2b
}-----// 92
```

3.3. Cut Points and Bridges.

```
#define MAXN 5000-----// f7
int low[MAXN], num[MAXN], curnum;-----// d7
void dfs(const vvi &adj, vi &cp, vii &bri, int u, int p) {-----// 22
---low[u] = num[u] = curnum++;-----// a3
---int cnt = 0; bool found = false;-----// 97
---rep(i,0,size(adj[u])) {-----// ae
---int v = adj[u][i];-----// 56
---if (num[v] == -1) {-----// 3b
---dfs(adj, cp, bri, v, u);-----// ba
---low[u] = min(low[u], low[v]);-----// be
---cnt++;-----// e0
---found = found || low[v] >= num[u];-----// 30
---if (low[v] > num[u]) bri.push_back(ii(u, v));-----// bf
---} else if (p != v) low[u] = min(low[u], num[v]); }-----// 76
---if (found && (p != -1 || cnt > 1)) cp.push_back(u); }-----// 3e
pair<vi,vii> cut_points_and_bridges(const vvi &adj) {-----// 76
---int n = size(adj);-----// c8
---vi cp; vii bri;-----// fb
---memset(num, -1, n << 2);-----// 45
---curnum = 0;-----// 07
---rep(i,0,n) if (num[i] == -1) dfs(adj, cp, bri, i, -1);-----// 7e
---return make_pair(cp, bri); }-----// 4c
```

3.4. Euler Path.

```
#define MAXV 1000-----// 2f
#define MAXE 5000-----// 87
vi adj[MAXV];-----// ff
int n, m, indeg[MAXV], outdeg[MAXV], res[MAXE + 1];-----// 49
ii start_end() {-----// 30
```

```
---int start = -1, end = -1, any = 0, c = 0;-----// 74
---rep(i,0,n) {-----// 20
---if (outdeg[i] > 0) any = i;-----// 63
---if (indeg[i] + 1 == outdeg[i]) start = i, c++;-----// 5a
---else if (indeg[i] == outdeg[i] + 1) end = i, c++;-----// 13
---else if (indeg[i] != outdeg[i]) return ii(-1,-1);-----// c1
---}-----// ed
---if ((start == -1) != (end == -1) || (c != 2 && c != 0)) return ii(-1,-1);-----// 54
---if (start == -1) start = end = any;-----// 5e
---return ii(start, end);-----// a2
}-----// eb
bool euler_path() {-----// b4
---ii se = start_end();-----// 8a
---int cur = se.first, at = m + 1;-----// b6
---if (cur == -1) return false;-----// ac
---stack<int> s;-----// 1c
---while (true) {-----// b3
---if (outdeg[cur] == 0) {-----// 0d
---res[at] = cur;-----// bd
---if (s.empty()) break;-----// c6
---cur = s.top(); s.pop();-----// 06
---} else s.push(cur), cur = adj[cur][--outdeg[cur]];-----// 9e
---}-----// a4
---return at == 0;-----// ac
}-----// 22
```

3.5. Bipartite Matching.

3.5.1. Alternating Paths algorithm.

```
vi* adj;-----// cc
bool* done;-----// b1
int* owner;-----// 26
int alternating_path(int left) {-----// da
---if (done[left]) return 0;-----// 08
---done[left] = true;-----// f2
---rep(i,0,size(adj[left])) {-----// 1b
---int right = adj[left][i];-----// 46
---if (owner[right] == -1 || alternating_path(owner[right])) {-----// f6
---owner[right] = left; return 1;-----// f2
---} }-----// 88
---return 0; }-----// 41
```

3.5.2. Hopcroft-Karp algorithm. Running time is  $O(|E|\sqrt{|V|})$ .

```
#define MAXN 5000-----// f7
int dist[MAXN+1], q[MAXN+1];-----// b8
#define dist(v) dist[v == -1 ? MAXN : v]-----// 0f
struct bipartite_graph {-----// 2b
---int N, M, *L, *R; vi *adj;-----// fc
---bipartite_graph(int _N, int _M) : N(_N), M(_M),-----// 8d
---L(new int[N]), R(new int[M]), adj(new vi[N]) {}-----// cd
---bipartite_graph() { delete[] adj; delete[] L; delete[] R; }-----// 89
---bool bfs() {-----// f5
```

```
-----int l = 0, r = 0;-----// 37
-----rep(v,0,N) if(L[v] == -1) dist(v) = 0, q[r++] = v;-----// f9
-----else dist(v) = INF;-----// aa
-----dist(-1) = INF;-----// f2
-----while(l < r) {-----// ba
-----    int v = q[l++];-----// 50
-----    if(dist(v) < dist(-1)) {-----// f1
-----        iter(u, adj[v]) if(dist(R[*u]) == INF)-----// 9b
-----        dist(R[*u]) = dist(v) + 1, q[r++] = R[*u];-----// 79
-----    }-----// b8
-----}-----// 0d
-----return dist(-1) != INF;-----// 43
-----}-----// 2c
-----bool dfs(int v) {-----// 26
-----    if(v != -1) {-----// d8
-----        iter(u, adj[v])-----// 99
-----        if(dist(R[*u]) == dist(v) + 1)-----// 74
-----            if(dfs(R[*u])) {-----// 40
-----                R[*u] = v, L[v] = *u;-----// 47
-----                return true;-----// a2
-----            }-----// 17
-----        dist(v) = INF;-----// 62
-----        return false;-----// 3c
-----    }-----// 3d
-----    return true;-----// ae
-----}-----// 0f
-----void add_edge(int i, int j) { adj[i].push_back(j); }-----// 92
-----int maximum_matching() {-----// a2
-----    int matching = 0;-----// 71
-----    memset(L, -1, sizeof(int) * N);-----// 72
-----    memset(R, -1, sizeof(int) * M);-----// bf
-----    while(bfs()) rep(i,0,N)-----// 3e
-----        matching += L[i] == -1 && dfs(i);-----// 1d
-----    return matching;-----// ec
-----}-----// 8b
};-----// b7

-----head = new int[n], curh = new int[n];-----// 6b
-----memset(head, -1, n * sizeof(int));-----// 56
-----}-----// 77
-----void destroy() { delete[] head; delete[] curh; }-----// f6
-----void reset() { e = e_store; }-----// 87
-----void add_edge(int u, int v, int uv, int vu = 0) {-----// cd
-----    e.push_back(edge(v, uv, head[u])); head[u] = ecnt++;-----// c9
-----    e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;-----// 89
-----}-----// 14
-----int augment(int v, int t, int f) {-----// 3f
-----    if (v == t) return f;-----// 6d
-----    for (int &i = curh[v], ret; i != -1; i = e[i].nxt)-----// f9
-----        if (e[i].cap > 0 && d[e[i].v] + 1 == d[v])-----// cc
-----            if ((ret = augment(e[i].v, t, min(f, e[i].cap))) > 0)-----// 1f
-----                return (e[i].cap -= ret, e[i^1].cap += ret, ret);-----// ac
-----    return 0;-----// 19
-----}-----// fd
-----int max_flow(int s, int t, bool res = true) {-----// 31
-----    if(s == t) return 0;-----// 9d
-----    e_store = e;-----// 57
-----    int f = 0, x, l, r;-----// 0e
-----    while (true) {-----// b5
-----        memset(d, -1, n * sizeof(int));-----// a8
-----        l = r = 0, d[q[r++] = t] = 0;-----// 0e
-----        while (l < r)-----// 7a
-----            for (int v = q[l++], i = head[v]; i != -1; i = e[i].nxt)-----// a2
-----                if (e[i^1].cap > 0 && d[e[i].v] == -1)-----// 29
-----                    d[q[r++] = e[i].v] = d[v]+1;-----// 28
-----            if (d[s] == -1) break;-----// a0
-----            memcpy(curh, head, n * sizeof(int));-----// 10
-----            while ((x = augment(s, t, INF)) != 0) f += x;-----// a6
-----        }-----// 96
-----        if (res) reset();-----// 21
-----        return f;-----// b6
-----    }-----// 1b
};-----// 3b
```

3.6. Maximum Flow.

3.6.1. *Dinic’s algorithm.* An implementation of Dinic’s algorithm that runs in  $O(|V|^2|E|)$ .

```
#define MAXV 2000-----// ba
int q[MAXV], d[MAXV];-----// e6
struct flow_network {-----// 12
    struct edge {-----// 1e
        int v, cap, nxt;-----// ab
        edge() { }-----// 38
        edge(int _v, int _cap, int _nxt) : v(_v), cap(_cap), nxt(_nxt) { }-----// bc
    };-----// 6e
    int n, ecnt, *head, *curh;-----// 46
    vector<edge> e, e_store;-----// 1f
    flow_network(int _n, int m = -1) : n(_n), ecnt(0) {-----// d3
        e.reserve(2 * (m == -1 ? n : m));-----// 24
```

3.6.2. *Edmonds Karp’s algorithm.* An implementation of Edmonds Karp’s algorithm that runs in  $O(|V||E|^2)$ .

```
#define MAXV 2000-----// ba
int q[MAXV], d[MAXV], p[MAXV];-----// 7b
struct flow_network {-----// 5e
    struct edge {-----// fc
        int v, cap, nxt;-----// cb
        edge(int _v, int _cap, int _nxt) : v(_v), cap(_cap), nxt(_nxt) { }-----// 7a
    };-----// 31
    int n, ecnt, *head;-----// 39
    vector<edge> e, e_store;-----// ea
    flow_network(int _n, int m = -1) : n(_n), ecnt(0) {-----// 34
        e.reserve(2 * (m == -1 ? n : m));-----// 92
        memset(head = new int[n], -1, n << 2);-----// 58
```

```

}-----// 3a
void destroy() { delete[] head; }-----// d5
void reset() { e = e_store; }-----// 1b
void add_edge(int u, int v, int uv, int vu=0) {-----// 7c
    e.push_back(edge(v, uv, head[u])); head[u] = ecnt++;-----// 4c
    e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;-----// bc
}-----// ef
int max_flow(int s, int t, bool res = true) {-----// 12
    if (s == t) return 0;-----// d6
    e_store = e;-----// 9e
    int f = 0, l, r, v;-----// 6f
    while (true) {-----// 42
        memset(d, -1, n << 2);-----// 3b
        memset(p, -1, n << 2);-----// 92
        l = r = 0, d[q[r++] = s] = 0;-----// 5f
        while (l < r)-----// 2c
            for (int u = q[l++], i = head[u]; i != -1; i = e[i].nxt)-----// c6
                if (e[i].cap > 0 &&-----// 8a
                    (d[v = e[i].v] == -1 || d[u] + 1 < d[v]))-----// 2f
                    d[v] = d[u] + 1, p[q[r++] = v] = i;-----// d5
            if (p[t] == -1) break;-----// 4f
            int x = INF, at = p[t];-----// b1
            while (at != -1) x = min(x, e[at].cap), at = p[e[at^1].v];-----// 8a
            at = p[t], f += x;-----// 2d
            while (at != -1)-----// cd
                e[at].cap -= x, e[at^1].cap += x, at = p[e[at^1].v];-----// 2e
        }-----// 47
        if (res) reset();-----// 3b
        return f;-----// bc
    }-----// 05
};-----// 75

```

3.7. Minimum Cost Maximum Flow. Running time is  $O(|V|^2|E| \log |V|)$ .

```

#define MAXV 2000-----// ba
int d[MAXV], p[MAXV], pot[MAXV];-----// 80
struct cmp {-----// d1
    bool operator()(int i, int j) {-----// 8a
        return d[i] == d[j] ? i < j : d[i] < d[j];-----// 89
    }-----// df
};-----// cf
struct flow_network {-----// eb
    struct edge {-----// 9a
        int v, cap, cost, nxt;-----// ad
        edge(int _v, int _cap, int _cost, int _nxt)-----// ec
            : v(_v), cap(_cap), cost(_cost), nxt(_nxt) { }-----// c4
    };-----// ad
    int n, ecnt, *head;-----// 46
    vector<edge> e, e_store;-----// 4b
    flow_network(int _n, int m = -1) : n(_n), ecnt(0) {-----// dd
        e.reserve(2 * (m == -1 ? n : m));-----// e6
        memset(head = new int[n], -1, n << 2);-----// 6c
    };-----// ec
}
}-----// f3
void destroy() { delete[] head; }-----// ac
void reset() { e = e_store; }-----// 88
void add_edge(int u, int v, int cost, int uv, int vu=0) {-----// b4
    e.push_back(edge(v, uv, cost, head[u])); head[u] = ecnt++;-----// 43
    e.push_back(edge(u, vu, -cost, head[v])); head[v] = ecnt++;-----// 53
}-----// 16
ii min_cost_max_flow(int s, int t, bool res = true) {-----// 6d
    if (s == t) return ii(0, 0);-----// 34
    e_store = e;-----// 70
    memset(pot, 0, n << 2);-----// 24
    int f = 0, c = 0, v;-----// d4
    while (true) {-----// 29
        memset(d, -1, n << 2);-----// fd
        memset(p, -1, n << 2);-----// b7
        set<int> cmp;-----// d8
        q.insert(s); d[s] = 0;-----// 1d
        while (!q.empty()) {-----// 04
            int u = *q.begin();-----// dd
            q.erase(q.begin());-----// 20
            for (int i = head[u]; i != -1; i = e[i].nxt) {-----// 02
                if (e[i].cap == 0) continue;-----// 1c
                int cd = d[u] + e[i].cost + pot[u] - pot[v = e[i].v];-----// 1d
                if (d[v] == -1 || cd < d[v]) {-----// d2
                    if (q.find(v) != q.end()) q.erase(q.find(v));-----// e2
                    d[v] = cd; p[v] = i;-----// f7
                    q.insert(v);-----// 74
                }-----// 6c
            }-----// 1b
        }-----// da
        if (p[t] == -1) break;-----// 09
        int x = INF, at = p[t];-----// e8
        while (at != -1) x = min(x, e[at].cap), at = p[e[at^1].v];-----// 32
        at = p[t], f += x;-----// 43
        while (at != -1)-----// 53
            e[at].cap -= x, e[at^1].cap += x, at = p[e[at^1].v];-----// 95
        c += x * (d[t] + pot[t] - pot[s]);-----// 44
        rep(i,0,n) if (p[i] != -1) pot[i] += d[i];-----// 86
    }-----// 4e
    if (res) reset();-----// d7
    return ii(f, c);-----// 9f
}-----// 4c
};-----// ec

```

3.8. All Pairs Maximum Flow.

3.8.1. Gomory-Hu Tree. An implementation of the Gomory-Hu Tree. The spanning tree is constructed using Gusfield’s algorithm in  $O(|V|^2)$  plus  $|V| - 1$  times the time it takes to calculate the maximum flow. If Dinic’s algorithm is used to calculate the max flow, the running time is  $O(|V|^3|E|)$ .

```

#include "dinic.cpp"-----// 58
-----// 25
bool same[MAXV];-----// 59

```

```

pair<vii, vvi> construct_gh_tree(flow_network &g) {-----// 77
---int n = g.n, v;-----// 5d
---vii par(n, ii(0, 0)); vvi cap(n, vi(n, -1));-----// 49
---rep(s,1,n) {-----// 9e
---int l = 0, r = 0;-----// 08
---par[s].second = g.max_flow(s, par[s].first, false);-----// 54
---memset(d, 0, n * sizeof(int));-----// c8
---memset(same, 0, n * sizeof(int));-----// b7
---d[q[r++] = s] = 1;-----// cb
---while (l < r) {-----// d4
---same[v = q[l++]] = true;-----// f6
---for (int i = g.head[v]; i != -1; i = g.e[i].nxt)-----// da
---if (g.e[i].cap > 0 && d[g.e[i].v] == 0)-----// 9a
---d[q[r++] = g.e[i].v] = 1;-----// 1f
---}-----// d4
---rep(i,s+1,n)-----// 35
---if (par[i].first == par[s].first && same[i]) par[i].first = s;-----// 93
---g.reset();-----// 87
---}-----// 22
---rep(i,0,n) {-----// 34
---int mn = INF, cur = i;-----// ac
---while (true) {-----// c9
---cap[cur][i] = mn;-----// 3b
---if (cur == 0) break;-----// 37
---mn = min(mn, par[cur].second), cur = par[cur].first;-----// e8
---}-----// de
---}-----// 99
---return make_pair(par, cap);-----// 75
}-----// f6
int compute_max_flow(int s, int t, const pair<vii, vvi> &gh) {-----// 2a
---if (s == t) return 0;-----// 7a
---int cur = INF, at = s;-----// 57
---while (gh.second[at][t] == -1)-----// e0
---cur = min(cur, gh.first[at].second), at = gh.first[at].first;-----// 00
---return min(cur, gh.second[at][t]);-----// 09
}-----// 07

```

### 3.9. Heavy-Light Decomposition.

```

#include "../data-structures/segment_tree.cpp"-----// 16
struct HLD {-----// 25
---int n, curhead, curloc;-----// d9
---vi sz, head, parent, loc;-----// 81
---vvi below; segment_tree values;-----// 96
---HLD(int n) : n(n), sz(n, 1), head(n), parent(n, -1), loc(n), below(n) {-----// 4f
---vi tmp(n, ID); values = segment_tree(tmp); }-----// a7
---void add_edge(int u, int v) { below[parent[v] = u].push_back(v); }-----// f8
---void update_cost(int u, int v, int c) {-----// 12
---if (parent[v] == u) swap(u, v); assert(parent[u] == v);-----// 9f
---values.update(loc[u], c); }-----// 9a
---void csz(int u) { rep(i,0,size(below[u]))-----// 61
---csz(below[u][i]), sz[u] += sz[below[u][i]]; }-----// e7

```

```

---void part(int u) {-----// da
---head[u] = curhead; loc[u] = curloc++;-----// cc
---int best = -1;-----// 55
---rep(i,0,size(below[u]))-----// 0f
---if (best == -1 || sz[below[u][i]] > sz[best]) best = below[u][i];-----// 7d
---if (best != -1) part(best);-----// 26
---rep(i,0,size(below[u]))-----// 44
---if (below[u][i] != best) part(curhead = below[u][i]); }-----// 84
---void build() { int u = curloc = 0;-----// c4
---while (parent[u] != -1) u++;-----// d4
---csz(u); part(curhead = u); }-----// 38
---int lca(int u, int v) {-----// 81
---vi uat, vat; int res = -1;-----// e9
---while (u != -1) uat.push_back(u), u = parent[head[u]];-----// 5c
---while (v != -1) vat.push_back(v), v = parent[head[v]];-----// 1f
---u = size(uat) - 1, v = size(vat) - 1;-----// a4
---while (u >= 0 && v >= 0 && head[uat[u]] == head[vat[v]])-----// fe
---res = (loc[uat[u]] < loc[vat[v]] ? uat[u] : vat[v]), u--, v--;-----// 13
---return res; }-----// 3b
---int query_upto(int u, int v) { int res = ID;-----// bf
---while (head[u] != head[v])-----// 81
---res = f(res, values.query(loc[head[u]], loc[u])),-----// 66
---u = parent[head[u]];-----// 72
---return f(res, values.query(loc[v] + 1, loc[u])); }-----// d7
---int query(int u, int v) { int l = lca(u, v);-----// fb
---return f(query_upto(u, l), query_upto(v, l)); } }-----// 21

```

### 3.10. Tarjan's Off-line Lowest Common Ancestors Algorithm.

```

#include "../data-structures/union_find.cpp"-----// 5e
struct tarjan_olca {-----// 87
---int *ancestor;-----// 39
---vi *adj, answers;-----// dd
---vii *queries;-----// 66
---bool *colored;-----// 97
---union_find uf;-----// 70
---tarjan_olca(int n, vi *adj) : adj(_adj), uf(n) {-----// 78
---colored = new bool[n];-----// 8d
---ancestor = new int[n];-----// f2
---queries = new vii[n];-----// 3e
---memset(colored, 0, n);-----// 6e
---}-----// 6b
---void query(int x, int y) {-----// d3
---queries[x].push_back(ii(y, size(answers)));-----// a0
---queries[y].push_back(ii(x, size(answers)));-----// 14
---answers.push_back(-1);-----// ca
---}-----// 6b
---void process(int u) {-----// 85
---ancestor[u] = u;-----// 1a
---rep(i,0,size(adj[u])) {-----// ce
---int v = adj[u][i];-----// dd
---process(v);-----// e8

```

```
uf.unite(u,v);-----// 55
ancestor[uf.find(u)] = u;-----// 1d
}-----// 57
colored[u] = true;-----// b9
rep(i,0,size(queries[u])) {-----// d7
    int v = queries[u][i].first;-----// 89
    if (colored[v]) {-----// cb
        answers[queries[u][i].second] = ancestor[uf.find(v)];-----// 63
    }-----// d0
}-----// 40
}-----// a9
};-----// 1e
```

4. STRINGS

4.1. Suffix Array. An  $O(n \log^2 n)$  construction of a Suffix Tree.

```
struct entry { ii nr; int p; };-----// f9
bool operator <(const entry &a, const entry &b) { return a.nr < b.nr; }-----// 77
struct suffix_array {-----// 87
    string s; int n; vvi P; vector<entry> L; vi idx;-----// b6
    suffix_array(string _s) : s(_s), n(size(s)) {-----// a3
        L = vector<entry>(n), P.push_back(vi(n)), idx = vi(n);-----// 12
        rep(i,0,n) P[0][i] = s[i];-----// 5c
        for (int stp = 1, cnt = 1; cnt >> 1 < n; stp++, cnt <= 1) {-----// 86
            P.push_back(vi(n));-----// 53
            rep(i,0,n)-----// 6f
                L[L[i].p = i].nr = ii(P[stp - 1][i],-----// e2
                    i + cnt < n ? P[stp - 1][i + cnt] : -1);-----// 43
            sort(L.begin(), L.end());-----// 5f
            rep(i,0,n)-----// a8
                P[stp][L[i].p] = i > 0 &&-----// 3a
                    L[i].nr == L[i - 1].nr ? P[stp][L[i - 1].p] : i;-----// 55
        }-----// 8b
        rep(i,0,n) idx[P[size(P) - 1][i]] = i;-----// 17
    }-----// d9
    int lcp(int x, int y) {-----// 71
        int res = 0;-----// d6
        if (x == y) return n - x;-----// bc
        for (int k = size(P) - 1; k >= 0 && x < n && y < n; k--)-----// fe
            if (P[k][x] == P[k][y]) x += 1 << k, y += 1 << k, res += 1 << k;-----// b7
        return res;-----// bc
    }-----// f1
};-----// f6
```

4.2. Aho-Corasick Algorithm.

```
struct aho_corasick {-----// 78
    struct out_node {-----// 3e
        string keyword; out_node *next;-----// f0
        out_node(string k, out_node *n) : keyword(k), next(n) { }-----// 26
    };-----// b9
    struct go_node {-----// 40
        map<char, go_node*> next;-----// 6b
```

```
        out_node *out; go_node *fail;-----// 3e
        go_node() { out = NULL; fail = NULL; }-----// 0f
    };-----// c0
    go_node *go;-----// b8
    aho_corasick(vector<string> keywords) {-----// 4b
        go = new go_node();-----// 77
        iter(k, keywords) {-----// f2
            go_node *cur = go;-----// a2
            iter(c, *k)-----// 6e
                cur = cur->next.find(*c) != cur->next.end() ? cur->next[*c] :-----// 97
                    (cur->next[*c] = new go_node());-----// af
            cur->out = new out_node(*k, cur->out);-----// 3f
        }-----// eb
        queue<go_node*> q;-----// 2c
        iter(a, go->next) q.push(a->second);-----// db
        while (!q.empty()) {-----// 07
            go_node *r = q.front(); q.pop();-----// e0
            iter(a, r->next) {-----// 18
                go_node *s = a->second;-----// 55
                q.push(s);-----// b5
                go_node *st = r->fail;-----// 53
                while (st && st->next.find(a->first) == st->next.end())-----// 0e
                    st = st->fail;-----// b3
                if (!st) st = go;-----// 0b
                s->fail = st->next[a->first];-----// c1
                if (s->fail) {-----// 98
                    if (!s->out) s->out = s->fail->out;-----// ad
                    else {-----// 5b
                        out_node* out = s->out;-----// b8
                        while (out->next) out = out->next;-----// b4
                        out->next = s->fail->out;-----// 62
                    }-----// a6
                }-----// 81
            }-----// 55
        }-----// bf
    }-----// de
    vector<string> search(string s) {-----// c4
        vector<string> res;-----// 79
        go_node *cur = go;-----// 85
        iter(c, s) {-----// 57
            while (cur && cur->next.find(*c) == cur->next.end())-----// df
                cur = cur->fail;-----// b1
            if (!cur) cur = go;-----// 92
            cur = cur->next[*c];-----// 97
            if (!cur) cur = go;-----// 01
            for (out_node *out = cur->out; out; out = out->next)-----// d7
                res.push_back(out->keyword);-----// 7c
        }-----// 56
        return res;-----// 6b
    }-----// 3e
};-----// de
```

4.3. The Z algorithm.

```
int* z_values(const string &s) {-----// 4d
---int n = size(s);-----// 97
---int* z = new int[n];-----// c4
---int l = 0, r = 0;-----// 1c
---z[0] = n;-----// 98
---rep(i,1,n) {-----// b2
---z[i] = 0;-----// 4c
-----if (i > r) {-----// 6d
---l = r = i;-----// 24
---while (r < n && s[r - l] == s[r]) r++;-----// 68
---z[i] = r - l; r--;-----// 07
-----} else if (z[i - l] < r - i + 1) z[i] = z[i - l];-----// 6f
-----else {-----// a8
---l = i;-----// 55
---while (r < n && s[r - l] == s[r]) r++;-----// 2c
---z[i] = r - l; r--; } }-----// 13
---return z;-----// 78
}-----// 16
```

4.4. Eertree.

```
#define MAXN 100100-----// 29
#define SIGMA 26-----// e2
#define BASE 'a'-----// a1
char *s = new char[MAXN];-----// db
struct state {-----// 33
---int len, link, to[SIGMA];-----// 24
} *st = new state[MAXN+2];-----// 57
struct eertree {-----// 78
---int last, sz, n;-----// ba
---eertree() : last(1), sz(2), n(0) {-----// 83
-----st[0].len = st[0].link = -1;-----// 3f
-----st[1].len = st[1].link = 0; }-----// 34
---int extend() {-----// c2
---char c = s[n++]; int p = last;-----// 25
---while (n - st[p].len - 2 < 0 || c != s[n - st[p].len - 2]) p = st[p].link;-----// 82
---if (!st[p].to[c-BASE]) {-----// 42
---int q = last = sz++;-----// fc
---st[p].to[c-BASE] = q;-----// c5
---st[q].len = st[p].len + 2;-----// 04
---do { p = st[p].link;-----// 77
-----} while (p != -1 && (n < st[p].len + 2 || c != s[n - st[p].len - 2]));
---if (p == -1) st[q].link = 1;-----// 6a
---else st[q].link = st[p].to[c-BASE];-----// 29
---return 1; }-----// 42
---last = st[p].to[c-BASE];-----// ec
---return 0; } };
```

5. MATHEMATICS

5.1. Big Integer.

```
struct intx {-----// cf
---intx() { normalize(1); }-----// 6c
---intx(string n) { init(n); }-----// b9
---intx(int n) { stringstream ss; ss << n; init(ss.str()); }-----// 36
---intx(const intx& other) : sign(other.sign), data(other.data) { }-----// 3b
---int sign;-----// 26
---vector<unsigned int> data;-----// 19
---static const int dcnt = 9;-----// 12
---static const unsigned int radix = 1000000000U;-----// f0
---int size() const { return data.size(); }-----// 29
---void init(string n) {-----// 13
---intx res; res.data.clear();-----// 4e
---if (n.empty()) n = "0";-----// 99
---if (n[0] == '-') res.sign = -1, n = n.substr(1);-----// 3b
---for (int i = n.size() - 1; i >= 0; i -= intx::dcnt) {-----// e7
---unsigned int digit = 0;-----// 98
---for (int j = intx::dcnt - 1; j >= 0; j--) {-----// 72
---int idx = i - j;-----// cd
---if (idx < 0) continue;-----// 52
---digit = digit * 10 + (n[idx] - '0');-----// 1f
---}-----// c0
---res.data.push_back(digit);-----// 07
---}-----// fb
---data = res.data;-----// 7d
---normalize(res.sign);-----// 76
---}-----// 6e
---intx& normalize(int nsign) {-----// 3b
---if (data.empty()) data.push_back(0);-----// fa
---for (int i = data.size() - 1; i > 0 && data[i] == 0; i--)-----// 27
---data.erase(data.begin() + i);-----// 67
---sign = data.size() == 1 && data[0] == 0 ? 1 : nsign;-----// ff
---return *this;-----// 40
---}-----// ac
---friend ostream& operator <<(ostream& outs, const intx& n) {-----// 0d
---if (n.sign < 0) outs << '-';-----// c0
---bool first = true;-----// 33
---for (int i = n.size() - 1; i >= 0; i--) {-----// 63
---if (first) outs << n.data[i], first = false;-----// 33
---else {-----// 1f
---unsigned int cur = n.data[i];-----// 0f
---stringstream ss; ss << cur;-----// 8c
---string s = ss.str();-----// 64
---int len = s.size();-----// 0d
---while (len < intx::dcnt) outs << '0', len++;-----// 0a
---outs << s;-----// 97
---}-----// f7
---}-----// e9
---return outs;-----// cf
---}-----// b9
---string to_string() const { stringstream ss; ss << *this; return ss.str(); }// fc
---bool operator <(const intx& b) const {-----// 21
```



```

-----if (sign != b.sign) return sign < b.sign;-----// cf
-----if (size() != b.size())-----// 4d
-----return sign == 1 ? size() < b.size() : size() > b.size();-----// 4d
-----for (int i = size() - 1; i >= 0; i--) if (data[i] != b.data[i])-----// 35
-----return sign == 1 ? data[i] < b.data[i] : data[i] > b.data[i];--// 27
-----return false;-----// ca
}-----// 32
---intx operator -() const { intx res(*this); res.sign *= -1; return res; }--// 9d
---friend intx abs(const intx &n) { return n < 0 ? -n : n; }-----// 02
---intx operator +(const intx& b) const {-----// f8
-----if (sign > 0 && b.sign < 0) return *this - (-b);-----// 36
-----if (sign < 0 && b.sign > 0) return b - (-*this);-----// 70
-----if (sign < 0 && b.sign < 0) return -((-*this) + (-b));-----// 59
---intx c; c.data.clear();-----// 18
-----unsigned long long carry = 0;-----// 5c
-----for (int i = 0; i < size() || i < b.size() || carry; i++) {-----// e3
-----carry += (i < size() ? data[i] : 0ULL) +-----// 91
----- (i < b.size() ? b.data[i] : 0ULL);-----// 0c
-----c.data.push_back(carry % intx::radix);-----// 86
-----carry /= intx::radix;-----// fd
-----}-----// 50
-----return c.normalize(sign);-----// 20
}-----// 70
---intx operator -(const intx& b) const {-----// 53
-----if (sign > 0 && b.sign < 0) return *this + (-b);-----// 8f
-----if (sign < 0 && b.sign > 0) return -(*this + b);-----// 1b
-----if (sign < 0 && b.sign < 0) return (-b) - (-*this);-----// a1
-----if (*this < b) return -(b - *this);-----// 36
---intx c; c.data.clear();-----// 6b
-----long long borrow = 0;-----// f8
-----rep(i,0,size()) {-----// a7
-----borrow = data[i] - borrow - (i < b.size() ? b.data[i] : 0ULL);-----// a5
-----c.data.push_back(borrow < 0 ? intx::radix + borrow : borrow);-----// 9b
-----borrow = borrow < 0 ? 1 : 0;-----// fb
-----}-----// dd
-----return c.normalize(sign);-----// 5c
}-----// 5e
---intx operator *(const intx& b) const {-----// b3
---intx c; c.data.assign(size() + b.size() + 1, 0);-----// 3a
-----rep(i,0,size()) {-----// 0f
-----long long carry = 0;-----// 15
-----for (int j = 0; j < b.size() || carry; j++) {-----// 95
-----if (j < b.size()) carry += (long long)data[i] * b.data[j];-----// 6d
-----carry += c.data[i + j];-----// c6
-----c.data[i + j] = carry % intx::radix;-----// a8
-----carry /= intx::radix;-----// dc
-----}-----// e3
-----}-----// f0
-----return c.normalize(sign * b.sign);-----// 09
}-----// a7
---friend pair<intx,intx> divmod(const intx& n, const intx& d) {-----// 40
-----assert(!(d.size() == 1 && d.data[0] == 0));-----// 42
-----intx q, r; q.data.assign(n.size(), 0);-----// 5e
-----for (int i = n.size() - 1; i >= 0; i--) {-----// 52
-----r.data.insert(r.data.begin(), 0);-----// cb
-----r = r + n.data[i];-----// ea
-----long long k = 0;-----// dd
-----if (d.size() < r.size())-----// 4d
-----k = (long long)intx::radix * r.data[d.size()];-----// d2
-----if (d.size() - 1 < r.size()) k += r.data[d.size() - 1];-----// af
-----k /= d.data.back();-----// 85
-----r = r - abs(d) * k;-----// 3b
-----// if (r < 0) for (ll t = 1LL << 62; t >= 1; t >= 1) {-----// 0e
-----//---- intx dd = abs(d) * t;-----// 9d
-----//---- while (r + dd < 0) r = r + dd, k -= t; }-----// a1
-----while (r < 0) r = r + abs(d), k--;-----// cb
-----q.data[i] = k;-----// 1a
-----}-----// 3c
-----return pair<intx, intx>(q.normalize(n.sign * d.sign), r);-----// 9e
}-----// a7
---intx operator /(const intx& d) const {-----// 22
-----return divmod(*this,d).first; }-----// c3
---intx operator %(const intx& d) const {-----// 32
-----return divmod(*this,d).second * sign; }-----// 0c
};-----// 64

5.1.1. Fast Multiplication.
#include "intx.cpp"-----// 83
#include "fft.cpp"-----// 13
-----// e0
intx fastmul(const intx &an, const intx &bn) {-----// ab
-----string as = an.to_string(), bs = bn.to_string();-----// 32
-----int n = size(as), m = size(bs), l = 1,-----// dc
-----len = 5, radix = 100000,-----// 4f
-----*a = new int[n], alen = 0,-----// b8
-----*b = new int[m], blen = 0;-----// 0a
-----memset(a, 0, n << 2);-----// 1d
-----memset(b, 0, m << 2);-----// 01
-----for (int i = n - 1; i >= 0; i -= len, alen++)-----// 6e
-----for (int j = min(len - 1, i); j >= 0; j--)-----// 43
-----a[alen] = a[alen] * 10 + as[i - j] - '0';-----// 14
-----for (int i = m - 1; i >= 0; i -= len, blen++)-----// b6
-----for (int j = min(len - 1, i); j >= 0; j--)-----// ae
-----b[blen] = b[blen] * 10 + bs[i - j] - '0';-----// 9b
-----while (l < 2*max(alen,blen)) l <= 1;-----// 51
-----cpx *A = new cpx[l], *B = new cpx[l];-----// 0d
-----rep(i,0,l) A[i] = cpx(i < alen ? a[i] : 0, 0);-----// ff
-----rep(i,0,l) B[i] = cpx(i < blen ? b[i] : 0, 0);-----// 7f
-----fft(A, l); fft(B, l);-----// 77
-----rep(i,0,l) A[i] *= B[i];-----// 1c
-----fft(A, l, true);-----// ec
-----ull *data = new ull[l];-----// f1

```

```
----rep(i,0,l) data[i] = (ull)(round(real(A[i])));-----// e2
----rep(i,0,l-1)-----// c8
-----if (data[i] >= (unsigned int)(radix)) {-----// 03
-----data[i+1] += data[i] / radix;-----// 48
-----data[i] %= radix;-----// 94
-----}-----// 47
--int stop = l-1;-----// 92
--while (stop > 0 && data[stop] == 0) stop--;-----// 5b
--stringstream ss;-----// a6
--ss << data[stop];-----// f3
--for (int i = stop - 1; i >= 0; i--)-----// 7b
--ss << setfill('0') << setw(len) << data[i];-----// 41
--delete[] A; delete[] B;-----// dd
--delete[] a; delete[] b;-----// 77
--delete[] data;-----// 5e
--return intx(ss.str());-----// 88
}-----// d8
```

5.2. **Binomial Coefficients.** The binomial coefficient  $\binom{n}{k} = \frac{n!}{k!(n-k)!}$  is the number of ways to choose  $k$  items out of a total of  $n$  items.

```
int nck(int n, int k) {-----// f6
---if (n - k < k) k = n - k;-----// 18
---int res = 1;-----// cb
---rep(i,1,k+1) res = res * (n - (k - i)) / i;-----// 16
---return res;-----// 6d
}-----// 3d
```

5.3. **Euclidean algorithm.**

```
int gcd(int a, int b) { return b == 0 ? a : gcd(b, a % b); }-----// d9
```

The extended Euclidean algorithm computes the greatest common divisor  $d$  of two integers  $a, b$  and also finds two integers  $x, y$  such that  $a \times x + b \times y = d$ .

```
int egcd(int a, int b, int& x, int& y) {-----// 85
---if (b == 0) { x = 1; y = 0; return a; }-----// 7b
---else {-----// 00
-----int d = egcd(b, a % b, x, y);-----// 34
-----x -= a / b * y;-----// 4a
-----swap(x, y);-----// 26
-----return d;-----// db
---}-----// 9e
}-----// 40
```

5.4. **Trial Division Primality Testing.**

```
bool is_prime(int n) {-----// 6c
---if (n < 2) return false;-----// c9
---if (n < 4) return true;-----// d9
---if (n % 2 == 0 || n % 3 == 0) return false;-----// 0f
---if (n < 25) return true;-----// ef
---int s = static_cast<int>(sqrt(static_cast<double>(n)));-----// 64
---for (int i = 5; i <= s; i += 6)-----// 6c
-----if (n % i == 0 || n % (i + 2) == 0) return false;-----// e9
---return true; }-----// 43
```

5.5. **Miller-Rabin Primality Test.**

```
#include "mod_pow.cpp"-----// c7
bool is_probable_prime(ll n, int k) {-----// be
---if (~n & 1) return n == 2;-----// d1
---if (n <= 3) return n == 3;-----// 39
---int s = 0; ll d = n - 1;-----// 37
---while (~d & 1) d >>= 1, s++;-----// 35
---while (k--) {-----// c8
-----ll a = (n - 3) * rand() / RAND_MAX + 2;-----// 06
-----ll x = mod_pow(a, d, n);-----// 64
-----if (x == 1 || x == n - 1) continue;-----// 9b
-----bool ok = false;-----// 03
-----rep(i,0,s-1) {-----// 13
-----x = (x * x) % n;-----// 90
-----if (x == 1) return false;-----// 5c
-----if (x == n - 1) { ok = true; break; }-----// a1
-----}-----// 3a
-----if (!ok) return false;-----// 37
---} return true; }-----// fe
```

5.6. **Sieve of Eratosthenes.**

```
vi prime_sieve(int n) {-----// 40
---int mx = (n - 3) >> 1, sq, v, i = -1;-----// 27
---vi primes;-----// 8f
---bool* prime = new bool[mx + 1];-----// ef
---memset(prime, 1, mx + 1);-----// 28
---if (n >= 2) primes.push_back(2);-----// f4
---while (++i <= mx) if (prime[i]) {-----// 73
-----primes.push_back(v = (i << 1) + 3);-----// be
-----if ((sq = i * ((i << 1) + 6) + 3) > mx) break;-----// 2d
-----for (int j = sq; j <= mx; j += v) prime[j] = false; }-----// 2e
---while (++i <= mx) if (prime[i]) primes.push_back((i << 1) + 3);-----// 29
---delete[] prime; // can be used for O(1) lookup-----// 36
---return primes; }-----// 72
```

5.7. **Modular Multiplicative Inverse.**

```
#include "egcd.cpp"-----// 55
-----// e8
int mod_inv(int a, int m) {-----// 49
---int x, y, d = egcd(a, m, x, y);-----// 3e
---if (d != 1) return -1;-----// 20
---return x < 0 ? x + m : x;-----// 3c
}-----// 69
```

5.8. **Chinese Remainder Theorem.**

```
#include "egcd.cpp"-----// 55
int crt(const vi& as, const vi& ns) {-----// c3
---int cnt = size(as), N = 1, x = 0, r, s, l;-----// 55
---rep(i,0,cnt) N *= ns[i];-----// b1
---rep(i,0,cnt) egcd(ns[i], l = N/ns[i], r, s), x += as[i] * s * l;-----// 21
---return mod(x, N); }-----// b2
```

5.9. **Linear Congruence Solver.** A function that returns all solutions to  $ax \equiv b \pmod n$ , modulo  $n$ .

```
#include "egcd.cpp"-----// 55
vi linear_congruence(int a, int b, int n) {-----// c8
  ---int x, y, d = egcd(a, n, x, y);-----// 7a
  ---vi res;-----// f5
  ---if (b % d != 0) return res;-----// 30
  ---int x0 = mod(b / d * x, n);-----// 48
  ---rep(k,0,d) res.push_back(mod(x0 + k * n / d, n));-----// 7e
  ---return res;-----// fe
}-----// c0
```

5.10. **Numeric Integration.**

```
double integrate(double (*f)(double), double a, double b,-----// 76
  -----double delta = 1e-6) {-----// c0
  ---if (abs(a - b) < delta)-----// 38
  ---return (b-a)/8 *-----// 56
  -----(f(a) + 3*f((2*a+b)/3) + 3*f((a+2*b)/3) + f(b));-----// e1
  ---return integrate(f, a,-----// 64
  -----(a+b)/2, delta) + integrate(f, (a+b)/2, b, delta);-----// 0c
}-----// 4b
```

5.11. **Fast Fourier Transform.** The Cooley-Tukey algorithm for quickly computing the discrete Fourier transform. The `fft` function only supports powers of twos. The `czt` function implements the Chirp Z-transform and supports any size, but is slightly slower.

```
#include <complex>-----// 8e
typedef complex<long double> cpx;-----// 25
// NOTE: n must be a power of two-----// 14
void fft(cpx *x, int n, bool inv=false) {-----// 36
  ---for (int i = 0, j = 0; i < n; i++) {-----// f9
  -----if (i < j) swap(x[i], x[j]);-----// 44
  -----int m = n>>1;-----// 9c
  -----while (1 <= m && m <= j) j -= m, m >>= 1;-----// fe
  -----j += m;-----// 11
  ---}-----// d0
  ---for (int mx = 1; mx < n; mx <= 1) {-----// 15
  -----cpx wp = exp(cpx(0, (inv ? -1 : 1) * pi / mx)), w = 1;-----// 79
  -----for (int m = 0; m < mx; m++, w *= wp) {-----// dc
  -----for (int i = m; i < n; i += mx << 1) {-----// 6a
  -----cpx t = x[i + mx] * w;-----// 12
  -----x[i + mx] = x[i] - t;-----// 73
  -----x[i] += t;-----// 0e
  -----}-----// 14
  -----}-----// a4
  ---}-----// bf
  ---if (inv) rep(i,0,n) x[i] /= cpx(n);-----// 16
}-----// 1c
void czt(cpx *x, int n, bool inv=false) {-----// c5
  ---int len = 2*n+1;-----// bc
  ---while (len & (len - 1)) len &= len - 1;-----// 65
  ---len <<= 1;-----// 21
  ---cpx w = exp(-2.0L * pi / n * cpx(0,1)),-----// 45
```

```
-----*c = new cpx[n], *a = new cpx[len],-----// 4e
-----*b = new cpx[len];-----// 30
---rep(i,0,n) c[i] = pow(w, (inv ? -1.0 : 1.0)*i*i/2);-----// 9e
---rep(i,0,n) a[i] = x[i] * c[i], b[i] = 1.0L/c[i];-----// e9
---rep(i,0,n-1) b[len - n + i + 1] = 1.0L/c[n-i-1];-----// 9f
---fft(a, len); fft(b, len);-----// 63
---rep(i,0,len) a[i] *= b[i];-----// 58
---fft(a, len, true);-----// 2d
---rep(i,0,n) {-----// ff
  ---x[i] = c[i] * a[i];-----// 77
  ---if (inv) x[i] /= cpx(n);-----// b1
  ---}-----// 27
---delete[] a;-----// 0a
---delete[] b;-----// 5c
---delete[] c;-----// f8
}-----// c6
```

5.12. **Formulas.**

- Number of permutations of  $n$  objects, where there are  $n_1$  objects of type 1,  $n_2$  objects of type 2,  $\dots$ ,  $n_k$  objects of type  $k$ :  $\binom{n}{n_1, n_2, \dots, n_k} = \frac{n!}{n_1! \times n_2! \times \dots \times n_k!}$
- Number of ways to choose  $k$  objects from a total of  $n$  objects where order does not matter and each item can be chosen multiple times:  $f_k^n = \binom{n+k-1}{k} = \frac{(n+k-1)!}{k!(n-1)!}$
- Number of integer solutions to  $x_1 + x_2 + \dots + x_n = k$  where  $x_i \geq 0$ :  $f_k^n$
- Number of strings with  $n$  sets of brackets such that the brackets are balanced:  
 $C_n = \sum_{k=0}^{n-1} C_k C_{n-1-k} = \frac{1}{n+1} \binom{2n}{n}$
- Number of triangulations of a convex polygon with  $n$  points, number of rooted binary trees with  $n+1$  vertices, number of paths across an  $n \times n$  lattice which do not rise above the main diagonal:  $C_n$
- Number of permutations of  $n$  objects with exactly  $k$  ascending sequences or *runs*:  
 $\langle n \rangle_k = \left\langle \binom{n}{n-k-1} \right\rangle = k \left\langle \binom{n-1}{k} \right\rangle + (n-k+1) \left\langle \binom{n-1}{k-1} \right\rangle = \sum_{i=0}^k (-1)^i \binom{n+1}{i} (k+1-i)^n, \langle n \rangle = \left\langle \binom{n}{n-1} \right\rangle = 1$
- Number of permutations of  $n$  objects with exactly  $k$  cycles:  $\left[ \binom{n}{k} \right] = \left[ \binom{n-1}{k-1} \right] + (n-1) \left[ \binom{n-1}{k} \right]$
- Number of ways to partition  $n$  objects into  $k$  sets:  $\left\{ \binom{n}{k} \right\} = k \left\{ \binom{n-1}{k} \right\} + \left\{ \binom{n-1}{k-1} \right\}, \left\{ \binom{n}{0} \right\} = \left\{ \binom{n}{n} \right\} = 1$
- Number of permutations of length  $n$  that have no fixed points (derangements):  $D_0 = 1, D_1 = 0, D_n = (n-1)(D_{n-1} + D_{n-2})$
- Number of permutations of length  $n$  that have exactly  $k$  fixed points:  $\binom{n}{k} D_{n-k}$
- **Jacobi symbol:**  $\left( \frac{a}{b} \right) = a^{(b-1)/2} \pmod b$
- **Heron's formula:** A triangle with side lengths  $a, b, c$  has area  $\sqrt{s(s-a)(s-b)(s-c)}$  where  $s = \frac{a+b+c}{2}$ .
- **Pick's theorem:** A polygon on an integer grid containing  $i$  lattice points and having  $b$  lattice points on the boundary has area  $i + \frac{b}{2} - 1$ .
- **Divisor sigma:** The sum of divisors of  $n$  to the  $x$ th power is  $\sigma_x(n) = \prod_{i=0}^r \frac{p_i^{(a_i+1)x} - 1}{p_i^x - 1}$  where  $n = \prod_{i=0}^r p_i^{a_i}$  is the prime factorization.
- **Euler's totient:** The number of integers less than  $n$  that are coprime to  $n$  are  $n \prod_{p|n} \left(1 - \frac{1}{p}\right)$  where each  $p$  is a distinct prime factor of  $n$ .
- $\gcd(2^a - 1, 2^b - 1) = 2^{\gcd(a,b)} - 1$
- **Wilson's theorem:**  $(n-1)! \equiv -1 \pmod n$  iff.  $n$  is prime
- **Lagrange polynomial** through points  $(x_0, y_0), \dots, (x_k, y_k)$  is  $L(x) = \sum_{j=0}^k y_j \prod_{\substack{0 \leq m \leq k \\ m \neq j}} \frac{x - x_m}{x_j - x_m}$

5.13. Numbers and Sequences. Some random prime numbers: 1031, 32771, 1048583, 33554467, 1073741827, 34359738421, 1099511627791, 35184372088891, 1125899906842679, 36028797018963971.

6. GEOMETRY

6.1. Primitives.

```
#include <complex>-----// 8e
#define P(p) const point &p-----// b8
#define L(p0, p1) P(p0), P(p1)-----// 30
#define C(p0, r) P(p0), double r-----// 08
#define PP(pp) pair<point,point> &pp-----// a1
typedef complex<double> point;-----// 9e
double dot(P(a), P(b)) { return real(conj(a) * b); }-----// 4a
double cross(P(a), P(b)) { return imag(conj(a) * b); }-----// f3
point rotate(P(p), double radians = pi / 2, P(about) = point(0,0)) { -----// 0b
    ---return (p - about) * exp(point(0, radians)) + about; }-----// f5
point reflect(P(p), L(about1, about2)) {-----// 45
    ---point z = p - about1, w = about2 - about1;-----// 74
    ---return conj(z / w) * w + about1; }-----// d1
point proj(P(u), P(v)) { return dot(u, v) / dot(u, u) * u; }-----// 98
point normalize(P(p), double k = 1.0) { -----// a9
    ---return abs(p) == 0 ? point(0,0) : p / abs(p) * k; } //TODO: TEST-----// 1c
bool parallel(L(a, b), L(p, q)) { return abs(cross(b - a, q - p)) < EPS; }-----// 74
double ccw(P(a), P(b), P(c)) { return cross(b - a, c - b); }-----// ab
bool collinear(P(a), P(b), P(c)) { return abs(ccw(a, b, c)) < EPS; }-----// 95
bool collinear(L(a, b), L(p, q)) {-----// de
    ---return abs(ccw(a, b, p)) < EPS && abs(ccw(a, b, q)) < EPS; }-----// 27
double angle(P(a), P(b), P(c)) {-----// 93
    ---return acos(dot(b - a, c - b) / abs(b - a) / abs(c - b)); }-----// a2
double signed_angle(P(a), P(b), P(c)) {-----// 46
    ---return asin(cross(b - a, c - b) / abs(b - a) / abs(c - b)); }-----// 80
double angle(P(p)) { return atan2(imag(p), real(p)); }-----// c0
point perp(P(p)) { return point(-imag(p), real(p)); }-----// 3c
double progress(P(p), L(a, b)) {-----// c7
    ---if (abs(real(a) - real(b)) < EPS)-----// 7d
        ---return (imag(p) - imag(a)) / (imag(b) - imag(a));-----// b7
    ---else return (real(p) - real(a)) / (real(b) - real(a)); }-----// 6c
bool intersect(L(a, b), L(p, q), point &res, bool segment = false) {-----// b4
    ---// NOTE: check for parallel/collinear lines before calling this function-----// 88
    ---point r = b - a, s = q - p;-----// 54
    ---double c = cross(r, s), t = cross(p - a, s) / c, u = cross(p - a, r) / c;-----// 29
    ---if (segment && (t < 0-EPS || t > 1+EPS || u < 0-EPS || u > 1+EPS))-----// 30
        ---return false;-----// c0
    ---res = a + t * r;-----// 88
    ---return true;-----// 03
}-----// 92
point closest_point(L(a, b), P(c), bool segment = false) {-----// 06
    ---if (segment) {-----// 90
        ---if (dot(b - a, c - b) > 0) return b;-----// 93
        ---if (dot(a - b, c - a) > 0) return a;-----// bb
        ---}-----// d5
    ---double t = dot(c - a, b - a) / norm(b - a);-----// 61
```

```
    ---return a + t * (b - a);-----// 4f
}-----// 19
double line_segment_distance(L(a,b), L(c,d)) {-----// f6
    ---double x = INFINITY;-----// 8c
    ---if (abs(a - b) < EPS && abs(c - d) < EPS) x = abs(a - c);-----// 5f
    ---else if (abs(a - b) < EPS) x = abs(a - closest_point(c, d, a, true));-----// 97
    ---else if (abs(c - d) < EPS) x = abs(c - closest_point(a, b, c, true));-----// 68
    ---else if ((ccw(a, b, c) < 0) != (ccw(a, b, d) < 0) &&-----// fa
        --- (ccw(c, d, a) < 0) != (ccw(c, d, b) < 0)) x = 0;-----// bb
    ---else {-----// 5b
        ---x = min(x, abs(a - closest_point(c,d, a, true)));-----// 07
        ---x = min(x, abs(b - closest_point(c,d, b, true)));-----// 75
        ---x = min(x, abs(c - closest_point(a,b, c, true)));-----// 48
        ---x = min(x, abs(d - closest_point(a,b, d, true)));-----// 75
    ---}-----// 60
    ---return x;-----// 57
}-----// 8e
int intersect(C(A, rA), C(B, rB), point &res1, point &res2) { -----// ca
    ---double d = abs(B - A);-----// 06
    ---if ((rA + rB) < (d - EPS) || d < abs(rA - rB) - EPS) return 0;-----// 5d
    ---double a = (rA*rA - rB*rB + d*d) / 2 / d, h = sqrt(rA*rA - a*a);-----// 5e
    ---point v = normalize(B - A, a), u = normalize(rotate(B-A), h);-----// da
    ---res1 = A + v + u, res2 = A + v - u;-----// c2
    ---if (abs(u) < EPS) return 1; return 2;-----// 95
}-----// 4e
int intersect(L(A, B), C(0, r), point &res1, point &res2) {-----// e4
    ---double h = abs(0 - closest_point(A, B, 0));-----// f4
    ---if(r < h - EPS) return 0;-----// 89
    ---point H = proj(0 - A, B - A) + A, v = normalize((B - A), sqrt(r*r - h*h));// a9
    ---res1 = H + v; res2 = H - v;-----// ab
    ---if(abs(v) < EPS) return 1; return 2;-----// f7
}-----// b8
int tangent(P(A), C(0, r), point &res1, point &res2) {-----// 15
    ---point v = 0 - A; double d = abs(v);-----// 2c
    ---if (d < r - EPS) return 0;-----// 14
    ---double alpha = asin(r / d), L = sqrt(d*d - r*r);-----// 45
    ---v = normalize(v, L);-----// 10
    ---res1 = A + rotate(v, alpha); res2 = A + rotate(v, -alpha);-----// 56
    ---if (abs(r - d) < EPS || abs(v) < EPS) return 1;-----// 1d
    ---return 2;-----// 97
}-----// 46
void tangent_outer(point A, double rA, point B, double rB, PP(P), PP(Q)) {-----// 61
    ---if (rA - rB > EPS) { swap(rA, rB); swap(A, B); }-----// 2a
    ---double theta = asin((rB - rA)/abs(A - B));-----// 0a
    ---point v = rotate(B - A, theta + pi/2), u = rotate(B - A, -(theta + pi/2));// e3
    ---u = normalize(u, rA);-----// 30
    ---P.first = A + normalize(v, rA); P.second = B + normalize(v, rB);-----// 08
    ---Q.first = A + normalize(u, rA); Q.second = B + normalize(u, rB);-----// 2a
}-----// 2d
```

6.2. Polygon.

```
#include "primitives.cpp"-----// e0
typedef vector<point> polygon;-----// b3
double polygon_area_signed(polygon p) {-----// 31
    ---double area = 0; int cnt = size(p);-----// a2
    ---rep(i,1,cnt-1) area += cross(p[i] - p[0], p[i + 1] - p[0]);-----// 51
    ---return area / 2; }-----// 66
double polygon_area(polygon p) { return abs(polygon_area_signed(p)); }-----// a4
#define CHK(f,a,b,c) (f(a) < f(b) && f(b) <= f(c) && ccw(a,c,b) < 0)-----// 8f
int point_in_polygon(polygon p, point q) {-----// 5d
    ---int n = size(p); bool in = false; double d;-----// 69
    ---for (int i = 0, j = n - 1; i < n; j = i++)-----// f3
    ---if (collinear(p[i], q, p[j]) &&-----// 9d
        ---0 <= (d = progress(q, p[i], p[j])) && d <= 1)-----// 4b
        ---return 0;-----// b3
    ---for (int i = 0, j = n - 1; i < n; j = i++)-----// 67
    ---if (CHK(real, p[i], q, p[j]) || CHK(real, p[j], q, p[i]))-----// b4
        ---in = !in;-----// ff
    ---return in ? -1 : 1; }-----// ba
// pair<polygon, polygon> cut_polygon(const polygon &poly, point a, point b) {--// 0d
//---- polygon left, right;-----// 0a
//---- point it(-100, -100);-----// 5b
//---- for (int i = 0, cnt = poly.size(); i < cnt; i++) {-----// 70
//----- int j = i == cnt-1 ? 0 : i + 1;-----// 02
//----- point p = poly[i], q = poly[j];-----// 44
//----- if (ccw(a, b, p) <= 0) left.push_back(p);-----// 8d
//----- if (ccw(a, b, p) >= 0) right.push_back(p);-----// 43
//----- // myintersect = intersect where-----// ba
//----- // (a,b) is a line, (p,q) is a line segment-----// 7e
//----- if (myintersect(a, b, p, q, it))-----// 6f
//----- left.push_back(it), right.push_back(it);-----// 8a
//---- }-----// e0
//---- return pair<polygon, polygon>(left, right);-----// 3d
// }-----// 07
```

6.3. Convex Hull.

```
#include "polygon.cpp"-----// 58
#define MAXN 1000-----// 09
point hull[MAXN];-----// 43
bool cmp(const point &a, const point &b) {-----// 32
    ---return abs(real(a) - real(b)) > EPS ?-----// 44
        ---real(a) < real(b) : imag(a) < imag(b); }-----// 40
int convex_hull(polygon p) {-----// cd
    ---int n = size(p), l = 0;-----// 67
    ---sort(p.begin(), p.end(), cmp);-----// 3d
    ---rep(i,0,n) {-----// e4
        ---if (i > 0 && p[i] == p[i - 1]) continue;-----// c7
        ---while (l >= 2 && ccw(hull[l - 2], hull[l - 1], p[i]) >= 0) l--;-----// 62
        ---hull[l++] = p[i];-----// bd
    ---}-----// d2
    ---int r = l;-----// 30
    ---for (int i = n - 2; i >= 0; i--) {-----// 59
```

```
        ---if (p[i] == p[i + 1]) continue;-----// af
        ---while (r - l >= 1 && ccw(hull[r - 2], hull[r - 1], p[i]) >= 0) r--;-----// 4d
        ---hull[r++] = p[i];-----// f5
    ---}-----// f6
    ---return l == 1 ? 1 : r - 1;-----// a6
}-----// 6d
```

6.4. Line Segment Intersection.

```
#include "primitives.cpp"-----// e0
bool line_segment_intersect(L(a, b), L(c, d), point &A, point &B) {-----// 6c
    ---if (abs(a - b) < EPS && abs(c - d) < EPS) {-----// db
        ---A = B = a; return abs(a - d) < EPS; }-----// ee
    ---else if (abs(a - b) < EPS) {-----// 03
        ---A = B = a; double p = progress(a, c,d);-----// c9
        ---return 0.0 <= p && p <= 1.0-----// 8a
        ---&& (abs(a - c) + abs(d - a) - abs(d - c)) < EPS; }-----// 27
    ---else if (abs(c - d) < EPS) {-----// 26
        ---A = B = c; double p = progress(c, a,b);-----// d9
        ---return 0.0 <= p && p <= 1.0-----// 8e
        ---&& (abs(c - a) + abs(b - c) - abs(b - a)) < EPS; }-----// 4f
    ---else if (collinear(a,b, c,d)) {-----// bc
        ---double ap = progress(a, c,d), bp = progress(b, c,d);-----// a7
        ---if (ap > bp) swap(ap, bp);-----// b1
        ---if (bp < 0.0 || ap > 1.0) return false;-----// 0c
        ---A = c + max(ap, 0.0) * (d - c);-----// f6
        ---B = c + min(bp, 1.0) * (d - c);-----// 5c
        ---return true; }-----// ab
    ---else if (parallel(a,b, c,d)) return false;-----// ca
    ---else if (intersect(a,b, c,d, A, true)) {-----// 10
        ---B = A; return true; }-----// bf
    ---return false;-----// b7
}-----// 8b
-----// e6
```

6.5. Great-Circle Distance. Computes the distance between two points (given as latitude/longitude coordinates) on a sphere of radius  $r$ .

```
double gc_distance(double pLat, double pLong,-----// 7b
    double qLat, double qLong, double r) {-----// a4
    ---pLat *= pi / 180; pLong *= pi / 180;-----// ee
    ---qLat *= pi / 180; qLong *= pi / 180;-----// 75
    ---return r * acos(cos(pLat) * cos(qLat) * cos(pLong - qLong) +-----// e3
        ---sin(pLat) * sin(qLat));-----// 1e
}-----// 60
-----// 3f
```

6.6. Triangle Circumcenter. Returns the unique point that is the same distance from all three points. It is also the center of the unique circle that goes through all three points.

```
#include "primitives.cpp"-----// e0
point circumcenter(point a, point b, point c) {-----// 76
    ---b -= a, c -= a;-----// 41
    ---return a + perp(b * norm(c) - c * norm(b)) / 2.0 / cross(b, c);-----// 7a
}-----// c3
```



6.7. Closest Pair of Points.

```
#include "primitives.cpp"-----// e0
-----// 85
struct cmpx { bool operator()(const point &a, const point &b) {-----// 01
-----return abs(real(a) - real(b)) > EPS ?-----// e9
-----real(a) < real(b) : imag(a) < imag(b); } };-----// 53
struct cmpy { bool operator()(const point &a, const point &b) {-----// 6f
-----return abs(imag(a) - imag(b)) > EPS ?-----// 0b
-----imag(a) < imag(b) : real(a) < real(b); } };-----// a4
double closest_pair(vector<point> pts) {-----// f1
----sort(pts.begin(), pts.end(), cmpx());-----// 0c
----set<point, cmpy> cur;-----// bd
----set<point, cmpy>::const_iterator it, jt;-----// a6
----double mn = INFINITY;-----// f9
----for (int i = 0, l = 0; i < size(pts); i++) {-----// ac
-----while (real(pts[i]) - real(pts[l]) > mn) cur.erase(pts[l++]);-----// 8b
-----it = cur.lower_bound(point(-INFINITY, imag(pts[i]) - mn));-----// fc
-----jt = cur.upper_bound(point(INFINITY, imag(pts[i]) + mn));-----// 39
-----while (it != jt) mn = min(mn, abs(*it - pts[i])), it++;-----// 09
-----cur.insert(pts[i]); }-----// 82
----return mn; }-----// 4c
```

6.8. 3D Primitives.

```
#define P(p) const point3d &p-----// a7
#define L(p0, p1) P(p0), P(p1)-----// 0f
#define PL(p0, p1, p2) P(p0), P(p1), P(p2)-----// 67
struct point3d {-----// 63
----double x, y, z;-----// e6
----point3d() : x(0), y(0), z(0) {}-----// af
----point3d(double _x, double _y, double _z) : x(_x), y(_y), z(_z) {}-----// fc
----point3d operator+(P(p)) const {-----// 17
----return point3d(x + p.x, y + p.y, z + p.z); }-----// 8e
----point3d operator-(P(p)) const {-----// fb
----return point3d(x - p.x, y - p.y, z - p.z); }-----// 83
----point3d operator-() const {-----// 89
----return point3d(-x, -y, -z); }-----// d4
----point3d operator*(double k) const {-----// 4d
----return point3d(x * k, y * k, z * k); }-----// fd
----point3d operator/(double k) const {-----// 95
----return point3d(x / k, y / k, z / k); }-----// 58
----double operator%(P(p)) const {-----// d1
----return x * p.x + y * p.y + z * p.z; }-----// 09
----point3d operator*(P(p)) const {-----// 4f
----return point3d(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x); }-----// ed
----double length() const {-----// 3e
----return sqrt(*this % *this); }-----// 05
----double distTo(P(p)) const {-----// dd
----return (*this - p).length(); }-----// 57
----double distTo(P(A), P(B)) const {-----// bd
----// A and B must be two different points-----// 4e
----return ((*this - A) * (*this - B)).length() / A.distTo(B); }-----// 6e
```

```
----point3d normalize(double k = 1) const {-----// db
----// length() must not return 0-----// 3c
----return (*this) * (k / length()); }-----// d4
----point3d getProjection(P(A), P(B)) const {-----// 86
----point3d v = B - A;-----// 64
----return A + v.normalize((v % (*this - A)) / v.length()); }-----// 53
----point3d rotate(P(normal)) const {-----// 55
----// normal must have length 1 and be orthogonal to the vector-----// eb
----return (*this) * normal; }-----// 5c
----point3d rotate(double alpha, P(normal)) const {-----// 21
----return (*this) * cos(alpha) + rotate(normal) * sin(alpha); }-----// 82
----point3d rotatePoint(P(0), P(axe), double alpha) const {-----// 7a
----point3d Z = axe.normalize(axe % (*this - 0));-----// ba
----return 0 + Z + (*this - 0 - Z).rotate(alpha, 0); }-----// 38
----bool isZero() const {-----// 64
----return abs(x) < EPS && abs(y) < EPS && abs(z) < EPS; }-----// 15
----bool isOnLine(L(A, B)) const {-----// 30
----return ((A - *this) * (B - *this)).isZero(); }-----// 58
----bool isInSegment(L(A, B)) const {-----// f1
----return isOnLine(A, B) && ((A - *this) % (B - *this)) < EPS; }-----// d9
----bool isInSegmentStrictly(L(A, B)) const {-----// 0e
----return isOnLine(A, B) && ((A - *this) % (B - *this)) < -EPS; }-----// ba
----double getAngle() const {-----// 0f
----return atan2(y, x); }-----// 40
----double getAngle(P(u)) const {-----// d5
----return atan2((*this * u).length(), *this % u); }-----// 79
----bool isOnPlane(PL(A, B, C)) const {-----// 8e
----return abs((A - *this) * (B - *this) % (C - *this)) < EPS; } };-----// 74
int line_line_intersect(L(A, B), L(C, D), point3d &O){-----// dc
----if (abs((B - A) * (C - A) % (D - A)) > EPS) return 0;-----// 6a
----if (((A - B) * (C - D)).length() < EPS)-----// 79
----return A.isOnLine(C, D) ? 2 : 0;-----// 09
----point3d normal = ((A - B) * (C - B)).normalize();-----// bc
----double s1 = (C - A) * (D - A) % normal;-----// 68
----0 = A + ((B - A) / (s1 + ((D - B) * (C - B) % normal))) * s1;-----// 56
----return 1; }-----// a7
int line_plane_intersect(L(A, B), PL(C, D, E), point3d &O) {-----// 09
----double V1 = (C - A) * (D - A) % (E - A);-----// c1
----double V2 = (D - B) * (C - B) % (E - B);-----// 29
----if (abs(V1 + V2) < EPS)-----// 81
----return A.isOnPlane(C, D, E) ? 2 : 0;-----// d5
----0 = A + ((B - A) / (V1 + V2)) * V1;-----// 38
----return 1; }-----// ce
bool plane_plane_intersect(P(A), P(nA), P(B), P(nB), point3d &P, point3d &Q) {-----// 5a
----point3d n = nA * nB;-----// 49
----if (n.isZero()) return false;-----// 03
----point3d v = n * nA;-----// d7
----P = A + (n * nA) * ((B - A) % nB / (v % nB));-----// 1a
----Q = P + n;-----// 9c
----return true; }-----// 1a
```

6.9. Polygon Centroid.



```

#include "polygon.cpp"-----// 58
point polygon_centroid(polygon p) {-----// 79
----double cx = 0.0, cy = 0.0;-----// d5
----double mnx = 0.0, mny = 0.0;-----// 22
----int n = size(p);-----// 2d
----rep(i,0,n)-----// 08
-----mnx = min(mnx, real(p[i])),-----// c6
-----mny = min(mny, imag(p[i]));-----// 84
----rep(i,0,n)-----// 3f
-----p[i] = point(real(p[i]) - mnx, imag(p[i]) - mny);-----// 49
----rep(i,0,n) {-----// 3c
-----int j = (i + 1) % n;-----// 5b
-----cx += (real(p[i]) + real(p[j])) * cross(p[i], p[j]);-----// 4f
-----cy += (imag(p[i]) + imag(p[j])) * cross(p[i], p[j]); }-----// 4a
----return point(cx, cy) / 6.0 / polygon_area_signed(p) + point(mnx, mny); }-----// a1

```

6.10. **Formulas.** Let  $a = (a_x, a_y)$  and  $b = (b_x, b_y)$  be two-dimensional vectors.

- $a \cdot b = |a||b| \cos \theta$ , where  $\theta$  is the angle between  $a$  and  $b$ .
- $a \times b = |a||b| \sin \theta$ , where  $\theta$  is the signed angle between  $a$  and  $b$ .
- $a \times b$  is equal to the area of the parallelogram with two of its sides formed by  $a$  and  $b$ . Half of that is the area of the triangle formed by  $a$  and  $b$ .

## 7. OTHER ALGORITHMS

### 7.1. 2SAT.

```

#include "../graph/scc.cpp"-----// c3
-----// 63
bool two_sat(int n, const vi& clauses, vi& all_truthy) {-----// f4
----all_truthy.clear();-----// 31
----vvi adj(2*n+1);-----// 7b
----rep(i,0,size(courses)) {-----// 76
-----adj[-clauses[i].first + n].push_back(courses[i].second + n);-----// eb
-----if (clauses[i].first != courses[i].second)-----// bc
-----adj[-clauses[i].second + n].push_back(courses[i].first + n);-----// f0
----}-----// da
----pair<union_find, vi> res = scc(adj);-----// 00
----union_find scc = res.first;-----// 20
----vi dag = res.second;-----// ed
----vi truth(2*n+1, -1);-----// c7
----for (int i = 2*n; i >= 0; i--) {-----// 50
-----int cur = order[i] - n, p = scc.find(cur + n), o = scc.find(-cur + n);-----// 4f
-----if (cur == 0) continue;-----// cd
-----if (p == o) return false;-----// d0
-----if (truth[p] == -1) truth[p] = 1;-----// d3
-----truth[cur + n] = truth[p];-----// 50
-----truth[o] = 1 - truth[p];-----// 8c
-----if (truth[p] == 1) all_truthy.push_back(cur);-----// 55
----}-----// c3
----return true;-----// eb
}-----// 6b

```

### 7.2. Stable Marriage.

```

vi stable_marriage(int n, int** m, int** w) {-----// e4
----queue<int> q;-----// f6
----vi at(n, 0), eng(n, -1), res(n, -1); vvi inv(n, vi(n));-----// c3
----rep(i,0,n) rep(j,0,n) inv[i][w[i][j]] = j;-----// f1
----rep(i,0,n) q.push(i);-----// d8
----while (!q.empty()) {-----// 68
-----int curm = q.front(); q.pop();-----// e2
-----for (int &i = at[curm]; i < n; i++) {-----// 7e
-----int curw = m[curm][i];-----// 95
-----if (eng[curw] == -1) { }-----// f7
-----else if (inv[curw][curm] < inv[curw][eng[curw]])-----// d6
-----q.push(eng[curw]);-----// 2e
-----else continue;-----// 1d
-----res[eng[curw] = curm] = curw, ++i; break;-----// a1
-----}-----// c4
----}-----// 3d
----return res;-----// 42
}-----// bf

```

### 7.3. Algorithm X.

```

bool handle_solution(vi rows) { return false; }-----// 63
struct exact_cover {-----// 95
----struct node {-----// 7e
-----node *l, *r, *u, *d, *p;-----// 19
-----int row, col, size;-----// ae
-----node(int _row, int _col) : row(_row), col(_col) {-----// c9
-----size = 0; l = r = u = d = p = NULL; }-----// c3
----};-----// c1
----int rows, cols, *sol;-----// 7b
----bool **arr;-----// e6
----node *head;-----// fe
----exact_cover(int _rows, int _cols) : rows(_rows), cols(_cols), head(NULL) {-----// b6
-----arr = new bool*[rows];-----// cf
-----sol = new int[rows];-----// 5f
-----rep(i,0,rows)-----// 9b
-----arr[i] = new bool[cols], memset(arr[i], 0, cols);-----// dd
----}-----// 21
----void set_value(int row, int col, bool val = true) { arr[row][col] = val; }-----// 9e
----void setup() {-----// a3
-----node ***ptr = new node**[rows + 1];-----// bd
-----rep(i,0,rows+1) {-----// 76
-----ptr[i] = new node*[cols];-----// eb
-----rep(j,0,cols)-----// cd
-----if (i == rows || arr[i][j]) ptr[i][j] = new node(i, j);-----// 16
-----else ptr[i][j] = NULL;-----// d2
-----}-----// ac
-----rep(i,0,rows+1) {-----// 55
-----rep(j,0,cols) {-----// 51
-----if (!ptr[i][j]) continue;-----// f7
-----int ni = i + 1, nj = j + 1;-----// 7a

```

```
-----while (true) {-----// fc
-----if (ni == rows + 1) ni = 0;-----// 4c
-----if (ni == rows || arr[ni][j]) break;-----// 8d
-----++ni;-----// 68
-----}-----// ad
-----ptr[i][j]->d = ptr[ni][j];-----// 84
-----ptr[ni][j]->u = ptr[i][j];-----// 66
-----while (true) {-----// 7f
-----if (nj == cols) nj = 0;-----// de
-----if (i == rows || arr[i][nj]) break;-----// 4c
-----++nj;-----// c5
-----}-----// 72
-----ptr[i][j]->r = ptr[i][nj];-----// 60
-----ptr[i][nj]->l = ptr[i][j];-----// 82
-----}-----// 0b
-----}-----// 16
-----head = new node(rows, -1);-----// 66
-----head->r = ptr[rows][0];-----// 3e
-----ptr[rows][0]->l = head;-----// 8c
-----head->l = ptr[rows][cols - 1];-----// 6a
-----ptr[rows][cols - 1]->r = head;-----// c1
-----rep(j,0,cols) {-----// 92
-----int cnt = -1;-----// d4
-----rep(i,0,rows+1)-----// bd
-----if (ptr[i][j]) cnt++, ptr[i][j]->p = ptr[rows][j];-----// f3
-----ptr[rows][j]->size = cnt;-----// c2
-----}-----// b9
-----rep(i,0,rows+1) delete[] ptr[i];-----// a5
-----delete[] ptr;-----// 72
-----}-----// 19
-----#define COVER(c, i, j) {-----// 91
-----c->r->l = c->l, c->l->r = c->r;-----// 82
-----for (node *i = c->d; i != c; i = i->d)-----// 62
-----for (node *j = i->r; j != i; j = j->r)-----// 26
-----j->d->u = j->u, j->u->d = j->d, j->p->size--;-----// c1
-----}-----// 89
-----#define UNCOVER(c, i, j) {-----// f0
-----for (node *i = c->u; i != c; i = i->u)-----// 7b
-----for (node *j = i->l; j != i; j = j->l)-----// 7b
-----j->p->size++, j->d->u = j->u->d = j;-----// 65
-----c->r->l = c->l->r = c;-----// 0e
-----}-----// f9
-----bool search(int k = 0) {-----// 75
-----if (head == head->r) {-----// 90
-----vi res(k);-----// 2a
-----rep(i,0,k) res[i] = sol[i];-----// 63
-----sort(res.begin(), res.end());-----// 11
-----return handle_solution(res);-----// 3d
-----}-----// a3
-----node *c = head->r, *tmp = head->r;-----// 41
-----for ( ; tmp != head; tmp = tmp->r) if (tmp->size < c->size) c = tmp;-----// 02
-----if (c == c->d) return false;-----// fc
-----COVER(c, i, j);-----// f6
-----bool found = false;-----// 8d
-----for (node *r = c->d; !found && r != c; r = r->d) {-----// 78
-----sol[k] = r->row;-----// c0
-----for (node *j = r->r; j != r; j = j->r) { COVER(j->p, a, b); }-----// f9
-----found = search(k + 1);-----// fb
-----for (node *j = r->l; j != r; j = j->l) { UNCOVER(j->p, a, b); }-----// 87
-----}-----// 7c
-----UNCOVER(c, i, j);-----// a7
-----return found;-----// c0
-----}-----// d2
};-----// d7

7.4. nth Permutation.
vector<int> nth_permutation(int cnt, int n) {-----// 78
vector<int> idx(cnt), per(cnt), fac(cnt);-----// 9e
rep(i,0,cnt) idx[i] = i;-----// bc
rep(i,1,cnt+1) fac[i - 1] = n % i, n /= i;-----// 2b
for (int i = cnt - 1; i >= 0; i--)-----// f9
per[cnt - i - 1] = idx[fac[i]], idx.erase(idx.begin() + fac[i]);-----// ee
return per;-----// ab
}-----// 37

7.5. Cycle-Finding.
ii find_cycle(int x0, int (*f)(int)) {-----// a5
int t = f(x0), h = f(t), mu = 0, lam = 1;-----// 8d
while (t != h) t = f(t), h = f(f(h));-----// 79
h = x0;-----// 04
while (t != h) t = f(t), h = f(h), mu++;-----// 9d
h = f(t);-----// 00
while (t != h) h = f(h), lam++;-----// 5e
return ii(mu, lam);-----// b4
}-----// 42

7.6. Dates.
int intToDay(int jd) { return jd % 7; }-----// 89
int dateToInt(int y, int m, int d) {-----// 96
return 1461 * (y + 4800 + (m - 14) / 12) / 4 +-----// a8
367 * (m - 2 - (m - 14) / 12 * 12) / 12-----// d1
3 * ((y + 4900 + (m - 14) / 12) / 100) / 4 +-----// be
d - 32075;-----// e0
}-----// fa
void intToDate(int jd, int &y, int &m, int &d) {-----// a1
int x, n, i, j;-----// 00
x = jd + 68569;-----// 11
n = 4 * x / 146097;-----// 2f
x -= (146097 * n + 3) / 4;-----// 58
i = (4000 * (x + 1)) / 1461001;-----// 0d
x -= 1461 * i / 4 - 31;-----// 09
j = 80 * x / 2447;-----// 3d
d = x - 2447 * j / 80;-----// eb
x = j / 11;-----// b7
```

```
----m = j + 2 - 12 * x;-----// 82
---y = 100 * (n - 49) + i + x;-----// 70
}-----// af
```

8. USEFUL INFORMATION

8.1. Tips & Tricks.

- How fast does our algorithm have to be? Can we use brute-force?
- Does order matter?
- Is it better to look at the problem in another way? Maybe backwards?
- Are there subproblems that are recomputed? Can we cache them?
- Do we need to remember everything we compute, or just the last few iterations of computation?
- Does it help to sort the data?
- Can we speed up lookup by using a map (tree or hash) or an array?
- Can we binary search the answer?
- Can we add vertices/edges to the graph to make the problem easier? Can we turn the graph into some other kind of a graph (perhaps a DAG, or a flow network)?
- Make sure integers are not overflowing.
- Is it better to compute the answer modulo  $n$ ? Perhaps we can compute the answer modulo  $m_1, m_2, \dots, m_k$ , where  $m_1, m_2, \dots, m_k$  are pairwise coprime integers, and find the real answer using CRT?
- Are there any edge cases? When  $n = 0, n = -1, n = 1, n = 2^{31} - 1$  or  $n = -2^{31}$ ? When the list is empty, or contains a single element? When the graph is empty, or contains a single vertex? When the graph contains self-loops? When the polygon is concave or non-simple?
- Can we use exponentiation by squaring?

8.2. Fast Input Reading.

```
void readn(register int *n) {-----// dc
---int sign = 1;-----// 32
---register char c;-----// a5
---*n = 0;-----// 35
---while((c = getc_unlocked(stdin)) != '\n') {-----// f3
---switch(c) {-----// 0c
---case '-': sign = -1; break;-----// 28
---case ' ': goto hell;-----// fd
---case '\n': goto hell;-----// 79
---default: *n *= 10; *n += c - '0'; break;-----// c0
---}-----// 2d
---}-----// c3
hell:-----// ba
---*n *= sign;-----// a0
}-----// 67
```

8.3. Bit Hacks.

- $n \& -n$  returns the first set bit in  $n$ .
- $n \& (n - 1)$  is 0 only if  $n$  is a power of two.
- `snoob(x)` returns the next integer that has the same amount of bits set as  $x$ . Useful for iterating through subsets of some specified size.

```
int snoob(int x) {-----// 73
---int y = x & -x, z = x + y;-----// 12
---return z | ((x ^ z) >> 2) / y;-----// 97
}-----// 14
```