

viRUs

Team Reference Document

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1. CODE TEMPLATES

1.1. Basic Configuration. Vim and (Caps Lock = Escape) configuration.

```
o.yqtxmal ekrpat # setxkbmap dvorak for dvorak on qwerty
setxkbmap -option caps:escape
set -o vi
xset r rate 150 100
cat > ~/.vimrc
set nosp et sw=4 ts=4 sts=4 si cindent hi=1000 nu ru noeb showcmd showmode
syn on | colorscheme slate
```

1.2. C++ Header. A C++ header.

```
#include <bits/stdc++.h>-----// 84
using namespace std;-----// 16
template <class T> int size(const T &x) { return x.size(); }-----// 5f
#define rep(i,a,b) for (__typeof(a) i=(a); i<(b); ++i)-----// 6c
#define iter(it,c) for (__typeof((c).begin()) it = (c).begin(); it != (c).end(); ++it)
typedef pair<int, int> ii;-----// 44
typedef vector<int> vi;-----// 9d
typedef vector<ii> vii;-----// eb
typedef long long ll;-----// 47
const int INF = 2147483647;-----// db
-----// d8
const double EPS = 1e-9;-----// 18
const double pi = acos(-1);-----// ec
typedef unsigned long long ull;-----// 30
typedef vector<vi> vvi;-----// 92
typedef vector<vii> vvii;-----// fc
template <class T> T mod(T a, T b) { return (a % b + b) % b; }-----// 3f
```

1.3. Java Template. A Java template.

```
import java.util.*;-----// 37
import java.math.*;-----// 89
import java.io.*;-----// 28
-----// a3
public class Main {-----// 17
---public static void main(String[] args) throws Exception {-----// 02
-----Scanner in = new Scanner(System.in);-----// ef
-----PrintWriter out = new PrintWriter(System.out, false);-----// 62
-----// code-----// e6
-----out.flush();-----// 56
---}-----// 79
}-----// 00
```

2. DATA STRUCTURES

2.1. Union-Find.

```
struct union_find {-----// 42
---vi p; union_find(int n) : p(n, -1) { }-----// 28
---int find(int x) { return p[x] < 0 ? x : p[x] = find(p[x]); }-----// ba
---bool unite(int x, int y) {-----// 6c
-----int xp = find(x), yp = find(y);-----// 64
-----if (xp == yp) return false;-----// 0b
```

```
-----if (p[xp] < p[yp]) p[xp] += p[yp], p[yp] = xp;-----// 3a
-----else p[yp] += p[xp], p[xp] = yp;-----// 3e
-----return true; }-----// 0b
----int size(int x) { return -p[find(x)]; } };-----// 28
```

2.2. Segment Tree.

```
#ifdef SEG_MIN-----// 03
const int ID = INF;-----// 56
int f(int a, int b) { return min(a, b); }-----// 4f
#else-----// 0e
const int ID = 0;-----// 3e
int f(int a, int b) { return a + b; }-----// dd
#endif-----// 16
struct segment_tree {-----// ab
---int n; vi data, lazy;-----// dd
---segment_tree() {}-----// 93
---segment_tree(const vi &arr) : n(size(arr)), data(4*n), lazy(4*n,INF) {-----// f1
---mk(arr, 0, n-1, 0); }-----// e9
---int mk(const vi &arr, int l, int r, int i) {-----// 12
---if (l == r) return data[i] = arr[l];-----// 5b
---int m = (l + r) / 2;-----// de
---return data[i] = f(mk(arr, l, m, 2*i+1), mk(arr, m+1, r, 2*i+2)); }-----// 0a
---int query(int a, int b) { return q(a, b, 0, n-1, 0); }-----// f6
---int q(int a, int b, int l, int r, int i) {-----// 22
---propagate(l, r, i);-----// 12
---if (r < a || b < l) return ID;-----// c7
---if (a <= l && r <= b) return data[i];-----// ce
---int m = (l + r) / 2;-----// 7a
---return f(q(a, b, l, m, 2*i+1), q(a, b, m+1, r, 2*i+2)); }-----// 5c
---void update(int i, int v) { u(i, v, 0, n-1, 0); }-----// 90
---int u(int i, int v, int l, int r, int j) {-----// 02
---propagate(l, r, j);-----// ae
---if (r < i || i < l) return data[j];-----// 92
---if (l == i && r == i) return data[j] = v;-----// 4a
---int m = (l + r) / 2;-----// cb
---return data[j] = f(u(i, v, l, m, 2*j+1), u(i, v, m+1, r, 2*j+2)); }-----// 34
---void range_update(int a, int b, int v) { ru(a, b, v, 0, n-1, 0); }-----// 71
---int ru(int a, int b, int v, int l, int r, int i) {-----// e0
---propagate(l, r, i);-----// 19
---if (l > r) return ID;-----// cc
---if (r < a || b < l) return data[i];-----// d9
---if (l == r) return data[i] += v;-----// 5f
---if (a <= l && r <= b) return (lazy[i] = v) * (r - l + 1) + data[i];-----// 76
---int m = (l + r) / 2;-----// e7
---return data[i] = f(ru(a, b, v, l, m, 2*i+1),-----// 0e
---ru(a, b, v, m+1, r, 2*i+2)); }-----// f2
---}-----// 47
---void propagate(int l, int r, int i) {-----// b5
---if (l > r || lazy[i] == INF) return;-----// 83
---data[i] += lazy[i] * (r - l + 1);-----// 99
---if (l < r) {-----// dd
```

```

-----if (lazy[2*i+1] == INF) lazy[2*i+1] = lazy[i];-----// ee
-----else lazy[2*i+1] += lazy[i];-----// 72
-----if (lazy[2*i+2] == INF) lazy[2*i+2] = lazy[i];-----// dd
-----else lazy[2*i+2] += lazy[i];-----// a4
-----}-----// e9
-----lazy[i] = INF;-----// c4
-----}-----// 2c
};-----// 17

```

2.3. Fenwick Tree.

```

struct fenwick_tree {-----// 98
--int n; vi data;-----// d3
---fenwick_tree(int _n) : n(_n), data(vi(n)) { }-----// db
---void update(int at, int by) {-----// 76
-----while (at < n) data[at] += by, at |= at + 1; }-----// fb
--int query(int at) {-----// 71
-----int res = 0;-----// c3
-----while (at >= 0) res += data[at], at = (at & (at + 1)) - 1;-----// 37
-----return res; }-----// e4
---int rsq(int a, int b) { return query(b) - query(a - 1); }-----// be
};-----// 57
struct fenwick_tree_sq {-----// d4
--int n; fenwick_tree x1, x0;-----// 18
---fenwick_tree_sq(int _n) : n(_n), x1(fenwick_tree(n)),-----// 2e
-----x0(fenwick_tree(n)) { }-----// 7c
---// insert f(y) = my + c if x <= y-----// 17
---void update(int x, int m, int c) { x1.update(x, m); x0.update(x, c); }-----// 45
---int query(int x) { return x*x1.query(x) + x0.query(x); }-----// 73
};-----// 13
void range_update(fenwick_tree_sq &s, int a, int b, int k) {-----// 89
---s.update(a, k, k * (1 - a)); s.update(b+1, -k, k * b); }-----// 7f
int range_query(fenwick_tree_sq &s, int a, int b) {-----// 15
---return s.query(b) - s.query(a-1); }-----// f3

```

2.4. Matrix.

```

template <class K> bool eq(K a, K b) { return a == b; }-----// 2a
template <> bool eq<double>(double a, double b) { return abs(a - b) < EPS; }-----// a7
template <class T>-----// 53
class matrix {-----// 85
public:-----// be
---int rows, cols;-----// d3
---matrix(int r, int c) : rows(r), cols(c), cnt(r * c) {-----// 34
-----data.assign(cnt, T(0)); }-----// d0
---matrix(const matrix& other) : rows(other.rows), cols(other.cols),-----// fe
-----cnt(other.cnt), data(other.data) { }-----// ed
---T& operator()(int i, int j) { return at(i, j); }-----// e0
---void operator +=(const matrix& other) {-----// c9
-----rep(i,0,cnt) data[i] += other.data[i]; }-----// 2e
---void operator -=(const matrix& other) {-----// f2
-----rep(i,0,cnt) data[i] -= other.data[i]; }-----// 52
---void operator *=(T other) {-----// 14
-----rep(i,0,cnt) data[i] *= other; }-----// dd

```

```

---matrix<T> operator +(const matrix& other) {-----// cb
---matrix<T> res(*this); res += other; return res; }-----// d5
---matrix<T> operator -(const matrix& other) {-----// a0
---matrix<T> res(*this); res -= other; return res; }-----// f5
---matrix<T> operator *(T other) {-----// 60
---matrix<T> res(*this); res *= other; return res; }-----// 73
---matrix<T> operator *(const matrix& other) {-----// 0a
---matrix<T> res(rows, other.cols);-----// d7
---rep(i,0,rows) rep(j,0,other.cols) rep(k,0,cols)-----// 4b
-----res(i, j) += at(i, k) * other.data[k * other.cols + j];-----// 08
---return res; }-----// 58
---matrix<T> transpose() {-----// 3a
---matrix<T> res(cols, rows);-----// fe
---rep(i,0,rows) rep(j,0,cols) res(j, i) = at(i, j);-----// 2b
---return res; }-----// 23
---matrix<T> pow(int p) {-----// da
---matrix<T> res(rows, cols), sq(*this);-----// e6
---rep(i,0,rows) res(i, i) = T(1);-----// 09
---while (p) {-----// ea
---if (p & 1) res = res * sq;-----// 66
---p >>= 1;-----// 17
---if (p) sq = sq * sq;-----// 85
---} return res; }-----// 18
---matrix<T> rref(T &det) {-----// bd
---matrix<T> mat(*this); det = T(1);-----// 6b
---for (int r = 0, c = 0; c < cols; c++) {-----// 33
---int k = r;-----// 42
---while (k < rows && eq<T>(mat(k, c), T(0))) k++;-----// 59
---if (k >= rows) continue;-----// aa
---if (k != r) {-----// fd
---det *= T(-1);-----// 06
---rep(i,0,cols)-----// 2f
---swap(mat.at(k, i), mat.at(r, i));-----// 01
---} det *= mat(r, r);-----// 35
---T d = mat(r,c);-----// 31
---rep(i,0,cols) mat(r, i) /= d;-----// 9e
---rep(i,0,rows) {-----// d3
---T m = mat(i, c);-----// 0f
---if (i != r && !eq<T>(m, T(0)))-----// ba
---rep(j,0,cols) mat(i, j) -= m * mat(r, j);-----// 30
---} r++;-----// 48
---} return mat; }-----// f6
private:-----// a6
---int cnt;-----// 99
---vector<T> data;-----// 7a
---inline T& at(int i, int j) { return data[i * cols + j]; }-----// b6
};-----// b3

```

2.5. AVL Tree.

```

#define AVL_MULTISSET 0-----// b5
-----// 61

```

```

template <class T>-----// 22
class avl_tree {-----// ff
public:-----// f6
    struct node {-----// 45
        T item; node *p, *l, *r;-----// a6
        int size, height;-----// 33
        node(const T &item, node *p = NULL) : item(_item), p(_p),-----// 4f
            l(NULL), r(NULL), size(1), height(0) { } };-----// 0d
    avl_tree() : root(NULL) { }-----// 5d
    node *root;-----// 91
    node* find(const T &item) const {-----// 65
        node *cur = root;-----// b4
        while (cur) {-----// 8b
            if (cur->item < item) cur = cur->r;-----// 71
            else if (item < cur->item) cur = cur->l;-----// cd
            else break; }-----// 4f
        return cur; }-----// 84
    node* insert(const T &item) {-----// 4e
        node *prev = NULL, **cur = &root;-----// 60
        while (*cur) {-----// aa
            prev = *cur;-----// f0
            if ((*cur)->item < item) cur = &((*cur)->r);-----// 1b
        }-----// 0a
        if AVL_MULTISSET-----// eb
            else cur = &((*cur)->l);-----// ff
        else-----// ff
            else if (item < (*cur)->item) cur = &((*cur)->l);-----// 54
            else return *cur;-----// 54
        #endif-----// af
    }-----// ec
    node *n = new node(item, prev);-----// eb
    *cur = n, fix(n); return n; }-----// 29
    void erase(const T &item) { erase(find(item)); }-----// 67
    void erase(node *n, bool free = true) {-----// 58
        if (!n) return;-----// 96
        if (!n->l && n->r) parent_leg(n) = n->r, n->r->p = n->p;-----// 12
        else if (n->l && !n->r) parent_leg(n) = n->l, n->l->p = n->p;-----// 6b
        else if (n->l && n->r) {-----// 6c
            node *s = successor(n);-----// e5
            erase(s, false);-----// 0a
            s->p = n->p, s->l = n->l, s->r = n->r;-----// 5a
            if (n->l) n->l->p = s;-----// 0b
            if (n->r) n->r->p = s;-----// ed
            parent_leg(n) = s, fix(s);-----// 82
            return;-----// e5
        } else parent_leg(n) = NULL;-----// de
        fix(n->p), n->p = n->l = n->r = NULL;-----// 43
        if (free) delete n; }-----// 23
    node* successor(node *n) const {-----// 23
        if (!n) return NULL;-----// 37
        if (n->r) return nth(0, n->r);-----// 23
        node *p = n->p;-----// a7
        while (p && p->r == n) n = p, p = p->p;-----// 9e
        return p; }-----// c7
    node* predecessor(node *n) const {-----// b4
        if (!n) return NULL;-----// dd
        if (n->l) return nth(n->l->size-1, n->l);-----// 10
        node *p = n->p;-----// ea
        while (p && p->l == n) n = p, p = p->p;-----// 6d
        return p; }-----// e7
    inline int size() const { return sz(root); }-----// ef
    void clear() { delete_tree(root), root = NULL; }-----// 84
    node* nth(int n, node *cur = NULL) const {-----// e4
        if (!cur) cur = root;-----// e5
        while (cur) {-----// 29
            if (n < sz(cur->l)) cur = cur->l;-----// 75
            else if (n > sz(cur->l)) n -= sz(cur->l) + 1, cur = cur->r;-----// cd
            else break; }-----// c0
        return cur; }-----// ed
    int count_less(node *cur) {-----// ec
        int sum = sz(cur->l);-----// bf
        while (cur) {-----// 6f
            if (cur->p && cur->p->r == cur) sum += 1 + sz(cur->p->l);-----// 5c
            cur = cur->p;-----// eb
        } return sum; }-----// a0
private:-----// d5
    inline int sz(node *n) const { return n ? n->size : 0; }-----// 3f
    inline int height(node *n) const { return n ? n->height : -1; }-----// a6
    inline bool left_heavy(node *n) const {-----// a0
        return n && height(n->l) > height(n->r); }-----// a8
    inline bool right_heavy(node *n) const {-----// 27
        return n && height(n->r) > height(n->l); }-----// c8
    inline bool too_heavy(node *n) const {-----// 0b
        return n && abs(height(n->l) - height(n->r)) > 1; }-----// f8
    void delete_tree(node *n) {-----// fd
        if (n) { delete_tree(n->l), delete_tree(n->r); delete n; } }-----// ef
    node*& parent_leg(node *n) {-----// 6a
        if (!n->p) return root;-----// ac
        if (n->p->l == n) return n->p->l;-----// 83
        if (n->p->r == n) return n->p->r;-----// cc
        assert(false); }-----// 20
    void augment(node *n) {-----// 72
        if (!n) return;-----// 0e
        n->size = 1 + sz(n->l) + sz(n->r);-----// 93
        n->height = 1 + max(height(n->l), height(n->r)); }-----// 41
    #define rotate(l, r) \
        node *l = n->l; \
        l->p = n->p; \
        parent_leg(n) = l; \
        n->l = l->r; \
        if (l->r) l->r->p = n; \
        l->r = n, n->p = l;

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-----augment(n), augment(l)-----// 81

---void left_rotate(node *n) { rotate(r, l); }-----// 45

---void right_rotate(node *n) { rotate(l, r); }-----// ca

---void fix(node *n) {-----// 0d

-----while (n) { augment(n);-----// 69

-----if (too_heavy(n)) {-----// 4c

-----if (left_heavy(n) && right_heavy(n->l)) left_rotate(n->l);-----// a9

-----else if (right_heavy(n) && left_heavy(n->r))-----// b9

-----right_rotate(n->r);-----// 08

-----if (left_heavy(n)) right_rotate(n);-----// 93

-----else left_rotate(n);-----// d5

-----n = n->p; }-----// 28

-----n = n->p; } }-----// a2

-----rep(i,0,len) newq[i] = q[i], newloc[i] = loc[i];-----// d7

-----memset(newloc + len, 255, (newlen - len) << 2);-----// 3e

-----delete[] q, delete[] loc;-----// 76

-----loc = newloc, q = newq, len = newlen;-----// 9e

#else-----// 8e

-----assert(false);-----// 23

#endif-----// 2a

-----}-----// 37

-----assert(loc[n] == -1);-----// 4e

-----loc[n] = count, q[count++] = n;-----// cf

-----if (fix) swim(count-1); }-----// b9

---void pop(bool fix = true) {-----// 4f

-----assert(count > 0);-----// 4d

-----loc[q[0]] = -1, q[0] = q[--count], loc[q[0]] = 0;-----// 66

-----if (fix) sink(0);-----// bb

-----}-----// bc

---int top() { assert(count > 0); return q[0]; }-----// 1f

---void heapify() { for (int i = count - 1; i > 0; i--)-----// d5

-----if (cmp(i, (i - 1) / 2)) swp(i, (i - 1) / 2); }-----// 43

---void update_key(int n) {-----// 62

-----assert(loc[n] != -1), swim(loc[n]), sink(loc[n]); }-----// ca

---bool empty() { return count == 0; }-----// 7e

---int size() { return count; }-----// 5f

---void clear() { count = 0, memset(loc, 255, len << 2); } }-----// de

2.6. Heap.

#define RESIZE-----// d0

#define SWP(x,y) tmp = x, x = y, y = tmp-----// fb

struct default_int_cmp {-----// 8d

---default_int_cmp() { }-----// 35

---bool operator()(const int &a, const int &b) { return a < b; } }-----// e9

template <class Compare = default_int_cmp>-----// 30

class heap {-----// 05

private:-----// 39

---int len, count, *q, *loc, tmp;-----// 0a

---Compare _cmp;-----// 98

---inline bool cmp(int i, int j) { return _cmp(q[i], q[j]); }-----// a0

---inline void swp(int i, int j) {-----// 1c

-----SWP(q[i], q[j]), SWP(loc[q[i]], loc[q[j]]); }-----// 67

---void swim(int i) {-----// 33

-----while (i > 0) {-----// 1a

-----int p = (i - 1) / 2;-----// 77

-----if (!cmp(i, p)) break;-----// a9

-----swp(i, p), i = p; } }-----// 93

---void sink(int i) {-----// ce

-----while (true) {-----// 3c

-----int l = 2*i + 1, r = l + 1;-----// b4

-----if (l >= count) break;-----// d5

-----int m = r >= count || cmp(l, r) ? l : r;-----// cc

-----if (!cmp(m, i)) break;-----// 42

-----swp(m, i), i = m; } }-----// 1d

public:-----// cd

---heap(int init_len = 128) : count(0), len(init_len), _cmp(Compare()) {-----// 17

-----q = new int[len], loc = new int[len];-----// f8

-----memset(loc, 255, len << 2); }-----// f7

---heap() { delete[] q; delete[] loc; }-----// 09

---void push(int n, bool fix = true) {-----// b7

-----if (len == count || n >= len) {-----// 0f

#ifdef RESIZE-----// a9

-----int newlen = 2 * len;-----// 22

-----while (n >= newlen) newlen *= 2;-----// 2f

-----int *newq = new int[newlen], *newloc = new int[newlen];-----// e3

2.7. Dancing Links.

template <class T>-----// 82

struct dancing_links {-----// 9e

---struct node {-----// 62

-----T item;-----// dd

-----node *l, *r;-----// 32

-----node(const T &item, node *_l = NULL, node *_r = NULL)-----// 6d

-----: item(_item), l(_l), r(_r) {-----// 6d

-----if (l) l->r = this;-----// 97

-----if (r) r->l = this;-----// 81

-----}-----// 2d

};-----// d3

---node *front, *back;-----// aa

---dancing_links() { front = back = NULL; }-----// 72

---node *push_back(const T &item) {-----// 83

-----back = new node(item, back, NULL);-----// c4

-----if (!front) front = back;-----// d2

-----return back;-----// c0

};-----// a9

---node *push_front(const T &item) {-----// 4a

-----front = new node(item, NULL, front);-----// 47

-----if (!back) back = front;-----// 10

-----return front;-----// cf

};-----// b6

---void erase(node *n) {-----// a0

-----if (!n->l) front = n->r; else n->l->r = n->r;-----// ab

```

-----if (!n->r) back = n->l; else n->r->l = n->l;-----// 1b
--}-// 7b
--void restore(node *n) {-----// 82
-----if (!n->l) front = n; else n->l->r = n;-----// a5
-----if (!n->r) back = n; else n->r->l = n;-----// 9d
--}-// eb
};-----// 5e

```

2.8. Misof Tree.

```

#define BITS 15-----// 7b
struct misof_tree {-----// fe
--int cnt[BITS][1<<BITS];-----// aa
--misof_tree() { memset(cnt, 0, sizeof(cnt)); }-----// b0
--void insert(int x) { for (int i = 0; i < BITS; cnt[i++][x]++, x >= 1); }-----// 5a
--void erase(int x) { for (int i = 0; i < BITS; cnt[i++][x]--, x >= 1); }-----// 49
--int nth(int n) {-----// 8a
--int res = 0;-----// a4
--for (int i = BITS-1; i >= 0; i--)-----// 99
--if (cnt[i][res <= 1] <= n) n -= cnt[i][res], res |= 1;-----// f4
--return res;-----// 3a
--}-// b5
};-----// 0a

```

2.9. k-d Tree.

```

#define INC(c) ((c) == K - 1 ? 0 : (c) + 1)-----// 77
template <int K>-----// cd
class kd_tree {-----// 7e
public:-----// c7
--struct pt {-----// 78
--double coord[K];-----// d6
--pt() {}-----// c1
--pt(double c[K]) { rep(i,0,K) coord[i] = c[i]; }-----// 15
--double dist(const pt &other) const {-----// a5
--double sum = 0.0;-----// 6c
--rep(i,0,K) sum += pow(coord[i] - other.coord[i], 2.0);-----// 5e
--return sqrt(sum); } }-----// ba
--struct cmp {-----// de
--int c;-----// a9
--cmp(int _c) : c(_c) {}-----// a0
--bool operator()(const pt &a, const pt &b) {-----// 00
--for (int i = 0, cc; i <= K; i++) {-----// a7
--cc = i == 0 ? c : i - 1;-----// 36
--if (abs(a.coord[cc] - b.coord[cc]) > EPS)-----// 54
--return a.coord[cc] < b.coord[cc];-----// f4
--}-----// 72
--return false; } }-----// b9
--struct bb {-----// 2d
--pt from, to;-----// 66
--bb(pt _from, pt _to) : from(_from), to(_to) {}-----// 93
--double dist(const pt &p) {-----// f4
--double sum = 0.0;-----// 16
--rep(i,0,K) {-----// fc

```

```

-----if (p.coord[i] < from.coord[i])-----// a9
--sum += pow(from.coord[i] - p.coord[i], 2.0);-----// ed
-----else if (p.coord[i] > to.coord[i])-----// d7
--sum += pow(p.coord[i] - to.coord[i], 2.0);-----// 7a
--}-// 21
--return sqrt(sum); }-----// 53
--bb bound(double l, int c, bool left) {-----// 9c
--pt nf(from.coord), nt(to.coord);-----// 39
--if (left) nt.coord[c] = min(nt.coord[c], l);-----// 2a
--else nf.coord[c] = max(nf.coord[c], l);-----// fc
--return bb(nf, nt); } }-----// d7
--struct node {-----// 04
--pt p; node *l, *r;-----// cf
--node(pt _p, node *_l, node *_r) : p(_p), l(_l), r(_r) { } }-----// cb
--node *root;-----// 16
--// kd_tree() : root(NULL) { }-----// 66
--kd_tree(vector<pt> pts) { root = construct(pts, 0, size(pts) - 1, 0); }-----// 35
--node* construct(vector<pt> &pts, int from, int to, int c) {-----// 4f
--if (from > to) return NULL;-----// 87
--int mid = from + (to - from) / 2;-----// ac
--nth_element(pts.begin() + from, pts.begin() + mid,-----// c0
--pts.begin() + to + 1, cmp(c));-----// d3
--return new node(pts[mid], construct(pts, from, mid - 1, INC(c)),-----// 36
--construct(pts, mid + 1, to, INC(c))); }-----// 97
--bool contains(const pt &p) { return _con(p, root, 0); }-----// fd
--bool _con(const pt &p, node *n, int c) {-----// 82
--if (!n) return false;-----// d7
--if (cmp(c)(p, n->p)) return _con(p, n->l, INC(c));-----// 46
--if (cmp(c)(n->p, p)) return _con(p, n->r, INC(c));-----// 1c
--return true; }-----// 58
--void insert(const pt &p) { _ins(p, root, 0); }-----// 1e
--void _ins(const pt &p, node* &n, int c) {-----// 80
--if (!n) n = new node(p, NULL, NULL);-----// 3b
--else if (cmp(c)(p, n->p)) _ins(p, n->l, INC(c));-----// cb
--else if (cmp(c)(n->p, p)) _ins(p, n->r, INC(c)); }-----// 2b
--void clear() { _clr(root); root = NULL; }-----// 56
--void _clr(node *n) { if (n) _clr(n->l), _clr(n->r), delete n; }-----// 43
--pt nearest_neighbour(const pt &p, bool allow_same=true) {-----// f1
--assert(root);-----// c0
--double mn = INFINITY, cs[K];-----// 66
--rep(i,0,K) cs[i] = -INFINITY;-----// e4
--pt from(cs);-----// d3
--rep(i,0,K) cs[i] = INFINITY;-----// c9
--pt to(cs);-----// 4e
--return _nn(p, root, bb(from, to), mn, 0, allow_same).first;-----// ae
--}-----// a0
--pair<pt, bool> _nn(-----// cd
--const pt &p, node *n, bb b, double &mn, int c, bool same) {-----// 65
--if (!n || b.dist(p) > mn) return make_pair(pt(), false);-----// 6f
--bool found = same || p.dist(n->p) > EPS, l1 = true, l2 = false;-----// a1
--pt resp = n->p;-----// b7

```



```
-----if (found) mn = min(mn, p.dist(resp));-----// 4d
-----node *n1 = n->l, *n2 = n->r;-----// 49
-----rep(i,0,2) {-----// 07
-----if (i == 1 || cmp(c)(n->p, p)) swap(n1, n2), swap(l1, l2);-----// 2b
-----pair<pt, bool> res =-----// 6e
-----_nn(p, n1, b.bound(n->p.coord[c], c, l1), mn, INC(c), same);-----// 6a
-----if (res.second && (!found || p.dist(res.first) < p.dist(resp)))-----// f6
-----resp = res.first, found = true;-----// 37
-----}-----// 57
-----return make_pair(resp, found); } }-----// 05
```

2.10. Sqrt Decomposition.

```
struct segment {-----// b2
---vi arr;-----// 8c
---segment(vi _arr) : arr(_arr) { } }-----// 11
vector<segment> T;-----// a1
int K;-----// dc
void rebuild() {-----// 17
---int cnt = 0;-----// 14
---rep(i,0,size(T))-----// b1
---cnt += size(T[i].arr);-----// d1
---K = static_cast<int>(ceil(sqrt(cnt)) + 1e-9);-----// 4c
---vi arr(cnt);-----// 14
---for (int i = 0, at = 0; i < size(T); i++)-----// 79
---rep(j,0,size(T[i].arr))-----// a4
---arr[at++] = T[i].arr[j];-----// f7
---T.clear();-----// 4c
---for (int i = 0; i < cnt; i += K)-----// 79
---T.push_back(segment(vi(arr.begin()+i, arr.begin()+min(i+K, cnt))));-----// f0
}-----// 03
int split(int at) {-----// 71
---int i = 0;-----// 8a
---while (i < size(T) && at >= size(T[i].arr))-----// 6c
---at -= size(T[i].arr), i++;-----// 9a
---if (i >= size(T)) return size(T);-----// 83
---if (at == 0) return i;-----// 49
---T.insert(T.begin() + i + 1, segment(vi(T[i].arr.begin() + at, T[i].arr.end())));
---T[i] = segment(vi(T[i].arr.begin(), T[i].arr.begin() + at));-----// af
---return i + 1;-----// ac
}-----// ea
void insert(int at, int v) {-----// 5f
---vi arr; arr.push_back(v);-----// 6a
---T.insert(T.begin() + split(at), segment(arr));-----// 67
}-----// cc
void erase(int at) {-----// be
---int i = split(at); split(at + 1);-----// da
---T.erase(T.begin() + i);-----// 6b
}-----// 4b
```

2.11. Monotonic Queue.

```
struct min_stack {-----// d8
---stack<int> S, M;-----// fe
```

```
void push(int x) {-----// 20
---S.push(x);-----// e2
---M.push(M.empty() ? x : min(M.top(), x)); }-----// 92
int top() { return S.top(); }-----// f1
int mn() { return M.top(); }-----// 02
void pop() { S.pop(); M.pop(); }-----// fd
bool empty() { return S.empty(); }-----// d2
};-----// 74
struct min_queue {-----// b4
---min_stack inp, outp;-----// 3d
---void push(int x) { inp.push(x); }-----// 6b
---void fix() {-----// 5d
---if (outp.empty()) while (!inp.empty())-----// 3b
---outp.push(inp.top()), inp.pop();-----// 8e
---}-----// 3f
---int top() { fix(); return outp.top(); }-----// dc
---int mn() {-----// 39
---if (inp.empty()) return outp.mn();-----// 01
---if (outp.empty()) return inp.mn();-----// 90
---return min(inp.mn(), outp.mn()); }-----// 97
---void pop() { fix(); outp.pop(); }-----// 4f
---bool empty() { return inp.empty() && outp.empty(); }-----// 65
};-----// 60
```

2.12. Convex Hull Trick.

```
struct convex_hull_trick {-----// 16
---vector<pair<double,double> > h;-----// b4
---double intersect(int i) {-----// 9b
---return (h[i+1].second-h[i].second)/(h[i].first-h[i+1].first); }-----// b9
---void add(double m, double b) {-----// a4
---h.push_back(make_pair(m,b));-----// f9
---while (size(h) >= 3) {-----// f6
---int n = size(h);-----// d8
---if (intersect(n-3) < intersect(n-2)) break;-----// 07
---swap(h[n-2], h[n-1]);-----// bf
---h.pop_back(); } }-----// 4b
---double get_min(double x) {-----// b0
---int lo = 0, hi = size(h) - 2, res = -1;-----// 5b
---while (lo <= hi) {-----// 24
---int mid = lo + (hi - lo) / 2;-----// 5a
---if (intersect(mid) <= x) res = mid, lo = mid + 1;-----// 1d
---else hi = mid - 1; }-----// b6
---return h[res+1].first * x + h[res+1].second; } }-----// 84
```

3. GRAPHS

3.1. Single-Source Shortest Paths.

3.1.1. Dijkstra's algorithm.

```
int *dist, *dad;-----// 46
struct cmp {-----// a5
---bool operator()(int a, int b) {-----// bb
---return dist[a] != dist[b] ? dist[a] < dist[b] : a < b; }-----// e6
```

```

-- union_find uf(n);-----// a8
-- vi dag;-----// 61
-- vvi rev(n);-----// c5
-- rep(i,0,n) rep(j,0,size(adj[i])) rev[adj[i][j]].push_back(i);-----// 7e
-- visited.resize(n, fill(visited.begin(), visited.end(), false));-----// 80
-- rep(i,0,n) if (!visited[i]) scc_dfs(rev, i);-----// 4e
-- fill(visited.begin(), visited.end(), false);-----// 59
-- stack<int> S;-----// bb
-- for (int i = n-1; i >= 0; i--) {-----// 96
--     if (visited[order[i]]) continue;-----// db
--     S.push(order[i]), dag.push_back(order[i]);-----// 68
--     while (!S.empty()) {-----// 9e
--         visited[u = S.top()] = true, S.pop(), uf.unite(u, order[i]);-----// b3
--         rep(j,0,size(adj[u])) if (!visited[v = adj[u][j]]) S.push(v);-----// 1b
--     }-----// 61
-- }-----// 57
-- return pair<union_find, vi>(uf, dag);-----// 2b
}-----// 92

```

3.3. Cut Points and Bridges.

```
#define MAXN 5000
int low[MAXN], num[MAXN], curnum;
void dfs(const vvi &adj, vi &cp, vii &bri, int u, int p) {
    low[u] = num[u] = curnum++;
    int cnt = 0; bool found = false;
    rep(i, 0, size(adj[u])) {
        int v = adj[u][i];
        if (num[v] == -1) {
            dfs(adj, cp, bri, v, u);
            low[u] = min(low[u], low[v]);
            cnt++;
            found = found || low[v] >= num[u];
            if (low[v] > num[u]) bri.push_back(ii(u, v));
        } else if (p != v) low[u] = min(low[u], num[v]);
    }
    if (found && (p != -1 || cnt > 1)) cp.push_back(u);
}
pair<vi, vii> cut_points_and_bridges(const vvi &adj) {
    int n = size(adj);
    vi cp;
    memset(num, -1, n <= 2);
    curnum = 0;
    rep(i, 0, n) if (num[i] == -1) dfs(adj, cp, bri, i, -1);
    return make_pair(cp, bri);
}
```

3.4. Euler Path.

```

#define MAXV 1000-----// 2f
#define MAXE 5000-----// 87
vi adj[MAXV];-----// ff
int n, m, indeg[MAXV], outdeg[MAXV], res[MAXE + 1];-----// 49
ii start_end() {-----// 30
----int start = -1, end = -1, any = 0, c = 0;-----// 74
----rep(i,0,n) {-----// 20
-----if (outdeg[i] > 0) any = i;-----// 63

```

```

#define MAXV 1000-----// 2f
#define MAXE 5000-----// 87
vi adj[MAXV];-----// ff
int n, m, indeg[MAXV], outdeg[MAXV], res[MAXE + 1];-----// 49
ii start_end() {-----// 30
----int start = -1, end = -1, any = 0, c = 0;-----// 74
----rep(i,0,n) {-----// 20
-----if (outdeg[i] > 0) any = i;-----// 63

```



```
-----if (indeg[i] + 1 == outdeg[i]) start = i, c++;-----// 5a
-----else if (indeg[i] == outdeg[i] + 1) end = i, c++;-----// 13
-----else if (indeg[i] != outdeg[i]) return ii(-1,-1);-----// c1
}-----// ed
if ((start == -1) != (end == -1) || (c != 2 && c != 0)) return ii(-1,-1);--// 54
if (start == -1) start = end = any;-----// 5e
return ii(start, end);-----// a2
}-----// eb
bool euler_path() {-----// b4
--ii se = start_end();-----// 8a
--int cur = se.first, at = m + 1;-----// b6
--if (cur == -1) return false;-----// ac
--stack<int> s;-----// 1c
--while (true) {-----// b3
-----if (outdeg[cur] == 0) {-----// 0d
-----res[at] = cur;-----// bd
-----if (s.empty()) break;-----// c6
-----cur = s.top(); s.pop();-----// 06
-----} else s.push(cur), cur = adj[cur][--outdeg[cur]];-----// 9e
--}-----// a4
--return at == 0;-----// ac
}-----// 22
```

3.5. Bipartite Matching.

3.5.1. Alternating Paths algorithm.

```
vi* adj;-----// cc
bool* done;-----// b1
int* owner;-----// 26
int alternating_path(int left) {-----// da
--if (done[left]) return 0;-----// 08
--done[left] = true;-----// f2
--rep(i,0,size(adj[left])) {-----// 1b
-----int right = adj[left][i];-----// 46
-----if (owner[right] == -1 || alternating_path(owner[right])) {-----// f6
-----owner[right] = left; return 1;-----// f2
-----} }-----// 88
--return 0; }-----// 41
```

3.5.2. Hopcroft-Karp algorithm. Running time is $O(|E|\sqrt{|V|})$.

```
#define MAXN 5000-----// f7
int dist[MAXN+1], q[MAXN+1];-----// b8
#define dist(v) dist[v == -1 ? MAXN : v]-----// 0f
struct bipartite_graph {-----// 2b
--int N, M, *L, *R; vi *adj;-----// fc
--bipartite_graph(int _N, int _M) : N(_N), M(_M),-----// 8d
--L(new int[N]), R(new int[M]), adj(new vi[N]) {}-----// cd
--bipartite_graph() { delete[] adj; delete[] L; delete[] R; }-----// 89
--bool bfs() {-----// f5
--int l = 0, r = 0;-----// 37
--rep(v,0,N) if(L[v] == -1) dist(v) = 0, q[r++] = v;-----// f9
--else dist(v) = INF;-----// aa
```

```
-----dist(-1) = INF;-----// f2
-----while(l < r) {-----// ba
-----int v = q[l++];-----// 50
-----if(dist(v) < dist(-1)) {-----// f1
-----iter(u, adj[v]) if(dist(R[*u]) == INF)-----// 9b
-----dist(R[*u]) = dist(v) + 1, q[r++] = R[*u];-----// 79
-----}-----// b8
-----}-----// 0d
-----return dist(-1) != INF;-----// 43
}-----// 2c
bool dfs(int v) {-----// 26
--if(v != -1) {-----// d8
--iter(u, adj[v])-----// 99
--if(dist(R[*u]) == dist(v) + 1)-----// 74
--if(dfs(R[*u])) {-----// 40
--R[*u] = v, L[v] = *u;-----// 47
--return true;-----// a2
--}-----// 17
--dist(v) = INF;-----// 62
--return false;-----// 3c
--}-----// 3d
--return true;-----// ae
}-----// 0f
void add_edge(int i, int j) { adj[i].push_back(j); }-----// 92
int maximum_matching() {-----// a2
--int matching = 0;-----// 71
--memset(L, -1, sizeof(int) * N);-----// 72
--memset(R, -1, sizeof(int) * M);-----// bf
--while(bfs()) rep(i,0,N)-----// 3e
--matching += L[i] == -1 && dfs(i);-----// 1d
--return matching;-----// ec
}-----// 8b
};-----// b7
```

3.6. Maximum Flow.

3.6.1. Dinic's algorithm. An implementation of Dinic's algorithm that runs in $O(|V|^2|E|)$.

```
#define MAXV 2000-----// ba
int q[MAXV], d[MAXV];-----// e6
struct flow_network {-----// 12
--struct edge {-----// 1e
--int v, cap, nxt;-----// ab
--edge() { }-----// 38
--edge(int _v, int _cap, int _nxt) : v(_v), cap(_cap), nxt(_nxt) { }-----// bc
--};-----// 6e
--int n, ecnt, *head, *curh;-----// 46
--vector<edge> e, e_store;-----// 1f
--flow_network(int _n, int m = -1) : n(_n), ecnt(0) {-----// d3
--e.reserve(2 * (m == -1 ? n : m));-----// 24
--head = new int[n], curh = new int[n];-----// 6b
--memset(head, -1, n * sizeof(int));-----// 56
--}-----// 77
```

```
---void destroy() { delete[] head; delete[] curh; }-----// f6
---void reset() { e = e_store; }-----// 87
---void add_edge(int u, int v, int uv, int vu = 0) {-----// cd
-----e.push_back(edge(v, uv, head[u])); head[u] = ecnt++;-----// c9
-----e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;-----// 89
---}-----// 14
---int augment(int v, int t, int f) {-----// 3f
---if (v == t) return f;-----// 6d
---for (int &i = curh[v], ret; i != -1; i = e[i].nxt)-----// f9
-----if (e[i].cap > 0 && d[e[i].v] + 1 == d[v])-----// cc
-----if ((ret = augment(e[i].v, t, min(f, e[i].cap))) > 0)-----// 1f
-----return (e[i].cap -= ret, e[i^1].cap += ret, ret);-----// ac
---return 0;-----// 19
---}-----// fd
---int max_flow(int s, int t, bool res = true) {-----// 31
-----if(s == t) return 0;-----// 9d
-----e_store = e;-----// 57
-----int f = 0, x, l, r;-----// 0e
-----while (true) {-----// b5
-----memset(d, -1, n * sizeof(int));-----// a8
-----l = r = 0, d[q[r++] = t] = 0;-----// 0e
-----while (l < r)-----// 7a
-----for (int v = q[l++], i = head[v]; i != -1; i = e[i].nxt)-----// a2
-----if (e[i^1].cap > 0 && d[e[i].v] == -1)-----// 29
-----d[q[r++] = e[i].v] = d[v]+1;-----// 28
-----if (d[s] == -1) break;-----// a0
-----memcpy(curh, head, n * sizeof(int));-----// 10
-----while ((x = augment(s, t, INF)) != 0) f += x;-----// a6
-----}-----// 96
-----if (res) reset();-----// 21
-----return f;-----// b6
---}-----// 1b
};-----// 3b
```

3.6.2. *Edmonds Karp’s algorithm.* An implementation of Edmonds Karp’s algorithm that runs in $O(|V||E|^2)$.

```
#define MAXV 2000-----// ba
int q[MAXV], d[MAXV], p[MAXV];-----// 7b
struct flow_network {-----// 5e
---struct edge {-----// fc
---int v, cap, nxt;-----// cb
---edge(int _v, int _cap, int _nxt) : v(_v), cap(_cap), nxt(_nxt) { }-----// 7a
---};-----// 31
---int n, ecnt, *head;-----// 39
---vector<edge> e, e_store;-----// ea
---flow_network(int _n, int m = -1) : n(_n), ecnt(0) {-----// 34
-----e.reserve(2 * (m == -1 ? n : m));-----// 92
-----memset(head = new int[n], -1, n << 2);-----// 58
-----}-----// 3a
---void destroy() { delete[] head; }-----// d5
---void reset() { e = e_store; }-----// 1b
```

```
---void add_edge(int u, int v, int uv, int vu=0) {-----// 7c
-----e.push_back(edge(v, uv, head[u])); head[u] = ecnt++;-----// 4c
-----e.push_back(edge(u, vu, head[v])); head[v] = ecnt++;-----// bc
---}-----// ef
---int max_flow(int s, int t, bool res = true) {-----// 12
---if (s == t) return 0;-----// d6
---e_store = e;-----// 9e
---int f = 0, l, r, v;-----// 6f
---while (true) {-----// 42
-----memset(d, -1, n << 2);-----// 3b
-----memset(p, -1, n << 2);-----// 92
-----l = r = 0, d[q[r++] = s] = 0;-----// 5f
-----while (l < r)-----// 2c
-----for (int u = q[l++], i = head[u]; i != -1; i = e[i].nxt)-----// c6
-----if (e[i].cap > 0 &&
-----d[v] = e[i].v == -1 || d[u] + 1 < d[v]))-----// 2f
-----d[v] = d[u] + 1, p[q[r++] = v] = i;-----// d5
-----if (p[t] == -1) break;-----// 4f
-----int x = INF, at = p[t];-----// b1
-----while (at != -1) x = min(x, e[at].cap), at = p[e[at^1].v];-----// 8a
-----at = p[t], f += x;-----// 2d
-----while (at != -1)-----// cd
-----e[at].cap -= x, e[at^1].cap += x, at = p[e[at^1].v];-----// 2e
-----}-----// 47
-----if (res) reset();-----// 3b
-----return f;-----// bc
---}-----// 05
};-----// 75
```

3.7. **Minimum Cost Maximum Flow.** Running time is $O(|V|^2|E|\log|V|)$.

```
#define MAXV 2000-----// ba
int d[MAXV], p[MAXV], pot[MAXV];-----// 80
struct cmp {-----// d1
---bool operator()(int i, int j) {-----// 8a
---return d[i] == d[j] ? i < j : d[i] < d[j];-----// 89
---}-----// df
};-----// cf
struct flow_network {-----// eb
---struct edge {-----// 9a
---int v, cap, cost, nxt;-----// ad
---edge(int _v, int _cap, int _cost, int _nxt)-----// ec
---: v(_v), cap(_cap), cost(_cost), nxt(_nxt) { }-----// c4
---};-----// ad
---int n, ecnt, *head;-----// 46
---vector<edge> e, e_store;-----// 4b
---flow_network(int _n, int m = -1) : n(_n), ecnt(0) {-----// dd
-----e.reserve(2 * (m == -1 ? n : m));-----// e6
-----memset(head = new int[n], -1, n << 2);-----// 6c
-----}-----// f3
---void destroy() { delete[] head; }-----// ac
---void reset() { e = e_store; }-----// 88
```

```
---void add_edge(int u, int v, int cost, int uv, int vu=0) {-----// b4
-----e.push_back(edge(v, uv, cost, head[u])); head[u] = ecnt++;-----// 43
-----e.push_back(edge(u, vu, -cost, head[v])); head[v] = ecnt++;-----// 53
---}-----// 16
---ii min_cost_max_flow(int s, int t, bool res = true) {-----// 6d
---if (s == t) return ii(0, 0);-----// 34
---e_store = e;-----// 70
---memset(pot, 0, n << 2);-----// 24
---int f = 0, c = 0, v;-----// d4
---while (true) {-----// 29
---    memset(d, -1, n << 2);-----// fd
---    memset(p, -1, n << 2);-----// b7
---    set<int, cmp> q;-----// d8
---    q.insert(s); d[s] = 0;-----// 1d
---    while (!q.empty()) {-----// 04
---        int u = *q.begin();-----// dd
---        q.erase(q.begin());-----// 20
---        for (int i = head[u]; i != -1; i = e[i].nxt) {-----// 02
---            if (e[i].cap == 0) continue;-----// 1c
---            int cd = d[u] + e[i].cost + pot[u] - pot[v = e[i].v];-----// 1d
---            if (d[v] == -1 || cd < d[v]) {-----// d2
---                if (q.find(v) != q.end()) q.erase(q.find(v));-----// e2
---                d[v] = cd; p[v] = i;-----// f7
---                q.insert(v);-----// 74
---            }-----// 6c
---        }-----// 1b
---    }-----// da
---    if (p[t] == -1) break;-----// 09
---    int x = INF, at = p[t];-----// e8
---    while (at != -1) x = min(x, e[at].cap), at = p[e[at].v];-----// 32
---    at = p[t], f += x;-----// 43
---    while (at != -1)-----// 53
---        e[at].cap -= x, e[at].cap += x, at = p[e[at].v];-----// 95
---    c += x * (d[t] + pot[t] - pot[s]);-----// 44
---    rep(i,0,n) if (p[i] != -1) pot[i] += d[i];-----// 86
---}-----// 4e
---if (res) reset();-----// d7
---return ii(f, c);-----// 9f
---}-----// 4c
};-----// ec
```

3.8. All Pairs Maximum Flow.

3.8.1. *Gomory-Hu Tree.* An implementation of the Gomory-Hu Tree. The spanning tree is constructed using Gusfield’s algorithm in $O(|V|^2)$ plus $|V| - 1$ times the time it takes to calculate the maximum flow. If Dinic’s algorithm is used to calculate the max flow, the running time is $O(|V|^3|E|)$.

```
#include "dinic.cpp"-----// 58
-----// 25
bool same[MAXV];-----// 59
pair<vii, vvi> construct_gh_tree(flow_network &g) {-----// 77
---int n = g.n, v;-----// 5d
---vii par(n, ii(0, 0)); vvi cap(n, vi(n, -1));-----// 49
```

```
---rep(s,1,n) {-----// 9e
---    int l = 0, r = 0;-----// 08
---    par[s].second = g.max_flow(s, par[s].first, false);-----// 54
---    memset(d, 0, n * sizeof(int));-----// c8
---    memset(same, 0, n * sizeof(int));-----// b7
---    d[q[r++] = s] = 1;-----// cb
---    while (l < r) {-----// d4
---        same[v = q[l++]] = true;-----// f6
---        for (int i = g.head[v]; i != -1; i = g.e[i].nxt)-----// da
---            if (g.e[i].cap > 0 && d[g.e[i].v] == 0)-----// 9a
---                d[q[r++] = g.e[i].v] = 1;-----// 1f
---    }-----// d4
---    rep(i,s+1,n)-----// 35
---        if (par[i].first == par[s].first && same[i]) par[i].first = s;-----// 93
---        g.reset();-----// 87
---}-----// 22
---rep(i,0,n) {-----// 34
---    int mn = INF, cur = i;-----// ac
---    while (true) {-----// c9
---        cap[cur][i] = mn;-----// 3b
---        if (cur == 0) break;-----// 37
---        mn = min(mn, par[cur].second), cur = par[cur].first;-----// e8
---    }-----// de
---}-----// 99
---return make_pair(par, cap);-----// 75
}-----// f6
int compute_max_flow(int s, int t, const pair<vii, vvi> &gh) {-----// 2a
---if (s == t) return 0;-----// 7a
---int cur = INF, at = s;-----// 57
---while (gh.second[at][t] == -1)-----// e0
---    cur = min(cur, gh.first[at].second), at = gh.first[at].first;-----// 00
---return min(cur, gh.second[at][t]);-----// 09
}-----// 07
```

3.9. Heavy-Light Decomposition.

```
#include "../data-structures/segment_tree.cpp"-----// 16
struct HLD {-----// 25
---int n, curhead, curloc;-----// d9
---vi sz, head, parent, loc;-----// 81
---vvi below; segment_tree values;-----// 96
---HLD(int _n) : n(_n), sz(n, 1), head(n), parent(n, -1), loc(n), below(n) {-----// 4f
---    vi tmp(n, ID); values = segment_tree(tmp); }-----// a7
---void add_edge(int u, int v) { below[parent[v] = u].push_back(v); }-----// f8
---void update_cost(int u, int v, int c) {-----// 12
---    if (parent[v] == u) swap(u, v); assert(parent[u] == v);-----// 9f
---    values.update(loc[u], c); }-----// 9a
---void csz(int u) { rep(i,0,size(below[u]))-----// 61
---        csz(below[u][i]), sz[u] += sz[below[u][i]]; }-----// e7
---void part(int u) {-----// da
---    head[u] = curhead; loc[u] = curloc++;-----// cc
---    int best = -1;-----// 55
```

```
-----rep(i,0,size(below[u]))-----// 0f
-----if (best == -1 || sz[below[u][i]] > sz[best]) best = below[u][i];-----// 7d
-----if (best != -1) part(best);-----// 26
-----rep(i,0,size(below[u]))-----// 44
-----if (below[u][i] != best) part(curhead = below[u][i]); }-----// 84
---void build() { int u = curloc = 0;-----// c4
-----while (parent[u] != -1) u++;-----// d4
-----csz(u); part(curhead = u); }-----// 38
---int lca(int u, int v) {-----// 81
-----vi uat, vat; int res = -1;-----// e9
-----while (u != -1) uat.push_back(u), u = parent[head[u]];-----// 5c
-----while (v != -1) vat.push_back(v), v = parent[head[v]];-----// 1f
-----u = size(uat) - 1, v = size(vat) - 1;-----// a4
-----while (u >= 0 && v >= 0 && head[uat[u]] == head[vat[v]])-----// fe
-----res = (loc[uat[u]] < loc[vat[v]] ? uat[u] : vat[v]), u--, v--;-----// 13
-----return res; }-----// 3b
---int query_upto(int u, int v) { int res = ID;-----// bf
-----while (head[u] != head[v])-----// 81
-----res = f(res, values.query(loc[head[u]], loc[u])),-----// 66
-----u = parent[head[u]];-----// 72
-----return f(res, values.query(loc[v] + 1, loc[u])); }-----// d7
---int query(int u, int v) { int l = lca(u, v);-----// fb
-----return f(query_upto(u, l), query_upto(v, l)); } }-----// 21
```

3.10. Tarjan’s Off-line Lowest Common Ancestors Algorithm.

```
#include "../data-structures/union_find.cpp"-----// 5e
struct tarjan_olca {-----// 87
---int *ancestor;-----// 39
---vi *adj, answers;-----// dd
---vii *queries;-----// 66
---bool *colored;-----// 97
---union_find uf;-----// 70
---tarjan_olca(int n, vi *_adj) : adj(_adj), uf(n) {-----// 78
-----colored = new bool[n];-----// 8d
-----ancestor = new int[n];-----// f2
-----queries = new vii[n];-----// 3e
-----memset(colored, 0, n);-----// 6e
-----}-----// 6b
---void query(int x, int y) {-----// d3
-----queries[x].push_back(ii(y, size(answers)));-----// a0
-----queries[y].push_back(ii(x, size(answers)));-----// 14
-----answers.push_back(-1);-----// ca
-----}-----// 6b
---void process(int u) {-----// 85
-----ancestor[u] = u;-----// 1a
-----rep(i,0,size(adj[u])) {-----// ce
-----int v = adj[u][i];-----// dd
-----process(v);-----// e8
-----uf.unite(u,v);-----// 55
-----ancestor[uf.find(u)] = u;-----// 1d
-----}-----// 57
```

```
-----colored[u] = true;-----// b9
-----rep(i,0,size(queries[u])) {-----// d7
-----int v = queries[u][i].first;-----// 89
-----if (colored[v]) {-----// cb
-----answers[queries[u][i].second] = ancestor[uf.find(v)];-----// 63
-----}-----// d0
-----}-----// 40
-----}-----// a9
};-----// 1e
```

4. STRINGS

4.1. Suffix Array. An $O(n \log^2 n)$ construction of a Suffix Tree.

```
struct entry { ii nr; int p; };-----// f9
bool operator <(const entry &a, const entry &b) { return a.nr < b.nr; }-----// 77
struct suffix_array {-----// 87
---string s; int n; vvi P; vector<entry> L; vi idx;-----// b6
---suffix_array(string _s) : s(_s), n(size(s)) {-----// a3
---L = vector<entry>(n), P.push_back(vi(n)), idx = vi(n);-----// 12
---rep(i,0,n) P[0][i] = s[i];-----// 5c
---for (int stp = 1, cnt = 1; cnt >> 1 < n; stp++, cnt <= 1) {-----// 86
---P.push_back(vi(n));-----// 53
---rep(i,0,n)-----// 6f
---L[L[i].p = i].nr = ii(P[stp - 1][i],-----// e2
---i + cnt < n ? P[stp - 1][i + cnt] : -1);-----// 43
---sort(L.begin(), L.end());-----// 5f
---rep(i,0,n)-----// a8
---P[stp][L[i].p] = i > 0 &&-----// 3a
---L[i].nr == L[i - 1].nr ? P[stp][L[i - 1].p] : i;-----// 55
---}-----// 8b
---rep(i,0,n) idx[P[size(P) - 1][i]] = i;-----// 17
---}-----// d9
---int lcp(int x, int y) {-----// 71
---int res = 0;-----// d6
---if (x == y) return n - x;-----// bc
---for (int k = size(P) - 1; k >= 0 && x < n && y < n; k--)-----// fe
---if (P[k][x] == P[k][y]) x += 1 << k, y += 1 << k, res += 1 << k;-----// b7
---return res;-----// bc
---}-----// f1
};-----// f6
```

4.2. Aho-Corasick Algorithm.

```
struct aho_corasick {-----// 78
---struct out_node {-----// 3e
---string keyword; out_node *next;-----// f0
---out_node(string k, out_node *n) : keyword(k), next(n) { }-----// 26
---};-----// b9
---struct go_node {-----// 40
---map<char, go_node*> next;-----// 6b
---out_node *out; go_node *fail;-----// 3e
---go_node() { out = NULL; fail = NULL; }-----// 0f
---};-----// c0
```

```
---go_node *go;-----// b8
---aho_corasick(vector<string> keywords) {-----// 4b
-----go = new go_node();-----// 77
-----iter(k, keywords) {-----// f2
-----go_node *cur = go;-----// a2
-----iter(c, *k)-----// 6e
-----cur = cur->next.find(*c) != cur->next.end() ? cur->next[*c] :-----// 97
----- (cur->next[*c] = new go_node());-----// af
-----cur->out = new out_node(*k, cur->out);-----// 3f
-----}-----// eb
-----queue<go_node*> q;-----// 2c
-----iter(a, go->next) q.push(a->second);-----// db
-----while (!q.empty()) {-----// 07
-----go_node *r = q.front(); q.pop();-----// e0
-----iter(a, r->next) {-----// 18
-----go_node *s = a->second;-----// 55
-----q.push(s);-----// b5
-----go_node *st = r->fail;-----// 53
-----while (st && st->next.find(a->first) == st->next.end())-----// 0e
-----st = st->fail;-----// b3
-----if (!st) st = go;-----// 0b
-----s->fail = st->next[a->first];-----// c1
-----if (s->fail) {-----// 98
-----if (!s->out) s->out = s->fail->out;-----// ad
-----else {-----// 5b
-----out_node* out = s->out;-----// b8
-----while (out->next) out = out->next;-----// b4
-----out->next = s->fail->out;-----// 62
-----}-----// a6
-----}-----// 81
-----}-----// 55
-----}-----// bf
-----}-----// de
---vector<string> search(string s) {-----// c4
---vector<string> res;-----// 79
---go_node *cur = go;-----// 85
---iter(c, s) {-----// 57
---while (cur && cur->next.find(*c) == cur->next.end())-----// df
---cur = cur->fail;-----// b1
---if (!cur) cur = go;-----// 92
---cur = cur->next[*c];-----// 97
---if (!cur) cur = go;-----// 01
---for (out_node *out = cur->out; out; out = out->next)-----// d7
---res.push_back(out->keyword);-----// 7c
---}-----// 56
---return res;-----// 6b
---}-----// 3e
};-----// de
```

4.3. The Z algorithm.

```
int* z_values(const string &s) {-----// 4d
---int n = size(s);-----// 97
---int* z = new int[n];-----// c4
---int l = 0, r = 0;-----// 1c
---z[0] = n;-----// 98
---rep(i,l,n) {-----// b2
---z[i] = 0;-----// 4c
---if (i > r) {-----// 6d
---l = r = i;-----// 24
---while (r < n && s[r - l] == s[r]) r++;-----// 68
---z[i] = r - l; r--;-----// 07
---} else if (z[i - l] < r - i + 1) z[i] = z[i - l];-----// 6f
---else {-----// a8
---l = i;-----// 55
---while (r < n && s[r - l] == s[r]) r++;-----// 2c
---z[i] = r - l; r--; } }-----// 13
---return z;-----// 78
}-----// 16
```

4.4. Eertree.

```
#define MAXN 100100-----// 29
#define SIGMA 26-----// e2
#define BASE 'a'-----// a1
char *s = new char[MAXN];-----// db
struct state {-----// 33
---int len, link, to[SIGMA];-----// 24
} *st = new state[MAXN+2];-----// 57
struct eertree {-----// 78
---int last, sz, n;-----// ba
---eertree() : last(1), sz(2), n(0) {-----// 83
---st[0].len = st[0].link = -1;-----// 3f
---st[1].len = st[1].link = 0; }-----// 34
---int extend() {-----// c2
---char c = s[n++]; int p = last;-----// 25
---while (n - st[p].len - 2 < 0 || c != s[n - st[p].len - 2]) p = st[p].link;-----// 82
---if (!st[p].to[c-BASE]) {-----// 42
---int q = last = sz++;-----// fc
---st[p].to[c-BASE] = q;-----// c5
---st[q].len = st[p].len + 2;-----// 04
---do { p = st[p].link;-----// 77
---} while (p != -1 && (n < st[p].len + 2 || c != s[n - st[p].len - 2]));
---if (p == -1) st[q].link = 1;-----// 6a
---else st[q].link = st[p].to[c-BASE];-----// 29
---return 1; }-----// 42
---last = st[p].to[c-BASE];-----// ec
---return 0; } };
```

5. MATHEMATICS

5.1. Big Integer.

```
struct intx {-----// cf
---intx() { normalize(1); }-----// 6c
```

```

---intx(string n) { init(n); }-----// b9
---intx(int n) { stringstream ss; ss << n; init(ss.str()); }-----// 36
---intx(const intx& other) : sign(other.sign), data(other.data) { }-----// 3b
---int sign;-----// 26
---vector<unsigned int> data;-----// 19
---static const int dcnt = 9;-----// 12
---static const unsigned int radix = 1000000000U;-----// f0
---int size() const { return data.size(); }-----// 29
---void init(string n) {-----// 13
-----intx res; res.data.clear();-----// 4e
-----if (n.empty()) n = "0";-----// 99
-----if (n[0] == '-') res.sign = -1, n = n.substr(1);-----// 3b
-----for (int i = n.size() - 1; i >= 0; i -= intx::dcnt) {-----// e7
-----    unsigned int digit = 0;-----// 98
-----    for (int j = intx::dcnt - 1; j >= 0; j--) {-----// 72
-----        int idx = i - j;-----// cd
-----        if (idx < 0) continue;-----// 52
-----        digit = digit * 10 + (n[idx] - '0');-----// 1f
-----    }-----// c0
-----    res.data.push_back(digit);-----// 07
-----}-----// fb
-----data = res.data;-----// 7d
-----normalize(res.sign);-----// 76
---}-----// 6e
---intx& normalize(int nsign) {-----// 3b
-----    if (data.empty()) data.push_back(0);-----// fa
-----    for (int i = data.size() - 1; i > 0 && data[i] == 0; i--)-----// 27
-----        data.erase(data.begin() + i);-----// 67
-----    sign = data.size() == 1 && data[0] == 0 ? 1 : nsign;-----// ff
-----    return *this;-----// 40
---}-----// ac
---friend ostream& operator <<(ostream& outs, const intx& n) {-----// 0d
-----    if (n.sign < 0) outs << '-';-----// c0
-----    bool first = true;-----// 33
-----    for (int i = n.size() - 1; i >= 0; i--) {-----// 63
-----        if (first) outs << n.data[i], first = false;-----// 33
-----        else {-----// 1f
-----            unsigned int cur = n.data[i];-----// 0f
-----            stringstream ss; ss << cur;-----// 8c
-----            string s = ss.str();-----// 64
-----            int len = s.size();-----// 0d
-----            while (len < intx::dcnt) outs << '0', len++;-----// 0a
-----            outs << s;-----// 97
-----        }-----// f7
-----    }-----// e9
-----    return outs;-----// cf
---}-----// b9
---string to_string() const { stringstream ss; ss << *this; return ss.str(); }// fc
---bool operator <(const intx& b) const {-----// 21
-----    if (sign != b.sign) return sign < b.sign;-----// cf
-----    if (size() != b.size())-----// 4d
-----        return sign == 1 ? size() < b.size() : size() > b.size();-----// 4d
-----    for (int i = size() - 1; i >= 0; i--) if (data[i] != b.data[i])-----// 35
-----        return sign == 1 ? data[i] < b.data[i] : data[i] > b.data[i];-----// 27
-----    return false;-----// ca
---}-----// 32
---intx operator -() const { intx res(*this); res.sign *= -1; return res; }---// 9d
---friend intx abs(const intx &n) { return n < 0 ? -n : n; }-----// 02
---intx operator +(const intx& b) const {-----// f8
-----    if (sign > 0 && b.sign < 0) return *this - (-b);-----// 36
-----    if (sign < 0 && b.sign > 0) return b - (-*this);-----// 70
-----    if (sign < 0 && b.sign < 0) return -((-*this) + (-b));-----// 59
-----    intx c; c.data.clear();-----// 18
-----    unsigned long long carry = 0;-----// 5c
-----    for (int i = 0; i < size() || i < b.size() || carry; i++) {-----// e3
-----        carry += (i < size() ? data[i] : 0ULL) +-----// 91
-----            (i < b.size() ? b.data[i] : 0ULL);-----// 0c
-----        c.data.push_back(carry % intx::radix);-----// 86
-----        carry /= intx::radix;-----// fd
-----    }-----// 50
-----    return c.normalize(sign);-----// 20
---}-----// 70
---intx operator -(const intx& b) const {-----// 53
-----    if (sign > 0 && b.sign < 0) return *this + (-b);-----// 8f
-----    if (sign < 0 && b.sign > 0) return -(-*this + b);-----// 1b
-----    if (sign < 0 && b.sign < 0) return (-b) - (-*this);-----// a1
-----    if (*this < b) return -(b - *this);-----// 36
-----    intx c; c.data.clear();-----// 6b
-----    long long borrow = 0;-----// f8
-----    rep(i,0,size()) {-----// a7
-----        borrow = data[i] - borrow - (i < b.size() ? b.data[i] : 0ULL);-----// a5
-----        c.data.push_back(borrow < 0 ? intx::radix + borrow : borrow);-----// 9b
-----        borrow = borrow < 0 ? 1 : 0;-----// fb
-----    }-----// dd
-----    return c.normalize(sign);-----// 5c
---}-----// 5e
---intx operator *(const intx& b) const {-----// b3
-----    intx c; c.data.assign(size() + b.size() + 1, 0);-----// 3a
-----    rep(i,0,size()) {-----// 0f
-----        long long carry = 0;-----// 15
-----        for (int j = 0; j < b.size() || carry; j++) {-----// 95
-----            if (j < b.size()) carry += (long long)data[i] * b.data[j];-----// 6d
-----            carry += c.data[i + j];-----// c6
-----            c.data[i + j] = carry % intx::radix;-----// a8
-----            carry /= intx::radix;-----// dc
-----        }-----// e3
-----    }-----// f0
-----    return c.normalize(sign * b.sign);-----// 09
---}-----// a7
---friend pair<intx,intx> divmod(const intx& n, const intx& d) {-----// 40
-----    assert(!(d.size() == 1 && d.data[0] == 0));-----// 42
-----    intx q, r; q.data.assign(n.size(), 0);-----// 5e

```



```
-----for (int i = n.size() - 1; i >= 0; i--) {-----// 52
-----r.data.insert(r.data.begin(), 0);-----// cb
-----r = r + n.data[i];-----// ea
-----long long k = 0;-----// dd
-----if (d.size() < r.size())-----// 4d
-----k = (long long)intx::radix * r.data[d.size()];-----// d2
-----if (d.size() - 1 < r.size()) k += r.data[d.size() - 1];-----// af
-----k /= d.data.back();-----// 85
-----r = r - abs(d) * k;-----// 3b
-----// if (r < 0) for (ll t = 1LL << 62; t >= 1; t >= 1) {-----// 0e
-----//---- intx dd = abs(d) * t;-----// 9d
-----//---- while (r + dd < 0) r = r + dd, k -= t; }-----// a1
-----while (r < 0) r = r + abs(d), k--;-----// cb
-----q.data[i] = k;-----// 1a
-----}-----// 3c
-----return pair<intx, intx>(q.normalize(n.sign * d.sign), r);-----// 9e
}-----// a7
intx operator /(const intx& d) const {-----// 22
return divmod(*this,d).first; }-----// c3
intx operator %(const intx& d) const {-----// 32
return divmod(*this,d).second * sign; }-----// 0c
};-----// 64
```

5.1.1. Fast Multiplication.

```
#include "intx.cpp"-----// 83
#include "fft.cpp"-----// 13
-----// e0
intx fastmul(const intx &an, const intx &bn) {-----// ab
---string as = an.to_string(), bs = bn.to_string();-----// 32
---int n = size(as), m = size(bs), l = 1,-----// dc
-----len = 5, radix = 100000,-----// 4f
-----*a = new int[n], alen = 0,-----// b8
-----*b = new int[m], blen = 0;-----// 0a
---memset(a, 0, n << 2);-----// 1d
---memset(b, 0, m << 2);-----// 01
---for (int i = n - 1; i >= 0; i -= len, alen++)-----// 6e
---for (int j = min(len - 1, i); j >= 0; j--)-----// 43
-----a[alen] = a[alen] * 10 + as[i - j] - '0';-----// 14
---for (int i = m - 1; i >= 0; i -= len, blen++)-----// b6
---for (int j = min(len - 1, i); j >= 0; j--)-----// ae
-----b[blen] = b[blen] * 10 + bs[i - j] - '0';-----// 9b
---while (l < 2*max(alen,blen)) l <= 1;-----// 51
---cpx *A = new cpx[l], *B = new cpx[l];-----// 0d
---rep(i,0,l) A[i] = cpx(i < alen ? a[i] : 0, 0);-----// ff
---rep(i,0,l) B[i] = cpx(i < blen ? b[i] : 0, 0);-----// 7f
---fft(A, l); fft(B, l);-----// 77
---rep(i,0,l) A[i] *= B[i];-----// 1c
---fft(A, l, true);-----// ec
---ull *data = new ull[l];-----// f1
---rep(i,0,l) data[i] = (ull)(round(real(A[i])));-----// e2
---rep(i,0,l-1)-----// c8
```

```
-----if (data[i] >= (unsigned int)(radix)) {-----// 03
-----data[i+1] += data[i] / radix;-----// 48
-----data[i] %= radix;-----// 94
-----}-----// 47
int stop = l-1;-----// 92
while (stop > 0 && data[stop] == 0) stop--;-----// 5b
stringstream ss;-----// a6
ss << data[stop];-----// f3
for (int i = stop - 1; i >= 0; i--)-----// 7b
ss << setfill('0') << setw(len) << data[i];-----// 41
delete[] A; delete[] B;-----// dd
delete[] a; delete[] b;-----// 77
delete[] data;-----// 5e
return intx(ss.str());-----// 88
}-----// d8
```

5.2. **Binomial Coefficients.** The binomial coefficient $\binom{n}{k} = \frac{n!}{k!(n-k)!}$ is the number of ways to choose k items out of a total of n items.

```
int nck(int n, int k) {-----// f6
if (n - k < k) k = n - k;-----// 18
int res = 1;-----// cb
rep(i,1,k+1) res = res * (n - (k - i)) / i;-----// 16
return res;-----// 6d
}-----// 3d
```

5.3. Euclidean algorithm.

```
int gcd(int a, int b) { return b == 0 ? a : gcd(b, a % b); }-----// d9
```

The extended Euclidean algorithm computes the greatest common divisor d of two integers a, b and also finds two integers x, y such that $a \times x + b \times y = d$.

```
int egcd(int a, int b, int& x, int& y) {-----// 85
if (b == 0) { x = 1; y = 0; return a; }-----// 7b
else {-----// 00
int d = egcd(b, a % b, x, y);-----// 34
x -= a / b * y;-----// 4a
swap(x, y);-----// 26
return d;-----// db
}-----// 9e
}-----// 40
```

5.4. Trial Division Primality Testing.

```
bool is_prime(int n) {-----// 6c
if (n < 2) return false;-----// c9
if (n < 4) return true;-----// d9
if (n % 2 == 0 || n % 3 == 0) return false;-----// 0f
if (n < 25) return true;-----// ef
int s = static_cast<int>(sqrt(static_cast<double>(n)));-----// 64
for (int i = 5; i <= s; i += 6)-----// 6c
if (n % i == 0 || n % (i + 2) == 0) return false;-----// e9
return true; }-----// 43
```

5.5. Miller-Rabin Primality Test.

```
#include "mod_pow.cpp"-----// c7
bool is_probable_prime(ll n, int k) {-----// be
---if (~n & 1) return n == 2;-----// d1
---if (n <= 3) return n == 3;-----// 39
---int s = 0; ll d = n - 1;-----// 37
---while (~d & 1) d >>= 1, s++;-----// 35
---while (k--) {-----// c8
-----ll a = (n - 3) * rand() / RAND_MAX + 2;-----// 06
-----ll x = mod_pow(a, d, n);-----// 64
-----if (x == 1 || x == n - 1) continue;-----// 9b
-----bool ok = false;-----// 03
-----rep(i,0,s-1) {-----// 13
-----x = (x * x) % n;-----// 90
-----if (x == 1) return false;-----// 5c
-----if (x == n - 1) { ok = true; break; }-----// a1
-----}-----// 3a
-----if (!ok) return false;-----// 37
---} return true; }-----// fe
```

5.6. Sieve of Eratosthenes.

```
vi prime_sieve(int n) {-----// 40
---int mx = (n - 3) >> 1, sq, v, i = -1;-----// 27
---vi primes;-----// 8f
---bool* prime = new bool[mx + 1];-----// ef
---memset(prime, 1, mx + 1);-----// 28
---if (n >= 2) primes.push_back(2);-----// f4
---while (++i <= mx) if (prime[i]) {-----// 73
-----primes.push_back(v = (i << 1) + 3);-----// be
-----if ((sq = i * ((i << 1) + 6) + 3) > mx) break;-----// 2d
-----for (int j = sq; j <= mx; j += v) prime[j] = false; }-----// 2e
---while (++i <= mx) if (prime[i]) primes.push_back((i << 1) + 3);-----// 29
---delete[] prime; // can be used for O(1) lookup-----// 36
---return primes; }-----// 72
```

5.7. Modular Multiplicative Inverse.

```
#include "egcd.cpp"-----// 55
-----// e8
int mod_inv(int a, int m) {-----// 49
---int x, y, d = egcd(a, m, x, y);-----// 3e
---if (d != 1) return -1;-----// 20
---return x < 0 ? x + m : x;-----// 3c
}-----// 69
```

5.8. Chinese Remainder Theorem.

```
#include "egcd.cpp"-----// 55
int crt(const vi& as, const vi& ns) {-----// c3
---int cnt = size(as), N = 1, x = 0, r, s, l;-----// 55
---rep(i,0,cnt) N *= ns[i];-----// b1
---rep(i,0,cnt) egcd(ns[i], l = N/ns[i], r, s), x += as[i] * s * l;-----// 21
---return mod(x, N); }-----// b2
```

5.9. Linear Congruence Solver. A function that returns all solutions to $ax \equiv b \pmod{n}$, modulo n .

```
#include "egcd.cpp"-----// 55
vi linear_congruence(int a, int b, int n) {-----// c8
---int x, y, d = egcd(a, n, x, y);-----// 7a
---vi res;-----// f5
---if (b % d != 0) return res;-----// 30
---int x0 = mod(b / d * x, n);-----// 48
---rep(k,0,d) res.push_back(mod(x0 + k * n / d, n));-----// 7e
---return res;-----// fe
}-----// c0
```

5.10. Numeric Integration.

```
double integrate(double (*f)(double), double a, double b,-----// 76
-----double delta = 1e-6) {-----// c0
---if (abs(a - b) < delta)-----// 38
-----return (b-a)/8 *-----// 56
----- (f(a) + 3*f((2*a+b)/3) + 3*f((a+2*b)/3) + f(b));-----// e1
---return integrate(f, a,-----// 64
----- (a+b)/2, delta) + integrate(f, (a+b)/2, b, delta);-----// 0c
}-----// 4b
```

5.11. Fast Fourier Transform. The Cooley-Tukey algorithm for quickly computing the discrete Fourier transform. The fft function only supports powers of twos. The czt function implements the Chirp Z-transform and supports any size, but is slightly slower.

```
#include <complex>-----// 8e
typedef complex<long double> cpx;-----// 25
// NOTE: n must be a power of two-----// 14
void fft(cpx *x, int n, bool inv=false) {-----// 36
---for (int i = 0, j = 0; i < n; i++) {-----// f9
-----if (i < j) swap(x[i], x[j]);-----// 44
-----int m = n>>1;-----// 9c
-----while (1 <= m && m <= j) j -= m, m >>= 1;-----// fe
-----j += m;-----// 11
-----}-----// d0
---for (int mx = 1; mx < n; mx <<= 1) {-----// 15
-----cpx wp = exp(cpx(0, (inv ? -1 : 1) * pi / mx)), w = 1;-----// 79
-----for (int m = 0; m < mx; m++, w *= wp) {-----// dc
-----for (int i = m; i < n; i += mx << 1) {-----// 6a
-----cpx t = x[i + mx] * w;-----// 12
-----x[i + mx] = x[i] - t;-----// 73
-----x[i] += t;-----// 0e
-----}-----// 14
-----}-----// a4
-----}-----// bf
---if (inv) rep(i,0,n) x[i] /= cpx(n);-----// 16
}-----// 1c
void czt(cpx *x, int n, bool inv=false) {-----// c5
---int len = 2*n+1;-----// bc
---while (len & (len - 1)) len &= len - 1;-----// 65
---len <<= 1;-----// 21
---cpx w = exp(-2.0L * pi / n * cpx(0,1)),-----// 45
```

```
-----*c = new cpx[n], *a = new cpx[len],-----// 4e
-----*b = new cpx[len];-----// 30
----rep(i,0,n) c[i] = pow(w, (inv ? -1.0 : 1.0)*i*i/2);-----// 9e
----rep(i,0,n) a[i] = x[i] * c[i], b[i] = 1.0L/c[i];-----// e9
----rep(i,0,n-1) b[len - n + i + 1] = 1.0L/c[n-i-1];-----// 9f
----fft(a, len); fft(b, len);-----// 63
----rep(i,0,len) a[i] *= b[i];-----// 58
----fft(a, len, true);-----// 2d
----rep(i,0,n) {-----// ff
-----x[i] = c[i] * a[i];-----// 77
-----if (inv) x[i] /= cpx(n);-----// b1
----}-----// 27
----delete[] a;-----// 0a
----delete[] b;-----// 5c
----delete[] c;-----// f8
}-----// c6
```

5.12. Formulas.

- Number of ways to choose k objects from a total of n objects where order matters and each item can only be chosen once: $P_k^n = \frac{n!}{(n-k)!}$
- Number of ways to choose k objects from a total of n objects where order matters and each item can be chosen multiple times: n^k
- Number of permutations of n objects, where there are n_1 objects of type 1, n_2 objects of type 2, \dots , n_k objects of type k : $\binom{n}{n_1, n_2, \dots, n_k} = \frac{n!}{n_1! \times n_2! \times \dots \times n_k!}$
- Number of ways to choose k objects from a total of n objects where order does not matter and each item can only be chosen once:
 $\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k} = \binom{n}{n-k} = \prod_{i=1}^k \frac{n-(k-i)}{i} = \frac{n!}{k!(n-k)!}$, $\binom{n}{0} = 1$, $\binom{0}{k} = 0$
- Number of ways to choose k objects from a total of n objects where order does not matter and each item can be chosen multiple times: $f_k^n = \binom{n+k-1}{k} = \frac{(n+k-1)!}{k!(n-1)!}$
- Number of integer solutions to $x_1 + x_2 + \dots + x_n = k$ where $x_i \geq 0$: f_k^n
- Number of subsets of a set with n elements: 2^n
- $|A \cup B| = |A| + |B| - |A \cap B|$
- $|A \cup B \cup C| = |A| + |B| + |C| - |A \cap B| - |A \cap C| - |B \cap C| + |A \cap B \cap C|$
- Number of ways to walk from the lower-left corner to the upper-right corner of an $n \times m$ grid by walking only up and to the right: $\binom{n+m}{m}$
- Number of strings with n sets of brackets such that the brackets are balanced:
 $C_n = \sum_{k=0}^{n-1} C_k C_{n-1-k} = \frac{1}{n+1} \binom{2n}{n}$
- Number of triangulations of a convex polygon with n points, number of rooted binary trees with $n+1$ vertices, number of paths across an $n \times n$ lattice which do not rise above the main diagonal: C_n
- Number of permutations of n objects with exactly k ascending sequences or runs:
 $\langle n \rangle_k = \langle n \rangle_{n-k-1} = k \langle n-1 \rangle_k + (n-k+1) \langle n-1 \rangle_{k-1} = \sum_{i=0}^k (-1)^i \binom{n+1}{i} (k+1-i)^n$, $\langle n \rangle_0 = \langle n-1 \rangle_1 = 1$
- Number of permutations of n objects with exactly k cycles: $[n]_k = \left[n \right]_{k-1} + (n-1) \left[n-1 \right]_k$
- Number of ways to partition n objects into k sets: $\left\{ n \right\}_k = k \left\{ n-1 \right\}_k + \left\{ n-1 \right\}_{k-1}$, $\left\{ n \right\}_0 = \left\{ n \right\}_1 = 1$
- Number of permutations of length n that have no fixed points (derangements): $D_0 = 1, D_1 = 0, D_n = (n-1)(D_{n-1} + D_{n-2})$
- Number of permutations of length n that have exactly k fixed points: $\binom{n}{k} D_{n-k}$
- **Jacobi symbol**: $\left(\frac{a}{b}\right) = a^{(b-1)/2} \pmod{b}$

- **Heron’s formula**: A triangle with side lengths a, b, c has area $\sqrt{s(s-a)(s-b)(s-c)}$ where $s = \frac{a+b+c}{2}$.
- **Pick’s theorem**: A polygon on an integer grid containing i lattice points and having b lattice points on the boundary has area $i + \frac{b}{2} - 1$.
- **Divisor sigma**: The sum of divisors of n to the x th power is $\sigma_x(n) = \prod_{i=0}^r \frac{p_i^{(a_i+1)x}-1}{p_i^x-1}$ where $n = \prod_{i=0}^r p_i^{a_i}$ is the prime factorization.
- **Divisor count**: A special case of the above is $\sigma_0(n) = \prod_{i=0}^r (a_i + 1)$.
- **Euler’s totient**: The number of integers less than n that are coprime to n are $n \prod_{p|n} \left(1 - \frac{1}{p}\right)$ where each p is a distinct prime factor of n .
- **König’s theorem**: In any bipartite graph, the number of edges in a maximum matching is equal to the number of vertices in a minimum vertex cover.
- The number of vertices of a graph is equal to its minimum vertex cover number plus the size of a maximum independent set.
- $\gcd(2^a - 1, 2^b - 1) = 2^{\gcd(a,b)} - 1$

5.13. **Numbers and Sequences.** Some random prime numbers: 1031, 32771, 1048583, 33554467, 1073741827, 34359738421, 1099511627791, 35184372088891, 1125899906842679, 36028797018963971.

6. GEOMETRY

6.1. Primitives.

```
#include <complex>-----// 8e
#define P(p) const point &p-----// b8
#define L(p0, p1) P(p0), P(p1)-----// 30
#define C(p0, r) P(p0), double r-----// 08
#define PP(pp) pair<point,point> &pp-----// a1
typedef complex<double> point;-----// 9e
double dot(P(a), P(b)) { return real(conj(a) * b); }-----// 4a
double cross(P(a), P(b)) { return imag(conj(a) * b); }-----// f3
point rotate(P(p), double radians = pi / 2, P(about) = point(0,0)) { -----// 0b
----return (p - about) * exp(point(0, radians)) + about; }-----// f5
point reflect(P(p), L(about1, about2)) {-----// 45
----point z = p - about1, w = about2 - about1;-----// 74
----return conj(z / w) * w + about1; }-----// d1
point proj(P(u), P(v)) { return dot(u, v) / dot(u, u) * u; }-----// 98
point normalize(P(p), double k = 1.0) { -----// a9
----return abs(p) == 0 ? point(0,0) : p / abs(p) * k; } //TODO: TEST-----// 1c
bool parallel(L(a, b), L(p, q)) { return abs(cross(b - a, q - p)) < EPS; }-----// 74
double ccw(P(a), P(b), P(c)) { return cross(b - a, c - b); }-----// ab
bool collinear(P(a), P(b), P(c)) { return abs(ccw(a, b, c)) < EPS; }-----// 95
bool collinear(L(a, b), L(p, q)) {-----// de
----return abs(ccw(a, b, p)) < EPS && abs(ccw(a, b, q)) < EPS; }-----// 27
double angle(P(a), P(b), P(c)) {-----// 93
----return acos(dot(b - a, c - b) / abs(b - a) / abs(c - b)); }-----// a2
double signed_angle(P(a), P(b), P(c)) {-----// 46
----return asin(cross(b - a, c - b) / abs(b - a) / abs(c - b)); }-----// 80
double angle(P(p)) { return atan2(imag(p), real(p)); }-----// c0
point perp(P(p)) { return point(-imag(p), real(p)); }-----// 3c
double progress(P(p), L(a, b)) {-----// c7
----if (abs(real(a) - real(b)) < EPS)-----// 7d
----return (imag(p) - imag(a)) / (imag(b) - imag(a));-----// b7
```

```
---else return (real(p) - real(a)) / (real(b) - real(a)); }-----// 6c
bool intersect(L(a, b), L(p, q), point &res, bool segment = false) {-----// b4
---// NOTE: check for parallel/collinear lines before calling this function---// 88
---point r = b - a, s = q - p;-----// 54
---double c = cross(r, s), t = cross(p - a, s) / c, u = cross(p - a, r) / c;---// 29
---if (segment && (t < 0-EPS || t > 1+EPS || u < 0-EPS || u > 1+EPS))-----// 30
---    return false;-----// c0
---res = a + t * r;-----// 88
---return true;-----// 03
}-----// 92
point closest_point(L(a, b), P(c), bool segment = false) {-----// 06
---if (segment) {-----// 90
---    if (dot(b - a, c - b) > 0) return b;-----// 93
---    if (dot(a - b, c - a) > 0) return a;-----// bb
---}-----// d5
---double t = dot(c - a, b - a) / norm(b - a);-----// 61
---return a + t * (b - a);-----// 4f
}-----// 19
double line_segment_distance(L(a,b), L(c,d)) {-----// f6
---double x = INFINITY;-----// 8c
---if (abs(a - b) < EPS && abs(c - d) < EPS) x = abs(a - c);-----// 5f
---else if (abs(a - b) < EPS) x = abs(a - closest_point(c, d, a, true));-----// 97
---else if (abs(c - d) < EPS) x = abs(c - closest_point(a, b, c, true));-----// 68
---else if ((ccw(a, b, c) < 0) != (ccw(a, b, d) < 0) &&-----// fa
---    (ccw(c, d, a) < 0) != (ccw(c, d, b) < 0)) x = 0;-----// bb
---else {-----// 5b
---    x = min(x, abs(a - closest_point(c,d, a, true)));-----// 07
---    x = min(x, abs(b - closest_point(c,d, b, true)));-----// 75
---    x = min(x, abs(c - closest_point(a,b, c, true)));-----// 48
---    x = min(x, abs(d - closest_point(a,b, d, true)));-----// 75
---}-----// 60
---return x;-----// 57
}-----// 8e
int intersect(C(A, rA), C(B, rB), point & res1, point & res2) {-----// ca
---double d = abs(B - A);-----// 06
---if ((rA + rB) < (d - EPS) || d < abs(rA - rB) - EPS) return 0;-----// 5d
---double a = (rA*rA - rB*rB + d*d) / 2 / d, h = sqrt(rA*rA - a*a);-----// 5e
---point v = normalize(B - A, a), u = normalize(rotate(B-A), h);-----// da
---res1 = A + v + u, res2 = A + v - u;-----// c2
---if (abs(u) < EPS) return 1; return 2;-----// 95
}-----// 4e
int intersect(L(A, B), C(0, r), point & res1, point & res2) {-----// e4
---double h = abs(0 - closest_point(A, B, 0));-----// f4
---if(r < h - EPS) return 0;-----// 89
---point H = proj(0 - A, B - A) + A, v = normalize((B - A), sqrt(r*r - h*h));// a9
---res1 = H + v; res2 = H - v;-----// ab
---if(abs(v) < EPS) return 1; return 2;-----// f7
}-----// b8
int tangent(P(A), C(0, r), point & res1, point & res2) {-----// 15
---point v = 0 - A; double d = abs(v);-----// 2c
---if (d < r - EPS) return 0;-----// 14
---double alpha = asin(r / d), L = sqrt(d*d - r*r);-----// 45
---v = normalize(v, L);-----// 10
---res1 = A + rotate(v, alpha); res2 = A + rotate(v, -alpha);-----// 56
---if (abs(r - d) < EPS || abs(v) < EPS) return 1;-----// 1d
---return 2;-----// 97
}-----// 46
void tangent_outer(point A, double rA, point B, double rB, PP(P), PP(Q)) {-----// 61
---if (rA - rB > EPS) { swap(rA, rB); swap(A, B); }-----// 2a
---double theta = asin((rB - rA)/abs(A - B));-----// 0a
---point v = rotate(B - A, theta + pi/2), u = rotate(B - A, -(theta + pi/2));// e3
---u = normalize(u, rA);-----// 30
---P.first = A + normalize(v, rA); P.second = B + normalize(v, rB);-----// 08
---Q.first = A + normalize(u, rA); Q.second = B + normalize(u, rB);-----// 2a
}-----// 2d

6.2. Polygon.
#include "primitives.cpp"-----// e0
typedef vector<point> polygon;-----// b3
double polygon_area_signed(polygon p) {-----// 31
---double area = 0; int cnt = size(p);-----// a2
---rep(i,1,cnt-1) area += cross(p[i] - p[0], p[i + 1] - p[0]);-----// 51
---return area / 2; }-----// 66
double polygon_area(polygon p) { return abs(polygon_area_signed(p)); }-----// a4
#define CHK(f,a,b,c) (f(a) < f(b) && f(b) <= f(c) && ccw(a,c,b) < 0)-----// 8f
int point_in_polygon(polygon p, point q) {-----// 5d
---int n = size(p); bool in = false; double d;-----// 69
---for (int i = 0, j = n - 1; i < n; j = i++)-----// f3
---    if (collinear(p[i], q, p[j]) &&-----// 9d
---        0 <= (d = progress(q, p[i], p[j])) && d <= 1)-----// 4b
---        return 0;-----// b3
---for (int i = 0, j = n - 1; i < n; j = i++)-----// 67
---    if (CHK(real, p[i], q, p[j]) || CHK(real, p[j], q, p[i]))-----// b4
---        in = !in;-----// ff
---return in ? -1 : 1; }-----// ba
// pair<polygon, polygon> cut_polygon(const polygon &poly, point a, point b) {-// 0d
//----- polygon left, right;-----// 0a
//----- point it(-100, -100);-----// 5b
//----- for (int i = 0, cnt = poly.size(); i < cnt; i++) {-----// 70
//-----     int j = i == cnt-1 ? 0 : i + 1;-----// 02
//-----     point p = poly[i], q = poly[j];-----// 44
//-----     if (ccw(a, b, p) <= 0) left.push_back(p);-----// 8d
//-----     if (ccw(a, b, p) >= 0) right.push_back(p);-----// 43
//-----     // myintersect = intersect where-----// ba
//-----     // (a,b) is a line, (p,q) is a line segment-----// 7e
//-----     if (myintersect(a, b, p, q, it))-----// 6f
//-----         left.push_back(it), right.push_back(it);-----// 8a
//----- }-----// e0
//----- return pair<polygon, polygon>(left, right);-----// 3d
// }-----// 07

6.3. Convex Hull.
```

```
#include "polygon.cpp"-----// 58
#define MAXN 1000-----// 09
point hull[MAXN];-----// 43
bool cmp(const point &a, const point &b) {-----// 32
    return abs(real(a) - real(b)) > EPS ?-----// 44
    : real(a) < real(b) : imag(a) < imag(b); }-----// 40
int convex_hull(polygon p) {-----// cd
    int n = size(p), l = 0;-----// 67
    sort(p.begin(), p.end(), cmp);-----// 3d
    rep(i,0,n) {-----// e4
        if (i > 0 && p[i] == p[i - 1]) continue;-----// c7
        while (l >= 2 && ccw(hull[l - 2], hull[l - 1], p[i]) >= 0) l--;-----// 62
        hull[l++] = p[i];-----// bd
    }-----// d2
    int r = l;-----// 30
    for (int i = n - 2; i >= 0; i--) {-----// 59
        if (p[i] == p[i + 1]) continue;-----// af
        while (r - l >= 1 && ccw(hull[r - 2], hull[r - 1], p[i]) >= 0) r--;-----// 4d
        hull[r++] = p[i];-----// f5
    }-----// f6
    return l == 1 ? 1 : r - 1;-----// a6
}-----// 6d
```

6.4. Line Segment Intersection.

```
#include "primitives.cpp"-----// e0
bool line_segment_intersect(L(a, b), L(c, d), point &A, point &B) {-----// 6c
    if (abs(a - b) < EPS && abs(c - d) < EPS) {-----// db
        A = B = a; return abs(a - d) < EPS; }-----// ee
    else if (abs(a - b) < EPS) {-----// 03
        A = B = a; double p = progress(a, c,d);-----// c9
        return 0.0 <= p && p <= 1.0-----// 8a
        && (abs(a - c) + abs(d - a) - abs(d - c)) < EPS; }-----// 27
    else if (abs(c - d) < EPS) {-----// 26
        A = B = c; double p = progress(c, a,b);-----// d9
        return 0.0 <= p && p <= 1.0-----// 8e
        && (abs(c - a) + abs(b - c) - abs(b - a)) < EPS; }-----// 4f
    else if (collinear(a,b, c,d)) {-----// bc
        double ap = progress(a, c,d), bp = progress(b, c,d);-----// a7
        if (ap > bp) swap(ap, bp);-----// b1
        if (bp < 0.0 || ap > 1.0) return false;-----// 0c
        A = c + max(ap, 0.0) * (d - c);-----// f6
        B = c + min(bp, 1.0) * (d - c);-----// 5c
        return true; }-----// ab
    else if (parallel(a,b, c,d)) return false;-----// ca
    else if (intersect(a,b, c,d, A, true)) {-----// 10
        B = A; return true; }-----// bf
    return false;-----// b7
}-----// 8b
-----// e6
```

6.5. Great-Circle Distance. Computes the distance between two points (given as latitude/longitude coordinates) on a sphere of radius r .

```
double gc_distance(double pLat, double pLong,-----// 7b
    double qLat, double qLong, double r) {-----// a4
    pLat *= pi / 180; pLong *= pi / 180;-----// ee
    qLat *= pi / 180; qLong *= pi / 180;-----// 75
    return r * acos(cos(pLat) * cos(qLat) * cos(pLong - qLong) +-----// e3
        sin(pLat) * sin(qLat));-----// 1e
}-----// 60
-----// 3f
```

6.6. Triangle Circumcenter. Returns the unique point that is the same distance from all three points. It is also the center of the unique circle that goes through all three points.

```
#include "primitives.cpp"-----// e0
point circumcenter(point a, point b, point c) {-----// 76
    b -= a, c -= a;-----// 41
    return a + perp(b * norm(c) - c * norm(b)) / 2.0 / cross(b, c);-----// 7a
}-----// c3
```

6.7. Closest Pair of Points.

```
#include "primitives.cpp"-----// e0
-----// 85
struct cmpx { bool operator()(const point &a, const point &b) {-----// 01
    return abs(real(a) - real(b)) > EPS ?-----// e9
    : real(a) < real(b) : imag(a) < imag(b); } };-----// 53
struct cmpy { bool operator()(const point &a, const point &b) {-----// 6f
    return abs(imag(a) - imag(b)) > EPS ?-----// 0b
    : imag(a) < imag(b) : real(a) < real(b); } };-----// a4
double closest_pair(vector<point> pts) {-----// f1
    sort(pts.begin(), pts.end(), cmpx());-----// 0c
    set<point, cmpy> cur;-----// bd
    set<point, cmpy>::const_iterator it, jt;-----// a6
    double mn = INFINITY;-----// f9
    for (int i = 0, l = 0; i < size(pts); i++) {-----// ac
        while (real(pts[i]) - real(pts[l]) > mn) cur.erase(pts[l++]);-----// 8b
        it = cur.lower_bound(point(-INFINITY, imag(pts[i]) - mn));-----// fc
        jt = cur.upper_bound(point(INFINITY, imag(pts[i]) + mn));-----// 39
        while (it != jt) mn = min(mn, abs(*it - pts[i])), it++;-----// 09
        cur.insert(pts[i]); }-----// 82
    return mn; }-----// 4c
```

6.8. 3D Primitives.

```
#define P(p) const point3d &p-----// a7
#define L(p0, p1) P(p0), P(p1)-----// 0f
#define PL(p0, p1, p2) P(p0), P(p1), P(p2)-----// 67
struct point3d {-----// 63
    double x, y, z;-----// e6
    point3d() : x(0), y(0), z(0) {}-----// af
    point3d(double _x, double _y, double _z) : x(_x), y(_y), z(_z) {}-----// fc
    point3d operator+(P(p)) const {-----// 17
        return point3d(x + p.x, y + p.y, z + p.z); }-----// 8e
    point3d operator-(P(p)) const {-----// fb
        return point3d(x - p.x, y - p.y, z - p.z); }-----// 83
    point3d operator-() const {-----// 89
```



```
-----return point3d(-x, -y, -z); }-----// d4
---point3d operator*(double k) const {-----// 4d
-----return point3d(x * k, y * k, z * k); }-----// fd
---point3d operator/(double k) const {-----// 95
-----return point3d(x / k, y / k, z / k); }-----// 58
---double operator%(P(p)) const {-----// d1
-----return x * p.x + y * p.y + z * p.z; }-----// 09
---point3d operator*(P(p)) const {-----// 4f
-----return point3d(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x); }-----// ed
---double length() const {-----// 3e
-----return sqrt(*this % *this); }-----// 05
---double distTo(P(p)) const {-----// dd
-----return (*this - p).length(); }-----// 57
---double distTo(P(A), P(B)) const {-----// bd
-----// A and B must be two different points-----// 4e
-----return ((*this - A) * (*this - B)).length() / A.distTo(B); }-----// 6e
---point3d normalize(double k = 1) const {-----// db
-----// length() must not return 0-----// 3c
-----return (*this) * (k / length()); }-----// d4
---point3d getProjection(P(A), P(B)) const {-----// 86
-----point3d v = B - A;-----// 64
-----return A + v.normalize((v % (*this - A)) / v.length()); }-----// 53
---point3d rotate(P(normal)) const {-----// 55
-----// normal must have length 1 and be orthogonal to the vector-----// eb
-----return (*this) * normal; }-----// 5c
---point3d rotate(double alpha, P(normal)) const {-----// 21
-----return (*this) * cos(alpha) + rotate(normal) * sin(alpha); }-----// 82
---point3d rotatePoint(P(0), P(axe), double alpha) const {-----// 7a
-----point3d Z = axe.normalize(axe % (*this - 0));-----// ba
-----return 0 + Z + (*this - 0 - Z).rotate(alpha, 0); }-----// 38
---bool isZero() const {-----// 64
-----return abs(x) < EPS && abs(y) < EPS && abs(z) < EPS; }-----// 15
---bool isOnLine(L(A, B)) const {-----// 30
-----return ((A - *this) * (B - *this)).isZero(); }-----// 58
---bool isInSegment(L(A, B)) const {-----// f1
-----return isOnLine(A, B) && ((A - *this) % (B - *this)) < EPS; }-----// d9
---bool isInSegmentStrictly(L(A, B)) const {-----// 0e
-----return isOnLine(A, B) && ((A - *this) % (B - *this)) < -EPS; }-----// ba
---double getAngle() const {-----// 0f
-----return atan2(y, x); }-----// 40
---double getAngle(P(u)) const {-----// d5
-----return atan2((*this * u).length(), *this % u); }-----// 79
---bool isOnPlane(PL(A, B, C)) const {-----// 8e
-----return abs((A - *this) * (B - *this) % (C - *this)) < EPS; } };;-----// 74
int line_line_intersect(L(A, B), L(C, D), point3d &O){-----// dc
---if (abs((B - A) * (C - A) % (D - A)) > EPS) return 0;-----// 6a
---if (((A - B) * (C - D)).length() < EPS)-----// 79
-----return A.isOnLine(C, D) ? 2 : 0;-----// 09
---point3d normal = ((A - B) * (C - B)).normalize();-----// bc
---double s1 = (C - A) * (D - A) % normal;-----// 68
---0 = A + ((B - A) / (s1 + ((D - B) * (C - B) % normal))) * s1;-----// 56
```

```
-----return 1; }-----// a7
int line_plane_intersect(L(A, B), PL(C, D, E), point3d &O) {-----// 09
---double V1 = (C - A) * (D - A) % (E - A);-----// c1
---double V2 = (D - B) * (C - B) % (E - B);-----// 29
---if (abs(V1 + V2) < EPS)-----// 81
-----return A.isOnPlane(C, D, E) ? 2 : 0;-----// d5
---0 = A + ((B - A) / (V1 + V2)) * V1;-----// 38
-----return 1; }-----// ce
bool plane_plane_intersect(P(A), P(nA), P(B), P(nB), point3d &P, point3d &Q) {--// 5a
---point3d n = nA * nB;-----// 49
---if (n.isZero()) return false;-----// 03
---point3d v = n * nA;-----// d7
---P = A + (n * nA) * ((B - A) % nB / (v % nB));-----// 1a
---Q = P + n;-----// 9c
-----return true; }-----// 1a
```

6.9. Polygon Centroid.

```
#include "polygon.cpp"-----// 58
point polygon_centroid(polygon p) {-----// 79
---double cx = 0.0, cy = 0.0;-----// d5
---double mnx = 0.0, mny = 0.0;-----// 22
---int n = size(p);-----// 2d
---rep(i,0,n)-----// 08
-----mnx = min(mnx, real(p[i]));-----// c6
-----mny = min(mny, imag(p[i]));-----// 84
---rep(i,0,n)-----// 3f
-----p[i] = point(real(p[i]) - mnx, imag(p[i]) - mny);-----// 49
---rep(i,0,n) {-----// 3c
-----int j = (i + 1) % n;-----// 5b
-----cx += (real(p[i]) + real(p[j])) * cross(p[i], p[j]);-----// 4f
-----cy += (imag(p[i]) + imag(p[j])) * cross(p[i], p[j]); }-----// 4a
---return point(cx, cy) / 6.0 / polygon_area_signed(p) + point(mnx, mny); }--// a1
```

6.10. Formulas. Let $a = (a_x, a_y)$ and $b = (b_x, b_y)$ be two-dimensional vectors.

- $a \cdot b = |a||b| \cos \theta$, where θ is the angle between a and b .
- $a \times b = |a||b| \sin \theta$, where θ is the signed angle between a and b .
- $a \times b$ is equal to the area of the parallelogram with two of its sides formed by a and b . Half of that is the area of the triangle formed by a and b .

7. OTHER ALGORITHMS

7.1. 2SAT.

```
#include "../graph/scc.cpp"-----// c3
-----// 63
bool two_sat(int n, const vii& clauses, vi& all_truthy) {-----// f4
---all_truthy.clear();-----// 31
---vvi adj(2*n+1);-----// 7b
---rep(i,0,size(clauses)) {-----// 76
-----adj[-clauses[i].first + n].push_back(clauses[i].second + n);-----// eb
-----if (clauses[i].first != clauses[i].second)-----// bc
-----adj[-clauses[i].second + n].push_back(clauses[i].first + n);-----// f0
---}-----// da
```



```
---pair<union_find, vi> res = scc(adj);-----// 00
---union_find scc = res.first;-----// 20
---vi dag = res.second;-----// ed
---vi truth(2*n+1, -1);-----// c7
---for (int i = 2*n; i >= 0; i--) {-----// 50
-----int cur = order[i] - n, p = scc.find(cur + n), o = scc.find(-cur + n);--// 4f
-----if (cur == 0) continue;-----// cd
-----if (p == o) return false;-----// d0
-----if (truth[p] == -1) truth[p] = 1;-----// d3
-----truth[cur + n] = truth[p];-----// 50
-----truth[o] = 1 - truth[p];-----// 8c
-----if (truth[p] == 1) all_truthy.push_back(cur);-----// 55
---}-----// c3
---return true;-----// eb
}-----// 6b
```

7.2. Stable Marriage.

```
vi stable_marriage(int n, int** m, int** w) {-----// e4
---queue<int> q;-----// f6
---vi at(n, 0), eng(n, -1), res(n, -1); vvi inv(n, vi(n));-----// c3
---rep(i,0,n) rep(j,0,n) inv[i][w[i][j]] = j;-----// f1
---rep(i,0,n) q.push(i);-----// d8
---while (!q.empty()) {-----// 68
-----int curm = q.front(); q.pop();-----// e2
-----for (int &i = at[curm]; i < n; i++) {-----// 7e
-----int curw = m[curm][i];-----// 95
-----if (eng[curw] == -1) { }-----// f7
-----else if (inv[curw][curm] < inv[curw][eng[curw]])-----// d6
-----q.push(eng[curw]);-----// 2e
-----else continue;-----// 1d
-----res[eng[curw] = curm] = curw, ++i; break;-----// a1
-----}-----// c4
---}-----// 3d
---return res;-----// 42
}-----// bf
```

7.3. Algorithm X.

```
bool handle_solution(vi rows) { return false; }-----// 63
struct exact_cover {-----// 95
---struct node {-----// 7e
---node *l, *r, *u, *d, *p;-----// 19
---int row, col, size;-----// ae
---node(int _row, int _col) : row(_row), col(_col) {-----// c9
---size = 0; l = r = u = d = p = NULL; }-----// c3
---};-----// c1
---int rows, cols, *sol;-----// 7b
---bool **arr;-----// e6
---node *head;-----// fe
---exact_cover(int _rows, int _cols) : rows(_rows), cols(_cols), head(NULL) {--// b6
---arr = new bool*[rows];-----// cf
---sol = new int[rows];-----// 5f
---rep(i,0,rows)-----// 9b
```

```
-----arr[i] = new bool[cols], memset(arr[i], 0, cols);-----// dd
}-----// 21
---void set_value(int row, int col, bool val = true) { arr[row][col] = val; }--// 9e
---void setup() {-----// a3
---node ***ptr = new node**[rows + 1];-----// bd
---rep(i,0,rows+1) {-----// 76
---ptr[i] = new node*[cols];-----// eb
---rep(j,0,cols)-----// cd
---if (i == rows || arr[i][j]) ptr[i][j] = new node(i, j);-----// 16
---else ptr[i][j] = NULL;-----// d2
---}-----// ac
---rep(i,0,rows+1) {-----// fc
---rep(j,0,cols) {-----// 51
---if (!ptr[i][j]) continue;-----// f7
---int ni = i + 1, nj = j + 1;-----// 7a
---while (true) {-----// fc
---if (ni == rows + 1) ni = 0;-----// 4c
---if (ni == rows || arr[ni][j]) break;-----// 8d
---++ni;-----// 68
---}-----// ad
---ptr[i][j]->d = ptr[ni][j];-----// 84
---ptr[ni][j]->u = ptr[i][j];-----// 66
---while (true) {-----// 7f
---if (nj == cols) nj = 0;-----// de
---if (i == rows || arr[i][nj]) break;-----// 4c
---++nj;-----// c5
---}-----// 72
---ptr[i][j]->r = ptr[i][nj];-----// 60
---ptr[i][nj]->l = ptr[i][j];-----// 82
---}-----// 0b
---}-----// 16
---head = new node(rows, -1);-----// 66
---head->r = ptr[rows][0];-----// 3e
---ptr[rows][0]->l = head;-----// 8c
---head->l = ptr[rows][cols - 1];-----// 6a
---ptr[rows][cols - 1]->r = head;-----// c1
---rep(j,0,cols) {-----// 92
---int cnt = -1;-----// d4
---rep(i,0,rows+1)-----// bd
---if (ptr[i][j]) cnt++, ptr[i][j]->p = ptr[rows][j];-----// f3
---ptr[rows][j]->size = cnt;-----// c2
---}-----// b9
---rep(i,0,rows+1) delete[] ptr[i];-----// a5
---delete[] ptr;-----// 72
}-----// 19
#define COVER(c, i, j) N-----// 91
c->r->l = c->l, c->l->r = c->r; N-----// 82
for (node *i = c->d; i != c; i = i->d) N-----// 62
for (node *j = i->r; j != i; j = j->r) N-----// 26
j->d->u = j->u, j->u->d = j->d, j->p->size--;-----// c1
#define UNCOVER(c, i, j) N-----// 89
```

```
-----for (node *i = c->u; i != c; i = i->u) N-----// f0
-----for (node *j = i->l; j != i; j = j->l) N-----// 7b
-----j->p->size++, j->d->u = j->u->d = j; N-----// 65
-----c->r->l = c->l->r = c;-----// 0e
----bool search(int k = 0) {-----// f9
-----if (head == head->r) {-----// 75
-----vi res(k);-----// 90
-----rep(i,0,k) res[i] = sol[i];-----// 2a
-----sort(res.begin(), res.end());-----// 63
-----return handle_solution(res);-----// 11
-----}-----// 3d
-----node *c = head->r, *tmp = head->r;-----// a3
-----for ( ; tmp != head; tmp = tmp->r) if (tmp->size < c->size) c = tmp;-----// 41
-----if (c == c->d) return false;-----// 02
-----COVER(c, i, j);-----// f6
----bool found = false;-----// 8d
-----for (node *r = c->d; !found && r != c; r = r->d) {-----// 78
-----sol[k] = r->row;-----// c0
-----for (node *j = r->r; j != r; j = j->r) { COVER(j->p, a, b); }-----// f9
-----found = search(k + 1);-----// fb
-----for (node *j = r->l; j != r; j = j->l) { UNCOVER(j->p, a, b); }-----// 87
-----}-----// 7c
-----UNCOVER(c, i, j);-----// a7
-----return found;-----// c0
----}------// d2
};-----// d7
```

7.4. *nth* Permutation.

```
vector<int> nth_permutation(int cnt, int n) {-----// 78
----vector<int> idx(cnt), per(cnt), fac(cnt);-----// 9e
----rep(i,0,cnt) idx[i] = i;-----// bc
----rep(i,1,cnt+1) fac[i - 1] = n % i, n /= i;-----// 2b
----for (int i = cnt - 1; i >= 0; i--)-----// f9
-----per[cnt - i - 1] = idx[fac[i]], idx.erase(idx.begin() + fac[i]);-----// ee
----return per;-----// ab
}------// 37
```

7.5. Cycle-Finding.

```
ii find_cycle(int x0, int (*f)(int)) {-----// a5
----int t = f(x0), h = f(t), mu = 0, lam = 1;-----// 8d
----while (t != h) t = f(t), h = f(f(h));-----// 79
----h = x0;-----// 04
----while (t != h) t = f(t), h = f(h), mu++;-----// 9d
----h = f(t);-----// 00
----while (t != h) h = f(h), lam++;-----// 5e
----return ii(mu, lam);-----// b4
}------// 42
```

7.6. Dates.

```
int intToDay(int jd) { return jd % 7; }-----// 89
int dateToInt(int y, int m, int d) {-----// 96
----return 1461 * (y + 4800 + (m - 14) / 12) / 4 +-----// a8
```

```
-----367 * (m - 2 - (m - 14) / 12 * 12) / 12 -----// d1
-----3 * ((y + 4900 + (m - 14) / 12) / 100) / 4 +-----// be
-----d - 32075;-----// e0
}------// fa
void intToDate(int jd, int &y, int &m, int &d) {-----// a1
----int x, n, i, j;-----// 00
----x = jd + 68569;-----// 11
----n = 4 * x / 146097;-----// 2f
----x -= (146097 * n + 3) / 4;-----// 58
----i = (4000 * (x + 1)) / 1461001;-----// 0d
----x -= 1461 * i / 4 - 31;-----// 09
----j = 80 * x / 2447;-----// 3d
----d = x - 2447 * j / 80;-----// eb
----x = j / 11;-----// b7
----m = j + 2 - 12 * x;-----// 82
----y = 100 * (n - 49) + i + x;-----// 70
}------// af
```

8. USEFUL INFORMATION

8.1. Tips & Tricks.

- How fast does our algorithm have to be? Can we use brute-force?
- Does order matter?
- Is it better to look at the problem in another way? Maybe backwards?
- Are there subproblems that are recomputed? Can we cache them?
- Do we need to remember everything we compute, or just the last few iterations of computation?
- Does it help to sort the data?
- Can we speed up lookup by using a map (tree or hash) or an array?
- Can we binary search the answer?
- Can we add vertices/edges to the graph to make the problem easier? Can we turn the graph into some other kind of a graph (perhaps a DAG, or a flow network)?
- Make sure integers are not overflowing.
- Is it better to compute the answer modulo n ? Perhaps we can compute the answer modulo m_1, m_2, \dots, m_k , where m_1, m_2, \dots, m_k are pairwise coprime integers, and find the real answer using CRT?
- Are there any edge cases? When $n = 0, n = -1, n = 1, n = 2^{31} - 1$ or $n = -2^{31}$? When the list is empty, or contains a single element? When the graph is empty, or contains a single vertex? When the graph contains self-loops? When the polygon is concave or non-simple?
- Can we use exponentiation by squaring?

8.2. Fast Input Reading.

```
void readn(register int *n) {-----// dc
----int sign = 1;-----// 32
----register char c;-----// a5
----*n = 0;-----// 35
----while((c = getc_unlocked(stdin)) != '\n') {-----// f3
-----switch(c) {-----// 0c
-----case '-': sign = -1; break;-----// 28
-----case ' ': goto hell;-----// fd
-----case '\n': goto hell;-----// 79
-----default: *n *= 10; *n += c - '0'; break;-----// c0
-----}-----// 2d
```

```
----}------// c3
hell:-----// ba
----*n *= sign;-----// a0
}------// 67
```

8.3. Bit Hacks.

- $n \& -n$ returns the first set bit in n .
- $n \& (n - 1)$ is 0 only if n is a power of two.
- `snoob(x)` returns the next integer that has the same amount of bits set as x . Useful for iterating through subsets of some specified size.

```
int snoob(int x) {-----// 73
----int y = x & -x, z = x + y;-----// 12
----return z | ((x ^ z) >> 2) / y;-----// 97
}------// 14
```