

Convex Hull

Approximate Convex Hull

Junhui DENG

deng@tsinghua.edu.cn

Thinking Approximation

❖ Why approximation?

- 1) Exact CH algorithms usually take much more time
- 2) In many applications, approximate convex hulls are good enough

❖ Not like the exact algorithms,

approximate algorithms are **not** guaranteed

to compute the **precise** hull

❖ How **better** is the approximation? And

how to estimate and bound the **error**?

Approximate Convex Hull

❖ Divide the plane into k vertical **strips** with a **uniform** width

$$(x_{\max} - x_{\min}) / k$$

❖ Find the highest/lowest point inside each strip

(what if an empty strip?)

❖ Connect all **highest**/**lowest** points in turn

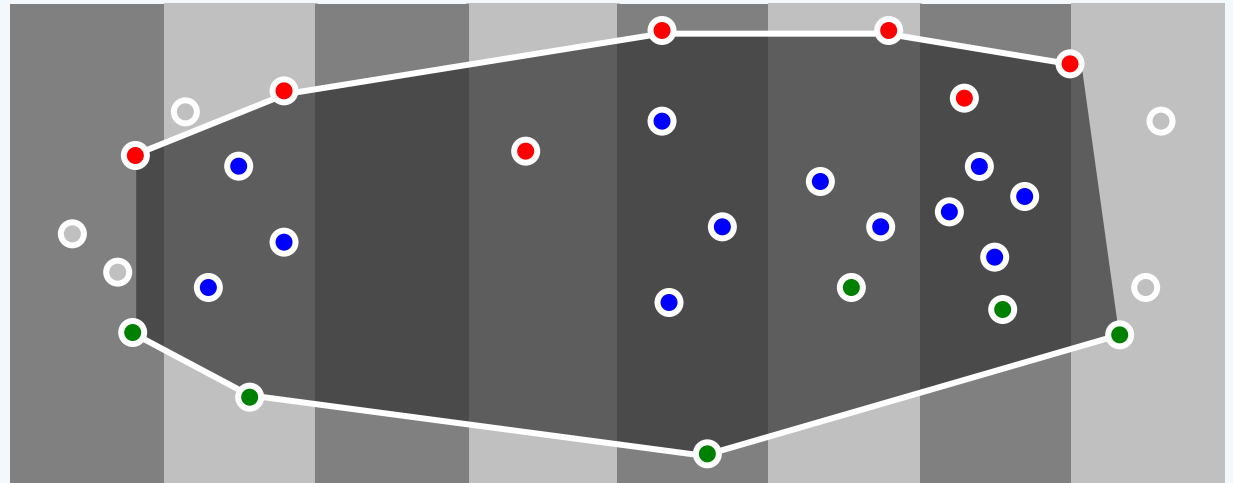
into a chain **monotone** w.r.t.

$$(\theta, -\infty) / (\theta, +\infty)$$

❖ Apply Graham scan

to compute the upper/lower hull

❖ Concatenate upper & lower hulls



Complexity

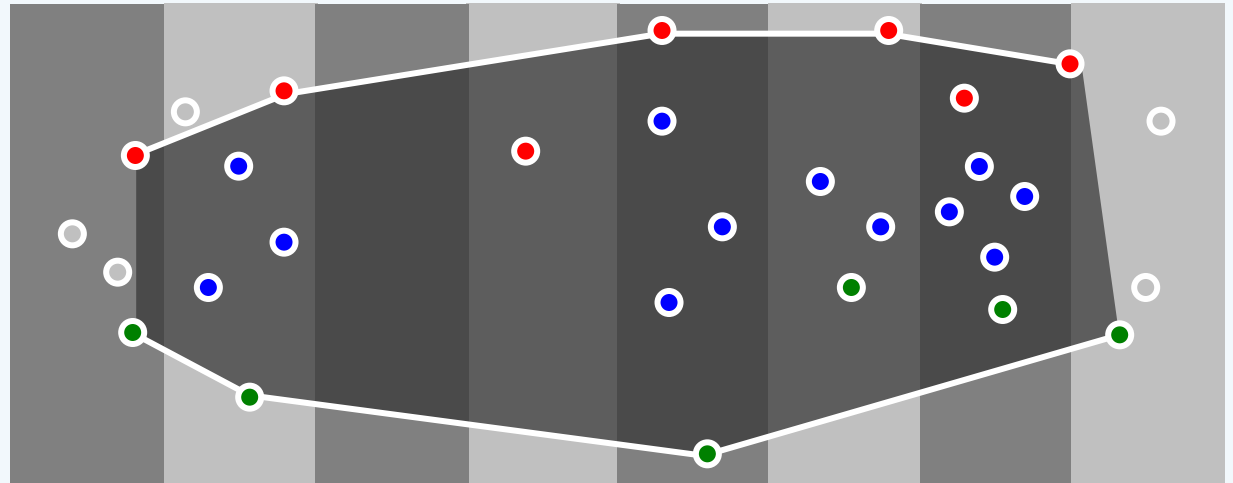
❶ Finding the leftmost and rightmost points costs $\Theta(n)$ time

❷ Finding the highest & lowest points in each strip

costs $\Theta(n)$ time all together

❸ Graham scan costs $\Theta(k)$ time,
where k is the number of strips

❖ An approximate convex hull
of n points in the plane
can be computed in $\Theta(n+k)$ time



Accuracy

- ❖ It is possible for some points to **escape** from the constructed hull
- ❖ Luckily they won't escape **too far away**
- ❖ Any point of P that lies outside the approximate hull is within a distance $(x_{\max} - x_{\min}) / k$ of the hull
- ❖ That means,
the error of approximate hull
is no more than the strip width

