

Geometric Range Search

Range Tree: Query

- Algorithm

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```
1. Determine the canonical subsets of points that
  satisfy the first query
  // there will be O(\log n) such canonical sets,
  // each of which is just represented as
  // a node in the x-tree
2. Find out from each canonical subset
     which points lie within the y-range
  // To do this,
  // for each canonical subset,
           we access the y-tree for the corresponding node
  // this will be again a [1D] range search (on the [y]-range)
                                                Computational Geometry, Tsinghua University
```