Geometric Intersection

Detecting Intersection Between Convex Polygons

Decrease-And-Conquer

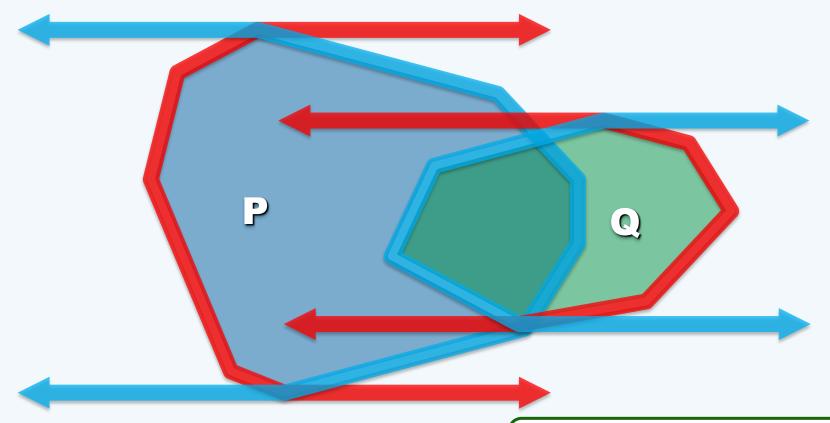
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Data Structure

❖ To apply a (variant of) binary search on the chains,

we store each semi-infinite convex chain in a sorted array



```
Detect_Intersection_Between(|P_L|, |Q_R|)
♦ If \max(|P_L|, |Q_R|) < 2
     return Trivial_Intersection(|P_1|, |Q_R|)
                                                                         //base
  Let [e_p] / [e_0] = the | median edge | of <math>[P_1] / [Q_R]
                                                                   //O(1) time
  Let |\nabla| = intersection of the 2 lines coinciding with |e_p| and |e_0| resp.
  Determine either //by the relative positions of [e_p], [e_0] and [v]
   - that the polygons intersect, or
                                                                   //O(1) time
   - that half of | P_i | or/and | P_o | can be eliminated
                                                                   //O(1) time
     from further considerations (recursion)
```