

Geometric Intersection

B0 Algorithm: Analysis

- Complexity of Event Queue

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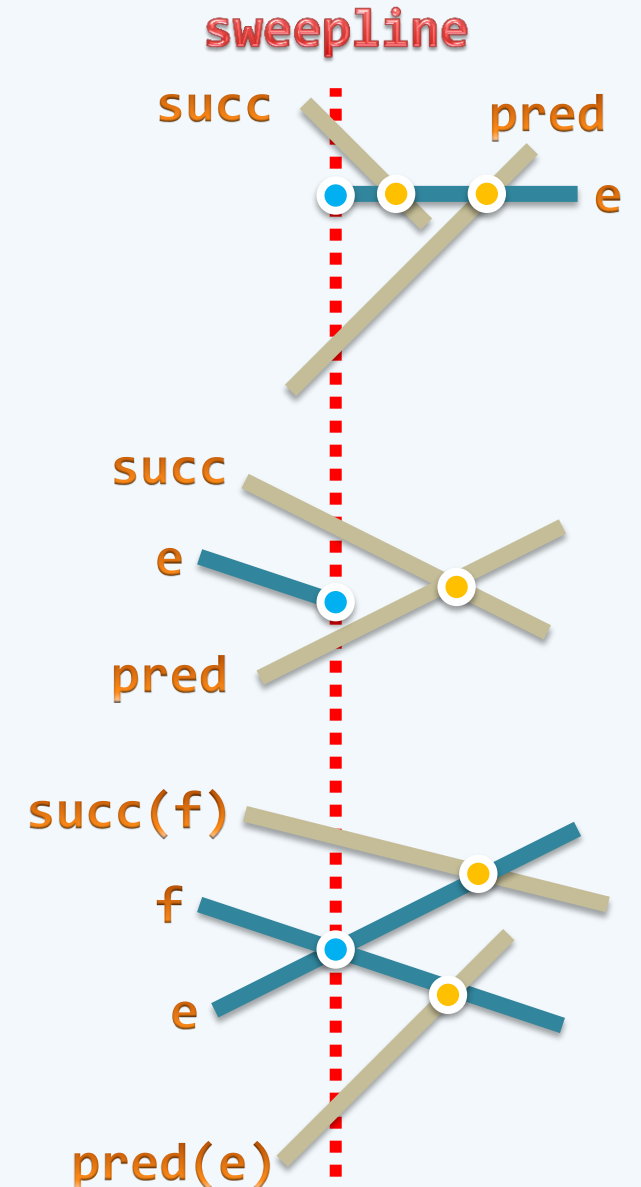
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Single Operation

- ❖ The time cost of the algorithm is dominated by those spent on updating the data structures



- ❖ Since \mathcal{E}/\mathcal{L} is implemented as PQ/BBST , each operation (query/insertion/deletion) can be done in $\mathcal{O}(\log S)$ time where S is the size of \mathcal{E}/\mathcal{L}
- ❖ What's the maximum size of \mathcal{E}/\mathcal{L} ?



Size of \mathcal{E}

- ❖ As we have seen, \mathcal{E} consists of events to be processed
- ❖ All events are classified into 3 types:

n left endpoints (blue)

n right endpoints (yellow)

I intersection points (red)



- ❖ \mathcal{E} would contain no more than $2n + I$ events at any time
- ❖ So the time for each operation is

$$O(\log(2n + I)) = O(\log(2n + n^2)) = O(\log n)$$

Maximum Size of \mathcal{E}

- ❖ Is it possible for \mathcal{E} to have a size up to $\Omega(2n + 1) = \Omega(n^2)$ at a time?
- ❖ By how many will $|\mathcal{E}|$ increase after each event?

No more than 1!

- left-endpoint:

$$\leq -1 + 2 = 1$$

- right-endpoint:

$$\leq -1 + 1 = 0$$

- intersection:

$$\leq -1 + 2 = 1$$

- ❖ Besides the updating operations,

how much time is required to initialize \mathcal{E} ?

