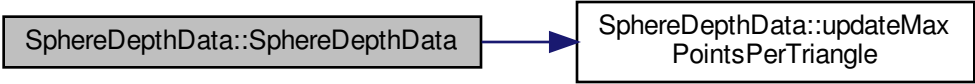


SphereDepthData::SphereDepthData



```
graph LR; A[SphereDepthData::SphereDepthData] --> B[SphereDepthData::updateMaxPointsPerTriangle]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'SphereDepthData::SphereDepthData'. The right box is white and contains the text 'SphereDepthData::updateMaxPointsPerTriangle'. A blue arrow points from the right side of the left box to the left side of the right box.

SphereDepthData::updateMax
PointsPerTriangle