

Basic Operations of PyParty

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0.1 Imports/configuration

```
In [17]: pylabl.rcParams['figure.figsize'] = 8, 5.5
import numpy as np
```

Part I

PyParty Tutorial

1 The Canvas Class

Canvas is the primary object that users will deal with in the pre-alpha version of pyparty. The canvas itself is a composite class, storing both an image (numpy.ndarray: .image) and a custom container for storing and manipulating particles (pyparty.ParticleManager: .particles).

To create a canvas, which is an image (ndarray) and a special container (ParticleManager) that stores, tracks and draws particles into the image (via array indexing).

The canvas tries to acts as an intuitive hybrid object for an image with particles, and selectives promotes the API of both images. For example, the public attribute *particles* hides the underlying *ParticleManager* instance, and instead returns particles as a list of tuples.

The reason that *_particles* is a private method is because Canvas promotes its own ParticleManager api through *particles*, which be default, returns a list of particle names (see next section). Since canvas is a composite class between an ndarray and Particle manager, I decided that attribute lookup should defer to the image (eg):

```
In [20]: print c.image.shape
print c.shape #

(512, 512, 3)
(512, 512, 3)
```

While slicing/indexing (see below) should defer to the particles, as the user could easily manipulate the image before and after applying particles.

2 Adding particles

Particles can be added to an image in a variety of ways.

2.1 Manually by passing parameters

First let's see what available particle types there are:

```
Out [22]: ['centered_particle', 'edge_particle', 'outside_particle']
```

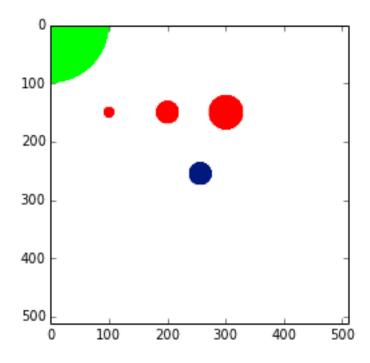
If we don't provide a name, they are automatically generated of the form (shape_index):

```
In [23]: for idx, r in enumerate( (10, 20, 30) ):
    c.add('circle', radius=r, center=(150, 100*(idx+1)), color=(1, 0, 0))
    auto_named = [p for p in c.particles if p not in named]
    auto_named
```

```
Out [23]: ['circle_4', 'circle_3', 'circle_5']
```

At any point, the image with drawn particles can be visualized with show(), a wrapper to matplotlib.plt.imshow()

```
In [24]: c.show();
```



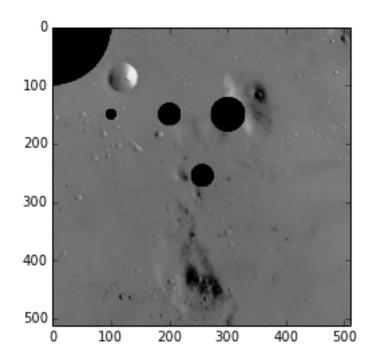
Notice that the large circles wrap around the corners. This is automatically done when image[rr, cc, :] is called...

3 Background images

The default background is a $(1024 \times 768 \times 3)$ rgb array set to white. This was used implicitly above. We can actually pass any array (ie image) and the particles will be redrawn over it. In the next cell, we'll load an image from skimage's pre-packaged data.

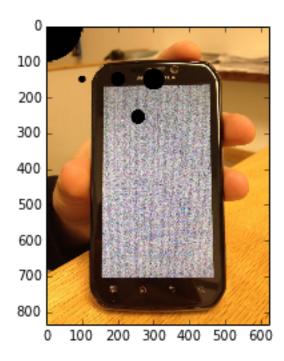
```
In [25]: from skimage.data import moon
    c.background = moon()
    c.show();

12-12 22:16:07 WARNING pyparty.tools.canvas: background color has been converted (from grayscale to RGB)
```



3.1 Image from harddrive/higher-resolution image:

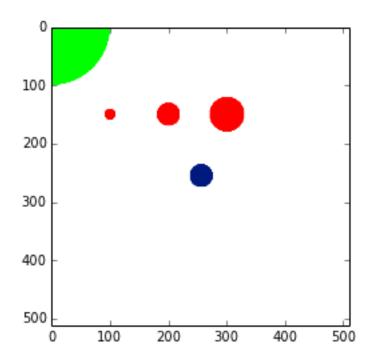
Relative or absolute paths should be automatically detected. The image is returned by *load_background()*.



The particles appear smaller because the resolution of this second image is larger. It is important to keep in mind that particle coordinates are absolute in pixels, so they Notice that the circles are applied to this image (top corner), but are black(BUG?).

3.2 Clearing background

```
In [27]: c.clear_background()
   c.show();
```



4 Integration with scikit image

The canvas object publicizes a few image attributes for convienence for example:

- shape
- ndim
- dtype

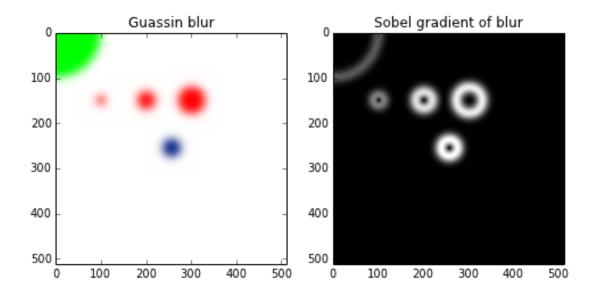
However, when using ndarray functions, pass the .image array directly.

```
In [28]: from skimage.filter import gaussian_filter, sobel
from skimage.color import rgb2gray

fig, (ax1, ax2) = plt.subplots(nrows=1, ncols=2, figsize=(8,8))

c_filtered = gaussian_filter(c.image, 10)
ax1.imshow(c_filtered)
ax1.set_title('Guassin blur')

# Sobel requires gray image; we convert from rgb
c_sobel = sobel(rgb2gray(c_filtered))
ax2.imshow(c_sobel, plt.cm.gray)
ax2.set_title('Sobel gradient of blur');
```



ONE IMPORTANT CAVEAT: Since guassian_filter returns an array, c_filtered is no longer a *Canvas*. I may add some support later to return a *Canvas* object with it's image attribute overwritten; however, one should keep in mind that the underlying particles **are unchanged** by the guassian filter; only the final "drawn" image has been altered. It may therefore be misleading to add this feature because one would need to remain aware that these blurry particles are not representative of what is actually stored by the Canvas. In any case, this is at least a little more convienent than referring to c.image so often!

```
In [29]: type(c), type(c_filtered)
Out [29]: (pyparty.tools.canvas.Canvas, numpy.ndarray)
```

5 Multiplots with matplotlib

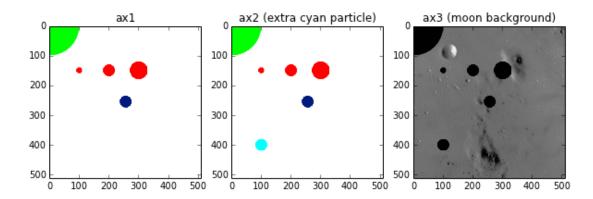
Canvas has a .show() method that wraps imshow. This has been called already above to produce the output images. .show() also optionally accepts AxesSubPlot objects from matplotlib (these are returned by plt.subplots()). Thus, it's easy to create multiple plots

```
In [30]: fig, (ax1, ax2, ax3) = plt.subplots(nrows=1, ncols=3, figsize = (10,10))
    ax1.set_title('ax1')
    c.show(ax1)

#Add a particle
    c.add('circle', name='cyanparticle', radius=20, center=(400,100), color=(0 ax2.set_title('ax2 (extra cyan particle)')
    c.show(ax2)

#Reuse an old background for plot, then clear it
    ax3.set_title('ax3 (moon background)')
    c.background = moon()
    c.show(ax3);
```

12-12 22:16:10 WARNING pyparty.tools.canvas: background color has been converted (from grayscale to RGB)

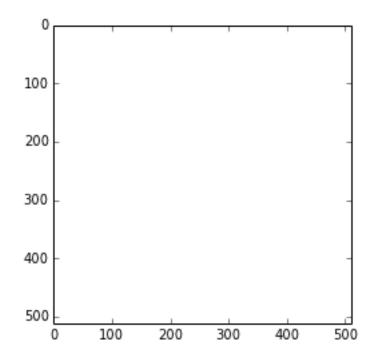


5.1 Clearing the particles/objects

The important methods are:

- remove(index or name): Removes a single particle from canvas #NOT YET IMPLELMENTED
- clear_background(): Removes all particles from the canvas
- clear_particles(): Resets the background image to the default
- clear_canvas(): Removes all particles and resets the background

First, let's clear out the cyan particle that was just added. Since we named it "cyanparticle", this it is easy to access



6 Indexing/Slicing