

# blib Code Reference v1.2

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## blib

blib - a bash library

The basic functions which are imported by default.

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version: Execute **blib version** or use **b\_version**.

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**The above statements apply to all modules of blib if not mentioned otherwise.**

## Coding Conventions

1. embrace the KISS principle
2. some general guidelines: <http://www.kfirlavi.com/blog/2012/11/14/defensive-bash-programming/>
3. use `b_[module]_[camel case function name]` to denote functions meant to be used by users of the library, `B_[module]_[upper case var name]` for global variables
4. use `BLIB_[module]_[upper case var name]` for global variables (to be avoided whenever possible) not meant to be used by library users (“private” variables); library users can use setters or getters
5. use the `BLIB_STORE` with the above naming conventions for “private” variables whenever possible
6. use `blib_[module]_[camel case function name]` to denote private functions not meant to be used by library users; the function name should not contain any underscores
7. the blib module itself is the only exception which can use `b_`, `B_`, `blib_`, `BLIB_` without module name
8. prefixes such as `t_`, `T_` and `UTD_` are exclusively related to test code
9. set exit codes (`!= 0 -> issue`) wherever it makes sense
10. keep the global namespace clean whenever possible
11. declare `-g` must be used in order to allow sourcing from a function (`b_import`)
12. modules must implement a function such as  
*b\_*[module]*\_getDeps*  
*returns:* newline-separated list of dependencies of the module

13. modules should provide a header similar to that of the blib source file in order to make the documentation generation work
14. modules may be placed in subfolders of arbitrary depth
15. use 0 to indicate true and 1 to indicate false for variables; for exit codes use a non-zero exit code to indicate the number of errors
16. functions should be tagged with the following tags, if applicable:
  - @StateChanging* - the function changes the internal state of the script in a way that will not propagate to supershells (e.g. global variables) and should thus not be called from subshells (unless the user wants the state to only change in that shell)
  - @B\_E* - the function uses B\_E for error handling and may thus behave differently depending on the implemented error handler

## Library Usage

with the default bash options:

```
source blib
b_checkVersion 1 0 || { >&2 echo "This script depends on blib (https://github.com/3hhh/blib)"
b_import [module]
```

## Dependencies

dirname  
readlink  
whoami  
sort  
cat  
mktemp  
rm  
su

## Global Variables

### B\_TEST\_MODE

*blib/B\_TEST\_MODE*

blib will set this variable to 0, if blib is running in test mode.

This variable may be used to bypass code during testing, if bats cannot test that code due to its limitations (e.g. for EXIT traps which bats uses for itself).

## **B\_CALLER\_NAME**

*blib/B\_CALLER\_NAME*

Name of the executable or script as String which called blib and any child libraries.

## **B\_ERR**

*blib/B\_ERR*

Global variable used for error handling throughout blib, cf. B\_E.

It is recommended to always set an at least partially static error message on confirmed errors as variables may be empty (which would indicate “no error” for B\_E).

## **B\_RC**

*blib/B\_RC*

Can be used to set the return code for B\_E in the case of an error. It defaults to 1.

This should be set to an integer value between 1 and 255. Any other value may cause undefined behaviour.

## **B\_LIB\_DIR**

*blib/B\_LIB\_DIR*

Path of the blib installation directory.

## **B\_SCRIPT**

*blib/B\_SCRIPT*

Global variable which can be used to obtain the two global variables B\_SCRIPT\_DIR and B\_SCRIPT\_NAME as follows:

```
eval "$B_SCRIPT"
```

## **B\_SCRIPT\_NAME**

*blib/B\_SCRIPT\_NAME*

Path of the sourced or executed bash script executing the eval (symlinks are resolved) of B\_SCRIPT.

## **B\_SCRIPT\_DIR**

*blib/B\_SCRIPT\_DIR*

Name of the sourced or executed bash script executing the eval (symlinks are resolved) of B\_SCRIPT.

## **Global Aliases**

Alias expansion is automatically enabled by blib as it is required for its core functionality. So if you have strange aliases defined in your shell environment, this may cause undefined blib behaviour.

## **B\_E**

*blib/B\_E*

The blib error handler: All blib modules use it whenever execution errors require special handling that the currently executing code cannot achieve.

Syntax:

```
B_ERR="This is an error message." ; B_E ;
```

If you need to set the return/exit code, you can do it with B\_RC:

```
B_ERR="This is another error message." ; B_RC=6 ; B_E ;
```

Calling B\_E means:

Check B\_ERR for an error message and if there is one, handle it. It can be placed at the end of a line or on its own line. B\_E will then process the error message in the way defined by the error handler (cf. b\_defaultErrorHandler) and stop any further execution of code in the current context (function, script, ...) returning a non-zero exit code (1) unless the described error was fixed. In the latter unlikely case it'll let execution proceed.

The error handler can be re-defined at runtime with b\_setErrorHandler.

## **Functions**

### **b\_printStackTrace [skip level]**

*blib/b\_printStackTrace*

[skip level]: skip that many levels of the stack trace (optional, default: 1 - skip this function call)

print the current stack trace in a human readable way

**returns:** stack trace with the first levels skipped as defined

## **b\_\_nop**

*blib/b\_\_nop*

Do nothing.

**returns:** nothing; sets a zero exit code

## **b\_\_version [part]**

*blib/b\_\_version*

Get the version of this blib instance.

[part]: Optional parameter defining the part of the version to retrieve (0: all as String (default), 1: major as Integer, 2: minor as Integer).

**returns:** blib version as string; always sets a zero exit code

## **b\_\_checkVersion [minimum allowed major] [minimum allowed minor] [maximum allowed major] [maximum allowed minor]**

*blib/b\_\_checkVersion*

Check whether the currently running blib instance meets the given blib version requirements.

To e.g. make sure you're on blib version 1.1 or higher, use

```
source blib
b__checkVersion 1 2 || { >&2 echo "This script depends on blib (https://github.com/3hhh/blib)"
```

[minimum allowed major]: The lowest acceptable major version number (default: 0).

[minimum allowed minor]: The lowest acceptable minor version number (default: 0).

[maximum allowed major]: The highest acceptable major version number (default: infinite).

[maximum allowed minor]: The highest acceptable minor version number (default: infinite).

**returns:** Sets a zero exit code, if and only if the currently running blib instance meets the version requirements.

## **b\_\_defaultErrorHandler [error out] [send err] [send stack trace]**

*blib/b\_\_defaultErrorHandler*

The blib default error handler.

As any error handler it must



1. handle the error message (if not the error itself) lying in B\_ERR
2. not take any non-numeric arguments
3. not error out itself
4. implement the below *[error out]* as its first parameter (to make b\_setBE work)
5. ideally use b\_error to send error messages to the user
6. return one of the following exit codes:
  - a) 0: **if and only if** the error was fixed entirely and the caller may ignore the error (i.e. probably never)
  - b) 1: The error wasn't fixed. Functions should return to their caller indicating an error (non-zero status code). Direct shell calls will exit. B\_ERR is **not** reset to blank, i.e. the next call to B\_E in the same context will cause another error. The caller may use this to either *throw* the error further or handle and clear the error.
  - c) 2: Force a stop of execution in the current shell / error out.

[error out]: Whether or not to call exit after the error message handling, if the error couldn't be handled (default: 0 = always error out / call exit). If set to 1, B\_E will allow e.g. functions to return to their callers.

[send err]: Whether or not to send the error message to the user (default: 0 = send).

[send stack trace]: Whether or not to send a stack trace to the user (default: 0 = send).

**returns:** see the description above

### **b\_setBE [error out]**

*blib/b\_setBE*

Set the [error out] behaviour of the currently configured error handler.

Contrary to b\_setErrorHandler this function may be called by blib modules as all error handlers are required to support [error out] as parameter.

Example for switching the error out behaviour:

```
b_setBE 1
funcThatMayCallB_E #without subshell
ret=$?
b_resetErrorHandler
```

[error out]: see b\_\_defaultErrorHandler (default: 0)

**returns:** nothing, always sets a zero exit code

*@StateChanging*

### **b\_\_setErrorHandler [handler]**

*blib/b\_\_setErrorHandler*

Set the error handler for all future executions of B\_E in the current scope.

You can do this in e.g. subshells to limit the effect.

blib modules should only use this function if absolutely necessary to temporarily modify the error behaviour whilst making sure that b\_resetErrorHandler is called in the end. Otherwise it will prevent library users from setting the general behaviour in their scripts.

Usually you do not want to write an entirely new handler, but modify the b\_defaultErrorHandler parameters with this setter or use b\_setBE for that.

[handler]: Function to handle errors. See b\_defaultErrorHandler for details.

**returns:** nothing

*@StateChanging*

### **b\_\_resetErrorHandler [reset B\_\_ERR]**

*blib/b\_\_resetErrorHandler*

Set the error handler to whatever it was before the last call to b\_setErrorHandler or b\_setBE.

[reset B\_\_ERR]: Whether or not to also reset B\_\_ERR (default: true/0).

**returns:** nothing, always sets a zero exit code

*@StateChanging*

### **b\_\_getErrorHandler**

*blib/b\_\_getErrorHandler*

Get the currently for B\_E configured error handler.

**returns:** the error handler function

### **b\_\_silence [function] [param 1] .. [param p]**

*blib/b\_\_silence*

Call the given function with its parameters in the current shell context whilst suppressing all of its output to both stdout and stderr. Anything written to B\_\_ERR however is passed to B\_E (which can still write to stderr).

This function is useful when you want to keep an error message set with B\_\_ERR, but discard everything else.

In contrast `yourfunction &> /dev/null` may also drop the error message, if you're using an error handler (see `B_E`) that writes to `stdout` or `stderr`.

[function]: The function to execute.

[param p]: An arbitrary number of function parameters.

**returns:** Sets the status code of the called function, but doesn't print anything. `B_E` is called on errors.

*@B\_E*

**b\_defaultMessageHandler** [message type] [message] [first part] [last part]

*blib/b\_defaultMessageHandler*

Handles the given message by printing information to `stdout` and errors to `stderr`. This is the default message handler used by `blib`. It can be changed by `b_setMessageHandler`.

Message handler implementations must support at least the parameters of this function, but may add additional parameters.

[message type]: 0=informational message, 1=error message.

[message]: String representing the message.

[first part]: If set to 0, assume that the given message is the first part of an overall chain of messages (default: 0).

[last part]: If set to 0, assume that the given message is the final part of an overall chain of messages (default: 0).

**returns:** Nothing. Never causes errors.

**b\_setDefaultMessageHandlerIntermediate** [intermediate]

*blib/b\_setDefaultMessageHandlerIntermediate*

[intermediate]: String to use as intermediate between two message parts with `b_defaultMessageHandler`, i.e. the resulting message should be [part 1][intermediate][part 2]. Default: Space.

**returns:** Nothing.

**b\_getDefaultMessageHandlerIntermediate**

*blib/b\_getDefaultMessageHandlerIntermediate*

Get the currently configured intermediate string for the `b_defaultMessageHandler`.

**returns:** The intermediate String.

**b\_info** [message] [first part] [last part] [message handler param 1] ...  
[message handler param n]

*blib/b\_info*

Send an informational message to the user. The message is dispatched via the currently configured message handler (default: `b_defaultMessageHandler`).

[message]: to send

[first part]: If set to 0, assume that the given message is the first part of an overall chain of messages (default: 0).

[last part]: If set to 0, assume that the given message is the final part of an overall chain of messages (default: 0).

[message handler param i]: Arbitrary parameters to pass to the currently configured message handler (cf. `b_setMessageHandler`).

**returns:** Nothing, always sets a zero exit code.

**b\_error** [message] [first part] [last part] [message handler param 1]  
... [message handler param n]

*blib/b\_error*

Send an error message to the user *without* erroring out. The message is dispatched via the currently configured message handler (default: `b_defaultMessageHandler`).

99.9% of all users will want to use the combination of `B_ERR` and `B_E` for proper error handling instead.

[message]: to send

[first part]: If set to 0, assume that the given message is the first part of an overall chain of messages (default: 0).

[last part]: If set to 0, assume that the given message is the final part of an overall chain of messages (default: 0).

[message handler param i]: Arbitrary parameters to pass to the currently configured message handler (cf. `b_setMessageHandler`).

**returns:** Nothing, always sets a zero exit code.

**b\_setMessageHandler** [handler]

*blib/b\_setMessageHandler*

Set the handler used to send messages to the user. By default, `b_defaultMessageHandler` is used.

[handler]: Function to handle the messages. See `b__defaultMessageHandler` for the requirements.

**returns:** Nothing.

### **b\_\_getMessageHandler**

*blib/b\_\_getMessageHandler*

Get the currently configured message handler.

**returns:** The message handler.

### **b\_\_enforceUser [user name]**

*blib/b\_\_enforceUser*

enforce that the user is the given one and if not, exit the script and set a non-zero status code

[user name]: user name to check against

**returns:** nothing

*@B\_\_E*

### **b\_\_isFunction [potential function name]**

*blib/b\_\_isFunction*

check whether the given function is defined

**returns:** zero exit code if the function is defined

### **b\_\_getBlibModules**

*blib/b\_\_getBlibModules*

get all available blib module names as a newline-separated list

**returns:** all available blib module names as newline-separated list

### **b\_\_listContains [list] [entry]**

*blib/b\_\_listContains*

check whether the given list contains the given entry

[list]: newline-separated list

[entry]: string to be found on a single line within the list (equality check)

**returns:** a zero exit code if the list contains the entry; a non-zero exit code otherwise

### **b\_\_checkDeps [list]**

*blib/b\_\_checkDeps*

check whether the given list of dependencies is met by the system running this function.

[list]: newline-separated list of binaries or commands that the system must be able to execute

**returns:** list of dependencies not met; a non-zero exit code is set, if the list contains elements

### **b\_\_blib\_\_getDeps**

*blib/b\_\_blib\_\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_\_import [module] [double import]**

*blib/b\_\_import*

Import the given module into the current context.

[module]: relative path of the module to import (relative to the blib/lib root directory)

[double import]: if set to 1, import the given module regardless of whether it was imported before (default: 0 = don't do duplicate imports)

**returns:** nothing, errors out if the import failed and sets a non-zero status code; if the import was successful or previously done, a zero exit code is set

*@StateChanging*

*@B\_E*

### **b\_\_generateStandalone [function] [module dep 1] .. [module dep n] - [function dep 1] .. [function dep d] - [function param 1] .. [function param p]**

*blib/b\_\_generateStandalone*

Create a standalone variant of blib in a single file running the given function when called (sourcing that file will only make the functions available) and print that file to stdout.

The current execution state is not retained.

[function]: The function to call when the generated script is executed. All script parameters when calling [output file] are passed to this function. The function must be available in the current context.

[module dep i]: Names of the modules to include in the standalone file. They do not need to be imported.

[-]: Dash used as separator between the various types of arguments. If none is provided, all parameters are assumed to be modules.

[function dep j]: An arbitrary number of functions that need to be added in order to satisfy the dependencies of the function to call (e.g. if function A is meant to be called, but uses function B internally, you'll have to pass B as one of its dependencies). Dependencies that can be found in added modules should *not* be added.

[function param p]: Static parameters to add to the function as single String. Dynamic parameters should be passed to the generated script.

**returns:** Sets a zero exit code and prints the output file to stdout on success. May error out otherwise.

@B\_E

**b\_execFuncInCurrentContext** [function] [module dep 1] .. [module dep n] - [function param 1] .. [function param p]

*blib/b\_execFuncInCurrentContext*

Execute the given function in the current context.

[function]: The function to execute.

[module dep i]: Names of the modules required by the function. They do not need to be imported by the function itself.

[-]: A dash as separator character between the various parameters.

[function param p]: An arbitrary number of function parameters.

**returns:** Whatever the executed function returns.

**b\_execFuncAs** [user] [function] [module dep 1] .. [module dep n] - [function dep 1] .. [function dep d] - [function param 1] .. [function param p]

*blib/b\_\_execFuncAs*

Attempt to execute the Bash function as the given user.

Whether or not this works highly depends on the underlying OS and its (sudo & su) configuration. In particular this function may cause further execution to wait for the user to type in the password of the requested user.

If the given user is identical to the current user, *b\_\_execFuncAs* may decide to run the function in the current context. Otherwise it may run in a different process.

[user]: User to execute the function as (default: root).

[function]: The function to execute.

[module dep i]: Names of the modules required by the function. They do not need to be imported by the function itself.

[-]: A dash as separator character between the various parameters.

[function dep j]: An arbitrary number of functions that need to be added in order to satisfy the dependencies of the function to call (e.g. if function A is meant to be called, but uses function B internally, you'll have to pass B as one of its dependencies). Dependencies that can be found in added modules should *not* be added.

[function param p]: An arbitrary number of function parameters.

**returns:** Whatever the executed function returns. A non-zero exit code may also indicate that the user switch didn't work. In particular *B\_E* is *not* called if the executed function returns an error.

*@B\_E*

**b\_\_isModule** [module name]

*blib/b\_\_isModule*

Test whether the given name represents a blib module name.

**returns:** sets a zero exit code if the given name is a valid module name

**args**

Stateful argument parser for bash.

Regular arguments and options are parsed via *b\_args\_parse*. Afterwards they can be retrieved via *b\_args\_get* and *b\_args\_getOption*. Options may have parameters, can be repeated and combined.



The module can also check the correctness of options. All remaining correctness checks (e.g. for regular or option parameters) are left to the user of this module.

Conventions:

- Options always start with - and may occur everywhere.
- Single character options may be combined, e.g. -ajh will be considered the same as -a -j -h. Long options such as --option cannot be combined.  
*Recommendation:* Use long options for those options which require parameters and single letter options for everything else.
- Everything after a space-separated double dash (--) is not considered an option, but a regular argument.

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0.8

## Dependencies

no dependencies

## Imports

types

## Global Variables

### B\_ARGS

*args/B\_ARGS*

Array of regular/non-option arguments in the order of their appearance. Instead of using it directly, it is recommended to use `b_args_get` instead. The array may be removed in future versions.

### B\_ARGS\_OPTS

*args/B\_ARGS\_OPTS*

Map of options. `[option]_[index]` is used as key with `[index]` starting at zero. The values are the option parameters (if any). Multiple option parameters are separated by tabs.

The latter separator can be changed via `b_args_setOptionParamSeparator` before calling `b_args_parse`.

The index will only increase if options are repeated.

Instead of using it directly, it is recommended to use `b_args_getOption` instead. The array may be removed in future versions.

## Functions

### **b\_\_args\_\_getDeps**

*args/b\_\_args\_\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_\_args\_\_setOptionParamSeparator [separator]**

*args/b\_\_args\_\_setOptionParamSeparator*

Set the separator for multiple option parameters.

[separator]: String to use as separator for multiple option parameters.

**returns:** Nothing.

### **b\_\_args\_\_getOptionParamSeparator**

*args/b\_\_args\_\_getOptionParamSeparator*

Get the separator for multiple option parameters.

**returns:** Nothing.

### **b\_\_args\_\_init [allow flag] [option 1] [option param count 1] ... [option n] [option param count n]**

*args/b\_\_args\_\_init*

Initialize the args module. It is recommended to call this function before using this module, if you want to achieve any non-default behaviour.

[allow flag]: If set to 0, assume that non-specified options do not have any parameters (default). If set to 1, enforce that only the given options are allowed and otherwise error out.

[option i]: An allowed option including its leading - prefix.

[option param count i]: Number of expected parameters for that option. The parameters must directly follow the option. If less parameters are found, the parser will error out.

**returns:** Nothing, always sets a zero exit code.

*@StateChanging*

*@B\_E*

**b\_args\_parse** [arguments]

*args/b\_args\_parse*

Parse the given arguments.

Call `b_args_init` before parsing, if you desire any non-default parsing behaviour.

[arguments]: The arguments meant to be parsed, usually “\$@”.

**returns:** Sets a zero exit code on success and calls `B_E` otherwise.

*@StateChanging*

*@B\_E*

**b\_args\_assertOptions** [option 1] ... [option n]

*args/b\_args\_assertOptions*

Assert that the parsed options contain only the given allowed options (or less).

[option i]: Option to check against.

[returns]: Sets a zero exit code, if the current parsed state contains only allowed options and errors out with `B_E` otherwise. Prints a list of invalid options in the error case.

*@B\_E*

**b\_args\_get** [index] [fallback]

*args/b\_args\_get*

Get the argument at the given index.

[index]: Index of the argument to retrieve, starting at 0.

[fallback]: Value to return, if the given index was provided as empty argument or is missing. Default: empty String

**returns:** The argument at the given index. An *empty* (existing!) argument will cause the fallback to be returned with a zero exit code. If no argument was found at that index, a nonzero exit code is set and the fallback is returned.

**b\_args\_getInt** [index] [fallback]

*args/b\_args\_getInt*

Convenience wrapper for `b_args_get` that also checks the type of the argument to be an integer.

**returns:** See `b_args_get`. Also sets a nonzero exit code, if the argument is not an integer.

### **b\_\_args\_\_getCount**

*args/b\_\_args\_\_getCount*

Get the number of arguments.

**returns:** Number of arguments.

### **b\_\_args\_\_getOption [option] [fallback] [repeat index] [parameter index]**

*args/b\_\_args\_\_getOption*

Check whether the given option is set and retrieve its parameter, if it was.

[option]: String defining the option, e.g. `--option` or `-a`.

[fallback]: Value to return if the option did not have any parameter or was not set. Default: empty String

[repeat index]: Index of the option to retrieve, if the option was repeated multiple times (default: 0 = first option).

[parameter index]: Index of the option parameter to retrieve, starting at 0 (default: return all option parameters, separated by `b__args__getOptionParamSeparator`).

**returns:** The option parameter, if the option was set. The fallback is returned and a zero exit code is set, if the option was set, but an *empty* (existing!) parameter was provided. A nonzero exit code indicates that the option was not set (the fallback is still returned).

### **b\_\_args\_\_getOptionInt [option] [fallback] [repeat index] [parameter index]**

*args/b\_\_args\_\_getOptionInt*

Convenience wrapper for `b__args__getOption` that also checks the type of the option to be an integer.

**returns:** See `b__args__getOption`. Also sets a nonzero exit code, if the option is not an integer.

### **b\_\_args\_\_getOptionCount**

*args/b\_\_args\_\_getOptionCount*

Get the number of options that were set.

**returns:** Number of options (incl. repeated options).

## **arr**

Collection of array related functions.

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0.2

### **Dependencies**

printf

### **Functions**

#### **b\_arr\_getDeps**

*arr/b\_arr\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

#### **b\_arr\_join [delimiter] [array]**

*arr/b\_arr\_join*

Join the given array; elements are separated with the given delimiter. The array is not checked to exist.

[delimiter]: String to use as delimiter.

[array]: Expanded array to join, e.g. “\${arr[@]}”.

**returns:** Joined version of the array. The exit code is always zero.

#### **b\_arr\_toList [array]**

*arr/b\_arr\_toList*

Create a newline-separated list from the given array.

[array]: Expanded array to join, e.g. “\${arr[@]}”.

**returns:** List version of the array. The exit code is always zero.

**b\_arr\_contains** [element] [array]

*arr/b\_arr\_contains*

Check whether an array contains an element.

[element]: element to check for its existence in the array

[array]: expanded array to check, e.g. "\${arr[@]}"

**returns:** an exit code of 0, if the element was found and 1 otherwise

**b\_arr\_mapsAreEqual** [map spec 1] [map spec 2]

*arr/b\_arr\_mapsAreEqual*

Check whether the two given maps/associative arrays are equal.

[map spec 1]: First map specification to check. Since maps cannot be passed directly to functions in Bash 4.2, you'll have to use "**\$(declare -p "yourmap")**" instead.

[map spec 1]: Second map specification to check.

**returns:** an exit code of 0, if the maps are equal and 1 otherwise; B\_E is only triggered on programming errors

@B\_E

## **cdoc**

Generate code documentation in many formats (e.g. html, pdf, manpage, ...) from code comments.

Lines applicable for the documentation in your code are assumed to match static (configurable) regular expressions. These lines are then fed to pandoc in order to generate a single html page (or pdf, manpage, ...) as documentation. If no conversion is required (input format = desired output format), pandoc is bypassed.

It should be possible to use this way of generating code documentation with most programming languages (incl. bash). The defaults however are set for bash and the blib way of documenting its code, i.e. you'll have to use the getters and setters of this module if you want something different. For instance the default is to check for lines starting with **#+** (a special bash comment line) and add everything afterwards to the output documentation.

Various callback functions can be used to add content to the output of **b\_cdoc\_generate**. See the documentation of that function for details.

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0.2

## Dependencies

mv  
rm  
mktemp

## Functions

### **b\_cdoc\_getDeps**

*cdoc/b\_cdoc\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_cdoc\_setExtractionRegex [regex]**

*cdoc/b\_cdoc\_setExtractionRegex*

Set the regular expression used to check for matching lines in code files. The first match (`${BASH_REMATCH[1]}`) is added to the documentation output.

**returns:** nothing

*@StateChanging*

### **b\_cdoc\_getExtractionRegex**

*cdoc/b\_cdoc\_getExtractionRegex*

See the setter.

**returns:** The property that was set.

### **b\_cdoc\_setFileFilterCallback [callback function name]**

*cdoc/b\_cdoc\_setFileFilterCallback*

Set the function to call by `b_cdoc_generate` exactly once right after it computed the list of applicable source code files.

The callback function should be declared as follows:

`callback_function_name [file list]`

[file list]: newline-separated list of files (no directories!)  
that `b_cdoc_generate` computed for document generation  
(in that order)

**returns:** the newline-separated list to use by `b_cdoc_generate` for document generation (default: the input); a non-zero exit

code will abort further processing

**returns:** nothing

*@StateChanging*

**b\_cdoc\_getFileFilterCallback**

*cdoc/b\_cdoc\_getFileFilterCallback*

See the setter.

**returns:** The property that was set.

**b\_cdoc\_setDocumentBeginCallback** [callback function name]

*cdoc/b\_cdoc\_setDocumentBeginCallback*

Set the function to call by b\_cdoc\_generate exactly once right before it starts generating the output document.

The callback function should be declared as follows:

callback\_function\_name [document output file] [document output format]

[document output file]: path to the document output file

(may not exist and should not be written to)

[document output format]: chosen output format

**returns:** whatever should be added at the beginning of the output document;  
a non-zero exit code will abort further processing

**returns:** nothing

*@StateChanging*

**b\_cdoc\_getDocumentBeginCallback**

*cdoc/b\_cdoc\_getDocumentBeginCallback*

See the setter.

**returns:** The property that was set.

**b\_cdoc\_setPostProcessingCallback** [callback function name]

*cdoc/b\_cdoc\_setPostProcessingCallback*

Set the function to call by b\_cdoc\_generate each time a code file was fully processed.

The callback function should be declared as follows:



```
callback_function_name [processed input] [input file] [document output format]
[processed input]: Everything that was found to match the
                    extraction regex in the [input file] by b_cdoc_generate.
[input file]:       The original input file.
[document output format]: chosen output format
returns:            whatever should be added to the output document for the
                    given input file (usually the processed input or some filtered
                    version of it); a non-zero exit code will abort further processing
```

@StateChanging

*cdoc/b\_cdoc\_getPostProcessingCallback*

**returns:** The property that was set.

*cdoc/b\_cdoc\_setDocumentEndCallback*

The callback function should be declared as follows:

**returns:** nothing

## b\_cdoc\_getDocumentEndCallback

**returns:** The property that was set.

### **b\_cdoc\_\_setSpaceCallback** [callback function name]

*cdoc/b\_cdoc\_\_setSpaceCallback*

Set the function to call by `b_cdoc__generate` each time it hits “space” (non-matching lines) between two matching lines.

The callback function should be declared as follows:

```
callback_function_name [matching line] [input file] [previous space count] [document output
[matching line]: The first matching line before which no match was found.
[input file]:    The original input file.
[previous space count]: The number of times this function was previously
                    called for the currently processed file.
[document output format]: chosen output format
returns:         whatever should be added in front of the matching line;
                    a non-zero exit code will abort further processing
```

**returns:** nothing

*@StateChanging*

### **b\_cdoc\_\_getSpaceCallback**

*cdoc/b\_cdoc\_\_getSpaceCallback*

See the setter.

**returns:** The property that was set.

### **b\_cdoc\_\_generate** [input files] [output file] [output format] [additional pandoc options]

*cdoc/b\_cdoc\_\_generate*

Generate a documentation file from the given list of input files or directories.

pseudo code description for the document generation:

1. call the file filter callback to obtain the final list of input source code files to use for document generation, respect the order (default: use all files passed as input)
2. call the document begin callback function with the output file path to get user-specific output (default: do nothing)
3. for all input files:
  - i. for all lines of a file:
    - a) store lines matching `b_cdoc__getExtractionRegex` in a variable *o*
    - b) between any two matching lines for `b_cdoc__getExtractionRegex` that had a non-matching line in between them: call the space callback function (default: add an empty line to the output)

- ii. pass *o* and the file name to the post processing callback function (default: return the input) - users could add e.g. the file name as section header here
- iii. add the output of the post processing function to the output document
- 4. call the document end callback function with the output file path to get user-specific output (default: do nothing)
- 5. do all necessary output conversions using pandoc

[input files]: Newline-separated list of files or directories to generate the documentation from. The given order is respected; directories are recursively searched for files. It is currently assumed that these files are encoded in UTF-8.

[output file]: Path to the documentation file to generate. Should not exist.

[output format]: The target format of the documentation to generate. See pandoc for a list of available output formats. If none is specified, pandoc is bypassed and the input format is chosen as output format. Passing “pandoc” will let pandoc decide based on the extension of the output file.

[additional pandoc options]: All remaining parameters will be directly passed to pandoc. If none are provided, -s is implicitly added as default.

**returns:** Sets a non-zero exit code and exits the script on errors. output from pandoc and other calls may be printed. Otherwise nothing is returned.

@B\_E

**b\_cdoc\_generateBlibStyle** [input files] [output file base path] [output format] [delete existing]

*cdoc/b\_cdoc\_generateBlibStyle*

A convenience wrapper for b\_cdoc\_generate which sets various reasonable parameters depending on the output format.

[input files]: see b\_cdoc\_generate

[output file base path]: path to a directory and base file name where to store the generated output documentation file; the final file name may differ as it is chosen by this function

[output format]: currently one of raw|html|pdf|man is supported (default: raw)

[delete existing]: whether or not to delete previously created output files (default: true/0); if set to false (1), the function will error out if a previously created file was found

**returns:** full path to the created documentation file on success; otherwise the function may error out

@B\_E

## Callback Functions

`b_cdoc_cbPrintNewline`

*cdoc/b\_cdoc\_cbPrintNewline*

Prints a newline character.

**returns:** nothing

`b_cdoc_cbPrintFirstParam` [param]

*cdoc/b\_cdoc\_cbPrintFirstParam*

Prints the first parameter.

[param]: The parameter to print.

**returns:** the first parameter

## daemon

Module providing access to a single background process providing some service (daemon). Exiting the foreground control process will *not* terminate the background process. Attempting to start multiple background daemons will be prevented in a thread-safe way.

Each background process is assumed to implement a `daemon_main` function and must be identified by a unique String.

If you need to exchange data with the background service, please have a look at the `multithreading/ipcv` or `multithreading/ipcm` modules.

Known Issue:

Since the daemon cannot detach from its session via `setsid` in bash, the daemon will remain in the process group of its parent. So killing the parent with e.g. Ctrl-C will cause the parent group including the daemon to terminate. As a workaround, users may either ignore SIGINT requests or make sure the parent exits as soon as possible (recommended).

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0.4

## Dependencies

kill

umask

mkdir

rm

mktemp

## Imports

multithreading/mtx

proc

## Global Variables

### **B\_DAEMON\_ID**

*daemon/B\_DAEMON\_ID*

Contains the ID of the daemon, if and only if the current process is the daemon process.

## Functions

### **b\_daemon\_getDeps**

*daemon/b\_daemon\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

**b\_daemon\_init** [**quiet flag**] [**main name**] [**stdout file**] [**stderr file**]  
[**umask setting**]

*daemon/b\_daemon\_init*

Init the module paramters. It is necessary to call this method *before* using any other of this module unless you want to use the default paramters.

[quiet flag]: If set to 0 (default), don't print anything to stdout during the execution of start|stop|restart|status. Otherwise use b\_info to print informational messages.

[main name]: Name of the main loop function to execute in the background process. Returning from that function will exit the background process. Default: **daemon\_main**

[stdout file]: Where the background process should write its stdout stream to (default: /dev/null). Lines are appended.

[stderr file]: Where the background process should write its stderr stream to (default: /dev/null). Lines are appended.

[umask settings]: The umask settings to apply to the daemon (default: 0).

**returns:** Nothing.

*@StateChanging*

**b\_daemon\_start** [id] [arg 1] ... [arg n]

*daemon/b\_daemon\_start*

Start the background process.

If you need to start it as a different user, simply run this function as a different user with e.g. (b\_execFuncAs)[#b\_execFuncAs]. Please keep in mind that control processes must have the permission to send signals to the daemon PID though.

[id]: Unique identifying String of the daemon to distinguish it from others.

[arg i]: An arbitrary number of arguments which can be passed to the main loop.

**returns:** Sets a zero exit code on success. Otherwise sets a non-zero exit code. In particular B\_E is called, if the daemon is already running.

*@B\_E*

**b\_daemon\_stop** [id] [termination signal] [kill timeout]

*daemon/b\_daemon\_stop*

Stop the background process.

[id]: Unique identifying String of the daemon to distinguish it from others.

[termination signal]: A number specifying the signal to send to the daemon (default: 15 / SIGTERM). See `kill -l` for an overview.

[kill timeout]: Time in seconds after which the background process will be killed, if it remains unresponsive to the termination signal (default: 0 = wait indefinitely).

**returns:** Sets a zero exit code, if the daemon terminated by itself. An exit code of 2 indicates that the daemon had to be killed. An exit code of 3 means that it wasn't running. B\_E is called on unexpected errors.

*@B\_E*

**b\_daemon\_restart** [id] [termination signal] [kill timeout] [arg 1] ... [arg n]

*daemon/b\_daemon\_restart*

Restart the background process.

[id]: Unique identifying String of the daemon to distinguish it from others.

[termination signal]: See `b_daemon_stop`.

[kill timeout]: See `b_daemon_stop`.

[arg i]: An arbitrary number of arguments which can be passed to the main loop.

**returns:** See `b_daemon_start`.

@B\_E

### **b\_daemon\_statusPid [id]**

*daemon/b\_daemon\_statusPid*

Check the status of the background process.

Doesn't print informational messages to stdout.

[id]: Unique identifying String of the daemon to distinguish it from others.

**returns:** The PID and sets a zero exit code, if the daemon is running and a non-zero exit code otherwise. B\_E is only called on exceptional errors.

@B\_E

### **b\_daemon\_status [id]**

*daemon/b\_daemon\_status*

Check the status of the background process and print informational messages to stdout (if configured).

[id]: Unique identifying String of the daemon to distinguish it from others.

**returns:** Sets a zero exit code, if the daemon is running and a non-zero exit code otherwise. B\_E is only called on exceptional errors.

@B\_E

### **b\_daemon\_getPid [id]**

*daemon/b\_daemon\_getPid*

Get the process ID of the background process.

[id]: Unique identifying String of the daemon to distinguish it from others.

**returns:** The process ID and sets a zero exit code, if it could be obtained. Please note that the process may be dead anyway (use `b_daemon_statusPid` for that). Otherwise a non-zero exit code is set. B\_E is only called on exceptional errors.

@B\_E

## date

Collection of date and time related functions.

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0.2

## Dependencies

date

## Functions

### **b\_date\_getDeps**

*date/b\_date\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_date\_addDays [date] [days] [format] [utc flag]**

*date/b\_date\_addDays*

Add the given number of days to the given date.

[date]: date to add days to; the format must be understood by the Unix date utility

[days]: number of days to add

[format]: output format of the date, in Unix date notation (default: use the localized output)

[utc flag]: if set to 0, use UTC as time zone if not specified for the input *and* use it for the output (default: 1 = local time zone)

**returns:** The input date with the given number of days added, in the requested format; returns a non-zero exit code on errors.

@B\_E

### **b\_date\_diffSeconds [date 1] [date 2]**

*date/b\_date\_diffSeconds*

Get the number of seconds between the two dates, i.e. [date 2] - [date 1].



[date 2], [date 1]: the two dates to subtract; the time one is assumed to be identical if not specified within the dates

**returns:** The number of seconds between the given two dates [date 2] - [date 1]; returns a non-zero exit code on errors.

*@B\_E*

## delay

Simplistic module to delay commands to a future time.  
Requires polling.

All timestamps in this module must be integers and a larger timestamp must denote a time *after* a smaller timestamp.

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0.3

## Dependencies

no dependencies

## B\_DELAY\_EXECUTED

*delay/B\_DELAY\_EXECUTED*

The number of commands executed during the last invocation of `b_delay_execute`.

## Functions

### **b\_delay\_getDeps**

*delay/b\_delay\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_delay\_to [timestamp] [command]**

*delay/b\_delay\_to*

Delay the given command to be executed at the given time.

[timestamp]: An integer timestamp (e.g. \$SECONDS, Unix timestamp in s/ms/ns, ...).

[command]: The command to execute at the given time.

**returns:** Nothing.

*@StateChanging*

**b\_delay\_execute** [timestamp]

*delay/b\_delay\_execute*

Execute all commands which are due at the given time.

[timestamp]: Integer timestamp representing the current point in time.

**returns:** Nothing. The exit code is equal to the number of commands with a non-zero exit code. B\_DELAY\_EXECUTED is updated with the number of commands executed.

*@StateChanging*

**b\_delay\_getCommandAt** [timestamp]

*delay/b\_delay\_getCommandAt*

Get the set of commands to be executed at the given point in time.

[timestamp]: Integer timestamp denoting the time for which to retrieve the commands.

**returns:** The commands to execute at that time.

## flog

Flexible log writer for bash supporting arbitrary piped output (files, network streams, stdout, stderr, ...) in a user-defined output format.

Log files can be automatically reduced to their last X lines.

In order to log to the system log, please use the logger command instead. This library is mostly meant for application logs handled in a more custom manner.

Currently only a single writer per instance of this library/thread is kept in memory, but you can user multiple one after another or in multiple threads. Each writer should have a dedicated log file to write to.

Exact format of log entries:

[header] [message]

[header]: Can be arbitrarily defined in the  
respective callback function. If nothing  
is defined, the below default header  
is used:

```
[default header] = '[default date] '  
[default date]: current date in the format as used  
                by date +"%F %T %Z" (the format can be changed)
```

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## Dependencies

date  
tail  
cat  
mktemp

## Imports

fs

## Global Variables

### **B\_FLOG\_SEV**

*flog/B\_FLOG\_SEV*

Global map for human readable severities which may be used by users of this script.

It was inspired by the severities of RFC5424.

Currently supported values: emergency|alert|critical|crit|error|err|warning|warn|notice|informational|info|debug

## Functions

### **b\_flog\_printSeverity** [severity]

*flog/b\_flog\_printSeverity*

[severity]: see `b_flog_init`

Print the given severity in a way for logging. This function is meant to be used as building block for header functions.

**returns:** a printed version of the given severity for logging

### **b\_flog\_close**

*flog/b\_flog\_close*

close the currently open log; is automatically called, but users may want to call it themselves to force the respective file descriptor to be closed before the program is ended

**returns:** nothing

*@StateChanging*

**b\_flog\_init** [log file name] [header callback function] [log reduction lines]

*flog/b\_flog\_init*

Initialize this log writer. This function **must** be called before any others.

[log file name]: name of the log file to write to; special files such as /dev/stdout, /dev/stderr (default), /dev/tcp, /dev/udp are supported if your bash version supports them; the file doesn't need to exist, but directories above it must exist

[header callback function]: optional name of the function to be called whenever a new log entry is generated; the function must be defined as follows:

```
[header callback function] [severity]
[severity]: see [b_flog_log](#b_flog_log)
returns: the full header meant to be used for the current moment in time
        with the given severity (without knowing the message details)
        and sets a non-zero exit code on errors; errors may cause the
        message to be logged without header
```

[log reduction lines]: if set to a positive integer, reduce the log file approximately to that number of lines during logging (default: 3000) - see `b_flog_setLogReductionLinesApprox` for details; this option has no effect on non-file outputs (stdout, network output, ...)

**returns:** sets a non-zero exit code on errors and may exit the script

*@StateChanging*

*@B\_E*

**b\_flog\_log** [message] [severity]

*flog/b\_flog\_log*

Log the given message with the given optional severity.

[message]: message to log

[severity]: users may pass arbitrary numbers or even Strings here, but it is recommended to stick to the priorities defined in `$BLIB_FLOG_SEV` (default: `#{B_FLOG_SEV["info"]}`)

**returns:** sets a non-zero exit code on errors and may exit the script

*@B\_E*

**b\_flogErrorHandler** [error out] [print stderr] [print stack trace] [print log errors] [log stack trace] [severity]

*flog/b\_flogErrorHandler*

An alternative to `b_defaultErrorHandler` which will log program errors using `flog`.

[error out]: see `b_defaultErrorHandler` (default: 0)

[print stderr]: see `b_defaultErrorHandler` (default: 1 / log only)

[print stack trace]: see `b_defaultErrorHandler` (default: 1 / log only)

[print log errors]: whether or not to print errors related to the logging itself to `stderr` (default: 0 / print)

[log stack trace]: whether or not to log the stack trace (default: 1 / do not log it)

[severity]: the severity to use for all errors, defaults to `$_{B_FLOG_SEV["critical"]}`

**returns:** see `b_defaultErrorHandler`

**b\_flog\_getDeps**

*flog/b\_flog\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

**b\_flog\_getDateFormat**

*flog/b\_flog\_getDateFormat*

Get the date format used for the header by this log writer (see “man date” for explanations).

**returns:** see above

**b\_flog\_setDateFormat** [format string]

*flog/b\_flog\_setDateFormat*

Set the date format used for the header by this log writer (see “man date” for explanations).

**returns:** nothing

*@StateChanging*

**b\_flog\_getLogReductionLinesLowerBound**

*flog/b\_flog\_getLogReductionLinesLowerBound*

Get the number of lines that the log file will at least have after a log file reduction.

**returns:** see above

**b\_flog\_getLogReductionLinesUpperBound**

*flog/b\_flog\_getLogReductionLinesUpperBound*

Get the maximum number of lines that the log file will have before it is reduced.

**returns:** see above

**b\_flog\_setLogReductionLinesLowerBound [bound]**

*flog/b\_flog\_setLogReductionLinesLowerBound*

Set the number of lines that the log file will at least have after a log file reduction.

[bound]: number of lines to use for that bound

**returns:** nothing

*@StateChanging*

**b\_flog\_setLogReductionLinesUpperBound**

*flog/b\_flog\_setLogReductionLinesUpperBound*

Set the maximum number of lines that the log file will have before it is reduced.

[bound]: number of lines to use for that bound

**returns:** nothing

*@StateChanging*

**b\_flog\_setLogReductionLinesApprox [line count]**

*flog/b\_flog\_setLogReductionLinesApprox*

Set the number of average number of lines that the log file should have; counts  $\leq 0$  indicate no limit.

[line count]: reduce the log after reaching  $1.2 \times [\text{line count}]$  lines to  $0.8 \times [\text{line count}]$  lines

**returns:** nothing

*@StateChanging*

### **b\_flog\_getHeaderFunction**

*flog/b\_flog\_getHeaderFunction*

Get the name of the header callback function that is used.

**returns:** see above

### **b\_flog\_setHeaderFunction [header function]**

*flog/b\_flog\_setHeaderFunction*

Set the name of the header callback function to be used.

[header function]: name of the header function to use

**returns:** nothing

*@StateChanging*

## **Header Functions**

**b\_flog\_defaultHeader [severity]**

*flog/b\_flog\_defaultHeader*

Default header callback function used with **b\_flog\_init**.

[severity]: the default header ignores the severity

**returns:** the default header meant to be used for the current moment in time

**b\_flog\_headerDateSeverity [severity]**

*flog/b\_flog\_headerDateSeverity*

An alternative to the default header callback function which appends the severity to the default header.

[severity]: see **b\_flog\_init**

**returns:** the default header with the severity appended

**b\_flog\_headerDateScriptSeverity [severity]**

*flog/b\_flog\_headerDateScriptSeverity*

An alternative to the default header callback function which appends the calling script and the severity to the default header.

[severity]: see **b\_flog\_init**

**returns:** the default header with the calling script and severity appended

## **fs**

Collection of file and file system related functions.

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0.3

### **Dependencies**

wc  
date  
findmnt  
mktemp  
mount  
head  
stat  
rm  
sync

### **Functions**

#### **b\_fs\_getDeps**

*fs/b\_fs\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

#### **b\_fs\_isEmptyDir [dir]**

*fs/b\_fs\_isEmptyDir*

Check whether the given directory is empty or non-existing. It is not checked whether the passed parameter is a file preventing a directory from being created.

[dir]: full path to the directory to check

**returns:** a zero exit code if the directory does not exist or is empty

#### **b\_fs\_getLastModifiedInDays [file]**

*fs/b\_fs\_getLastModifiedInDays*

Get the number of days since when a file was last modified.



[file]: Full path to the file to check.

**returns:** The time in days since the last modification. Sets a non-zero exit code on errors.

@B\_E

**b\_fs\_getLineCount** [file]

*fs/b\_fs\_getLineCount*

Get the number of lines of the given file.

[file]: full path to a file

**returns:** the number of lines; a non-zero exit code is set on errors

@B\_E

**b\_fs\_waitForFile** [file] [maximum time]

*fs/b\_fs\_waitForFile*

Sleep until the given file appears. The check interval is 1s.

[file]: full path to the file or directory to wait for

[maximum time]: maximum time in s to wait for the file to appear (default: forever)

**returns:** Sets a zero exit code if the file appeared and a non-zero exit code on a timeout.

**b\_fs\_getMountpoints** [device]

*fs/b\_fs\_getMountpoints*

Get all mountpoints for the given device.

[device]: Full path to the device (incl. /dev/) for which to obtain the mountpoints.

**returns:** A newline-separated list of mountpoints where the given device is mounted to. Sets a non-zero exit code if no such mountpoints were found.

**b\_fs\_mountIfNecessary** [device] [mount point] [enforce]

*fs/b\_fs\_mountIfNecessary*

Mount the given device if it isn't already mounted.

[device]: Full path to the device (incl. /dev/) to mount.

[mount point]: Full path where to mount the device. If no mount point is specified, a /tmp/ mount point is chosen. Non-existing directories are created. Is ignored if another mount point already exists.

[enforce]: If set to 0, enforce the given mount point to be used in addition to potentially existing ones (default: 1).

**returns:** The chosen mount point or a newline-separated list of existing mount points on success; sets a non-zero exit code on failure.

@B\_E

### **b\_fs\_createLoopDeviceIfNecessary** [file]

*fs/b\_fs\_createLoopDeviceIfNecessary*

Create a loop device for the given file if no old one exists. Usually requires root access rights.

[file]: File for which to create a loop device.

**returns:** Created loop device or previously used one (incl. /dev/). Sets a non-zero exit code, if no device could be created.

@B\_E

### **b\_fs\_removeUnusedLoopDevice** [device|file]

*fs/b\_fs\_removeUnusedLoopDevice*

Remove a loop device, if and only if it is unused by the operating system. Otherwise mark it for removal once it becomes unused. Usually requires root access rights.

[device|file]: Full path (incl. /dev/) to the loop device or to the backing file.

**returns:** Sets a zero exit code, if the loop device was not used and could thus be successfully removed *or* does not exist. A nonzero exit code indicates that the device is still being used. B\_E is called on other errors.

@B\_E

### **b\_fs\_parseSize** [string] [check flag]

*fs/b\_fs\_parseSize*

Parse human-readable file system sizes that include units.

[string]: A string denoting a file system size of the format [number][unit]. Unit may be one of KB 1000, K 1024, MB 10001000, M 10241024, GB 100010001000, G 102410241024, and so on for T, P. If no unit is provided, the number is assumed to denote bytes. The number must be an integer.

[check flag]: Check whether the result makes sense (default: 0/true). This check will make integer overflows less likely.

**returns:** The respective number of bytes meant with the given string. B\_E is called on parsing errors.

@B\_E

**b\_fs\_removeWithOverwrite** [file] [randomness source]

*fs/b\_fs\_removeWithOverwrite*

Overwrite the given file with random data, then remove it. This is meant to prevent a potential reconstruction of the file after its removal.

*Warning:* The reconstruction may still work on some types of file systems or physical storage systems (e.g. on flash disks).

[file]: Full path to the file to remove. Directories are currently not supported.

[randomness source]: Device to use as source of random data (default: /dev/urandom).

**returns:** Nothing. B\_E is called on errors.

@B\_E

## http

Collection of http related functions.

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0.2

## Dependencies

curl

## Global Variables

**B\_HTTP\_CHECKURLS**

*http/B\_HTTP\_CHECKURLS*

Each call to b\_http\_getOnlineStatus causes one of the URLs in this array to be visited.

It is recommended to pick a relatively large number of URLs with SSL support to remain relatively anonymous, if b\_http\_getOnlineStatus is called multiple times.

Defaults to the European/US Alexa Top 10 (which hopefully blends in to the masses).

## Functions

### **b\_http\_getDeps**

*http/b\_http\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_http\_rawUrlEncode [string]**

*http/b\_http\_rawUrlEncode*

Encode the given string according to RFC 3986.

[string]: to encode

**returns:** Returns a string in which all non-alphanumeric characters except `_.~` have been replaced with a percent (%) sign followed by two hex digits. This is the encoding described in RFC 3986 for protecting literal characters from being interpreted as special URL delimiters, and for protecting URLs from being mangled by transmission media with character conversions (like some email systems). A non-zero exit code is set on errors.

*@B\_E*

### **b\_http\_rawUrlDecode [string]**

*http/b\_http\_rawUrlDecode*

Decode the given string encoded with `b_str_rawUrlEncode` or an equivalent function.

[string]: to decode

**returns:** The literal string with all hex characters replaced; a non-zero exit code is set on errors.

### **b\_http\_getOnlineStatus [timeout]**

*http/b\_http\_getOnlineStatus*

Find out whether we are online or not by attempting an http connection. One of `B_HTTP_CHECKURLS` is possibly visited during the process.

[timeout]: Timeout in seconds for hanging checks (default: 5).

**returns:** 0, if we're online, 1 if only DNS works, 2 if neither DNS nor http(s) worked, 3 if the check timed out; B\_E will be called if the status cannot be determined.

*@B\_E*

## ini

Stateful ini reader for bash.

Currently only a single file per instance of this library/thread is kept in memory, but you can read multiple files one after another or in multiple threads.

Implementation Specifics:

- names/keys & values are case sensitive
- comment lines may start with ; or #
- whitespace lines are ignored
- duplicate names may result in undefined behaviour (usually the second will override the first)
- all characters following the = are considered part of the value (incl. whitespace); whitespace before and after the value may be trimmed by the getters though (check their description)
- values are not interpreted (e.g. quotes, escape characters, ...)
- whitespace around keys and around section qualifiers is ignored

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## Dependencies

no dependencies

## Functions

### **b\_ini\_getDeps**

*ini/b\_ini\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_ini\_read [ini file]**

*ini/b\_ini\_read*

read the given ini file and keep it in thread-local memory so that subsequent calls to the `b_ini_get` functions will return the values from the ini file; subsequent calls to this function will update the internal state to represent the file last read in this thread

[ini file]: path to the ini file to read

**returns:** an error message on errors and sets a non-zero exit code on errors

*@StateChanging*

*@B\_E*

**b\_ini\_get** [name] [section]

*ini/b\_ini\_get*

get the value for the ini entry with the given name as String in raw format

[name]: name/key of the ini entry to retrieve

[section]: section where to look for the entry with the given name (default: without section)

**returns:** value of the ini entry matching exactly the given section and name incl. any whitespace; a non-zero exit code is set if such an entry wasn't found

**b\_ini\_getString** [name] [section]

*ini/b\_ini\_getString*

get the value for the ini entry with the given name as String and remove all whitespace around the returned String

[name]: name/key of the ini entry to retrieve

[section]: section where to look for the entry with the given name (default: without section)

**returns:** value of the ini entry matching exactly the given section and name excl. any whitespace around; a non-zero exit code is set if such an entry wasn't found

**b\_ini\_getInt** [name] [section]

*ini/b\_ini\_getInt*

get the value for the ini entry with the given name as integer

[name]: see `b_ini_get`

[section]: see `b_ini_get`

**returns:** see `b__ini_get`; additionally it is checked whether the return value is an integer (if not, a non-zero exit code of 2 is set and the return value is undefined)

**b\_\_ini\_getBool** [name] [section]

*ini/b\_\_ini\_getBool*

get the value for the ini entry with the given name as boolean

[name]: see `b__ini_get`

[section]: see `b__ini_get`

**returns:** see `b__ini_get`; 0 is returned via echo for true, 1 for false; the exit code indicates a potential error during parsing (2) or a missing entry (1) and *not* true/false

**b\_\_ini\_assertNames** [section 1] [name 1] ... [name n] – [section 2]  
[name 1] ... [name m]

*ini/b\_\_ini\_assertNames*

Assert that the given sections contains *at most* the given names and no additional ones.

This is a useful function to detect user mistakes and should be called right after `b__ini_read`.

Multiple sections can be separated with “–”.

[section]: see `b__ini_get`

[name]: see `b__ini_get`

**returns:** Sets a zero exit code if and only if the last read ini file doesn’t contain any additional names. Otherwise `B_E` is triggered. `B_ERR` will list the invalid names.

@*B\_E*

## multithreading/ipcm

An inter-process map implementation.

The map is available to all running processes during a single boot session.

Both reading and writing to the map can be done from any number of processes.

---

### Overall Features

---

# readers	multiple
# writers	multiple

Overall Features	
read consistency	always
write consistency	always
blocking	on writes

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## Dependencies

no dependencies

## Imports

multithreading/ipcv  
multithreading/mtx

## Functions

### **b\_ipcm\_getDeps**

*multithreading/ipcm/b\_ipcm\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_ipcm\_setNamespace [namespace]**

*multithreading/ipcm/b\_ipcm\_setNamespace*

Set the common process namespace to use. All processes inside the same namespace share a common state.

It is recommended to call this function a single time before any other functions of this module. Otherwise the default namespace, which may include unrelated processes, is used.

[namespace]: Name of the namespace to set.

**returns:** Errors out, if the name is unacceptable.

*@StateChanging*

*@B\_E*



### **b\_ipcm\_getNamespace**

*multithreading/ipcm/b\_ipcm\_getNamespace*

Retrieve the currently used namespace.

**returns:** The currently used namespace.

### **b\_ipcm\_change [key] [change function] [maximum time]**

*multithreading/ipcm/b\_ipcm\_change*

Change the given key/value combination inside the map in a thread-safe way. May wait for changes done by other processes.

[key]: A global unique identifier for the given value.

[change function]: Name of the function to execute the change of the value. It will be called with the current key as first parameter and the current value as second. It is expected to print the new value to set for this key. A non-zero exit code will cause b\_ipcm\_change to abort the change.

[maximum time]: maximum time in ms to wait for other processes to complete their operation (default: -1 = indefinitely)

**returns:** A zero exit code and prints the new value, if the change succeeded. An exit code of B\_RC+1 indicates that the change function returned a non-zero exit code. B\_E is called otherwise.

@B\_E

### **b\_ipcm\_get [key] [fallback]**

*multithreading/ipcm/b\_ipcm\_get*

Retrieve the data found at the given key.

[key]: A global unique identifier for the data to retrieve.

[fallback]: Data to return if nothing was found for the given key (default: empty).

**returns:** Sets a zero exit code and returns the data found on success. If no data was found, the fallback data is returned and a zero exit code is set. B\_E is called on errors.

### **b\_ipcm\_unsetNamespace [namespace] [maximum time]**

*multithreading/ipcm/b\_ipcm\_unsetNamespace*

Unsets the given namespace and all keys stored within it.

It is recommended to call this function when all processes finished their work.

[namespace]: The namespace to unset (default: the current namespace).

[maximum time]: maximum time in ms to wait for other processes to complete their operation (default: 0 = indefinitely)

**returns:** Sets a zero exit code only upon successful removal. Otherwise B\_E is triggered.

@B\_E

## multithreading/ipcv

Provides means for inter-process communication (ipc) via global bash variables (v).

This implementation uses shared memory, i.e. it should be reasonably fast.

Only a single process or thread is assumed to be writing (i.e. use b\_ipcv\_save) a variable at a time and multiple processes may read it (using e.g. b\_ipcv\_load). If you need to write a single variable from multiple processes, please consider using the multithreading/mtx module or similar locking means in combination with this module (or just multithreading/ipcm).

Overall Features	
# readers	multiple
# writers	single
read consistency	always
write consistency	only for one writer
blocking	never

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0.3

## Dependencies

findmnt  
mkdir  
mktemp  
mv  
rm

## Functions

### b\_ipcv\_getDeps

*multithreading/ipcv/b\_ipcv\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

**b\_ipcv\_save** [namespace] [var name 1] .. [var name n]

*multithreading/ipcv/b\_ipcv\_save*

Save the current values of the given variables so that they are made available for other processes under the given namespace.

Please note that each variable is saved atomically, but individually. I.e. if you need multiple values to be updated at the same time, please use a single variable (e.g. a map).

[namespace]: Name for a common group under which the given variables should be saved. The combination of [namespace] and [variable name] must be a unique identifier across all processes running on the system.

[var name i]: The name of the global variable to make accessible for other processes. An arbitrary number of variable names can be specified.

**returns:** Nothing, but a non-zero exit code indicates failed variable save attempts. A failed save attempt also triggers B\_E.

@B\_E

**b\_ipcv\_load** [namespace] [var name 1] .. [var name n]

*multithreading/ipcv/b\_ipcv\_load*

Load the given variables from the given namespace into the current process context.

[namespace]: Name of the group under which the variable was saved with b\_ipcv\_save. Must exist.

[var name i]: Name of the variable to load. Multiple names can be specified.

**returns:** A non-zero exit code indicates the number of variables that could not be loaded unless some unexpected error occurred and B\_E is triggered. Please note that a failed load attempt/unavailable variable does generally not trigger B\_E.

@B\_E

**b\_ipcv\_loadNamespace** [namespace] [check existence]

*multithreading/ipcv/b\_ipcv\_loadNamespace*

Load all variables that can be loaded for the given namespace into the current process context.

[namespace]: Name of the group for which to load all available variables.

[check existence]: Whether or not to make sure that the namespace to load exists (default: 0/check). Otherwise non-existing namespaces will not cause an error.

**returns:** Sets a zero exit code on success. Failing to load any single available variable will always trigger B\_E.

@B\_E

**b\_ipcv\_unset** [namespace] [var name 1] .. [var name n]

*multithreading/ipcv/b\_ipcv\_unset*

Unset/Remove the given variables from the global namespace.

Please note that the variables will remain set in your current process context, if they were set before. Use the standard bash **unset** for that.

[namespace]: Group where the given variables belong to.

[var name i]: Name of the variable to remove. Multiple may be specified.

**returns:** The number of variables which could not be unset. B\_E is not triggered for these.

@B\_E

**b\_ipcv\_unsetNamespace** [namespace]

*multithreading/ipcv/b\_ipcv\_unsetNamespace*

Remove the given global namespace and all variables it contains.

Please note that the variables will remain set in your current process context, if they were set before. Use the standard bash **unset** for that.

[namespace]: To remove.

**returns:** Sets a zero exit code only upon successful removal. Otherwise B\_E is triggered.

@B\_E

## **multithreading/mtx**

Collection of mutex related functions.

Mutex: Only a single process may have it at any point in time.

Lock: A specific maximum number of processes may have it at any point in time.

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0.3

## Dependencies

mkdir  
touch  
sleep  
rm  
rmdir  
cat  
mktemp

## Imports

proc

## Functions

### **b\_mtx\_getDeps**

*multithreading/mtx/b\_mtx\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_mtx\_setSleepTime [ms]**

*multithreading/mtx/b\_mtx\_setSleepTime*

Sets the time to sleep for this module whenever active polling is done (default: 500).

[ms]: time in milliseconds between active polling requests for e.g. mutexes done by this module; must be an integer

**returns:** Nothing, always sets a zero exit code.

### **b\_mtx\_getSleepTime**

*multithreading/mtx/b\_mtx\_getSleepTime*

Gets the time to sleep for this module whenever active polling is done.

**returns:** The currently set time to sleep in ms.

### **b\_\_mtx\_create** [base dir]

*multithreading/mtx/b\_\_mtx\_create*

Allocate a new mutex without claiming it (use b\_\_mtx\_try for that).

[base dir]: Path to an *existing* directory where to store the mutex (default: not specified). By default this module will pick a temporary location. If you need a mutex that persists across reboots, please set a directory that persists across reboots here. The path should point to a local, non-network file system destination. The module must be able to create remove files or directories there at will.

**returns:** A string identifying the mutex (mutex ID). Sets a non-zero exit code on errors.

@B\_E

### **b\_\_mtx\_release** [mutex] [block ID]

*multithreading/mtx/b\_\_mtx\_release*

Release the given mutex so that it can be used by other block IDs/threads.

[mutex]: A mutex obtained via b\_\_mtx\_create.

[block ID]: The block ID for which to release the mutex (default: \$\$).

**returns:** Sets a non-zero exit code if the mutex could not be removed as another process is blocking it and a zero exit code on successful removal.

### **b\_\_mtx\_forceRelease** [mutex]

*multithreading/mtx/b\_\_mtx\_forceRelease*

Release the given mutex so that it can be used by other blockIDs/threads. Warning: This function can remove mutexes from other threads and should generally *only* be used for the removal of mutexes which are known to be stale by the calling application.

[mutex]: A mutex obtained via b\_\_mtx\_create.

**returns:** Nothing and sets a zero exit code.

### **b\_\_mtx\_pass** [mutex] [block ID]

*multithreading/mtx/b\_\_mtx\_pass*

Pass a blocked mutex to another block ID (i.e. change the block ID of the given mutex).

You should only do this if you currently own the mutex and the new process is ready to take over.

[mutex]: A mutex obtained via `b_mtx_create`.

[block ID]: The block ID to set for the given mutex.

**returns:** Sets a zero exit code on success and a non-zero exit code otherwise.

@B\_E

**b\_mtx\_try** [mutex] [block ID] [claim stale] [claim own]

*multithreading/mutex/b\_mtx\_try*

Attempt to obtain the given mutex. Return immediately even if it cannot be obtained.

[mutex]: A mutex obtained via `b_mtx_create`. You may also use a static and otherwise unused directory path as mutex and share it across all relevant processes.

[block ID]: The ID to use by which to block (default: running (sub)shell process id \$\$). This should be the process ID of the process attempting to obtain the mutex or you should know what you're doing. If you're in a subshell that should deploy a mutex against other subshells, store their \$BASHPID and call the function with that.

[claim stale]: If set to 0, claim the mutex even if it is still blocked by some other process, but that process isn't running anymore. If set to 1 (default), the function returns without obtaining the mutex. In general this should only be used in situations where a mutex has a high probability of being stale (e.g. application start).

[claim own]: If set to 0 (default), claim the mutex if it appears to be blocked by the provided block ID. If set to 1, consider it blocked even then.

**returns:** The function incl. parameters to execute to remove the mutex if it was obtained and an error message stating the reason otherwise. The provided function *should* be called as part of an exit trap of the calling script or via eval. Sets an exit code of 0, if the mutex was obtained. An exit code of 1 is set, if the mutex was blocked and another non-zero exit code if some other error occurred (the mutex might be blocked even then).

Example code:

```
local mutex=""
local mutexRet=""
mutex="$(b_mtx_create)" || { B_ERR="Failed to create a mutex." ; B_E }
mutexRet="$(b_mtx_try "$mutex")" \
|| { B_ERR="Failed to obtain the mutex $mutex. Reason: $mutexRet" ; B_E }
#assuming the mutex is only meant to be removed after full
#execution of the script:
trap "$mutexRet" EXIT
```

```
#direct removal:
#b_mtx_release "$mutex"
```

**b\_mtx\_waitFor** [mutex] [block ID] [claim stale] [maximum time]

*multithreading/mtx/b\_mtx\_waitFor*

Wait for the given mutex to become available. This will block script execution.

[mutex]: see b\_mtx\_try

[block ID]: see b\_mtx\_try

[claim stale]: see b\_mtx\_try

[maximum time]: maximum time in ms to wait for the mutex to become available  
(default: -1 = indefinitely)

**returns:** see b\_mtx\_try

## **multithreading/multiw**

Allow multiple processes to write to a *virtual* file at the same time without causing write inconsistencies (written data from each process mangled with each other).

This is achieved by keeping one file per process and relies on the assumption that both replacing and reading a symlink on your Linux distribution is atomic.

In order for this to work, all write operations must go through this module.

Currently reading only returns the data written by the process which wrote last. If you need some sort of appending, it makes more sense to deploy a mutex using e.g. the multithreading/mtx module.

Overall Features	
# readers	multiple
# writers	multiple
read consistency	partial, last writer wins
write consistency	always
blocking	never

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## Dependencies

shuf  
mv  
ln  
stat  
rm

## Functions

### **b\_multiw\_getDeps**

*multithreading/multiw/b\_multiw\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_multiw\_setMaxHangTime [seconds]**

*multithreading/multiw/b\_multiw\_setMaxHangTime*

Set the maximum time that a process is expected to hang between two instructions. This is relevant for various internal guarantees.

[seconds]: Time in seconds that a process hangs at most.

**returns:** Nothing.

*@StateChanging*

### **b\_multiw\_getMaxHangTime**

*multithreading/multiw/b\_multiw\_getMaxHangTime*

Get the maximum time that a process is expected to hang between two instructions. This is relevant for various internal guarantees.

**returns:** Time in seconds.

### **b\_multiw\_write [file path]**

*multithreading/multiw/b\_multiw\_write*

Write all data lying in stdin to the given *virtual* file in a thread-safe way.

[file path]: Full path to the virtual file to write to. Must not be a regular file (but may not exist).

**returns:** A zero exit code, if the write operation was successful and a non-zero exit code otherwise.

@B\_E

**b\_multiw\_remove** [file path]

*multithreading/multiw/b\_multiw\_remove*

Remove the given virtual file *and all of its revisions*.

This function should only be called when all processes finished reading and writing. It is recommended to use it over the standard Linux `rm` as the latter will leave remnants behind.

**returns:** A zero exit code on success.

@B\_E

## os/osid

Functions for operating system identification.

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## Dependencies

no dependencies

## Functions

**b\_osid\_getDeps**

*os/osid/b\_osid\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

**b\_osid\_init** [force]

*os/osid/b\_osid\_init*

[force]: if set to 0, force an init even if it would otherwise not be necessary (default: 1 - only initialize if it didn't happen before)

Initialize the osid module. It should normally *not* be necessary to call this function directly, but it will be called by the osid module internally as needed.

**returns:** May error out and set a non-zero exit code on failures.

### **b\_\_osid\_\_isDebian**

*os/osid/b\_\_osid\_\_isDebian*

Check whether the OS running this function is a Debian Linux.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isDebianLike**

*os/osid/b\_\_osid\_\_isDebianLike*

Check whether the OS running this function is a Debian Linux or one of its derivatives (e.g. ubuntu).

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isOpenSuse**

*os/osid/b\_\_osid\_\_isOpenSuse*

Check whether the OS running this function is a OpenSUSE.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isFedora**

*os/osid/b\_\_osid\_\_isFedora*

Check whether the OS running this function is a Fedora Linux.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isCentOS**

*os/osid/b\_\_osid\_\_isCentOS*

Check whether the OS running this function is a CentOS.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isRedHat**

*os/osid/b\_\_osid\_\_isRedHat*

Check whether the OS running this function is a RedHat Linux.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isUbuntu**

*os/osid/b\_\_osid\_\_isUbuntu*

Check whether the OS running this function is an Ubuntu Linux.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isFedoraLike**

*os/osid/b\_\_osid\_\_isFedoraLike*

Check whether the OS running this function is a Fedora Linux or one of its derivatives (e.g. CentOS, Red Hat, Qubes OS).

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isQubesDom0**

*os/osid/b\_\_osid\_\_isQubesDom0*

Check whether the OS running this function is a Qubes OS in dom0.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

### **b\_\_osid\_\_isQubesVM**

*os/osid/b\_\_osid\_\_isQubesVM*

Check whether the OS running this function is a Qubes OS in a VM.

**returns:** Sets a zero exit code if the check returns true. Does not print any output.

## os/qubes4/dom0

Collection of functions supporting scripting in Qubes OS 4.x dom0.

**Important:** Whenever you parse output from VMs to dom0, you **must** be extra careful and assume it totally untrusted as parsing bugs are a plausible attack vector for compromised VMs. Passing data to potentially compromised VMs of course also exposes that data's confidentiality.

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### Dependencies

qvm-run  
qvm-block  
qvm-ls  
qvm-shutdown  
qvm-check  
qubes-prefs  
dirname  
basename  
mktemp  
ps  
sleep  
cat  
timeout  
dd  
tee  
xxd  
python3  
kill  
losetup  
setsid  
sort  
tar

### Imports

fs  
proc  
types

## Functions

### **b\_\_dom0\_\_getDeps**

*os/qubes4/dom0/b\_\_dom0\_\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### **b\_\_dom0\_\_setVMDeps [list] [keep defaults]**

*os/qubes4/dom0/b\_\_dom0\_\_setVMDeps*

Set the dependencies for all VMs used with this module to the given list of binaries.

These dependencies are checked before *any* execution of commands in *any* VM; in particular whenever `b__dom0__qvmRun`, `b__dom0__execIn`, `b__dom0__execStrIn` or `b__dom0__execFuncIn` are called.

[list]: Newline-separated list of binaries or commands that VMs must be able to execute.

[keep defaults]: If set to 0 (default), merge the default list of dependencies with the supplied one. Otherwise only keep the supplied list of dependencies.

**returns:** Nothing.

*@StateChanging*

### **b\_\_dom0\_\_getVMDeps**

*os/qubes4/dom0/b\_\_dom0\_\_getVMDeps*

Getter for `b__dom0__setVMDeps`.

**returns:** The current list of dependencies for VMs.

### **b\_\_dom0\_\_qvmRun [parameter 1] ... [parameter n]**

*os/qubes4/dom0/b\_\_dom0\_\_qvmRun*

A wrapper for `qvm-run` which sets reasonable defaults for shell scripting and applies various fixes.

Most calls to `qvm-run` should be made via this function rather than interacting with `qvm-run` directly as the Qubes OS `qvm-run` was designed with interactive shell usage in mind whereas this wrapper is intended for bash developers.

Particular features:

- a certain set of reasonable default parameters is used: `-p -q -n -u root`

- `-n` was set as auto-starting VMs during Bash scripting can heavily influence the user experience (imagine the VM being shut down manually by the user whilst a bash script is running -> constant restarts)
- `stdin` is redirected to `/dev/null` by default to avoid potential security implications (accidental reads from `dom0` `stdin` passed to a VM); this can be overridden using `-stdin`
- `stdout` has the VM output and the exit code is the one of the VM
- distinguished exit conditions (executed command failed vs. `qvm-run` failed)
- workarounds for known Qubes bugs wrt `qvm-run` may be implemented here (e.g. qubes issues #3083, #4476, #4633 in the past)
- VM dependencies set with `b_dom0_setVMDeps` are checked

Please note that calling this function will make your script wait for the execution of the commands in the client VM.

Wherever possible, this function should be combined with `b_silence` as the VM output shouldn't be trusted. Otherwise please keep in mind that **both** `stdout` and `stderr` may have untrusted output which may even contain binary data. In order to validate against binary data you can e.g. use `b_types_parseString`.

[parameters]: Any parameters supported by `qvm-run`. If you pass `-a`, the default `-n` will be overridden. If you pass `-u`, the default root user is overridden. If you pass `-v`, `-q` will be overridden. If you pass `-stdin`, even `stdin` is passed to `qvm-run`. `-p` can be overridden by using `/dev/null` redirection. Only the short parameter versions are supported.

**returns:** Sets the exit code of `qvm-run` and prints its output. May error out using `B_E` if `qvm-run` itself fails.

@B\_E

### **b\_dom0\_getDispVMs**

*os/qubes4/dom0/b\_dom0\_getDispVMs*

Get a list of all currently existing disposable VMs.

[returns]: The currently existing disposable VMs as newline-separated list.

@B\_E

### **b\_dom0\_startDispVM [template]**

*os/qubes4/dom0/b\_dom0\_startDispVM*

Start a dispVM from the given template in the background and return its name. The disposable VM will remain started until it is shut down. If you only wish to execute a single command, please use `b_dom0_qvmRun` with the `-dispVM` parameter.

It may take a while for this function to obtain the name of the dispVM.

[template]: The template to use for the dispVM. If no template is specified, use the default Qubes template.

**returns:** Name of the dispVM that was started and sets a zero exit code on success. This function may error out.

@B\_E

**b\_dom0\_execIn** [vm] [file] [user]

*os/qubes4/dom0/b\_dom0\_execIn*

Execute the file as bash code in the given VM and wait for it to finish.

See b\_dom0\_qvmRun for various notes and words of caution.

[vm]: Name of the VM where to execute the given string. The VM is assumed to be started.

[file]: Bash file to execute in the given VM.

[user]: user as which to execute the bash file (default: root)

**returns:** Whatever the executed Bash code prints in the VM to stderr or stdout; the status code is set to the one of the executed Bash code on success (0). Non-zero exit codes and error messages may come from both this function as well as the code executed in the given VM.

@B\_E

**b\_dom0\_execStrIn** [vm] [string] [user]

*os/qubes4/dom0/b\_dom0\_execStrIn*

Execute the String as bash code in the given VM and wait for it to finish.

Convenience wrapper for b\_dom0\_execIn.

See b\_dom0\_qvmRun for various notes and words of caution.

[vm]: see b\_dom0\_execIn

[string]: Bash String to execute in the given VM.

[user]: see b\_dom0\_execIn

**returns:** see b\_dom0\_execIn; B\_E is *not* called if the executed command returns an error

@B\_E



**b\_dom0\_execFuncIn** [vm] [user] [function] [module dep 1] .. [module dep n] - [function dep 1] .. [function dep d] - [function param 1] .. [function param p]

*os/qubes4/dom0/b\_dom0\_execFuncIn*

Execute the Bash function in the given VM and wait for it to finish.

Convenience wrapper for b\_dom0\_execIn.

See b\_dom0\_qvmRun for various notes and words of caution.

[vm]: see b\_dom0\_execIn

[user]: see b\_dom0\_execIn

[function]: Name of the function as it is declared in the current scope.

[module dep i]: Names of the modules required by the function. They do not need to be imported by the function itself.

[-]: A dash as separator character between the various parameters.

[function dep j]: An arbitrary number of functions that need to be added in order to satisfy the dependencies of the function to call (e.g. if function A is meant to be called, but uses function B internally, you'll have to pass B as one of its dependencies). Dependencies that can be found in added modules must *not* be added.

[function param p]: An arbitrary number of function parameters.

**returns:** see b\_dom0\_execIn; B\_E is *not* called if the executed command returns an error

@B\_E

**b\_dom0\_waitForFileIn** [vm] [file] [maximum time]

*os/qubes4/dom0/b\_dom0\_waitForFileIn*

Convenience wrapper for b\_fs\_waitForFile.

[vm]: VM where to execute.

@B\_E

**b\_dom0\_isMountedIn** [vm] [device]

*os/qubes4/dom0/b\_dom0\_isMountedIn*

Check whether the device is mounted in the given VM.

[vm]: VM where to execute.

[device]: Full path to the device (incl. /dev/) to check.

**returns:** Sets a zero exit code if the device is mounted in the VM; a non-zero exit code means that it's either not mounted or some other error occurred.

@B\_E

**b\_dom0\_mountIfNecessary** [vm] [device] [mount point] [enforce]

*os/qubes4/dom0/b\_dom0\_mountIfNecessary*

Mount the given device in the target VM if it isn't already mounted there. Actually a wrapper for `b_fs_mountIfNecessary`.

[vm]: VM where to execute.

[device]: Full path to the device (incl. /dev/) to mount.

[mount point]: Full path where to mount the device. If no mount point is specified, a /tmp/ mount point is chosen. Non-existing directories are created. Is ignored if another mount point already exists.

[enforce]: If set to 0, enforce the given mount point to be used in addition to potentially existing ones (default: 1).

**returns:** The chosen mount point or a newline-separated list of existing mount points on success; sets a non-zero exit code on failure. As these strings are returned from the VM, extra care must be taken when parsing them.

@B\_E

**b\_dom0\_createLoopDeviceIfNecessary** [vm] [file]

*os/qubes4/dom0/b\_dom0\_createLoopDeviceIfNecessary*

Create a loop device for the file in the given VM if no old one exists. Actually a wrapper for `b_fs_createLoopDeviceIfNecessary`.

This usually requires root privileges.

[vm]: VM where to execute.

[file]: File for which to create a loop device.

**returns:** Created loop device or previously used one (incl. /dev/). Sets a non-zero exit code, if no device could be created.

@B\_E

**b\_dom0\_removeUnusedLoopDevice** [vm] [device|file] [type] [map]

*os/qubes4/dom0/b\_dom0\_removeUnusedLoopDevice*

Remove a loop device from the given VM, if it is *neither* used by Qubes OS *nor* by the given VM.

*Important:* Calling this function may cause the device to be removed as soon as it becomes unused by the VM (and the VM *only!*). So if you called this function, you should *not* use the device any further from dom0 with e.g. `qvm-block` afterwards - even if it wasn't removed.

[vm]: VM where to remove the loop device.

[device|file]: Full path (incl. `/dev/`) to the loop device or to the backing file inside the VM.

[type]: Whether the given path represents a loop device (0) or the backing file (1). If not specified, a device will be assumed, if and only if the path starts with `/dev/`.

[map]: Optional output from a previous call to `b_dom0_parseQvmBlock`. If none is specified, this function will internally call `b_dom0_parseQvmBlock`.

**returns:** Sets a zero exit code, if the loop device was not used and could thus be successfully removed *or* does not exist. A nonzero exit code indicates that the device is still being used. `B_E` is called on other errors.

@B\_E

**b\_dom0\_copy** [dom0 file] [target VM] [target VM dir] [overwrite]  
[parent dir]

*os/qubes4/dom0/b\_dom0\_copy*

Grab a file or directory in dom0 and push it to the given file path in the target VM.

[dom0 file]: location of the dom0 file or directory to read from, assumed to exist

[target VM]: VM to write to, assumed to exist. Must be started.

[target VM dir]: full path to the parent directory in the target VM to copy the file or directory to; non-existing parent directories are created; the name is taken from the name of the file/directory in dom0

[overwrite]: Whether or not to overwrite an existing [destination file] (default: 0 = overwrite).

[parent dir]: Set this to 0, if the [target VM dir] is the target *parent* directory (default) and to 1 if it includes the target file or folder *name* as last element.

**returns:** Sets an exit code of 0, if everything went fine, and a non-zero exit code otherwise.

@B\_E

**b\_dom0\_crossCopy** [source VM] [source file] [target VM] [target VM dir] [overwrite] [parent dir]

*os/qubes4/dom0/b\_dom0\_crossCopy*

Cross copy a file or directory from one VM to another, initiated by dom0. No user prompt is displayed.

[source VM]: Where to copy the source file from. Must be started.

[source file]: The file or directory to copy.

[target VM]: Where to copy the file to. Must be started.

[target VM dir]: full path to the parent directory in the target VM to copy the file or directory to; non-existing parent directories are created; the name is taken from the name of the file/directory in dom0

[overwrite]: Whether or not to overwrite an existing [destination file] (default: 0 = overwrite).

[parent dir]: Set this to 0, if the [target VM dir] is the target *parent* directory (default) and to 1 if it includes the target file or folder *name* as last element.

**returns:** Sets an exit code of 0, if everything went fine, and a non-zero exit code otherwise.

@B\_E

**b\_dom0\_ensureRunning** [vm 1] ... [vm n]

*os/qubes4/dom0/b\_dom0\_ensureRunning*

Start the given VMs if needed.

[vm i]: The VM to start.

**returns:** Nothing. B\_E will be called for VMs that could not be started (maybe they don't exist?).

@B\_E

**b\_dom0\_isRunning** [vm 1] ... [vm n]

*os/qubes4/dom0/b\_dom0\_isRunning*

Check whether the given VMs are running *and* fully operational / not hanging / not booting.

In contrast `qvm-check --running [vm]` returns true for VMs which are currently booting and `qvm-ls` doesn't check whether the OS of a VM is hanging.

[vm i]: The VM to check.

**returns:** Nothing. B\_E will be called for VMs that are not running (or don't exist?).

@B\_E

**b\_dom0\_isHalted** [vm 1] ... [vm n]

*os/qubes4/dom0/b\_dom0\_isHalted*

Check whether the given VMs are halted.

[vm i]: The VM to check.

**returns:** Nothing. B\_E will be called for VMs that are not halted (or don't exist?).

@B\_E

**b\_dom0\_ensureHalted** [vm 1] ... [vm n]

*os/qubes4/dom0/b\_dom0\_ensureHalted*

Shut down the given VMs if needed.

[vm i]: The VM to halt.

**returns:** Nothing. B\_E will be called for VMs that could not be halted (maybe they don't exist?).

@B\_E

**b\_dom0\_exists** [vm]

*os/qubes4/dom0/b\_dom0\_exists*

Check whether the given VM exists.

[vm]: The VM to check.

**returns:** Sets a zero exit code, if the VM exists a non-zero exit code otherwise.

**b\_dom0\_openCrypt** [vm] [device] [mapper name] [rw flag] [mount point] [key file] [additional options]

*os/qubes4/dom0/b\_dom0\_openCrypt*

In the given VM, open the given crypto device with dm-crypt and mount it to the mount point.

[vm]: The VM where to open the crypto device.

[device]: Full path to the device (incl. /dev/) to open.

[mapper name]: The name to assign to the decrypted version of the crypto block device. The created decrypted device will be found at `/dev/mapper/[mapper name]`.

[rw flag]: 0=open read-write, 1=open read-only (default: 0)

[mount point]: Where to mount the decrypted data to. Non-existing directories will be created. If no mount point is specified, it will not be mounted (default).

[key file]: Full vm path to the key to use for decryption. If none is specified, password-based decryption is assumed and stdin will be read to obtain the password.

[additional options]: Single string with additional cryptsetup parameters to pass on (default: none). They are passed *as-is*, i.e. you'll have to take care of proper escaping etc. yourself.

**returns:** nothing (except for user interaction prompts if no key file is provided), but sets a non-zero exit code on errors

@B\_E

**b\_dom0\_closeCrypt** [vm] [mapper name] [mount point]

*os/qubes4/dom0/b\_dom0\_closeCrypt*

Close a crypto device opened with `b_dom0_openCrypt`.

[vm]: The VM where to close the crypto device.

[mapper name]: The name used when it was opened.

[mount point]: If the decrypted data is mounted inside the [vm], please specify the mount point here so that it can be unmounted before closing the device. Otherwise the function will attempt to close the device without unmounting (likely to fail).

**returns:** nothing, but sets a non-zero exit code on errors

@B\_E

**b\_dom0\_parseQvmBlock** [variable name] [input]

*os/qubes4/dom0/b\_dom0\_parseQvmBlock*

Parse data from `qvm-block ls` to an associative array.

The indices of the associative array will be of the format `[counter]_[field]` (counters run from 0 (inclusive) to max (exclusive)).

The special index “max” is equal to the number of lines. It can be used for iterations over the map.

Currently supported [field] values: backend|device id|id|description|used by|read-only|frontend-dev

[variable name]: Name of the associative array to use as output.

[input]: Optional output from a previous `qvm-block ls` call; if none is specified, this function will execute the call and use its output.

**returns:** A string specifying an associative array in bash syntax. You can eval that string to obtain all relevant data or use the more convenient `b_dom0_getQvmBlockInfo`. On errors `B_E` is called.

@B\_E

**b\_dom0\_getQvmBlockInfo** [map] [retrieve field] [filter field 1] [filter value 1] .. [filter field n] .. [filter value n]

*os/qubes4/dom0/b\_dom0\_getQvmBlockInfo*

Convenience function to retrieve information from the output of `b_dom0_parseQvmBlock`. Searches for the given filter values in the given fields and retrieves the first field value matching all filters.

More simple, but less flexible than `b_dom0_parseQvmBlock`.

[map]: Optional output from a previous call to `b_dom0_parseQvmBlock`. If none is specified, this function will internally call `b_dom0_parseQvmBlock`.

[retrieve field]: Name of the field to retrieve.

[filter field i]: Name of any field supported by `b_dom0_parseQvmBlock`.

[filter value i]: The value to search for in [filter field i] (equality check).

**returns:** The value of the requested field and sets a zero exit code on success. Sets a non-zero exit code if no matching value could be found. On errors `B_E` is called.

@B\_E

**b\_dom0\_attachFile** [dom0 file] [target VM] [rw flag]

*os/qubes4/dom0/b\_dom0\_attachFile*

Attach the given file from dom0 (!) as block device to the target VM.

The function may attempt to acquire root privileges (and thus display a password prompt).

[dom0 file]: Full path to the file *in dom0* to attach.

[target VM]: VM to attach the file to. Must be started.

[rw flag]: If set to 0, attaches the dom0 file in r/w (read-write) mode. If set to 1 (default), attaches the file in r/o (read only) mode.

**returns:** The full path to the device created in the target VM and sets a zero exit code on success. Otherwise a non-zero exit code is set.

@B\_E

**b\_dom0\_attachVMDisk** [source VM] [target VM] [dom0 working folder] [rw flag]

*os/qubes4/dom0/b\_dom0\_attachVMDisk*

Attach the entire private disk image (private.img) of the source VM to the target VM.

**Warning:** This is contradictory to all Qubes principles and should only be done if you know exactly what you're doing. Qubes OS even has some countermeasures to prevent accidental use of this feature which are bypassed here.

[source VM]: Name of the VM whose private disk to attach to the target VM. *All data* of that VM will be shared with the target VM. Will be shut down as part of this function and must remain shut down as long as the disk is attached.

[target VM]: VM where to attach the disk as block device to. Must be started.

[dom0 working folder]: Path to a folder that this function may use at will to create or delete temporary data. Must be on the same drive as /var/lib/qubes (for example /tmp/ does *not* work) and should **exclusively** be used for calls to this function. Can safely be removed once your program finishes and the target VM is shut down.

[rw flag]: If set to 0, attaches the disk file in r/w (read-write) mode. If set to 1 (default), attaches the file in r/o (read only) mode.

**returns:** The full path to the device created in the target VM and sets a zero exit code on success. Otherwise a non-zero exit code is set.

@B\_E

**b\_dom0\_crossAttachDevice** [source VM] [source device] [target VM] [rw flag]

*os/qubes4/dom0/b\_dom0\_crossAttachDevice*

Attach the given block device from the source VM to the target VM. This is merely a convenience wrapper for **qvm-block attach**.

[source VM]: VM where the source file can be found.

[source device]: Device to attach to the [target VM].

[target VM]: VM to attach the device to. Must be started.

[rw flag]: If set to 0, attaches the [source device] in r/w (read-write) mode. If set to 1 (default), attaches the file in r/o (read only) mode.

**returns:** The full path to the device created in the target VM and sets a zero exit code on success. Otherwise a non-zero exit code is set.



@B\_E

**b\_dom0\_crossAttachFile** [source VM] [source file] [target VM] [rw flag]

*os/qubes4/dom0/b\_dom0\_crossAttachFile*

Attach the given file from the source VM as block device to the target VM.

[source VM]: VM where the source file can be found.

[source file]: File to attach as block device.

[target VM]: VM to attach the file to. Must be started.

[rw flag]: If set to 0, attaches the [source file] in r/w (read-write) mode. If set to 1 (default), attaches the file in r/o (read only) mode.

**returns:** The full path to the device created in the target VM and sets a zero exit code on success. Otherwise a non-zero exit code is set.

@B\_E

**b\_dom0\_detachDevice** [vm] [device]

*os/qubes4/dom0/b\_dom0\_detachDevice*

Attempts to detach the given device from the VM. This may fail if the VM is using the device and thus it is usually a better idea to just shut the VM down.

[vm]: VM from which to detach the device.

[device]: Full path to the device in the VM. E.g. the return values of `b_dom0_crossAttachFile`, `b_dom0_attachFile` or `b_dom0_attachVMDisk`.

**returns:** nothing, but sets a zero exit code on success

@B\_E

**b\_dom0\_enterEventLoop** [callback function] [heartbeat interval]

*os/qubes4/dom0/b\_dom0\_enterEventLoop*

Enter a blocking loop to react to Qubes OS events. `b_dom0_disconnectEventLoop` can be used to disconnect from the event loop asynchronously, e.g. from exit traps.

If you want to obtain an overview of Qubes OS events, please use the `qwatch` utility manually.

[callback function]: Name of the function to call for *every* Qubes OS event. Since the number of events may be high, the function should do appropriate filtering

at high performance.

The callback function should be declared as follows:

`callback_function_name [subject] [event name] [event info] [timestamp]`  
[subject]: The subject name Qubes OS provides. Usually the VM for which the event was reported. 'None' appears to mean 'dom0'.  
[event name]: Name of the event for which the callback function was called.  
[event info]: May contain additional information about the event (e.g. arguments).  
[timestamp]: When the event was received in ms since EPOCH.  
returns: Nothing. A non-zero exit code will abort further processing.  
[heartbeat interval]: Interval in ms at which to send heartbeat events (default: no heartbeat events).

**returns:** Nothing, but uses the exit code of the last callback function execution as its own. Sets an exit code of 0, if the event loop was terminated by `b_dom0_disconnectEventLoop`. `B_E` is only called on exceptional errors.

*@StateChanging*

*@B\_E*

### **b\_dom0\_disconnectEventLoop**

*os/qubes4/dom0/b\_dom0\_disconnectEventLoop*

Send a termination request to a dom0 event loop started with `b_dom0_enterEventLoop`. This is useful to exit the event loop from outside of it.

**returns:** A non-zero exit code indicates that either no active event loop existed or the signal sending failed. Never errors out to be suitable for e.g. exit traps.

*@StateChanging*

### **b\_dom0\_testMultiple [vm] [operator] [list]**

*os/qubes4/dom0/b\_dom0\_testMultiple*

Run multiple `test` checks inside the given VM with a single `qvm-run` call.

[vm]: Where to run the checks.

[operator]: The test operator to use for the list of parameters, e.g. `-f`.

[list]: Newline-separated list of parameters to check, e.g. a list of files for the `-f` operator.

**returns:** The subset of the list that matched the operator and sets a zero exit code on success.

*@B\_E*

## **proc**

Collection of process and thread related functions.

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0.2

### **Dependencies**

tail  
timeout

### **Functions**

#### **b\_\_proc\_\_getDeps**

*proc/b\_\_proc\_\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

#### **b\_\_proc\_\_pidExists [pid]**

*proc/b\_\_proc\_\_pidExists*

Check whether the given process ID exists on the system.

[pid]: process ID to check for existence (process exists)

**returns:** A zero exit code, if it exists and a non-zero exit code if it doesn't; this function attempts to check the existence of the given process across *all* users, but it cannot guarantee correctness if the user running this script has very low privileges.

#### **b\_\_proc\_\_childExists [pid]**

*proc/b\_\_proc\_\_childExists*

Check whether the given process ID exists *and* is a *direct* child of the calling bash process.

[pid]: process ID to check

**returns:** A zero exit code, if the caller is a parent of the given pid.

**b\_\_proc\_\_waitForPid** [pid] [maximum time]

*proc/b\_\_proc\_\_waitForPid*

Wait for the given process to exit. If it doesn't exist, exit immediately.

[pid]: Process ID of the process to wait for. Doesn't need to be a child.

[maximum time]: Maximum time in seconds to wait for the process to exit (default: 0 = indefinitely).

**returns:** Nothing, always sets a zero exit code. Use b\_\_proc\_\_pidExists if you need to know whether the process finished.

## **str**

Collection of string related functions.

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0.1

## **Dependencies**

no dependencies

## **Functions**

**b\_\_str\_\_getDeps**

*str/b\_\_str\_\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

**b\_\_str\_\_stripQuotes** [string]

*str/b\_\_str\_\_stripQuotes*

Remove any single or double quotes around the given string.

[string]: string which might be enclosed in single or double quotes ( ' or " )

**returns:** [string] without the enclosed single or double quotes, if there were any; if none were found the original string is returned; the exit code is always zero

**b\_\_str\_\_trim** [string]

*str/b\_\_str\_\_trim*

remove any whitespace from around a string

[string]: string to trim

**returns:** [string] beginning and ending without whitespace; the exit code is always zero

## **tcOLORS**

Defines some tput related constants. In order to change terminal colors you can then use something such as

```
echo "$(tput setaf ${B_TCOLORS[red]})This is red, \  
$(tput setaf ${B_TCOLORS[blue]})this blue, $(tput sgr0)this normal."
```

tput can do a lot more than colors, see: man tput & man terminfo.

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0.1

## **Dependencies**

tput

## **Global Variables**

### **B\_TCOLORS**

*tcOLORS/B\_TCOLORS*

Global map for human readable colors to tput style color identifiers.

Currently supported values: black|red|green|yellow|blue|magenta|cyan|white

## **Functions**

### **b\_\_tcOLORS\_\_getDeps**

*tcOLORS/b\_\_tcOLORS\_\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

## traps

Collection of trap related functions.

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0.2

### Dependencies

no dependencies

### Functions

#### **b\_traps\_getDeps**

*traps/b\_traps\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

#### **b\_traps\_getCodeFor [signal]**

*traps/b\_traps\_getCodeFor*

Retrieve the current trap code / commands for the given signal.

**returns:** The current code and sets a zero exit code on success.

@B\_E

#### **b\_traps\_add [code] [signal] [tag] [append flag]**

*traps/b\_traps\_add*

Add the given commands to the given trap signal.

[code]: Whatever should be added to the trap.

[signal]: Name of the signal to add the commands to.

[tag]: An optional *unique* marker for these commands so that they can be removed with `b_traps_remove` later on.

[append flag]: Whether to append the new commands to the end (0: default) or insert them in the beginning (1).

**returns:** Whatever the internal call to *trap* to set the new trap returns.

@B\_E

**b\_traps\_\_prepend** [code] [signal] [tag]

*traps/b\_traps\_\_prepend*

Prepend the given commands to the ones currently existing for the given trap signal.

Convenience wrapper to b\_traps\_\_add with [append flag] set to 1.

[code]: see b\_traps\_\_add

[signal]: see b\_traps\_\_add

[tag]: see b\_traps\_\_add

**returns:** see b\_traps\_\_add

@B\_E

**b\_traps\_\_remove** [signal] [tag]

*traps/b\_traps\_\_remove*

Remove the commands tagged with the given tag from the signal trap.

[signal]: Name of the signal to remove the commands from.

[tag]: The *unique* marker to identify the commands to be removed.

**returns:** Nothing, but sets a zero exit code on success. May error out if the tag isn't found or the internal trap call failed.

@B\_E

## types

Functions for data type checks and conversions.

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0.2

## Dependencies

mktemp

mkfifo

rm

wc

strings

tee

head

## Global Variables

### B\_TYPES\_ENCODINGS

*types/B\_TYPES\_ENCODINGS*

Global map for human readable string encodings which can be used for `b_types_parseString`.

Currently supported values: 7-bit|8-bit|16-bit-bigendian|16-bit-littleendian|32-bit-bigendian|32-bit-littleendian

See the strings manpage for further explanations.

## Functions

### b\_types\_getDeps

*types/b\_types\_getDeps*

Get the dependencies of this module.

**returns:** newline-separated list of dependencies of this module

### b\_types\_parseString [encoding]

*types/b\_types\_parseString*

Checks whether whatever is lying in `stdin` is a string (and not binary) and if so, prints it to `stdout`.

#### Important:

- bash has major issues whenever binary data is involved. For example equality checks may return undefined results. So whenever you are unsure as to whether a variable is a string or not, better pass it thorough this function.
- The input is taken from *stdin* rather than as parameter as binary parameters may also cause issues (special bytes etc.).
- Even builtins such as `echo` do not necessarily play well with binary data. So it is recommended to pipe binary data through this function before further processing.

Examples:

```
#check a file
```

```
b_types_parseString < "/path/to/potential/binary" > /dev/null && echo "It is a string file"
```

```
#read parts of a file as string
```

```
str="$(dd if="/path/to/another/file" bs=1 skip=8 | b_types_parseString)"
```

```
[ $? -eq 0 ] && echo "Found the following string: $str"
```



[encoding]: The encoding of the string lying in stdin. Use `B_TYPES_ENCODINGS` for this parameter. Defaults to `${B_TYPES_ENCODINGS["7-bit"]}`, which makes sense in 99% of all cases as scripts should use ASCII only anyway (when no user-interaction is involved) in order to remain portable. Keep in mind that bash also needs to support the target encoding in order to support further processing.

**returns:** The data as String, if the input data was found to be a String. If no String was found to be lying in stdin, the output is an undefined string and a non-zero exit code is set. `B_E` is only called on exceptional errors.

@B\_E

### **b\_types\_isInteger [string]**

*types/b\_types\_isInteger*

Check whether the given String is an integer (positive or negative) or not.

[string]: The string to check. If it may be binary data, please make sure to pass it through `b_types_parseString` first.

**returns:** Nothing, but sets a zero exit code if and only if the given string represents an integer.

### **tests/00\_\_first.bats**

This is not a real test, but can be used to execute some code *before* any bats tests are run.

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### **tests/args.bats**

Bats tests for the args module.

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### **tests/arr.bats**

Bats tests for the arr module.

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0.3

### **tests/blib.bats**

Bats tests for blib main.

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### **tests/cdoc.bats**

Bats tests for the cdoc module.

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### **tests/daemon.bats**

Bats tests for the daemon module.

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### **tests/date.bats**

Bats tests for the date module.

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### **tests/delay.bats**

Bats tests for the date module.

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### **tests/flog.bats**

Bats tests for the flog library.

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### **tests/fs.bats**

Bats tests for the arr module.

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### **tests/http.bats**

Bats tests for the http module.

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### **tests/ini.bats**

Bats tests for the ini module.

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### **tests/multithreading/ipcm.bats**

Bats tests for the ipcm module.

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### **tests/multithreading/ipcv.bats**

Bats tests for the ipcw module.

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### **tests/multithreading/mtx.bats**

Bats tests for the arr module.

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### **tests/multithreading/multiw.bats**

Bats tests for the multiw module.

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### **tests/os/osid.bats**

Bats tests for the os/osid module.

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### **tests/os/qubes4/dom0.bats**

Bats tests for the os/qubes4/dom0 module.

**Important:** This is *test* code and should not be used in production environments as quite often it is lacking checks wrt untrusted VM output from e.g. `b_dom0_qvmRun`. Developers should follow the standards outlined there for their projects.

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### **tests/proc.bats**

Bats tests for the arr module.

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### **tests/str.bats**

Bats tests for the str module.

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### **tests/tcolors.bats**

Bats tests for the tcolors module.

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## **tests/test\_\_common.bash**

Some code and vars meant to be shared across bats tests.

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### **Global Variables**

#### **TEST\_\_STATE**

*tests/test\_\_common.bash/TEST\_\_STATE*

A map which can be used to create a persistent state across multiple tests.  
By default, bats creates a new shell environment for each test it runs, resetting all changes to global variables.  
The state can be managed with the load/save/clearBlibTestState functions below.

### **Functions**

#### **loadBlib**

*tests/test\_\_common.bash/loadBlib*

Loads blib for testing.

#### **skipIfNoUserData**

*tests/test\_\_common.bash/skipIfNoUserData*

Skip the test if no user data was found.

#### **skipIfNoUserData**

*tests/test\_\_common.bash/skipIfNoUserData*

Skip the test if pandoc is not installed.

#### **skipIfNotQubesDom0**

*tests/test\_\_common.bash/skipIfNotQubesDom0*

Skip the test if we're not running inside Qubes OS dom0.

### **loadBlibTestState**

*tests/test\_common.bash/loadBlibTestState*

Load the TEST\_STATE with the data that was saved last via saveBlibState. If you want to use TEST\_STATE, call this function during test setup.

### **saveBlibState**

*tests/test\_common.bash/saveBlibState*

Save the current TEST\_STATE to make it available for further tests.

### **clearBlibTestState**

*tests/test\_common.bash/clearBlibTestState*

Clears the current test state and removes its persistent files.

### **testGetterSetter [setter function] [value to set] [reset]**

*tests/test\_common.bash/testGetterSetter*

Executes the given setter function *in the current environment* and makes sure the respective getter function (assumed to have the same name with just a *get* instead of *set*) returns that value.

[setter function]: name of the setter function to call

[value to set]: value to set with the setter function

[reset]: if set to 0 (default), reset the value back to its original value after testing the setter function

**returns:** nothing, but errors out on test failures

### **startTimer**

*tests/test\_common.bash/startTimer*

Start a new time measurement window.

**returns:** nothing

### **endTimer**

*tests/test\_common.bash/endTimer*

Get the difference in time in seconds since the last time startTimer was called.

**returns:** time difference in seconds

**funcTimeout** [timeout] [function] [args]

*tests/test\_common.bash/funcTimeout*

Run the given function with a timeout inside a subshell.

[timeout]: Timeout in seconds after which to terminate the function.

[function]: The function to execute.

[args]: Function arguments.

**returns:** An exit code of 124, if the function timed out. Otherwise returns whatever the function returned.

**runSL** [commands]

*tests/test\_common.bash/runSL*

A version of the bats **run** command which makes sure that the bash runtime state does not change after running the given commands (SL = stateless).

This *should* be the default method of executing tests for blib.

If the given commands are expected to change the state, use runSC instead. In particular the default bats **run** should almost never be used.

Also prints an identifier for easier debugging. The identifier starts at 1 on the first run call per test and increases with each further run call.

**WARNING:** As the bats **run** it runs inside a subshell. So don't expect changes to persist.

[commands]: The commands to run.

**returns:** whatever bats run returns

**runSC** [commands]

*tests/test\_common.bash/runSC*

A version of the bats **run** command which ignore changes to the bash runtime state (SC = state changing).

If the given commands are expected to be stateless, use runSL instead. In particular the default bats **run** should almost never be used.

Also prints an identifier for easier debugging. The identifier starts at 1 on the first run call per test and increases with each further run call.

**WARNING:** As the bats **run** it runs inside a subshell. So don't expect changes to persist.

[commands]: The commands to run.

**returns:** whatever bats run returns

## **tests/traps.bats**

Bats tests for the cdoc module.

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## **tests/types.bats**

Bats tests for the types module.

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## **tests/user\_test\_data.bash.example**

Example of a `user_test_data` file.

That file is meant for static bash variables that must be set *by the user* (as they may e.g. be OS specific) in order for some tests to work.

If that file doesn't exist or could not be loaded, these tests may be skipped by blib.

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## **Global Variables**

### **UTD\_ONLINE**

*tests/user\_test\_data.bash.example/UTD\_ONLINE*

Whether or not the test machine is connected to the Internet.

### **UTD\_OS**

*tests/user\_test\_data.bash.example/UTD\_OS*

Specify your operating system here, currently supported values:  
debian|fedora|red hat|centos|ubuntu|opensuse|qubes dom0|other  
Qubes VMs should be specified with their OS.

### **UTD\_QUBES**

*tests/user\_test\_data.bash.example/UTD\_QUBES*



Specify whether you are running Qubes OS and in what environment here, possible values:

no|vm|dom0

### UTD\_QUBES\_TESTVM

*tests/user\_test\_data.bash.example/UTD\_QUBES\_TESTVM*

If you're using Qubes OS, please specify a *disposable* virtual machine with a static name to be used for testing here. This test VM may crash, be destroyed or whatever - so please don't use a production VM!

Apart from that, the tests will be conducted with disposable VMs with dynamic names using your default template.

Example command to create such a test VM:

```
qvm-create --class DispVM --prop netvm='' --template nonet-dvm -l red d-testing
```

Can safely be ignored if you don't run Qubes OS-related tests.

### UTD\_QUBES\_TESTVM\_PERSISTENT

*tests/user\_test\_data.bash.example/UTD\_QUBES\_TESTVM\_PERSISTENT*

If you're using Qubes OS, please specify a *persistent/non-disposable* virtual machine with a static name to be used for testing here. This test VM may crash, be destroyed or whatever - so please don't use a production VM!

Example command to create such a test VM:

```
qvm-create -l red --prop netvm='' testing-pers
```

Can safely be ignored if you don't run Qubes OS-related tests.

### UTD\_QUBES\_DISPVM\_TEMPLATE

*tests/user\_test\_data.bash.example/UTD\_QUBES\_DISPVM\_TEMPLATE*

Qubes OS disposable VM template to use for testing. The test code will create disposable VMs from that template. It will *not* modify the template itself.

If no template is specified, the Qubes OS default template is used.

### UTD\_QUBES\_DOM0\_WD

*tests/user\_test\_data.bash.example/UTD\_QUBES\_DOM0\_WD*

Full path to a folder in Qubes dom0 that can be created and deleted at will (working directory). Do **not** use an existing folder here!

Can safely be ignored if you don't run Qubes OS-related tests.

## **UTD\_PW\_FREE\_USER**

*tests/user\_test\_data.bash.example/UTD\_PW\_FREE\_USER*

A user that allows password-less logons with sudo or su for testing.

If you run bats as root, neither sudo nor su should ask for a password.

Tests requiring admin privileges (e.g. mounting devices) may require this to be root or skip otherwise.

## **tests/ZZ\_last.bats**

This is not a real test, but can be used to execute some code *after* any bats tests are run.

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0.1

## **Reference List**

B\_ARGS

b\_args\_assertOptions

b\_args\_get

b\_args\_getCount

b\_args\_getDeps

b\_args\_getInt

b\_args\_getOption

b\_args\_getOptionCount

b\_args\_getOptionInt

b\_args\_getOptionParamSeparator

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