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USER MANUAL

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# **Nomadik Multiprocessing Framework Execution Engine Scheduling Model**

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**NMF version 1.8 and more**  
April 2009



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# Chapter 1

## Design guides

### 1.1 Situation that break re-entrancy

#### 1.1.1 Multiple synchronous call

When two client components could make synchronous call to one server component, you must take care about not breaking re-entrancy since no synchronization is insert during synchronous call.

##### By two components running at different priorities

When deploying arhitecture found in [Figure 1.1](#) and if such sequence occure:

1. `Client A` component is scheduled.
2. `Client A` component call synchronously `Server` component without been exit from it.
3. An event is posting to `Client B` (for example by an interrupt handler).
4. `Client B` which is more prioritized start its execution and preempt `Client A`.
5. `Client B` component call synchronously `Server` component driving to re-enter in it.

This will break re-entrancy of `Server` component.

Nevertheless, this construction is allowed if `Server` component is a state-less component (no writable global variable).

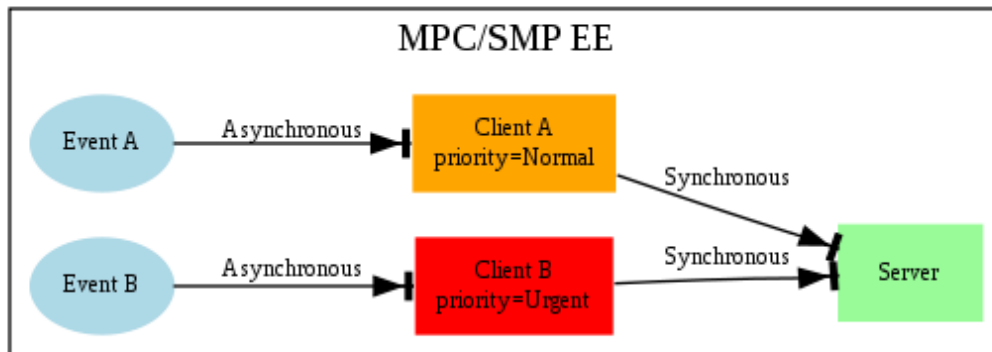


Figure 1.1: Re-entrancy on synchronous call by two components running at different priority

### By two components running at same priority in SMP EE

When deploying architecture found in [Figure 1.2](#) and if such sequence occurs:

1. Client A component is scheduled by first core.
2. Client A component call synchronously Server component without been exit from it.
3. Client B component is scheduled by second core.
4. Client B component call synchronously Server component driving to re-enter in it.

This will break re-entrancy of Server component.

Nevertheless, this construction is allowed if Server component is a state-less component (no writable global variable).

## 1.2 Situation that break Real-time

### 1.2.1 Infinite loop in component

### 1.2.2 Call of blocking IO in component in SMP EE

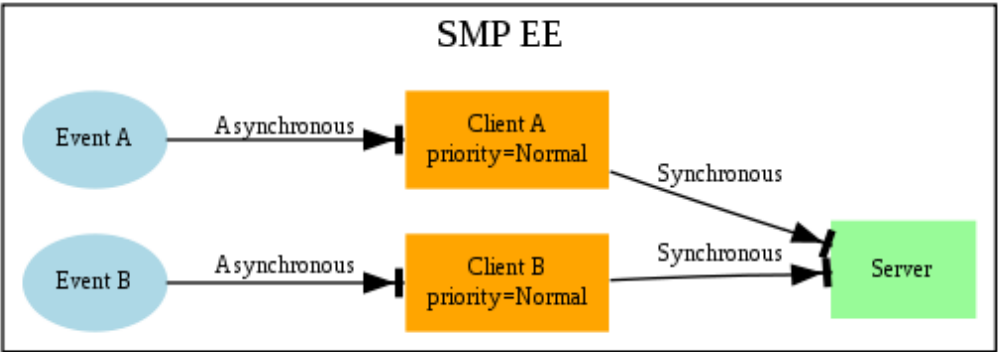


Figure 1.2: Re-entrancy on synchronous call by two components running at same priority on SMP EE

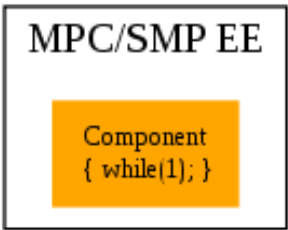


Figure 1.3: Infinite loop in component

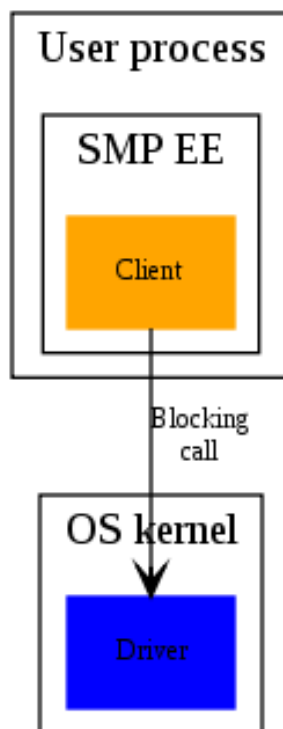


Figure 1.4: Call of blocking IO in component



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