18.06 11/29/22

Practice Problems

1. Remember that a matrix Q is unitary if $Q^HQ = I$. A matrix is orthogonal if it is real and unitary; that is, if it is real and $Q^TQ = I$.

a) Find the flaw in this argument:

False Claim: all eigenvalues of an orthogonal matrix are ± 1 . Indeed, if $Qx = \lambda x$,

$$\lambda^2 x^T x = (Qx)^T (Qx) = x^T (Q^T Q) x = x^T x,$$

therefore $\lambda^2 = 1$, so $\lambda = \pm 1$.

If you're stuck, think about what happens for a rotation matrix

$$R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}.$$

b) Correct the proof to show

True Claim: all eigenvalues of a unitary matrix have magnitude 1 (e.g. $\lambda = e^{i\phi}$ for some ϕ).

- c) Show that the eigenvectors for different eigenvalues of a unitary matrix are orthogonal.
- d) Show that the determinant of any real unitary matrix (e.g., an orthogonal matrix) is ± 1 using eigenvalues. (Note: you already proved this on a previous pset in a different way.)
- **2.** Here is a quick "proof" that the eigenvalues of **every** real matrix A are real:

False Proof:
$$Ax = \lambda x$$
 gives $x^T A x = \lambda x^T x$, so $\lambda = \frac{x^T A x}{x^T x} = \frac{\text{real}}{\text{real}}$.

Find the flaw in this reasoning – a hidden assumption that is not justified. You can test those steps on the 90° rotation matrix

$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \qquad \lambda = i, \ x = \begin{pmatrix} i \\ 1 \end{pmatrix}.$$

- **3.** a) If S is a positive definite matrix, show that S^{-1} is also positive definite.
 - b) If S and T are positive definite, show that their sum S + T is also positive definite. If $S = A^H A$ and $T = B^H B$ for full-column-rank matrices A and B, then can you write down a full column-rank matrix C so that $S + T = C^T C$?
- **4.** Say A is a 3×3 real matrix. The matrix $B = A + A^T$ has eigenvalues $\lambda_1 = 2, \lambda_2 = 0, \lambda_3 = 1$, with corresponding eigenvectors $x_1 = \begin{bmatrix} 1 & 2 & 1 \end{bmatrix}, x_2 = \begin{bmatrix} -2 & 1 & 0 \end{bmatrix}$ and $x_3 = \begin{bmatrix} 1 & 2 & -5 \end{bmatrix}$.
 - a) What is e^B ? (It's fine to leave your answer as a product of several matrices, as long as each matrix is written down explicitly)
 - b) Let $C = (I B)(I + B)^{-1}$. What are the eigenvalues and eigenvectors of C?
 - c) Give a good approximation for

$$y = C^{100} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

in terms of a single eigenvector.