

USING MACHINE LEARNING FOR NON LINEAR EDDY-VISCOSITY MODELS

Lars Davidson

NON-LINEAR $k - \varepsilon$ MODEL

- Non-linear $k - \omega$ model by Craft *et al.* [1]. $a_{ij} \equiv \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij}$

$$\begin{aligned}
 a_{ij} = & \boxed{-2c_\mu \tau \bar{S}_{ij}} + c_1 \tau^2 \left(\bar{S}_{ik} \bar{S}_{kj} - \frac{1}{3} \bar{S}_{\ell k} \bar{S}_{\ell k} \delta_{ij} \right) + c_2 \tau^2 (\bar{\Omega}_{ik} \bar{S}_{kj} - \bar{S}_{ik} \bar{\Omega}_{kj}) \\
 & + c_3 \tau^2 \left(\bar{\Omega}_{ik} \bar{\Omega}_{jk} - \frac{1}{3} \bar{\Omega}_{\ell k} \bar{\Omega}_{\ell k} \delta_{ij} \right) + c_4 \tau^3 (\bar{S}_{ik} \bar{S}_{k\ell} \bar{\Omega}_{\ell j} - \bar{\Omega}_{i\ell} \bar{S}_{\ell k} \bar{S}_{kj}) + c_5 \tau^3 (\bar{\Omega}_{i\ell} \bar{\Omega}_{\ell m} \bar{S}_{mj} + \bar{S}_{i\ell} \bar{\Omega}_{\ell m} \\
 & - c_5 \frac{2}{3} \bar{\Omega}_{mn} \bar{\Omega}_{n\ell} \bar{S}_{\ell m} \delta_{ij} + c_6 \tau^3 \bar{S}_{k\ell} \bar{S}_{k\ell} \bar{S}_{ij} + c_7 \tau^3 \bar{\Omega}_{k\ell} \bar{\Omega}_{k\ell} \bar{S}_{ij}, \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} - \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \tau = k/\varepsilon
 \end{aligned} \tag{1}$$

NON-LINEAR $k - \varepsilon$ MODEL

- Non-linear $k - \omega$ model by Craft *et al.* [1]. $a_{ij} \equiv \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij}$

$$\begin{aligned}
 a_{ij} = & \boxed{-2c_\mu \tau \bar{S}_{ij}} + c_1 \tau^2 \left(\bar{S}_{ik} \bar{S}_{kj} - \frac{1}{3} \bar{S}_{\ell k} \bar{S}_{\ell k} \delta_{ij} \right) + c_2 \tau^2 (\bar{\Omega}_{ik} \bar{S}_{kj} - \bar{S}_{ik} \bar{\Omega}_{kj}) \\
 & + c_3 \tau^2 \left(\bar{\Omega}_{ik} \bar{\Omega}_{jk} - \frac{1}{3} \bar{\Omega}_{\ell k} \bar{\Omega}_{\ell k} \delta_{ij} \right) + c_4 \tau^3 (\bar{S}_{ik} \bar{S}_{k\ell} \bar{\Omega}_{\ell j} - \bar{\Omega}_{i\ell} \bar{S}_{\ell k} \bar{S}_{kj}) + c_5 \tau^3 (\bar{\Omega}_{i\ell} \bar{\Omega}_{\ell m} \bar{S}_{mj} + \bar{S}_{i\ell} \bar{\Omega}_{\ell m} \\
 & - c_5 \frac{2}{3} \bar{\Omega}_{mn} \bar{\Omega}_{n\ell} \bar{S}_{\ell m} \delta_{ij} + c_6 \tau^3 \bar{S}_{k\ell} \bar{S}_{k\ell} \bar{S}_{ij} + c_7 \tau^3 \bar{\Omega}_{k\ell} \bar{\Omega}_{k\ell} \bar{S}_{ij}, \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} - \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \tau = k/\varepsilon
 \end{aligned} \tag{1}$$

- Fully developed channel flow includes only $c_1 - c_3$

NON-LINEAR $k - \varepsilon$ MODEL

- Non-linear $k - \omega$ model by Craft *et al.* [1]. $a_{ij} \equiv \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij}$

$$a_{ij} = \boxed{-2c_\mu \tau \bar{S}_{ij}} + c_1 \tau^2 \left(\bar{S}_{ik} \bar{S}_{kj} - \frac{1}{3} \bar{S}_{\ell k} \bar{S}_{\ell k} \delta_{ij} \right) + c_2 \tau^2 (\bar{\Omega}_{ik} \bar{S}_{kj} - \bar{S}_{ik} \bar{\Omega}_{kj}) \quad (1)$$

$$+ c_3 \tau^2 \left(\bar{\Omega}_{ik} \bar{\Omega}_{jk} - \frac{1}{3} \bar{\Omega}_{\ell k} \bar{\Omega}_{\ell k} \delta_{ij} \right) + c_4 \tau^3 (\bar{S}_{ik} \bar{S}_{k\ell} \bar{\Omega}_{\ell j} - \bar{\Omega}_{i\ell} \bar{S}_{\ell k} \bar{S}_{kj}) + c_5 \tau^3 (\bar{\Omega}_{i\ell} \bar{\Omega}_{\ell m} \bar{S}_{mj} + \bar{S}_{i\ell} \bar{\Omega}_{\ell m}$$

$$- c_5 \frac{2}{3} \bar{\Omega}_{mn} \bar{\Omega}_{nl} \bar{S}_{\ell m} \delta_{ij} + c_6 \tau^3 \bar{S}_{k\ell} \bar{S}_{k\ell} \bar{S}_{ij} + c_7 \tau^3 \bar{\Omega}_{k\ell} \bar{\Omega}_{k\ell} \bar{S}_{ij}, \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} - \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \tau = k/\varepsilon$$

- Fully developed channel flow includes only $c_1 - c_3$

$$a_{11} = \frac{1}{12} \tau^2 \left(\frac{\partial \bar{v}_2}{\partial x_1} \right)^2 (c_1 - 6c_2 + c_3), \quad a_{22} = \frac{1}{12} \tau^2 \left(\frac{\partial \bar{v}_2}{\partial x_1} \right)^2 (c_1 + 6c_2 + c_3) \quad (2)$$

$$a_{33} = -\frac{1}{6} \tau^2 \left(\frac{\partial \bar{v}_2}{\partial x_1} \right)^2 (c_1 + c_3)$$

THE LOW-RE NUMBER MODEL BY CRAFT *et al.* [1]

$$\overline{v_1'^2} = \frac{k\nu_t}{12\tilde{\varepsilon}} \left(\frac{\partial \bar{v}_1}{\partial x_2} \right)^2 (c_0 + 6c_2) + \frac{2}{3}k, \quad \overline{v_2'^2} = \frac{k\nu_t}{12\tilde{\varepsilon}} \left(\frac{\partial \bar{v}_1}{\partial x_2} \right)^2 (c_0 - 6c_2) + \frac{2}{3}k$$

$$\overline{v_3'^2} = -\frac{k\nu_t}{6\tilde{\varepsilon}} \left(\frac{\partial \bar{v}_1}{\partial x_2} \right)^2 c_0 + \frac{2}{3}k, \quad \overline{v_1'v_2'} = -\nu_t \frac{\partial \bar{v}_1}{\partial x_2}, \quad \tilde{\varepsilon} = \varepsilon - \nu \left(\frac{\partial k^{1/2}}{\partial y} \right)^2, \quad \nu_t = c_\mu \frac{k^2}{\tilde{\varepsilon}}$$

$$c_\mu = \frac{0.667r_\eta [1 - \exp(-0.415 \exp(1.3\eta^{5/6}))]}{1 + 1.8\eta}, \quad \eta = r_\eta \frac{k}{\tilde{\varepsilon}} \frac{\partial \bar{v}_1}{\partial x_2}, \quad R_t = \frac{k^2}{\nu\tilde{\varepsilon}}$$

$$A_2 = a_{11}a_{22} + a_{11}a_{33} + a_{22}a_{33} - 2a_{12}a_{21}$$

$$f_\mu = 1.1(\tilde{\varepsilon}/\varepsilon)^{1/2} \frac{1 - 0.8 \exp(-R_t/30)}{1 + 0.6A_2 + 0.2A_2^{3.5}}$$

$$r_\eta = 1 + (1 - \exp(-(2A_2)^3)) \left[1 + 4(\exp(-R_t/20))^{1/2} \right]$$

$$f_q = \frac{r_\eta}{1 + 0.0086\eta^2)^{1/2}}, \quad c_1 = -0.05 \frac{f_q}{f_\mu}, \quad c_2 = 0.11 \frac{f_q}{f_\mu}, \quad c_3 = 0.21 \frac{f_q}{f_\mu}$$

THE LOW-RE NUMBER MODEL BY CRAFT *et al.* [1]: PREDICTIONS

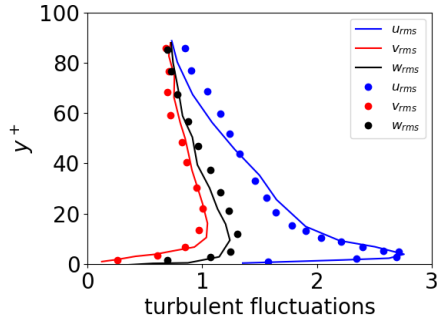


FIGURE: Turbulent fluctuations in fully developed-channel flow at $Re_b = 13\,750$. Lines: predictions taken from [1]; symbols: DNS data taken from [1]

NON-LINEAR $k - \varepsilon$ MODEL: MACHINE LEARNING

With $c_0 \equiv c_1 + c_3$, Eq. 2 at Slide 2 reads

NON-LINEAR $k - \varepsilon$ MODEL: MACHINE LEARNING

With $c_0 \equiv c_1 + c_3$, Eq. 2 at Slide 2 reads

$$\begin{aligned}\overline{v_1'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 + 6c_2) + \frac{2}{3}k, & \overline{v_2'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 - 6c_2) + \frac{2}{3}k \\ \overline{v_3'^2} &= -\frac{k}{6}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 c_0 + \frac{2}{3}k, & \overline{v_1'v_2'} &= -c_\mu\tau \frac{\partial \bar{v}_1}{\partial x_2}, & c_\mu &= 0.09, & \tau &= k/\varepsilon\end{aligned}$$

NON-LINEAR $k - \varepsilon$ MODEL: MACHINE LEARNING

With $c_0 \equiv c_1 + c_3$, Eq. 2 at Slide 2 reads

$$\begin{aligned}\overline{v_1'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 + 6c_2) + \frac{2}{3}k, & \overline{v_2'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 - 6c_2) + \frac{2}{3}k \\ \overline{v_3'^2} &= -\frac{k}{6}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 c_0 + \frac{2}{3}k, & \overline{v_1'v_2'} &= -c_\mu\tau \frac{\partial \bar{v}_1}{\partial x_2}, & c_\mu &= 0.09, & \tau &= k/\varepsilon\end{aligned}$$

Inverting the matrix above we get the coefficients

NON-LINEAR $k - \varepsilon$ MODEL: MACHINE LEARNING

With $c_0 \equiv c_1 + c_3$, Eq. 2 at Slide 2 reads

$$\begin{aligned}\overline{v_1'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 + 6c_2) + \frac{2}{3}k, & \overline{v_2'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 - 6c_2) + \frac{2}{3}k \\ \overline{v_3'^2} &= -\frac{k}{6}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 c_0 + \frac{2}{3}k, & \overline{v_1'v_2'} &= -c_\mu\tau \frac{\partial \bar{v}_1}{\partial x_2}, & c_\mu &= 0.09, & \tau &= k/\varepsilon\end{aligned}$$

Inverting the matrix above we get the coefficients

$$c_0 = -\frac{6a_{33}}{\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2}, \quad c_2 = \frac{2a_{11} + a_{33}}{\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2}$$

NON-LINEAR $k - \varepsilon$ MODEL: MACHINE LEARNING

With $c_0 \equiv c_1 + c_3$, Eq. 2 at Slide 2 reads

$$\begin{aligned}\overline{v_1'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 + 6c_2) + \frac{2}{3}k, & \overline{v_2'^2} &= \frac{k}{12}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 (c_0 - 6c_2) + \frac{2}{3}k \\ \overline{v_3'^2} &= -\frac{k}{6}\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2 c_0 + \frac{2}{3}k, & \overline{v_1'v_2'} &= -c_\mu\tau \frac{\partial \bar{v}_1}{\partial x_2}, & c_\mu &= 0.09, & \tau &= k/\varepsilon\end{aligned}$$

Inverting the matrix above we get the coefficients

$$c_0 = -\frac{6a_{33}}{\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2}, \quad c_2 = \frac{2a_{11} + a_{33}}{\tau^2 \left(\frac{\partial \bar{v}_1}{\partial x_2}\right)^2}$$

Now let's train a Neural Network model (`pytorch` in Python) using DNS data to compute c_0 and c_2 .

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

Input: I've tried four options

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

Input: I've tried four options

① $(\partial U^+ / \partial y^+)^2$

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

Input: I've tried four options

- ① $(\partial U^+ / \partial y^+)^2$
- ② $(\partial U^+ / \partial y^+)^2$ and $(\partial U^+ / \partial y^+)^{-1}$

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

Input: I've tried four options

- ① $(\partial U^+ / \partial y^+)^2$
- ② $(\partial U^+ / \partial y^+)^2$ and $(\partial U^+ / \partial y^+)^{-1}$
- ③ $T^2 (\partial U / \partial y)^2$ and $T (\partial U^+ / \partial y^+)^{-1}$, $T = k / \varepsilon$

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (`pytorch` accepts multiple output variables).

Input: I've tried four options

- ① $(\partial U^+ / \partial y^+)^2$
- ② $(\partial U^+ / \partial y^+)^2$ and $(\partial U^+ / \partial y^+)^{-1}$
- ③ $T^2 (\partial U / \partial y)^2$ and $T (\partial U^+ / \partial y^+)^{-1}$, $T = k / \varepsilon$
- ④ $(\partial U^+ / \partial y^+)^2$ and k^+ / ε^+

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

Input: I've tried four options

- ① $(\partial U^+ / \partial y^+)^2$
- ② $(\partial U^+ / \partial y^+)^2$ and $(\partial U^+ / \partial y^+)^{-1}$
- ③ $T^2 (\partial U / \partial y)^2$ and $T (\partial U^+ / \partial y^+)^{-1}$, $T = k / \varepsilon$
- ④ $(\partial U^+ / \partial y^+)^2$ and k^+ / ε^+

Other possible input options:

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

Input: I've tried four options

- ① $(\partial U^+ / \partial y^+)^2$
- ② $(\partial U^+ / \partial y^+)^2$ and $(\partial U^+ / \partial y^+)^{-1}$
- ③ $T^2 (\partial U / \partial y)^2$ and $T (\partial U^+ / \partial y^+)^{-1}$, $T = k / \varepsilon$
- ④ $(\partial U^+ / \partial y^+)^2$ and k^+ / ε^+

Other possible input options:

- ① $\nu_t^+ \equiv \nu_t / \nu$

INPUT (INFLUENCE) VARIABLE AND OUTPUT VARIABLES

Output: c_0 and c_2 (pytorch accepts multiple output variables).

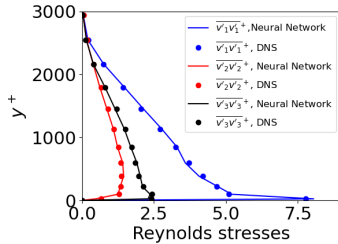
Input: I've tried four options

- ① $(\partial U^+ / \partial y^+)^2$
- ② $(\partial U^+ / \partial y^+)^2$ and $(\partial U^+ / \partial y^+)^{-1}$
- ③ $T^2 (\partial U / \partial y)^2$ and $T (\partial U^+ / \partial y^+)^{-1}$, $T = k / \varepsilon$
- ④ $(\partial U^+ / \partial y^+)^2$ and k^+ / ε^+

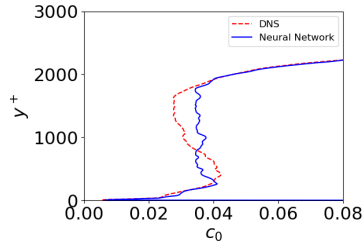
Other possible input options:

- ① $\nu_t^+ \equiv \nu_t / \nu$
- ② y^+

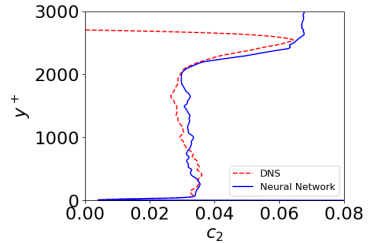
NEURAL NETWORK: DNS DATA, BOUNDARY-LAYER $Re_\theta = 8180$ [4]



(A) Reynolds stresses.



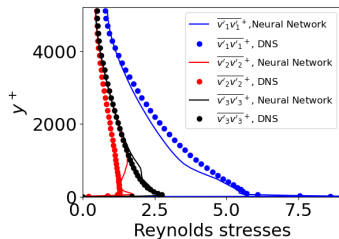
(B) Predicted c_0 coefficient.



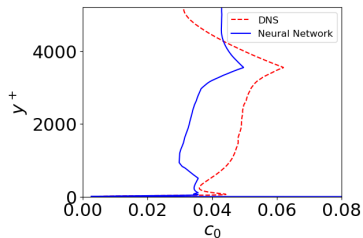
(C) Predicted c_2 coefficient.

CHANNEL FLOW, $Re_\tau = 5200$

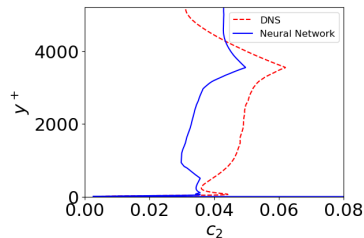
- Predicted Reynolds stresses of channel flow with trained NN (no CFD)



(A) Reynolds stresses.



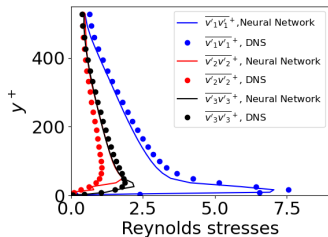
(B) Predicted c_0 coefficient.



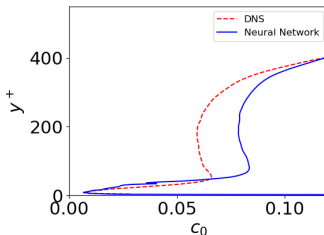
(C) Predicted c_2 coefficient.

CHANNEL FLOW, $Re_\tau = 550$

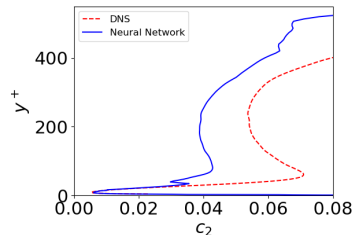
- Below I show predicted Reynolds stresses with trained NN (no CFD)



(A) Reynolds stresses.





(B) Predicted c_0 coefficient.



(C) Predicted c_2 coefficient.

REFERENCES

- [1] T. J. Craft, B. E. Launder, and K. Suga. Prediction of turbulent transitional phenomena with a nonlinear eddy-viscosity model. *International Journal of Heat and Fluid Flow*, 18:15–28, 1997.
- [2] L. Davidson. pyCALC-LES: a Python code for DNS, LES and Hybrid LES-RANS . Division of Fluid Dynamics, Dept. of Mechanics and Maritime Sciences, Chalmers University of Technology, Gothenburg, 2021.
- [3] L. Davidson. Using machine learning for formulating new wall functions for detached eddy simulation . In *14th International ERCOFTAC Symposium on Engineering Turbulence Modelling and Measurements (ETMM14), barcelona/Digital, Spain 6–8 September, 2023*.
- [4] G. Eitel-Amor, R. Orlu, and P. Schlatter. Simulation and validation of a spatially evolving turbulent boundary layers up to $Re_\theta = 8300$. *International Journal of Heat and Fluid Flow*, 47:57–69, 2014.

REFERENCES

- [5] J.A. Sillero, J. Jimenez, and R.D. Moser. One-point statistics for turbulent wall-bounded flows at Reynolds numbers up to $\delta^+ \simeq 2000$. *Physics of Fluids*, 25(105102), 2014.