

# Vector

Vector: Object끼리 더하고, Scalar이 의해 곱해질 수 있는 object.

## Vector의 종류

- ① Geometric Vector.  $\vec{x}$ ,  $\vec{x} + \vec{y} = \vec{z}$   $k\vec{x} = \vec{w}$
- ② Polynomial
- ③ Signal.
- ④  $\mathbb{R}^n = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$
- ⑤  $\mathbb{R}^{m \times n}$

"Closure" : Vector 끼리끼 Scaling이나 Adding은 다른 Vector space 생성.

## Systems of Linear Equations

m equation n unknown variables.

$$\begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix} \Rightarrow \text{Solution} \begin{cases} \text{Unique} \\ \text{No} \\ \text{Infinite} \end{cases} \quad \text{가려지함.}$$

## Matrix.

- $A \in \mathbb{R}^{m \times n}$ ,  $B \in \mathbb{R}^{m \times n}$  일 때

$A+B :=$  성분끼리 더함  $\in \mathbb{R}^{m \times n}$  : Element-wise Sum.

- $A \in \mathbb{R}^{m \times n}$ ,  $B \in \mathbb{R}^{n \times k}$  일 때,

$C = AB \in \mathbb{R}^{m \times k}$  이기 때문에  $C_{ij} = \sum_{l=1}^n a_{il} b_{lj}$

↪ Inner Product of i-th row of A and j-th column of A

- Properties of matrix addition and multiplication

- Associativity:  $(AB)C = A(BC) = ABC$

- Distributivity:  $(A+B)C = AC+BC$

- Multiplication with the identity matrix:  $\forall A \in \mathbb{R}^{n \times n} : I_n A = A I_n = A$

- Matrix Inverse :  $AB = I_n = BA$  when  $A \in \mathbb{R}^{n \times n}$ ,  $B \in \mathbb{R}^{n \times n} \Rightarrow A = B^{-1}, B = A^{-1}$

- 성질을 고려해서: Regular, Invertible, Nonsingular  $\Leftrightarrow$  Noninvertible, Singular

## Matrix.

- Transpose :  $A \in \mathbb{R}^{m \times n}$ ,  $B \in \mathbb{R}^{n \times m}$   $b_{ij} = a_{ji}$  is called transpose of A  $B = A^T$   
 $\hookrightarrow (AB)^T = B^T A^T$

## • Symmetric Matrix.

-  $A^T = A$  and  $A \in \mathbb{R}^{n \times n}$

- when A and B are symmetric,  $A+B$  is also symmetric

## • Multiplication

- by scalar.

$A \in \mathbb{R}^{m \times n}$  and  $\lambda \in \mathbb{R}$ ,  $\Rightarrow \lambda A = A$   $k_{ij} = \lambda A_{ij}$

- Compact representation of systems of linear equations.

$Ax = b \rightarrow x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \Rightarrow A \in \mathbb{R}^{m \times n}, B \in \mathbb{R}^m$  일때. How to solve?

①  $x = A^{-1}b$  when  $A \in \mathbb{R}^{m \times m}$  is Non Singular  $\Rightarrow$  매우 오래걸림 ( $m$ 이 클수록)

② Make Simpler form

$\hookrightarrow$  - 1. Exchange two equation (row  $\rightarrow$  | 2 |)

- 2. Multiply with constant  $\lambda \neq 0$  to an equation (row의 상수배)

- 3. Addition of two equations



Row-Echelon Form.

① All-zero row는 Matrix의 제일 아래로

② Pivot이 앞의 열에서 존재할수록 가장 위로 배치

$\hookrightarrow$  Pivot: first non zero number from the left

ex)  $\begin{bmatrix} 2 & 3 & 4 & 5 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 2 & 4 \end{bmatrix}$   $\bullet$ : Pivot

$\hookrightarrow$  Echelon (계단식)

- Gaussian Elimination의 의해 Row-Echelon Form 형성.

$Ax = b \Leftrightarrow [A|b] \xrightarrow{\text{Gaussian Elimination}} R(\text{Row-Echelon Form})$

Augmented Matrix = Concatenation with A and B

## Gaussian Elimination.

- example

$$\left[ \begin{array}{ccc|c} 2 & 1 & 3 & 2 \\ 0 & 0 & 4 & 3 \\ 0 & 0 & 0 & a \end{array} \right] : \text{Row-Echelon Form} \Rightarrow \begin{cases} \text{when } a=0, \text{ at least one solution} \\ \text{when } a \neq 0, \text{ no solution} \end{cases}$$

↓

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} + x_2 \begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix} \text{ 의 1개}$$

not pivot column  
free Variable ( $\lambda_1, \lambda_2$ )  
 $x_1$ 과  $x_3$  은 basic Variable

↪ Particular Solution ( $b=0$  일 때,  $\text{homogeneous system}$ )

• Free Variable: 자유롭게 결정되는 Variable (주변 변수로 지정) ⇒ Solution Set 결정.

• Basic Variable: Particular Solution 이 의해 결정되는 Variable

↪ Row-Echelon Form에서 Pivot Column 이 대응하는 Variable

\* Unique Solution 인 경우, Free Variable 이 존재하지 않음.

Infinite Solution 인 경우 Free Variable 이 존재함.

← 역도 성립.

## Back Substitution.

- After Gaussian Elimination, lowest row 부터 구하는 방법.

## ③ Make Another Simpler Form. (Reduced-Echelon Form).

- Row-Echelon Form

- Every Pivot = 1

- Pivot 이 위, 아래 행의 요소는 모두 0 (Pivot is the only nonzero entity in its column)  
⇒ back propagation process 이 사용 but Gaussian Elimination 보다 더 간단하게 사용.

- 만약 Nonsingular (Invertible) 한다면  $A$  의 Inverse Matrix 를 구하는 방법임.

$$\left[ A | I_n \right] \rightsquigarrow \dots \rightarrow \left[ I_n | A^{-1} \right]$$

## Solving System of Linear Equation.

- by using the Inverse.

① If  $A$  is invertible,

$x = A^{-1}b$  and  $x$  is Unique Solution.

② If  $A$  has linearly Independent columns, (Assumption)

$$Ax = b \Leftrightarrow A^T Ax = A^T b \Leftrightarrow x = (A^T A)^{-1} A^T b$$

↳  $(A^T A)^{-1} A^T$ : Moore-Penrose pseudo-inverse of  $A$

↳ why?

if  $A \in \mathbb{R}^{k \times 2}$  (when  $k > 2$ ),  $A$  is singular matrix. (and No square Matrix  $B$ )

$A^T A$  is square matrix (can be Nonsingular)

$x = (A^T A)^{-1} A^T b$  와 같은 Solution은

$\|Ax - b\|^2$ 를 최소화하는 Approximation Solution으로 대응됨. (Linear Regression)

※ Linearly Independent.

$$\left\{ \begin{array}{c} x_1 \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} + x_2 \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \dots x_m \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} = b \end{array} \right. \text{ 이 때 } \begin{array}{c} \parallel \\ \alpha_1 \end{array} \quad \begin{array}{c} \parallel \\ \alpha_2 \end{array} \quad \begin{array}{c} \parallel \\ \alpha_k \end{array}$$

$b=0$ 을 만족하는

$x_1, \dots, x_m$ 이 모두 0일 때만 성립시

$\alpha = \{ \alpha_1, \alpha_2, \dots, \alpha_p \}$ 인 Vector가

$A$ 의 선형독립 (Linearly Independent)