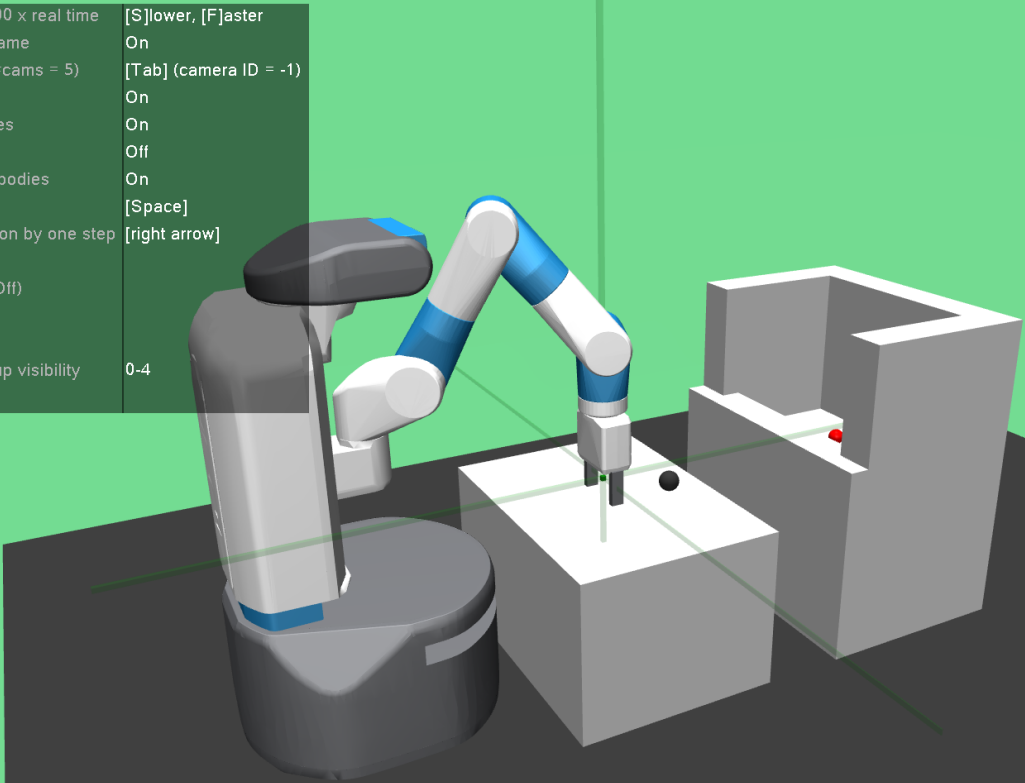


- Run speed = 1.000 x real time
- Ren[d]er every frame
- Switch camera (#cams = 5)
- [C]ontact forces
- Referenc[e] frames
- T[r]ansparent
- Display [M]ocap bodies
- Stop
- Advance simulation by one step
- [H]ide Menu
- Record [V]ideo (Off)
- Cap[t]ure frame
- Start [i]pdb
- Toggle geomgroup visibility

[S]lower, [F]aster  
On  
[Tab] (camera ID = -1)  
On  
On  
Off  
On  
[Space]  
[right arrow]  
0-4



FPS 29  
Solver iterations 2

Step 1300  
timestep 0.00200  
n\_substeps 20