Tom Marty



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in LinkedIn

Montreal, Canada

Twitter

EDUCATION

Ph.D. in Machine Learning

Jan. 2024 –

MILA - Montréal Institute of Learning Algorithms - GPA 4.00

Montréal, Canada

M.Sc. in Machine Learning

Sep. 2021 – Jun. 2023

Polytechnique Montréal - GPA 3.91

Montréal, Canada

B.Sc. in Computer Science, minor in Applied Mathematics

Sep. 2018 - Jun. 2021

X 2018, Ecole Polytechnique - GPA 3.84

Palaiseau, France

Lycée Jean-Baptiste Say

Sep. 2016 – Jun. 2018

"Classe préparatoire" Intensive multi-disciplinary preparation - GPA 4.00 - Top 0.1%

Paris, France

RESEARCH INTEREST

• Broad interest: Artificial intelligence, Machine Learning, Generative AI and Operational Research

• Methodological interest: Causality, Bayesian Statistics, OOD Generalization, Information Theory

• Applications: Fairness, Robust Machine Learning, Open-Ended Decision Making, AI for video-games

INDUSTRY AND ACADEMIC EXPERIENCE

Visiting Researcher

Apr. 2023 – Sept. 2023

ServiceNow Research

Montréal, Canada

• Developped WorkArena (ICML2024): an open-source Benchmark and Gym environment for evaluating Agent at solving common-knowledge tasks on a Web Browser

Research Supervisor

Jan. 2022 – Sept. 2022

Corail Research Group

Montréal, Canada

- Supervised five interns on the development of the open-source project SeaPearl
- Teaching Assistant for the course INF8215 given by Quentin Cappart in Fall 21 and Fall 22

Research Engineer Intern

Jan. 2021 – Sept. 2021

Corail Research Group

Montréal, Canada

- Developped SeaPearl : an open-source RL-driven generic Constraint Programming solver
- Used Deep Q-networks and Heterogeneous GNNs to approximate optimal decision process

Software Engineer Intern

Jun. 2020 – Sept. 2020

Dronisos, drone light show company

Bordeaux, France

- Developed Harmony, a Physics based meta-heuristic that secures massive drone swarms
- Harmony currently in use reduced the allocated securing time from 2 weeks (handmade) to 2 seconds
- Achieved automatic securing on the company first 1000 drones choreography (+500k\$ show)

Publications

Learning a Generic Value-Selection Heuristic Inside a Constraint Programming Solver

Tom Marty*, Tristan François, Pierre Tessier, Louis Gautier, Léo-Boisvert, Louis-Martin Rousseau, Quentin Cappart, (extended version)

Constraint Journal *under review

WorkArena: How Capable Are Web Agents at Solving Common Knowledge Work Tasks? Alexandre Drouin, Maxime Gasse, Massimo Caccia, Issam H Laradji, Manuel Del Verne, Tom Marty, Léo Boisvert, Megh Thakkar, Quentin Cappart, David Vazquez, Nicolas Chapados, Alexandre Lacoste International Conference on Machine Learning (ICML). 2024.

The Unsolved Challenges of LLMs as Generalist Web Agents: A Case Study

Rim Assouel*, **Tom Marty***, Massimo Caccia, Issam H. Laradji, Alexandre Drouin, Sai Rajeswar, Hector Palacios, Quentin Cappart, David Vazquez, Nicolas Chapados, Maxime Gasse, Alexandre Lacoste Foundation Models for Decision Making Workshop (NeurIPS). 2023.

Learning a Generic Value-Selection Heuristic Inside a Constraint Programming Solver

Tom Marty*, Tristan François, Pierre Tessier, Louis Gautier, Louis-Martin Rousseau, Quentin Cappart

Constraint Programming (CP). 2023.

OTHER PROJECTS

Leveraging Information Theory to create better optimizers | Python, Pytorch Lightning

May. 2024 -

• Work in progress...

On the Necessity of Human Insight to Improve Adversarial Robustness

Mar. 2024 –

• Work in progress...

WorkArena: an Open-Source Benchmark for evaluating Web Agents | Python

Apr. 2023 – Mar. 2024

Paper accepted at ICML 2024 Vienna, and presented at NVIDIA GTC 2024

SeaPearl: an Open-Source RL-driven Constraint-Programming Solver | Julia

Fev. 2021 – Jul. 2023

• Paper accepted at CP2023, Toronto

Adversarial Attacks on Sentiment Classification models | Python, HuggingFace

Fev. 2022 – May. 2022

- Adversarial fine-tunning on large NLP models: Eleuther AI GPT 125M/1.3B/2.7B/6B parameters
- Evidence of a correlation between scaling and robustness against increasingly subtle Adversarial Attacks

Diffusion Geodesic distance for non-linear dimensionality reduction | Python

Oct. 2021 – Jan. 2022

- Approximated the geodesic distance using a diffusion process over the manifold
- Proposed a new data visualization algorithm based on Multi-Dimentionnal Scaling and Diffusion Geodesic

Autonomous Drone Swarm Deployment - DGA contest | Python, PyTorch

Nov. 2020 – Mar. 2021

- Multi-agent Q-Learning method for deployment optimization
- Density-Based Spatial Clustering for point of interest detection

Realtime 3D Deep Motion Capture | C++, OpenCV, PyTorch

Oct. 2020 – Dec. 2020

- Implemented a method of inferring a full character's 3d pose using only a camera as an input
- Inspired by a EECV 2020 research paper to implement the algorithm

Sketch-based Shape Retrieval | Python, C++, OpenGL

Sep. 2020 – Dec. 2020

- Implemented a method to find any specific 3d model in a database using a drawing as an input
- Succeeded to faithfully retrieve several simple 3D shapes by using a single drawing given by a user

Honors and Awards

Distinguished Paper Award at CP2023, Toronto	Sept. 2023
MITACS Accelerate scholarship of two units for my internship at ServiceNow Research	Mar. 2023
Oustanding Investment Mention, Ecole Polytechnique de Paris	Jul. 2022
Vallet Fondation scholarships for outstanding CPGE students	2018

TEACHING EXPERIENCE

Teaching Assistant

Fall 2022

Fall 2021

 $\it INF8215, Artificial Intelligence: Algorithms and methods$

Teaching Assistant
INF8215, Artificial Intelligence: Algorithms and methods

Nov. 2018 – Mar. 2019

Teaching Assistant
Ministry of National Education

France

- Responsible for a group of up to 20 undergraduate students during scientific workshops
- Worked alongside the academic team to prepare students for entrance exams

Public Speaking Club: Rethorix

Oct. 2019 - Oct. 2020

• Organization of an eloquence contest between the schools of the Plateau de Saclay

President of Nuit du Styx

Nov. 2020

• General organization and logistic of an electronic music festival gathering more than 2000 peoples

SKILLS & HOBBIES

Languages: French: Native | English: Fluent | Russian: Primary

Developer Toolbox: Git, Pytorch, Lightning, Hydra, WandB, VScode, SLURM, CI testing

Programming Languages: Python, Julia, C++, R

Remote Controlled UAV: Conception, Building, Programmation, Testing, Adjustment

Activities: Outdoor climbing, river surf, ski, montain hiking

REFERENCE

Prof. Dhanya Sridhar (Ph.D. advisor)

Core academic member of MILA - AI CIFAR Chair holder

Email: dhanya.sridhar@mila.quebec

Dr. Alexandre Lacoste

Staff Research Engineer, ServiceNow Research Email: alexandre.lacoste@servicenow.com

Prof. Quentin Cappart (M.Sc. advisor)

Assistant Professor at Polytechnique Montréal

Email: quentin.cappart@polymtl.ca