


# Tom Marty

 [3rdcore.github.io](https://3rdcore.github.io)  
 Github

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 LinkedIn

Montreal, Canada  
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## EDUCATION

<b>Ph.D. in Machine Learning</b> <i>Université de Montréal (Mila) - GPA 4.00</i>	Jan. 2024 – <i>Montréal, Canada</i>
<b>M.Sc. in Machine Learning</b> <i>Polytechnique Montréal - GPA 3.91</i>	Sep. 2021 – Jun. 2023 <i>Montréal, Canada</i>
<b>B.Sc. in Computer Science, minor in Applied Mathematics</b> <i>X 2018, Ecole Polytechnique - GPA 3.84</i>	Sep. 2018 – Jun. 2021 <i>Palaiseau, France</i>
<b>Advanced Preparatory Class for Competitive Exams</b> <i>Lycée Jean-Baptiste Say - GPA 4.00 - Top 0.1% national</i>	Sep. 2016 – Jun. 2018 <i>Paris, France</i>

## RESEARCH INTEREST

- **Broad interest** : Artificial intelligence, Machine Learning, Generative AI and Operational Research
- **Methodological interest** : **Causality**, Bayesian Statistics, OOD Generalization, Information Theory
- **Applications** : Fairness, Robust Machine Learning, Open-Ended Decision Making, AI for video-games

## INDUSTRY AND ACADEMIC EXPERIENCE

<b>Visiting Researcher</b> <i>ServiceNow Research</i>	Apr. 2023 – Sept. 2023 <i>Montréal, Canada</i>
<ul style="list-style-type: none"><li>• Developed WorkArena (ICML2024): an open-source Benchmark and Gym environment for evaluating Agent at solving common-knowledge tasks on a Web Browser</li></ul>	
<b>Research Supervisor</b> <i>Corail Research Group</i>	Jan. 2022 – Sept. 2022 <i>Montréal, Canada</i>
<ul style="list-style-type: none"><li>• Supervised five interns on the development of the open-source project SeaPearl</li><li>• Teaching Assistant for the course INF8215 given by Quentin Cappart in Fall 21 and Fall 22</li></ul>	
<b>Research Engineer Intern</b> <i>Corail Research Group</i>	Jan. 2021 – Sept. 2021 <i>Montréal, Canada</i>
<ul style="list-style-type: none"><li>• Developed <i>SeaPearl</i> : an open-source RL-driven generic Constraint Programming solver</li><li>• Used Deep Q-networks and Heterogeneous GNNs to approximate optimal decision process</li></ul>	
<b>Software Engineer Intern</b> <i>Dronisos, drone light show company</i>	Jun. 2020 – Sept. 2020 <i>Bordeaux, France</i>
<ul style="list-style-type: none"><li>• Developed <i>Harmony</i>, a Physics based meta-heuristic that secures massive drone swarms</li><li>• <i>Harmony</i> - currently in use - reduced the allocated securing time from 2 weeks (handmade) to 2 seconds</li><li>• Achieved automatic securing on the company first 1000 drones choreography (+500k\$ show)</li></ul>	

## CONFERENCE AND JOURNAL PUBLICATIONS

### In-Context Learning and Occam's Razor

Eric Elmoznino\*, **Tom Marty**\*, Tejas Kasetty, Leo Gagnon, Sarthak Mittal, Mahan Fathi, Dhanya Sridhar, Guillaume Lajoie

*\*under review*

 Code  PDF

### Learning and Fine-Tuning a Generic Value-Selection Heuristic Inside a Constraint Programming Solver

**Tom Marty**\*, Léo Bois-Vert\*, Tristan François, Pierre Tessier, Louis Gautier, Léo-Boisvert, Louis-Martin Rousseau, Quentin Cappart, Constraint **Journal**. 2024.

 Code  PDF

### The BrowserGym Ecosystem for Web Agent Research

Thibault Le Sellier De Chezelles, Maxime Gasse, Alexandre Drouin, Massimo Caccia, Léo Boisvert, Megh Thakkar, **Tom Marty**, Rim Assouel, Sahar Omid Shayan, Lawrence Keunho Jang, Xing Han Lù, Ori Yoran, Dehan Kong, Frank F. Xu, Siva Reddy, Quentin Cappart, Graham Neubig, Ruslan Salakhutdinov, Nicolas Chapados, Alexandre Lacoste

*\*under review*

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### WorkArena: How Capable Are Web Agents at Solving Common Knowledge Work Tasks?

Alexandre Drouin, Maxime Gasse, Massimo Caccia, Issam H Laradji, Manuel Del Verne, **Tom Marty**, Léo Boisvert, Megh Thakkar, Quentin Cappart, David Vazquez, Nicolas Chapados, Alexandre Lacoste  
International Conference on Machine Learning (ICML). 2024.

[!\[\]\(a870788d6ed9b8fd294b7654a8c8526b\_img.jpg\) Project](#) [!\[\]\(18065afa4ef6662bca9f3f6088f7de30\_img.jpg\) Code](#) [!\[\]\(b985170eefb48b9b3ef593e79310e8f5\_img.jpg\) PDF](#)

### The Unsolved Challenges of LLMs as Generalist Web Agents: A Case Study

Rim Assouel\*, **Tom Marty**\*, Massimo Caccia, Issam H. Laradji, Alexandre Drouin, Sai Rajeswar, Hector Palacios, Quentin Cappart, David Vazquez, Nicolas Chapados, Maxime Gasse, Alexandre Lacoste  
Foundation Models for Decision Making Workshop (NeurIPS FMDM). 2023.

[!\[\]\(6059a5aa8b4ca7bb793408023d6c6e42\_img.jpg\) PDF](#)

### Learning a Generic Value-Selection Heuristic Inside a Constraint Programming Solver

**Tom Marty**\*, Tristan François, Pierre Tessier, Louis Gautier, Louis-Martin Rousseau, Quentin Cappart  
Constraint Programming (CP). 2023.

[!\[\]\(9c2e8d1b5bd77cb5c9f83b7a9cff79fd\_img.jpg\) Code](#) [!\[\]\(f822cba4d3f2ea10b4ad95c475f0f631\_img.jpg\) PDF](#)

## OTHER PROJECTS

### In-Context Invariant Learning

Dec. 2024 –

- Work in progress...

### BrowserGym : an Open-Source Benchmark for evaluating Web Agents | *Python*

Apr. 2023 – Mar. 2024

- Paper accepted at ICML 2024 Vienna, presented at NVIDIA GTC 2024

### SeaPearl : an Open-Source RL-driven Constraint-Programming Solver | *Julia*

Fev. 2021 – Jul. 2023

- Paper accepted at CP2023, Toronto

### Adversarial Attacks on Sentiment Classification models | *Python, HuggingFace*

Fev. 2022 – May. 2022

- Adversarial fine-tuning on large NLP models : Eleuther AI GPT 125M/1.3B/2.7B/6B parameters
- Evidence of a correlation between scaling and robustness against increasingly subtle Adversarial Attacks

### Diffusion Geodesic distance for non-linear dimensionality reduction | *Python*

Oct. 2021 – Jan. 2022

- Approximated the geodesic distance using a diffusion process over the manifold
- Proposed a new data visualization algorithm based on Multi-Dimensional Scaling and Diffusion Geodesic

### Autonomous Drone Swarm Deployment - DGA contest | *Python, PyTorch*

Nov. 2020 – Mar. 2021

- Multi-agent Q-Learning method for deployment optimization
- Density-Based Spatial Clustering for point of interest detection

### Realtime 3D Deep Motion Capture | *C++, OpenCV, PyTorch*

Oct. 2020 – Dec. 2020

- Implemented a method of inferring a full character's 3d pose using only a camera as an input
- Inspired by a EECV 2020 research paper to implement the algorithm

### Sketch-based Shape Retrieval | *Python, C++, OpenGL*

Sep. 2020 – Dec. 2020

- Implemented a method to find any specific 3d model in a database using a drawing as an input
- Succeeded to faithfully retrieve several simple 3D shapes by using a single drawing given by a user

Visit [!\[\]\(98c78cd2a2ac28d8c69439852e303d4f\_img.jpg\)](#) my website to know more about me and my projects!

## HONORS AND AWARDS

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Distinguished Paper Award at CP2023, Toronto	Sept. 2023
MITACS Accelerate scholarship of two units for my internship at ServiceNow Research	Mar. 2023
Oustanding Investment Mention, Ecole Polytechnique de Paris	Jul. 2022
Vallet Fondation scholarships for outstanding CPGE students	2018

## TEACHING EXPERIENCE

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<b>Teaching Assistant</b> <i>INF8215, Artificial Intelligence : Algorithms and methods</i>	Fall 2022
<b>Teaching Assistant</b> <i>INF8215, Artificial Intelligence : Algorithms and methods</i>	Fall 2021
<b>Teaching Assistant</b> <i>Ministry of National Education</i>	Nov. 2018 – Mar. 2019 <i>France</i>
<ul style="list-style-type: none"><li>• Responsible for a group of up to 20 undergraduate students during scientific workshops</li><li>• Worked alongside the academic team to prepare students for entrance exams</li></ul>	

## REVIEWING AND COMMUNITY SERVICE

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Reviewer: NeurIPS2024 CALM Workshop, MAIS2024, HRAIM 2024	2024
Reviewer: Constraint Programming — CP2023	2023

## STUDENT ASSOCIATION

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<b>Public Speaking Club: Rethorix</b> <ul style="list-style-type: none"><li>• Organization of an eloquence contest between the schools of the Plateau de Saclay</li></ul>	Oct. 2019 – Oct. 2020
<b>President of Nuit du Styx</b> <ul style="list-style-type: none"><li>• General organization and logistic of an electronic music festival gathering more than 2000 peoples</li></ul>	Nov. 2020

## SKILLS & HOBBIES

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**Languages:** French : Native | English : Fluent | Russian : Primary  
**Developer Toolbox:** Git, Pytorch, Lightning, Hydra, WandB, VScode, SLURM, CI testing  
**Programming Languages:** Python, Julia, C++, R

**Remote Controlled UAV:** Conception, Building, Programmation, Testing, Adjustment  
**Activities:** Outdoor climbing, river surf, ski, montain hiking

## REFERENCE

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**Prof. Dhanya Sridhar** (Ph.D. advisor)  
Assistant Professor at UdeM, Core academic member at MILA - AI CIFAR Chair holder  
Email : dhanya.sridhar@mila.quebec

**Dr. Alexandre Lacoste**  
Staff Research Engineer, ServiceNow Research  
Email : alexandre.lacoste@servicenow.com

**Prof. Quentin Cappart** (M.Sc. advisor)  
Assistant Professor at Polytechnique Montréal  
Email : quentin.cappart@polymtl.ca