

# Tom Marty

 3rdcore.github.io

 tom.marty@mila.quebec

 Google Scholar

  

## EDUCATION

### Ph.D. in Machine Learning

*Mila, Université de Montréal - GPA 4.00*

Jan. 2024 –

*Montréal, Canada*

### M.Sc. in Machine Learning

*Polytechnique Montréal - GPA 3.91*

Sep. 2021 – Jun. 2023

*Montréal, Canada*

### B.Sc. in Computer Science, minor in Applied Mathematics

*X 2018, Ecole Polytechnique - GPA 3.84*

Sep. 2018 – Jun. 2021

*Palaiseau, France*

### Advanced Preparatory Class for Competitive Exams

*Lycée Jean-Baptiste Say - GPA 4.00 - Top 0.1% national*

Sep. 2016 – Jun. 2018

*Paris, France*

## RESEARCH INTEREST

- **Broad interest** : Deep Learning, Generative modeling and Operational Research
- **Methodological interest** : Flow-based model, Causality, Generalization, Information Theory
- **Applications** : ML for biology, Robust Machine Learning, Open-Ended Decision Making

## INDUSTRY AND ACADEMIC EXPERIENCE

### Visiting Researcher

*ServiceNow Research*

Apr. 2023 – Sept. 2023

*Montréal, Canada*

- Developed WorkArena (ICML2024): an open-source Benchmark and Gym environment for evaluating Agent at solving common-knowledge tasks on a Web Browser

### Research Supervisor

*Corail Research Group*

Jan. 2022 – Sept. 2022

*Montréal, Canada*

- Supervised five interns on the development of the open-source project SeaPearl
- Teaching Assistant for the course INF8215 given by Quentin Cappart in Fall 21 and Fall 22

### Research Engineer Intern

*Corail Research Group*

Jan. 2021 – Sept. 2021

*Montréal, Canada*

- Developed *SeaPearl* : an open-source RL-driven generic Constraint Programming solver
- Used Deep Q-networks and Heterogeneous GNNs to approximate optimal decision process

### Software Engineer Intern

*Dronisos, drone light show company*

Jun. 2020 – Sept. 2020

*Bordeaux, France*

- Developed *Harmony*, a Physics based meta-heuristic that secures massive drone swarms
- *Harmony* - currently in use - reduced the allocated securing time from 2 weeks (handmade) to 2 seconds
- Achieved automatic securing on the company first 1000 drones choreography (+500k\$ show)

## CONFERENCE AND JOURNAL PUBLICATIONS

### In-Context Learning and Occam's Razor

Eric Elmoznino\*, **Tom Marty**\*, Tejas Kasetty, Leo Gagnon, Sarthak Mittal, Mahan Fathi, Dhanya Sridhar, Guillaume Lajoie

International Conference on Machine Learning (ICML 2025)

 Code  PDF

### Next-Token Prediction Should be Ambiguity-Sensitive: A Meta-Learning Perspective

Leo Gagnon, Eric Elmoznino, Sarthak Mittal, **Tom Marty**, Tejas Kasetty, Dhanya Sridhar, Guillaume Lajoie

International Conference on Machine Learning (FoMo@ICML 2025)

 PDF

### The BrowserGym Ecosystem for Web Agent Research

Thibault Le Sellier De Chezelles, Maxime Gasse, Alexandre Drouin, Massimo Caccia, Léo Boisvert, Megh Thakkar, **Tom Marty**, Rim Assouel, Sahar Omid Shayan, Lawrence Keunho Jang, Xing Han Lù, Ori Yoran, Dehan Kong, Frank F. Xu, Siva Reddy, Quentin Cappart, Graham Neubig, Ruslan Salakhutdinov, Nicolas Chapados, Alexandre Lacoste

Transactions on Machine Learning Research (TMLR 2025) .

[↩️ Code](#) [📄 PDF](#)

### Learning and Fine-Tuning a Generic Value-Selection Heuristic Inside a Constraint Programming Solver

**Tom Marty\***, Léo Bois-Vert\*, Tristan François, Pierre Tessier, Louis Gautier, Léo-Boisvert, Louis-Martin Rousseau, Quentin Cappart, Constraint **Journal** 2024.

[↩️ Code](#) [📄 PDF](#)

### WorkArena: How Capable Are Web Agents at Solving Common Knowledge Work Tasks?

Alexandre Drouin, Maxime Gasse, Massimo Caccia, Issam H Laradji, Manuel Del Verne, **Tom Marty**, Léo Boisvert, Megh Thakkar, Quentin Cappart, David Vazquez, Nicolas Chapados, Alexandre Lacoste

International Conference on Machine Learning (ICML 2024) .

[🔗 Project](#) [↩️ Code](#) [📄 PDF](#)

### The Unsolved Challenges of LLMs as Generalist Web Agents: A Case Study

Rim Assouel\*, **Tom Marty\***, Massimo Caccia, Issam H. Laradji, Alexandre Drouin, Sai Rajeswar, Hector Palacios, Quentin Cappart, David Vazquez, Nicolas Chapados, Maxime Gasse, Alexandre Lacoste  
Foundation Models for Decision Making Workshop (FMDM@NeurIPS 2023) .

[↩️ Code](#) [📄 PDF](#)

### Learning a Generic Value-Selection Heuristic Inside a Constraint Programming Solver

**Tom Marty\***, Tristan François, Pierre Tessier, Louis Gautier, Louis-Martin Rousseau, Quentin Cappart  
**Distinguished paper**, Constraint Programming (CP 2023).

[↩️ Code](#) [📄 PDF](#)

## OTHER PROJECTS

### In-Context Invariant Learning

Dec. 2024 –

- Work in progress...

### BrowserGym : an Open-Source Benchmark for evaluating Web Agents | *Python*

Apr. 2023 – Mar. 2024

- Paper accepted at ICML 2024 Vienna, presented at NVIDIA GTC 2024

### SeaPearl : an Open-Source RL-driven Constraint-Programming Solver | *Julia*

Fev. 2021 – Jul. 2023

- Paper accepted at CP2023, Toronto

### Adversarial Attacks on Sentiment Classification models | *Python, HuggingFace*

Fev. 2022 – May. 2022

- Adversarial fine-tuning on large NLP models : Eleuther AI GPT 125M/1.3B/2.7B/6B parameters
- Evidence of a correlation between scaling and robustness against increasingly subtle Adversarial Attacks

### Diffusion Geodesic distance for non-linear dimensionality reduction | *Python*

Oct. 2021 – Jan. 2022

- Approximated the geodesic distance using a diffusion process over the manifold
- Proposed a new data visualization algorithm based on Multi-Dimensional Scaling and Diffusion Geodesic

### Autonomous Drone Swarm Deployment - DGA contest | *Python, PyTorch*

Nov. 2020 – Mar. 2021

- Multi-agent Q-Learning method for deployment optimization
- Density-Based Spatial Clustering for point of interest detection

### Realtime 3D Deep Motion Capture | *C++, OpenCV, PyTorch*

Oct. 2020 – Dec. 2020

- Implemented a method of inferring a full character's 3d pose using only a camera as an input
- Inspired by a EECV 2020 research paper to implement the algorithm

### Sketch-based Shape Retrieval | *Python, C++, OpenGL*

Sep. 2020 – Dec. 2020

- Implemented a method to find any specific 3d model in a database using a drawing as an input
- Succeeded to faithfully retrieve several simple 3D shapes by using a single drawing given by a user

Visit [🔗 my website](#) to know more about me and my projects!

## HONORS AND AWARDS

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FRQNT doctoral training scholarship: 25000\$ (x4 years)	Mar. 2025
Distinguished Paper Award at CP2023, Toronto	Sept. 2023
MITACS Accelerate scholarship: 30000\$	Mar. 2023
Outstanding Investment Mention, Ecole Polytechnique de Paris	Jul. 2022
Vallet Foundation scholarships for outstanding CPGE students: 5000€ (x2 years)	2018

## TEACHING EXPERIENCE

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<b>Teaching Assistant</b> <i>IFT6390: Fundamentals of machine learning</i>	Fall 2025
<b>Teaching Assistant</b> <i>INF8215, Artificial Intelligence : Algorithms and methods</i>	Fall 2022
<b>Teaching Assistant</b> <i>INF8215, Artificial Intelligence : Algorithms and methods</i>	Fall 2021
<b>Teaching Assistant</b> <i>Ministry of National Education</i>	Nov. 2018 – Mar. 2019 France
<ul style="list-style-type: none"><li>• Responsible for a group of up to 20 undergraduate students during scientific workshops</li><li>• Worked alongside the academic team to prepare students for entrance exams</li></ul>	

## COMMUNITY INVOLVEMENT AND SERVICE

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<b>Tea Talks Committee Member</b> – Research Seminar held at Mila	2025
<b>Speaker</b> at AI Summer School in Benin (EEIA) – Supporting Underserved Communities	2025
<b>Reviewer</b> for NeurIPS 2025 NewInML Workshop	2025
<b>Reviewer</b> for NeurIPS 2024 CALM Workshop, MAIS 2024, HRAIM 2024	2024
<b>Reviewer</b> for CP2023	2023
<b>President</b> of Nuit du Styx festival	2020
<ul style="list-style-type: none"><li>• Oversaw general organization and logistics for an electronic music festival with over 2000 attendees</li></ul>	
<b>Member</b> of Rethorix, Public Speaking Club	2019
<ul style="list-style-type: none"><li>• Organized an eloquence contest between schools in the Plateau de Saclay area</li></ul>	

## SKILLS & HOBBIES

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**Languages:** French : Native | English : Fluent | Russian : Primary  
**Developer Toolbox:** Pytorch, Lightning, Git, Hydra, HPC, WandB, SLURM, CI Testing  
**Programming Languages:** Python, Julia, C++, R

**Activities:** Outdoor climbing, Surfing, Snowboarding, mountain hiking, UAV robotics

## REFERENCE

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**Prof. Dhanya Sridhar** (Ph.D. advisor)  
Assistant Professor at UdeM, Core academic member at MILA - AI CIFAR Chair holder  
Email : dhanya.sridhar@mila.quebec

**Dr. Alexandre Lacoste**  
Staff Research Engineer, ServiceNow Research  
Email : alexandre.lacoste@servicenow.com

**Prof. Quentin Cappart** (M.Sc. advisor)  
Assistant Professor at Polytechnique Montréal  
Email : quentin.cappart@polymtl.ca