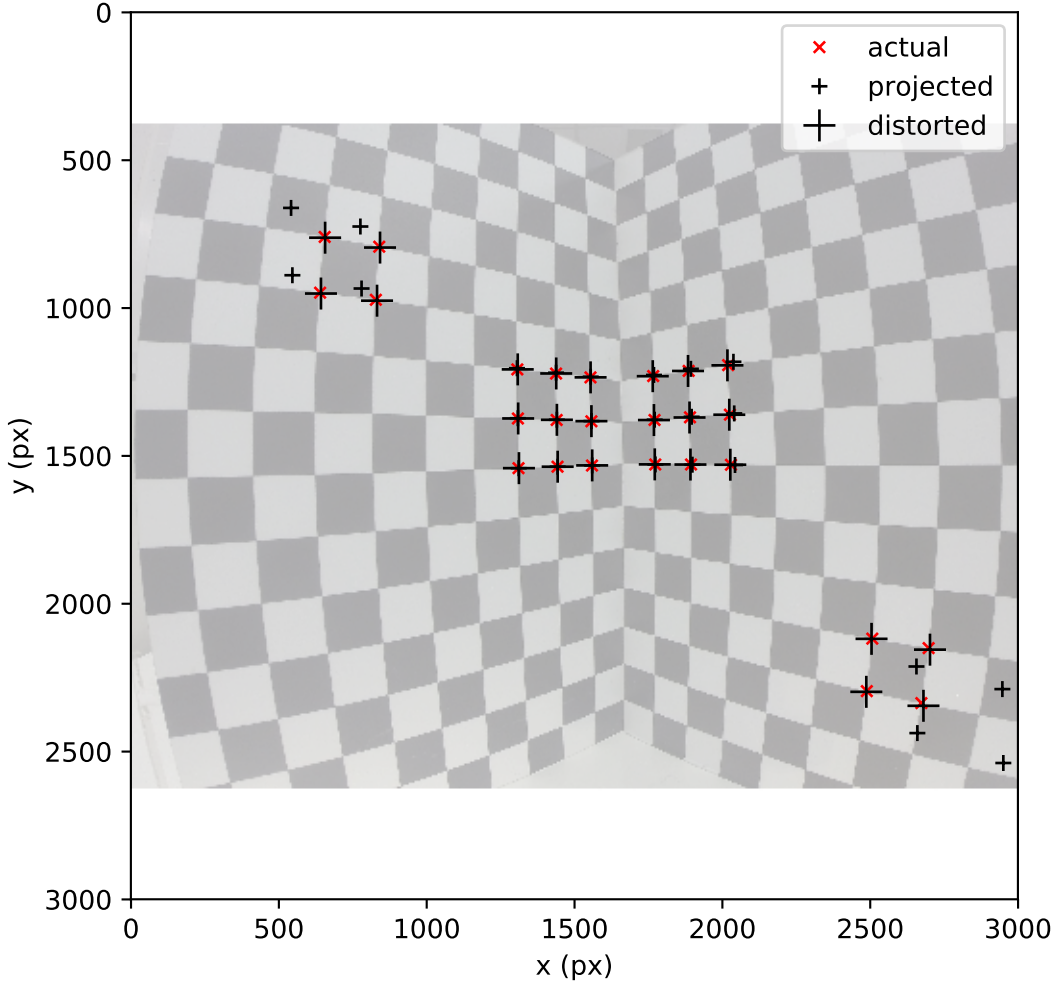
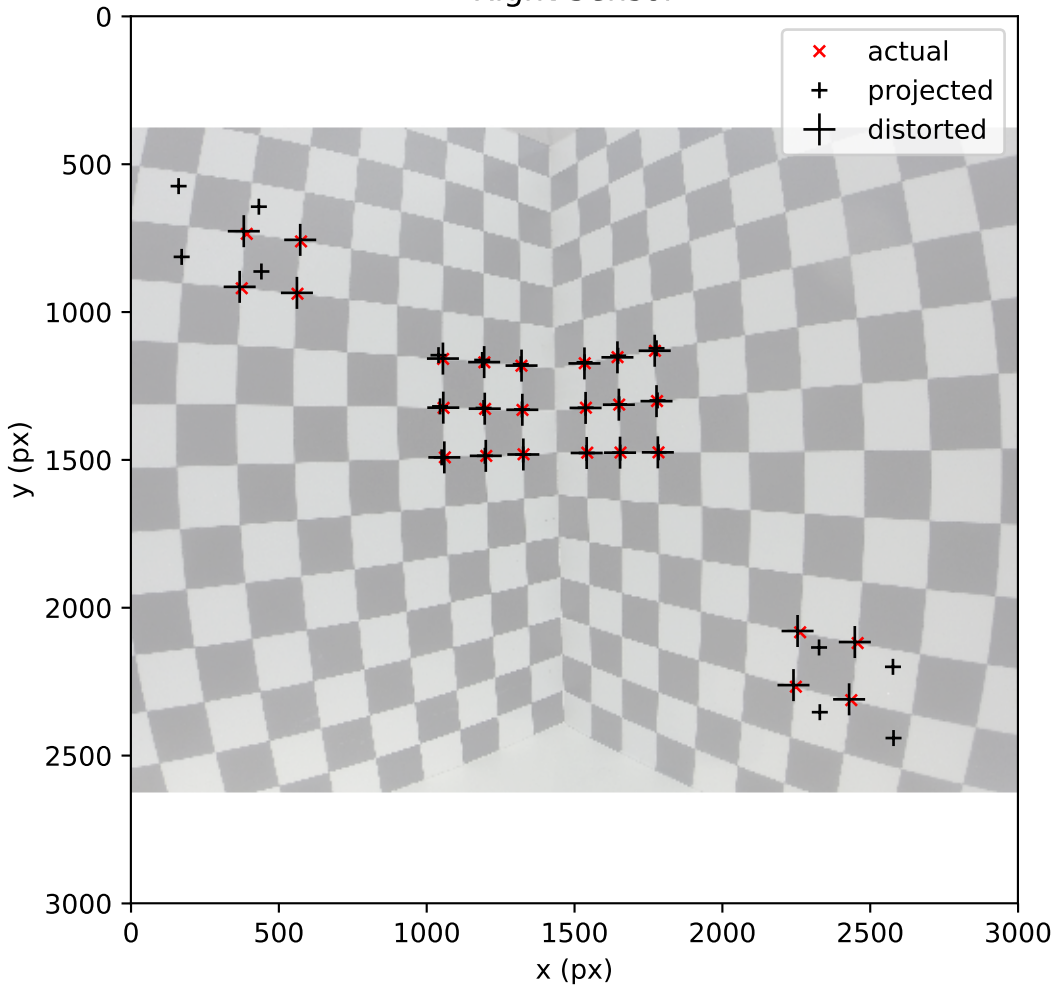


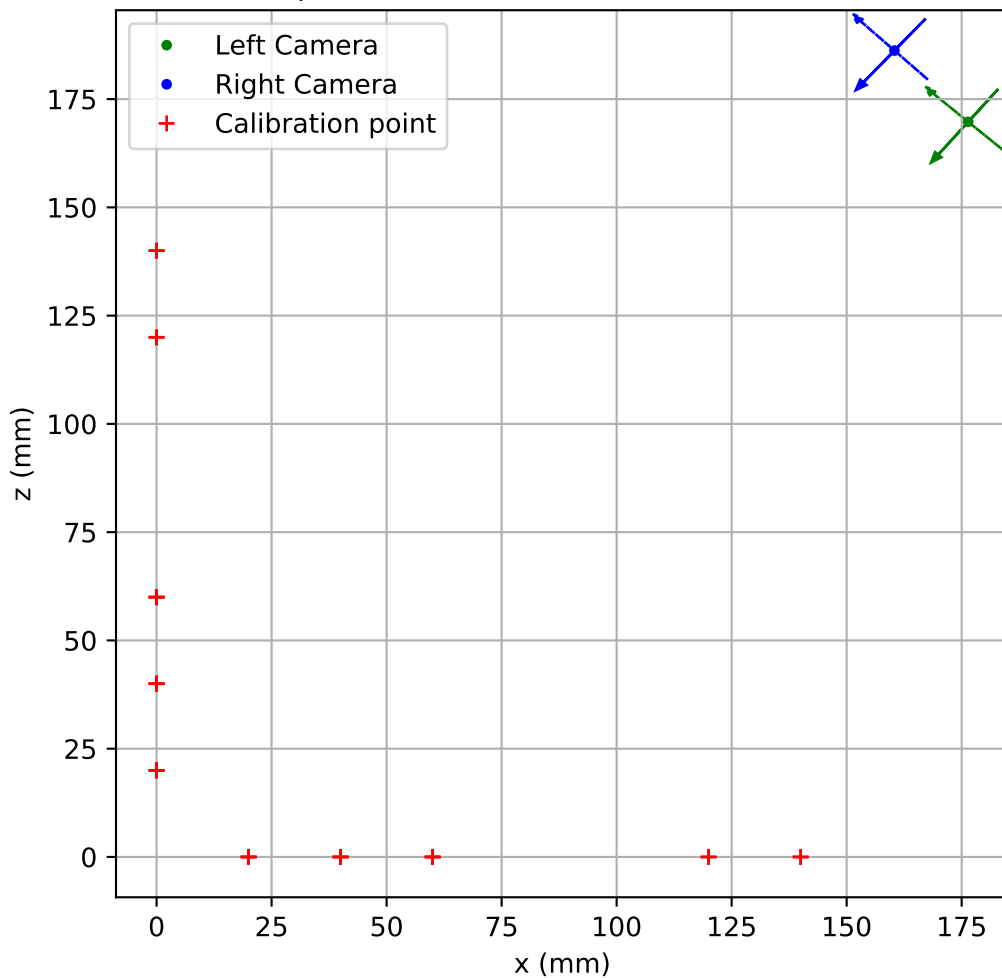
Left Sensor



Right Sensor



Cameras and Calibration Points
Top-Down View (In world coordinates)



Cameras and Calibration Points

Orthographic Projection (In world coordinates)

