

# REScala: “Animal” case study observations

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## 1 Advantages of Signals & Events (vs events-only / signal-only)

### 1.1 Main point: detection of changes

We need the combination of events and signals to model processes which depend on the change of a value.

**Example:** The germination of a plant is defined through a process of aging, growing, and reaching a maximum size. This can be expressed very concise with signals:

```
class Plant extends BoardElement {  
  
  val age = world.time.hour.changed.iterate(0)(_ + 1)  
  val grows = age.changed && { _ % Plant.GrowTime == 0}  
  val size = grows.iterate(0)(acc => math.min(Plant.MaxSize, acc + 1))  
  val expands = size.changedTo(Plant.MaxSize)  
  
  expands += { _ =>  
    germinate() // spawn a new plant in proximity to this one  
  }  
}
```

The equivalent event-based code has to do a manual check on every update:

```
class Plant extends BoardElement {  
  
  var age = 0  
  var size = 0  
  val grows = new ImperativeEvent[Unit]  
  val expands = grows && ( _ => size == Plant.MaxSize)  
  
  expands += { _ =>  
    germinate() // spawn a new plant in proximity to this one  
  }  
  
  tickHandler = {_: Unit =>  
    age += 1  
    if(age % Plant.GrowTime == 0){
```

```

    val oldSize = size
    size = math.min(Plant.MaxSize, size + 1)
    if(size != oldSize)
        grows()
  }
}

```

The equivalent signal-only code would have to perform a manual check for a value change as well. In the absence of events (in particular the **changed** event), the relationship would have to be defined as a pure functional dependency, rather than through an explicit **grow** event. The code in the **tick** function has to do a lot of ugly manual checks. In addition, the reaction to a very specific condition (size has reached a maximum value), gets cluttered into the **tick** method, which should not have anything to do with that.

```

class Plant(override implicit val world: World) extends BoardElement {

  val age = Var(0)
  val size = Signal { math.min(Plant.MaxSize, age() / Plant.GrowTime) }

  def tick {
    // we have to store the old size now, otherwise we could not detect changes
    val oldSize = size.getValue

    age() = age.getValue + 1

    if(size.getValue != oldSize){ // did the value change
      if(size.getValue == Plant.MaxSize) // did the value reach MaxSize
        germinate() // spawn a new plant in proximity to this one
    }
  }
}

```

## 2 Shortcomings of Signal code

### 2.1 Handlers on late bound events

Sometimes we want to define an event on a signal which is late bound. This works (but we have to make the event lazy). However, we can not *register an event handler* on this event. When the object **Animal** gets instantiated, the signal **isDead** is still unbound.

```

abstract class Animal {

  val isDead: Signal[Boolean] // this value is abstract

  lazy val dies = isDead changedTo true // we can do this
  dies += {_ => world.board.clear(position.getValue)} // we can not do this
}

class Carnivore extends Animal {
  isDead = Signal { energy() > 10 } // subclass substitutes concrete signal
}

```

```
}
```

## 2.2 Overriding signal values

We can override any signal value in a subclass. However, as a signal is a `val` member, we can not access the super-value. Consider the class `Animal` with member `energyDrain`. In the subtype `Female`, we want to override this value, by multiplying this signal with a given factor. However

```
abstract class Animal {  
    val energyDrain = Signal {...}  
}  
  
trait Female extends Animal {  
    val isPregnant = Signal {...}  
    val factor = Signal { if(isPregant()) 1.2 else 1 } // multiply energy drain by 1.2 if  
    pregnant.  
    override val energyDrain = Signal { super.energyDrain() * factor() } // problem:  
    super can not be used on val members!  
}
```