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DRAFT DOCUMENT

The feature has 3 functions and 1 events:

[0x6100]TouchPadRawXY

```
GetTouchPadInfo = [0]GetTouchPadInfo()
GetRawReportState = [1]GetRawReportState()
void = [2]SetRawReportState(uint8_t state)
```

[0x6100] EVENT TouchPadRawXY

DualXYData = [0]TwoFingersDataReport()

[0x6100] FUNCT GetTouchpadInfo()

Summary

Returns the TouchPad characteristics (size, number of dots, data ranges, etc)

Parameters

none

Returns

byte num (in payload)	description	remarks			
0	X size (dots) H	max pixels reported MSB			
1	X size (dots) L	max pixels reported LSB			
2	Y size (dots) H	max pixels reported MSB			
3	Y size (dots) L	max pixels reported LSB			
4	Z data range (size)	0x00 means no range 0x0F means 16bits			
5	Area data range (size)	0x0F means 16bits			
6	Timestamps unit given in 0.1ms	A value of 10 means timestamps are in units of 1 mSec See Note 1)			
7	Max number of fingers				
8		0x00 = reserved 0x01 = LOWER-LEFT 0x02 = LOWER-RIGHT 0x03 = UPPER-LEFT 0x04 = UPPER-RIGHT Note: corners are defined by looking at device from above, with lower edge toward the user and upper facing the PC screen			
9	RESERVED				
10	RESERVED				
11	RESERVED				
12	RESERVED				
13	DPI_H	Touchpad Resolution MSB (Same resolution in X and Y)			
14	DPI_L	Touchpad Resolution LSB (Same resolution in X and Y)			
15	RESERVED				

Note 1) Exception: A device that reports 8 in this field has a timestamp unit of 1ms (i.e field value equivalent to 10). There is no support for devices with 0.8 mSec timestamp unit.

Errors None

[0x6100] FUNCT GetRawReportState

Summary

Returns the TouchPad raw reporting state byte.

Parameters

none

Returns

bit 7	6	5	4	3	2	1	0
RSVD	RSVD	RSVD	raw and native	width/height 4-bit reporting	enhance	add force data on 16bits	enable raw

Byte 0: State

[0x6100] FUNCT SetRawReportState

Summary

Sets the TouchPad raw reporting state byte.

Parameters Byte 0: state

Returns

bit 7	6	5	4	3	2	1	0
RSVD	RSVD	RSVD	eaw and native	width/height 4-bit reporting	enhance	add Z info on 16bits	enable raw

none

Reporting state details:

bit0: enable raw reporting

- $0 = \mathsf{DISABLED}$ (Touchpad reports on standard HID pipe. Gestures are processed in the touchpad)
- 1 = ENABLED: (Touchpad reports raw data on HIDPP pipe, nothing is sent on the standard HID pipe. No gesture processing is done by the touchpad)

bit1: (add Z info on 16bits)

- 0 = DISABLED (Area byte in report contains the contact area. Z is reported as 8 bit value)
- 1 = ENABLED (Area byte in report contains the MSB of a 16bit Z value. No area is reported)

bit2: - Enhance

- 0 = DISABLED (Normal settings for sensor)
- 1 = ENABLED (Enhanced sensibility for sensor)

bit3: - Width/Height reporting (4-bit each) instead of Area

0 = DISABLED

1 = ENABLED (report width/height)

bit4: - Send RAW data as well as recognized gestures/tracking/scrolling messages. (dual mode)

0 = DISABLED

1 = ENABLED (send both, raw data on hidpp pipe and standard data on hid channel) This mode may degrade the tracking smoothness.

Returns none

EVENT [0] format:

[0x6100] Event TouchPadRawTouchPoints

Summary

Sends data for two fingers, out of the N currently used. Sent by chunks of 2 fingers.

Parameters

none

Returns

DualXYData [16 x 8bits]

byte num (in payload)	description	covers		
1	Timestamp (MSB)	tags this packet (both		
1	Timestamp (LSB)	touch points)		
2	2b Contact type			
2	6b X (MSB)			
4	X (LSB)			
4	2b Contact status 6b Y (MSB)			
5	Y (LSB)	touch point 1		
5 6	Z/Force			
7	Area or (width +			
_	height)			
8	4b Finger ID			
	1b proximity			
	detection			
	1b mechanical button			
	1b Spurious Flag			
	1b End-of-Frame (*)			
9	2b Contact type			
	6b X (MSB)			
10	X (LSB)			
11	2b Contact status	touch point 2		
10	6b Y (MSB)	touch point 2		
12 Y (LSB)				
13	Z/Force			
14	Area			
15	4b Finger ID			
	4b Total number of			
	fingers in this frame			

CONTACT TYPE:

00 = finger

01 = reserved

10 = reserved

11 = reserved

CONTACT STATUS (2bits)

00 = no finger (released)

01 = touch

10 = hover

11 = reserved

Note: in order to release finger the device will send an empty report (ie with all data to 0).

It is important to note that X=0, Y=0, Force=0, Area=0 are still valid values, therefore the host software (driver) should check for CONTACT_STATUS = 0x00 to assess the release of that finger.

In case more than 2 fingers are present, two or more event will be sent to complete the frame:

The **timestamp** will be the same (it represents the timestamp of the moment when the frame is captured)

The total number of fingers (in the frame) is repeated in all messages of the frame

The last message of the frame will be "tagged" with the **1b End-of-Frame** bit set to 1.