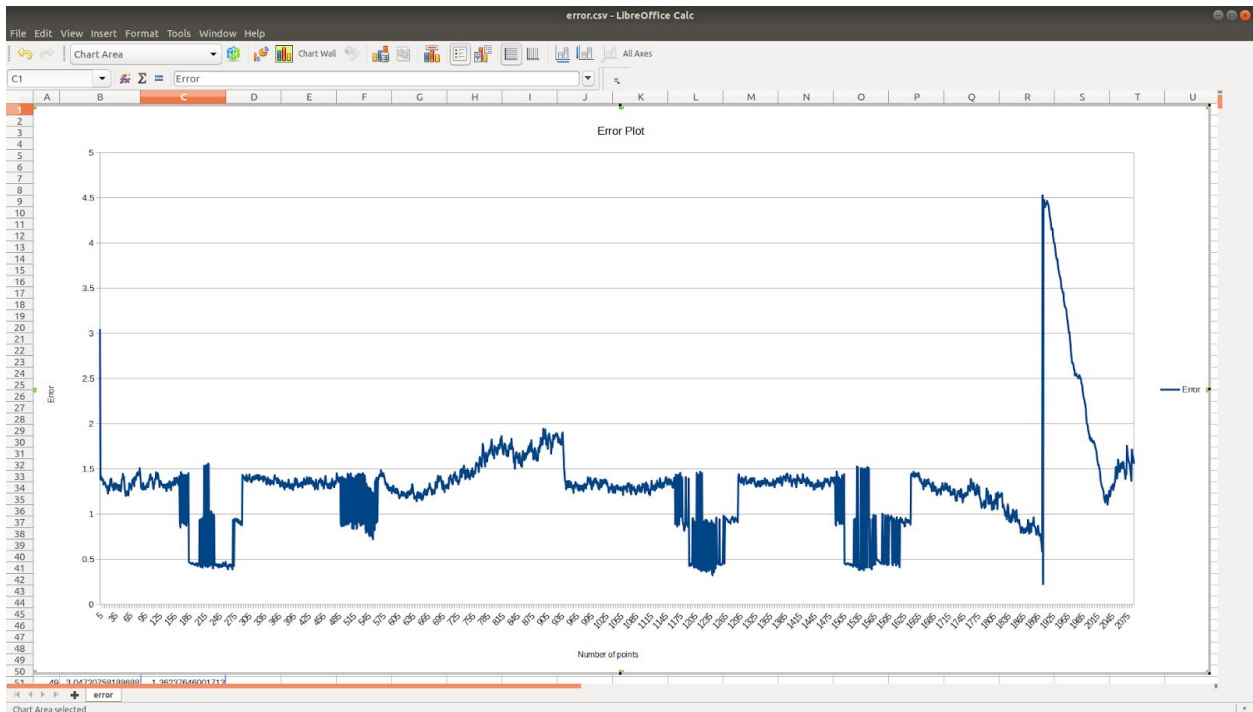


Pure Pursuit Lab

Team Name: VirtualFastKeyboardFurious

Absolute Track = 1.31659553426849

Max Error = 4.52795741087074



Error_plot for the Track

The error is calculated between Particle Filter current odom guess and Desired target which is lookahead distance ahead of the robot.

The spike in the error at the start and almost to end is because of waypoints start after some distance from the map center and that can be seen when the robot has completed a loop and back to the same point.