Drive

We need channel two for the Right wheel to drive the robot.

We need channel three for the left wheel to drive the robot.

Arm

We need button 7U for the arm to move forward.

We need button 7D for the arm to move backward.

Collection system

We need button 6U for the design to move forward.

We need button 6D for the design to move backward.

EE

We need button 8L for the EE to move forward.

We need button 8R for the EE to move backward.