

MEAM 211

<http://www.seas.upenn.edu/~meam211>

Introduction

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What is Dynamics? The Big Picture

Three parts

- ❑ Geometry
 - Shapes, curves
- ❑ Kinematics
 - Motion
 - Curves, shapes + time
- ❑ Kinetics
 - Motion and causes of motion (forces)

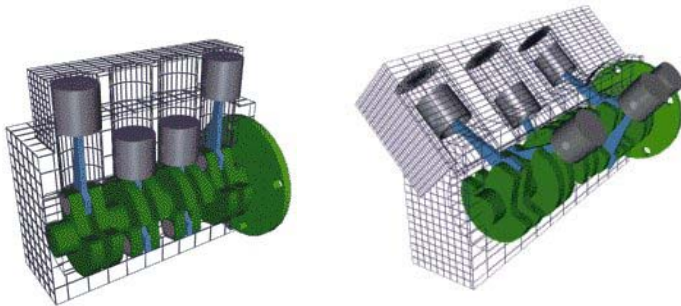
Types of Problems

- Describe motion
- Given motion, what forces caused motion?
- Given forces, predict motion

What is Dynamics? And why should we study it?

Motivating Examples

- Cruise missile
- Internal combustion engine
- Mechanisms

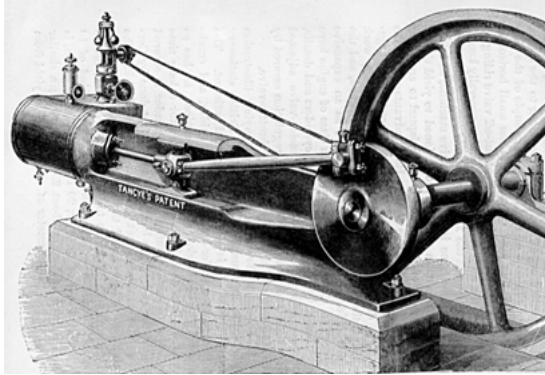


<http://auto.howstuffworks.com/engine5.htm>

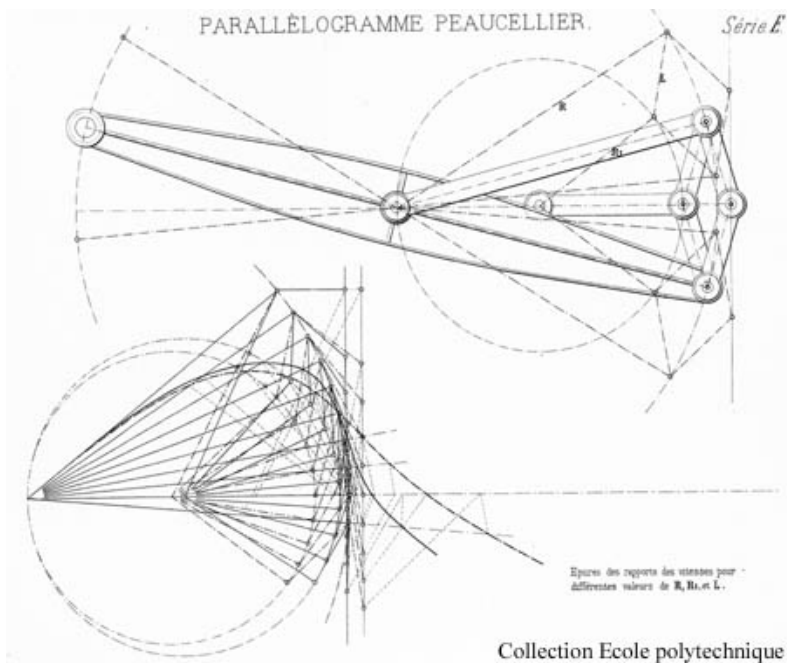


Mechanisms

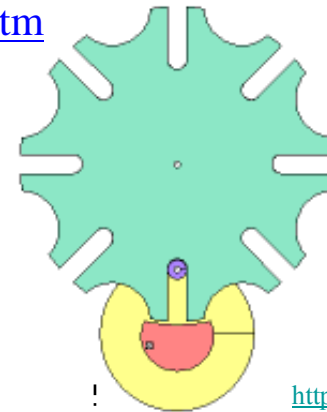
<http://www.brockeng.com/mechanism/index.htm>



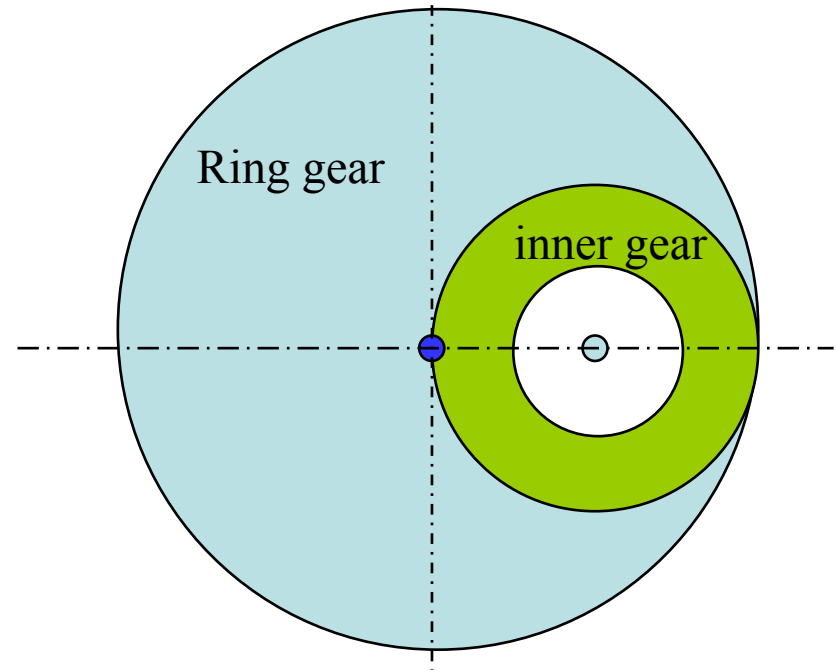
<http://www.history.rochester.edu/steam/thurston/1878/>



Collection Ecole polytechnique



<http://www.krev.com/>



<http://www.ornithopter.de/english/crank.htm>

Mechanisms: The Pantograph Mechanism

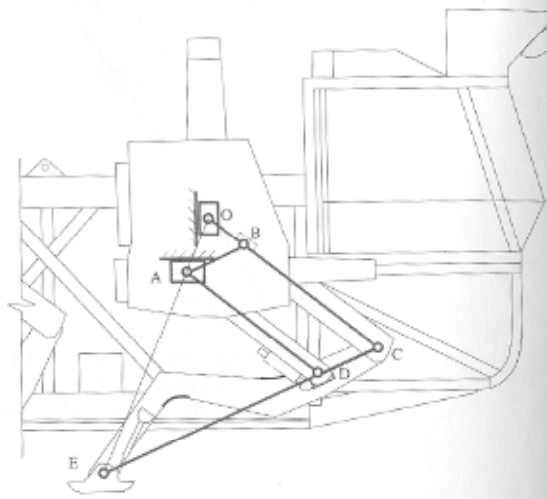


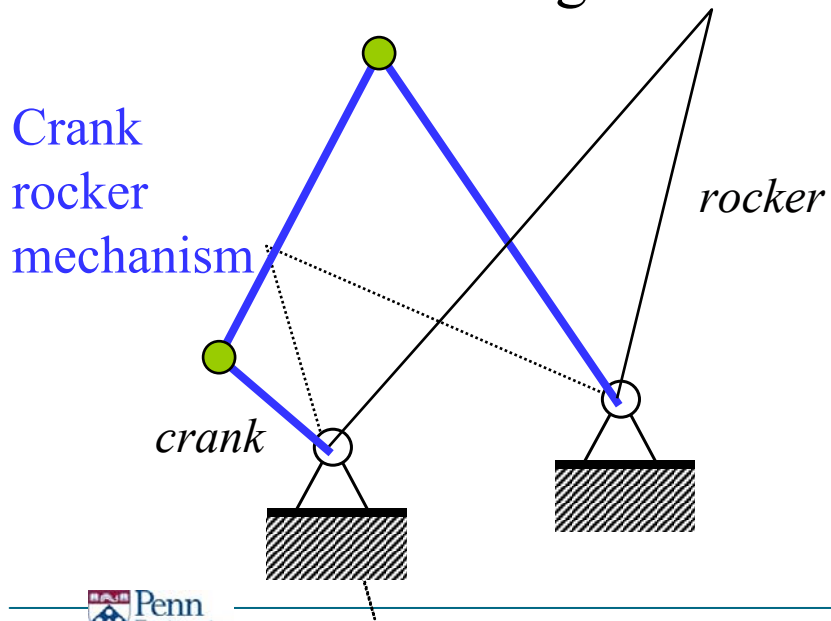
Figure 5.9 The leg mechanism of the Adaptive Suspension Vehicle. Point *O* moves on a slide that is vertical relative to the leg mounting structure to produce a corresponding vertical motion of the ankle point *E*. Point *A* moves on a slide that is horizontal relative to the vehicle body to drive point *E* along a horizontal path.



Mechanisms: Oscillating Water Sprinkler



Four-bar linkage – crank rocker



Planetary Gear

500:1 reduction



Head-controlled Feeding Device for Quadriplegics

- ❑ Head motion controls a passive (mechanical) feeder



Dynamics: Historical Perspective

□ Chapter I

- Newtonian mechanics
 - Kepler - planetary motion
 - Galileo - importance of acceleration
 - Newton - *Principia Mathematica* (1687)

100 years later ...

Historical Perspective (Continued)

□ Chapter II

● Lagrangian mechanics

- Bernoulli - principle of virtual work, statics
- Euler - dynamics of rotating rigid bodies
- D'Alembert - extension of virtual work to dynamics
- Lagrange - *Mechanique Analytique* (1788)

Analytical mechanics

- Analytical because it is based on a few fundamental principles
- Lagrange describes it as an approach which does not require drawing any diagrams (e.g. free body diagrams)

Focus in MEAM 211

- ❑ Newtonian mechanics
- ❑ No relativistic effects (no quantum mechanics)
 - Reasonable velocities
 - Reasonable length scales
- ❑ Practical problems
- ❑ Analysis and Design
- ❑ Projects linked to MEAM 247

Lectures and Recitation

Lectures

- New material
- Problem solving

Instructor

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Recitation

1. Forum for solving problems
2. Computer-Aided-Engineering labs

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