Three Projects

Simulation

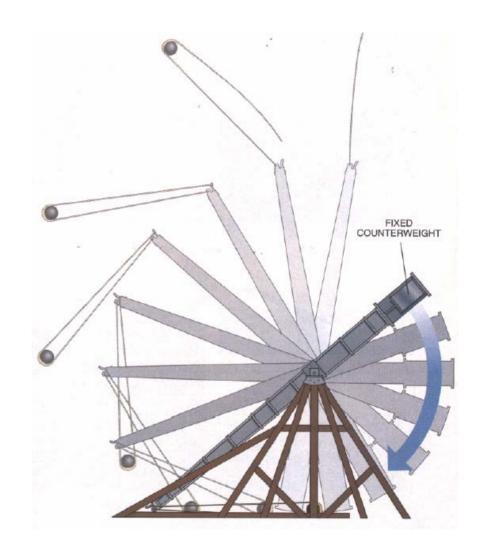
- Last year's project: Guidance system for a cruise missile
- Analysis, computer program

Linkage design

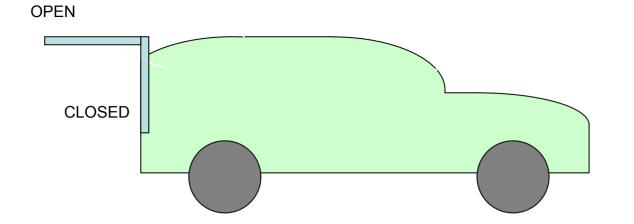
- Last year's project: Mechanism for a mini-van door
- Design, analysis and prototype

■ Trebuchet

- Designing a launching mechanism using principles of dynamics
- Write a computer program for analysis
- Build a prototype to validate model, design

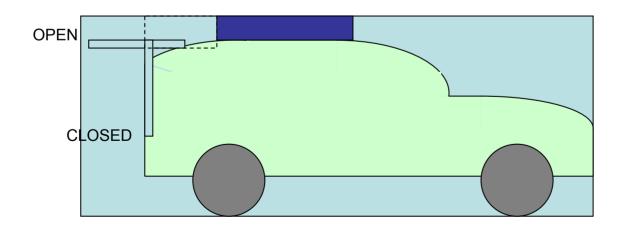






PROBLEM

DOOR IN OLD DESIGN SWINGS OUT



NEED

DOOR IN NEW DESIGN SWINGS OUT 40% LESS



Exercise Machine



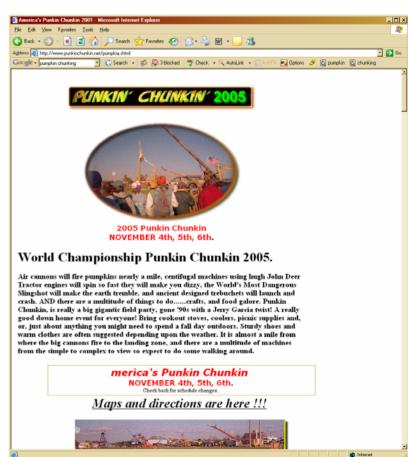




Trebuchet



http://en.wikipedia.org/wiki/Trebuchet





Trebuchet projects from 2006











Homework, Midterms, Quizzes, Final

Weekly work

- HW assigned weekly
 - Due every Friday
 - > Early bird points for Wed submissions
 - Graded HW returned following Wed
- Quizzes to make sure you stay on top of things
- Worst grades forgotten
- No late work (incentive for early completion)

Midterms and Finals

- Comprehensive
- Closed book, but cheat sheet allowed
- Performance will strongly correlate with good performance in weekly work



Class Participation

- Interaction in class;and/or
- Email questions or items of discussion to me
 - "Top" emails will be addressed in class the following week
 - Items must be
 - > Address questions related to dynamics
 - > Topical
 - > Preferably not simply questions about material covered in the class



Schedule

	Da	s Lecture		Recitation	Reading	Homewor	k Project Work	Lab work (247)
1	М		, kinematics of particles		1.1-1.5			
	W	Introduction	to computing, matlab, kinematics of particles		2.1, 2.2			
	F			Matlab recitation				
2	M	MLK Day - r	o class					
	W	Kinematics (of particles, state space notation, some kinetics, Project I		2.3, 3.1, App A	HW 1	Project I	
ਰ	F			Matlab recitation			Matlab	
3 💆	М	Kiematics of	particles, path coordinates		2.4			
	W	Degrees of f	reedom, mechanisms, machines, linkages		2.5, Notes	HW 2		
7 2	F			Matlab recitation				
Kinematic	М	Linkage ana	lysis		Notes			
	V	1.4 1 11.	thesis of linkages, Quiz 1 (not announced)		Notes	HW 3	Project I due	
				Problem Solving				
5 5-Feb	b N	%	articles, FBDs and IRDs, Project II		3.1-3.3		Project II	
7-Feb		ပ ၅	lysis of mechanisms		3.1-3.3	HW 4	Synthesis and	
9-Feb		tics		Problem Solving			analysis	
6 12-Fe		T. e	lysis of mechanisms, linear momentum		3.4		of linkages	
14-Fe		Kineti Particl	ntum, conservation laws			HW 5	. 3	
146 5		, T	ew	Problem Solving				
	H	X P						
of S	√√	ттрасс			3.7-3.8		Project II due	
\circ) E			Problem Solving	317 313			Project II presentation
e n	M	Work and er	nergy, power, efficiency	. resiem serring	4.1-4.3			r oject 11 presentation
7 7	W					HW 6		
五.正	E				3.1 3.3			
<u>-</u>								
System or Particles	`Ц	tics d				_		
9 12-Ma	arj N	atics	ut a fixed point: Kinetics, work and energy, catapults		6.1, 7.2			
9 12-Ma 14-Ma	ar N	natics ited	ut a fixed point: Kinetics, work and energy, catapults f rigid bodies (relative motion of rigid body), Quiz 2 (not announc			HW 7		
9 12-Ma 14-Ma 16-Ma	ar N ar V	ematics isited	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc	eed) Problem Solving	7.2, 7.5	HW 7	Project III	
9 12-Ma 14-Ma 16-Ma 10 19-Ma	ar N ar V ar N	nematics visited	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis		7.2, 7.5 6.2, 6.3		Design	
9 12-Ma 14-Ma 16-Ma 10 19-Ma 21-Ma	ar N ar V ar N ar N	inematic evisited	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc	Problem Solving	7.2, 7.5 6.2, 6.3	HW 7	Design optimization	
9 12-Ma 14-Ma 16-Ma .0 19-Ma	ar N ar V ar N ar N	nematic visited	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc ous centers and velocity analyis, acceleration analysis ion, rotating frames		7.2, 7.5 6.2, 6.3 6.3, 6.4		Design optimization of a	
9 12-Ma 14-Ma 16-Ma 0 19-Ma 21-Ma	ar N ar V ar N ar N ar V	Kinematic Revisited	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation	Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1	HW 8	Design optimization	
9 12-Ma 14-Ma 16-Ma .0 19-Ma 21-Ma	ar Nar Var Nar Var Nar Var Nar V	Kinematic Revisited	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion	Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1		Design optimization of a	
9 12-Ma 14-Ma 16-Ma 0 19-Ma 21-Ma 23-Ma	ar N ar N ar N ar N ar N ar N	Kinematic Revisited	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew	Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1	HW 8	Design optimization of a	
9 12-Ma 14-Ma 16-Ma 0 19-Ma 21-Ma 23-Ma	ar N ar N ar N ar N ar N ar N	Kinetics: Ro Midterm rev	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew	Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3	HW 8	Design optimization of a	
9 12-Ma 14-Ma 16-Ma 0 19-Ma 21-Ma 23-Ma	ar N ar N ar N ar N ar N ar N	Kinetics: Ro Midterm rev	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew	Problem Solving Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1	HW 8	Design optimization of a	
9 12-Ma 14-Ma 16-Ma 0 19-Ma 21-Ma 23-Ma	ar Nar Var Nar Var Nar V	Kinetics: Ro Midterm rev	f rigid bodies (relative motion of rigid body), Quiz 2 (not announce bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation (ation about a fixed point (revisited), general motion iew eneral motion (continued), linear and angular momentum	Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3 7.3, 7.4	HW 8	Design optimization of a	
12-Ma 14-Ma 16-Ma 0 19-Ma 21-Ma 23-Ma	ar Nar Var Nar Var Nar V	Kinetics: Ro Midterm rev	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation fation about a fixed point (revisited), general motion iew eneral motion (continued), linear and angular momentum of 2D rigid bodies	Problem Solving Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3 7.3, 7.4 7.5	HW 8	Design optimization of a	
9 12-Ma 14-Ma 16-Ma 0 19-Ma 21-Ma 23-Ma	ar N ar N ar N ar N ar N ar N	Kinetics: Ro Midterm II Kinetics of G	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew eneral motion (continued), linear and angular momentum of 2D rigid bodies prdinates, angular Velocity of 3D rigid bodies	Problem Solving Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3 7.3, 7.4 7.5	HW 8	Design optimization of a trebuchet	
9 12-Ma9 14-Ma9 16-Ma9 0 19-Ma9 21-Ma9 23-Ma9 VSO	ar Nar Var Nar Var Nar V	Kinetics: Ro Midterm II Kinetics of G	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc pus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew eneral motion (continued), linear and angular momentum of 2D rigid bodies prdinates, angular Velocity of 3D rigid bodies monstration, pizza	Problem Solving Problem Solving Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3 7.3, 7.4 7.5	HW 8	Design optimization of a trebuchet	Project III presentation
9 12-Mag 14-Mag 16-Mag 16-Mag 21-Mag 23-Mag 23-Mag 23-Mag 4 16-Ap 4 16	ar Nar Var Nar	Kinetics: Ro Midterm II Kinetics of G	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew eneral motion (continued), linear and angular momentum of 2D rigid bodies prodinates, angular Velocity of 3D rigid bodies monstration, pizza city and angular acceleration in 3 dimensions, Quiz 3 (not announce)	Problem Solving Problem Solving Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3 7.3, 7.4 7.5 8.1 8.2-8.3	HW 9 HW 10	Design optimization of a trebuchet	Project III presentation
9 12-Mag 14-Mag 16-Mag 16-Mag 21-Mag 23-Mag 23-Mag 4 16-Ap 4 16-Ap	ar Nar Var Nar	Kinetics: Ro Midterm II Kinetics of G	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc pus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew eneral motion (continued), linear and angular momentum of 2D rigid bodies prdinates, angular Velocity of 3D rigid bodies monstration, pizza	Problem Solving Problem Solving Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3 7.3, 7.4 7.5 8.1	HW 8	Design optimization of a trebuchet	Project III presentation
9 12-Ma 14-Ma 16-Ma 10 19-Ma 21-Ma 23-Ma	ar Nar Variation	Kinetics: Ro Midterm rev Kinetics of C	f rigid bodies (relative motion of rigid body), Quiz 2 (not announc bus centers and velocity analyis, acceleration analysis ion, rotating frames vilinear translation tation about a fixed point (revisited), general motion iew eneral motion (continued), linear and angular momentum of 2D rigid bodies prodinates, angular Velocity of 3D rigid bodies monstration, pizza city and angular acceleration in 3 dimensions, Quiz 3 (not announce)	Problem Solving Problem Solving Problem Solving Problem Solving	7.2, 7.5 6.2, 6.3 6.3, 6.4 7.1 7.2, 7.3 7.3, 7.4 7.5 8.1 8.2-8.3	HW 9 HW 10	Design optimization of a trebuchet	Project III presentation



Website

http://www.seas.upenn.edu/~meam211

Check regularly

- Weekly homework
- FAQ
- Reading assignments
- All notes/handouts/slides
- Project materials
- Contact information

All emails directed to meam211@seas.upenn.edu



Logistics

- □ Lectures: Mon, Wed
 - Slides online
- Recitation mandatory: Friday (2 sections)
- □ First three recitations will be in computer labs
- HW: Due Fri (early bird points for Wed submission)
- Quizzes
 - 3 quizzes (unannounced!)
- Projects 2 and 3
 - Group project
 - Same groups as MEAM 247!
 - Fabrication counts as MEAM 247 lab
- □ Project 1
 - Group members can collaborate
 - Individual reports

By Friday

List of group members with email addresses to TA with signatures; or

Email to meam211@seas with all group members cc'ed

