

High torque servos 12V-24V

ASME-03B

380kg

WANG OFFICE

High torque servos 12V-24V

ebay ID: wingxine http://www.aliexpress.com/store/32

Application: Robot, mechanical arm, production line, the camera haeundae control robot



### **FEATURES**

- wireless remote control and analog voltage control
- Metal gear high torque outpu
- Current limiting control
- Easy to install, strong and durable

### Application

- Large arm of the robot joints and heavy load of leg joint movement control
- Industrial automation production line robot control
- Accurate control of the valve Angle
- Large camera haeundae remote control

### RECOMMENDED OPERATING CONDITIONS

Parameter	26583			
Operating Voltage	11V-24V/DC (11V/MIN~30V/MAX)			
No-load current	<400mA			
Limit Angle	±150° or 0°~300° (MAX)			
Control mode	This pulse mode:1ms~2ms(pulse width)  2ms pulse mode:0.5ms~2.5ms(pulse width)  voltage mode  0V-5V input voltage (0V to 0°,5V to 270°)			
Material 📢 📀	Gear and shaft: alloy steel; gear box: aluminum			
Weight	550g			
Dimension	95mm*60mm*110mm			
Mechanical Life	> 1,000,000/full load (conservative values)			

### **BSOLUTE MAXIMUM RATINGS**

Parameter				
limit input voltage	11V~30V/DC (MAX) 5A±0.2A (MAX)			
limited output current				
limit Angle	±150° or 0°~300° (MAX)			
Comband and do	PPM mode	1ms pulse mode : 1ms~2ms(pulse width)		
Control mode	voltage mode	2ms pulse mode: 0.5ms~2.5ms(pulse width)  0V-5V input voltage (0.22V to 0°,4.78V to 300°)		
Weight	510g~560g			

### Models and Specifications

Models	Starting Torque	Holding Torque	Rated speed(24Vpower)
ASME-02A	260kg.cm max	220kg.cm max	0.12s/60°MAX
ASME-02B	380kg.cm max	340kg.cm max	0.5s/60°MAX

DC POWER

INPUT



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PPM PULSE/Analog Voltage Control

Sensitivity range Adj Angle output range Adj Voltage Output

Position output

Signal line "5V" output or floating select

Signal input port

Indicator light

Analog / pulse Input Settings

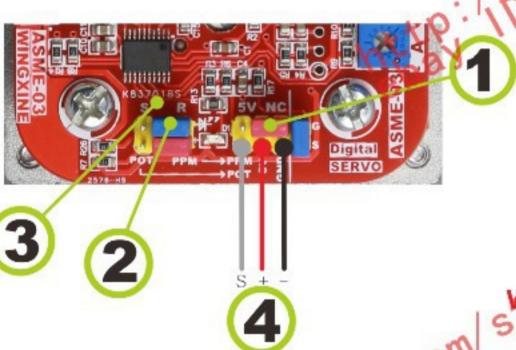
ms/2ms Pulse mode settings

- Power steering line basis having indicated polarity wiring.
- Potentiometer A: used to adjust the servo motion sensitivity.
- 3. Potentiometer B: used to adjust the rotation angle range of the steering gear shaft.

Turn the steering angle and contraction ratio of the input sign With mechanical steering midpoint symmetry contraction.

- 4. position output: for external devices coarse detection steering ang is actually running. Input voltage range of 0V ~ 5V. The effective operation of the correspondence between the angle and voltage is: 0 ° to 0.22V 300 ° to 4.78V
- 5. Indicator light LED is flashing, servos work properly.
- 6. Mode settings: See description below.

G:The power input reverse will burn servos direc please check when wiring!



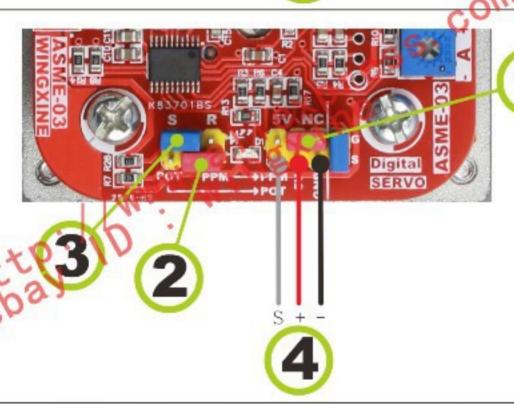
### RC MODE ("1ms"Pulse Width Mode)

- 1, the jumper settings "NC" position.
- 2, the jumper settings "PPM" position.
- the jumper is set in "R" position.
- 4, (1)"PPM" pin is signal input.

(Servo controller "S" pin or RC receiver "S" pin, generally are used on model aircraft "S" indicates)

(2) "GND" pin connected to negative signal line. (Serva controller "-" foot or remote control receiver "-" feet, generally are used on model aircraft "-" indicates)

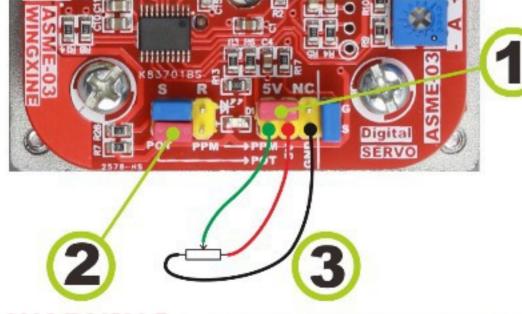
VARNING: The servo an independent power supply, so "+" does not require wiring.



### RC MODE ("2ms"Pulse Width Mode)

- 1, the jumper settings "NC" position.
- the jumper settings "PPM" position.
- the jumper is set in "S" position.
- 4, (1)"PPM" pin is signal input.
  - (Servo controller "S" pin or RC receiver "S" pin, generally are used on model aircraft "S" indicates)
  - (2) "GND" pin connected to negative signal line. (Servo controller "-" foot or remote control receiver "-" feet, generally are used on model aircraft "-" indicates)

WARNING: The servo an independent power supply, so "+" does not require wiring.



## Voltage input or Potentiometer input MODE

- 1, the jumper settings "5V" position.
- 2, the jumper settings "POT" position.
- 3, (1) signal input terminal labeled "POT" pin is connected to the potentiometer wiper.
  - (2) labeled "5V" and "GND" pins are connected to the potentiometer two fixed ends.

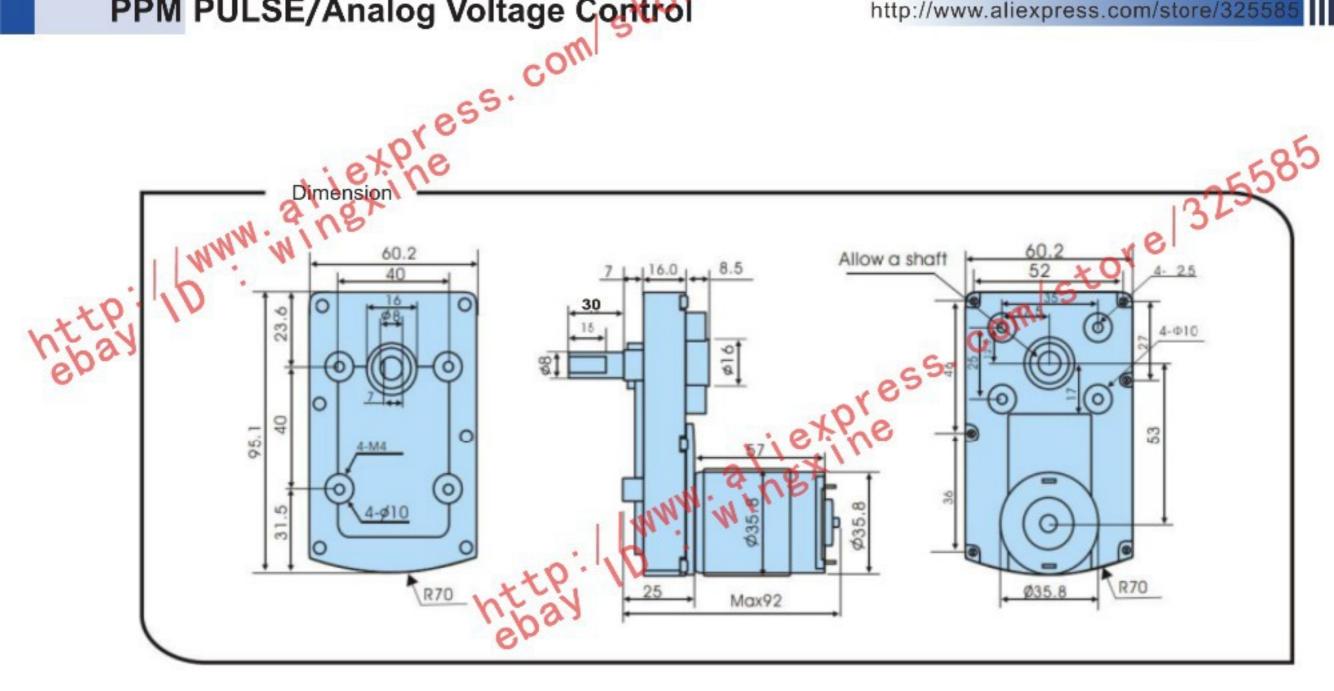
If the input voltage directly controls the time to pick "5V" pin "the 1st position" jumpers set in the "NC" position, just pick "POT" and "GND" pin. Input voltage range of 0V to +5 V (DC).

WARNING:

- 1, the steering gear output "+5 V" power supply can only meet
  - the potentiometer, Do not use servos to supply power to other equipment.
- 2, the potential selection: 10k, 50k, 100k, potentiometer whith resistance greater than 10k.

# ALFS

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