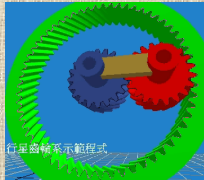


## Chapter 12 Gear Trains



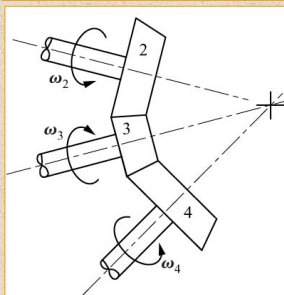
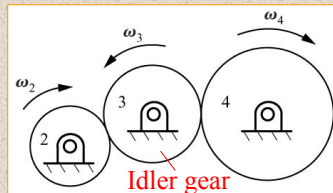
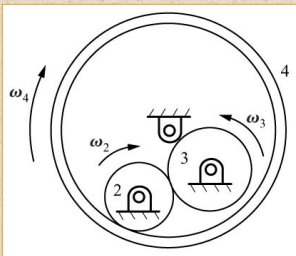
2005/6/11

機構學 (C. F. Chang)



1

## Simple Gear Trains (簡單輪系)



2005/6/11

機構學 (C. F. Chang)

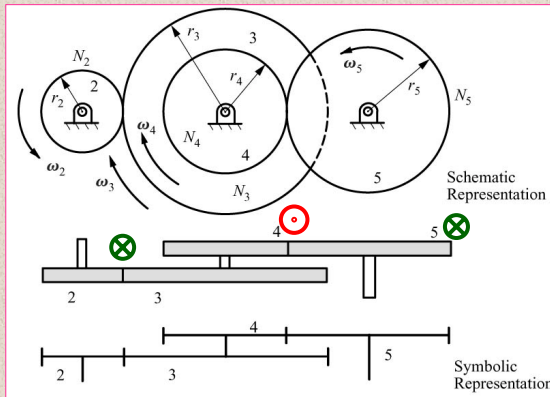
- Simple gear trains have only one gear on each shaft (各軸上皆只有一個齒輪)
- Velocity ratio,  $\omega_i/\omega_o$ , is a function of the numbers of teeth on the input and output gears only. That is,  $\omega_i/\omega_o = N_o/N_i$  (簡單輪系之速度比僅與首尾兩輪之齒數比有關)
- Each gear must have the same normal pitch if the gears are to mesh properly (各齒輪之法周節必須相同)

2

## Compound Gear Trains (複式齒輪系)

Compound gear trains are characterized by the presence of two or more gears attached to the same shaft (有些軸上有兩個以上的齒輪)

$$\frac{\omega_i}{\omega_o} = \pm \frac{\text{product of driven tooth numbers}}{\text{product of driver tooth numbers}} = \pm \frac{\text{從動輪之齒數乘積}}{\text{驅動輪之齒數乘積}}$$



$$\frac{\omega_2}{\omega_5} = \frac{\omega_2}{\omega_3} \frac{\omega_3}{\omega_4} \frac{\omega_4}{\omega_5} = + \frac{N_3 N_5}{N_2 N_4}$$

2005/6/11

機構學 (C. F. Chang)

3

### Example 12.1

#### Analysis of a Compound Gear Train

$$r_p = \frac{Nm}{2} = \frac{N}{2P_d} \quad \frac{\omega_i}{\omega_o} = \pm \frac{\text{product of driven tooth numbers}}{\text{product of driver tooth numbers}}$$

**Problem:**

Assume that the compound gear train in the figure has the tooth number given in parentheses. The angular velocity of gear 2 is 200 rpm in the direction shown.

**Determine:**

- (1) the magnitude and direction of the angular velocity of gear 10,
- (2) the velocity of the rack that is gear 11.

**Sol:**

(1) Determine  $\omega_{10} = \omega_9$

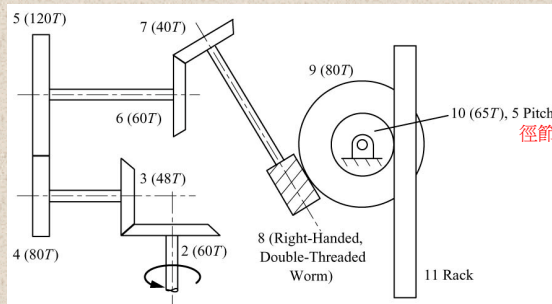
$$\frac{\omega_2}{\omega_{10}} = \frac{\omega_2}{\omega_9} = + \frac{N_3 N_5 N_7 N_9}{N_2 N_4 N_6 N_8}$$

$$\frac{200}{\omega_{10}} = \frac{48}{60} \frac{120}{80} \frac{40}{60} \frac{80}{2} = 32$$

$$\omega_{10} = 200 / 32 = 6.25 \text{ rpm}$$

(2) Determine  $v_{11}$

$$v_{11} = r_{10} \omega_{10} = \left( \frac{65}{5} / 2 \right) (6.25 (2\pi/60)) = 4.255 \text{ in} \leftarrow \text{Ans}$$



2005/6/11

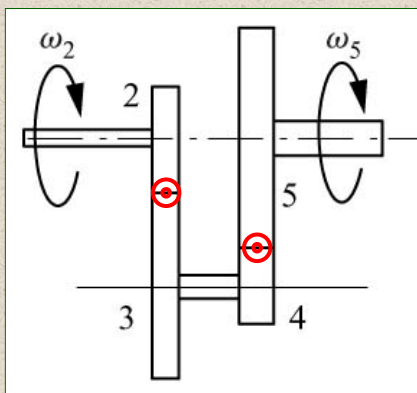
機構學 (C. F. Chang)

4

## A Concentric Gear Reducer with a Two-Stage Reduction

$$P_t = P_n \cos \psi$$

$$P_t = \frac{N}{2r}$$



$$r_2 + r_3 = r_4 + r_5$$

$$\frac{\omega_2}{\omega_5} = \frac{\omega_2}{\omega_3} \frac{\omega_3}{\omega_5} = \frac{\omega_2}{\omega_3} \frac{\omega_4}{\omega_5} = + \frac{N_3 N_5}{N_2 N_4}$$

In concentric gear train, the input and output shafts are collinear  
回歸齒輪系: 複式齒輪系之首尾兩輪的軸線重合 (節省空間)

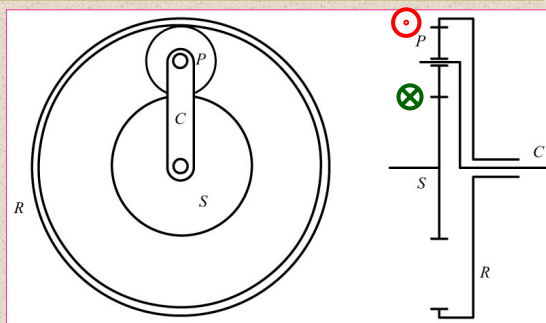
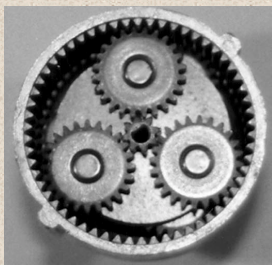
2005/6/11

機構學 (C. F. Chang)

5

## Planetary Gear Trains / Epicyclic Gear Trains

行星齒輪系 / 周轉輪系



S: sun gear (太陽齒輪)

P: planet gear (行星齒輪)

C: carrier, arm (行星架, 旋臂)

R: internal ring gear (環齒輪)

$$\frac{\omega_i - \omega_c}{\omega_j - \omega_c} = \pm \frac{N \dots N_j}{N_i \dots N}$$

The ratio of velocities relative to the carrier

Gears i and j are gears that mesh with planet gear(s)

$$\text{Ex: } \frac{\omega_p - \omega_c}{\omega_s - \omega_c} = - \frac{N_c N_s}{N_p N_c} = - \frac{N_s}{N_p}$$

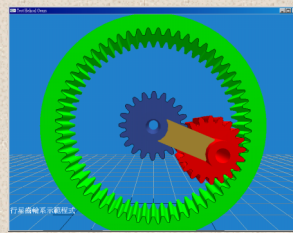
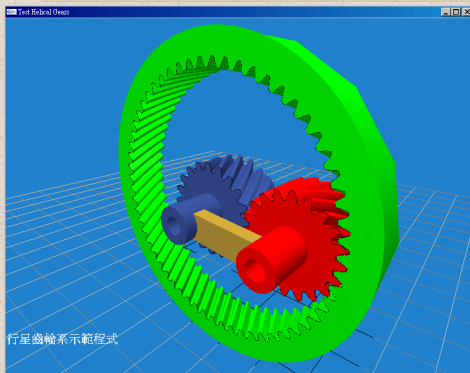
2005/6/11

機構學 (C. F. Chang)

6



## Demo



Spur gears  $N_s=20$ ,  $N_p=20$ ,  $N_R=60$   
 Sun gear:  $\omega_s = \omega_a (1 + (N_r/N_s)) = 4\omega_a$   
 Planet gear:  $\omega_p = \omega_a (1 - (N_r/N_p)) = -2\omega_a$   
 Ring gear:  $\omega_r = 0$   
 Driver: Carrier, Arm,  $\omega_a$

Sun gear:  $\psi_s = 30^\circ$ ,  $N_s = 20$ ,  $\omega_s = 0$   
 Planet gear:  $\psi_p = -30^\circ$ ,  $N_p = 20$ ,  $\omega_p = \omega_a (1 + (N_r/N_p)) = 2\omega_a$   
 Ring gear:  $\psi_r = -30^\circ$ ,  $N_r = 60$ ,  $\omega_r = \omega_a (1 + (N_s/N_r)) = 1.333 \omega_a$   
 Driver: Carrier, Arm,  $\omega_a$   
 Pressure angle:  $\phi_n = 20^\circ$   
 Modulus:  $m_n = 2$

2005/6/11

機構學 (C. F. Chang)

7

## Ex: 12-4

Given:

$\omega_C = -150$  rpm,  $\omega_5 = -50$  rpm, and the tooth numbers are given in the figure

Find:

the angular velocity of gear 2

Sol:

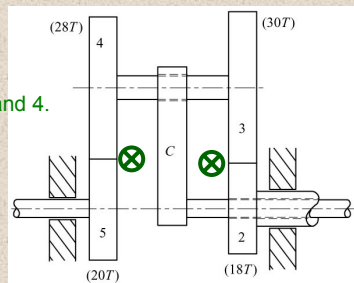
Note that gears 2 and 5 mesh with planet gears 3 and 4.

Choosing  $i=2$ ,  $j=5$ , we get

$$\frac{\omega_2 - \omega_C}{\omega_5 - \omega_C} = + \frac{N_5 N_3}{N_2 N_4}$$

$$\frac{\omega_2 + 150}{-50 + 150} = \frac{20 \cdot 30}{18 \cdot 28}$$

$$\omega_2 = -30.95 \text{ rpm} \leftarrow \text{ANS}$$



2005/6/11

機構學 (C. F. Chang)

8

## Ex 12-5

Given:

$$\omega_2 = 60 \text{ rpm (ccw)}$$

Find:

the angular velocity of gear 5

Sol:

Note that  $\omega_7 = 0$  since gear 7 is a fixed ring gear

Besides, gears 2, 5, and 7 mesh with planet gears

(1)  $i = 2, j = 5$

$$\frac{\omega_2 - \omega_C}{\omega_5 - \omega_C} = + \frac{N_5 N_3}{N_2 N_4} \rightarrow \frac{60 - \omega_C}{\omega_5 - \omega_C} = \frac{20 \cdot 30}{18 \cdot 28}$$

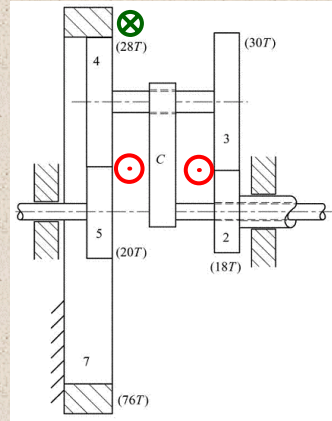
(2)  $i = 2, j = 7$

$$\frac{\omega_2 - \omega_C}{\omega_7 - \omega_C} = - \frac{N_7 N_3}{N_2 N_4} \rightarrow \frac{60 - \omega_C}{0 - \omega_C} = - \frac{76 \cdot 30}{18 \cdot 28}$$

$$\omega_C = 10.862 \text{ rpm}$$

(3) Solving (1) for  $\omega_5$  yields

$$\omega_5 = 52.137 \text{ rpm} \leftarrow \text{ANS}$$



2005/6/11

機構學 (C. F. Chang)

9

## Ex 12-6

Given:

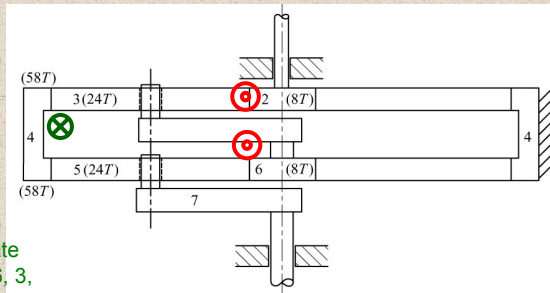
$$\omega_2 = 60 \text{ rpm (ccw)}, \omega_4 = 0$$

Find:

the velocity ratio  $\omega_2 / \omega_7$

Sol:

There are two arms, so we separate the gears into two sets. Gears 2, 6, 3, and 4 are of set 1, while gears 6, 5, 4, and 7 are of set 2.



(1) For set 1

$$\frac{\omega_2 - \omega_6}{\omega_4 - \omega_6} = - \frac{N_4}{N_2} \rightarrow \frac{60 - \omega_6}{0 - \omega_6} = - \frac{58}{8} \rightarrow \omega_6 = \frac{480}{66} = \frac{80}{11}$$

(2) For set 2

$$\frac{\omega_6 - \omega_7}{\omega_4 - \omega_7} = - \frac{N_4}{N_6} \rightarrow \frac{(80/11) - \omega_7}{0 - \omega_7} = - \frac{58}{8} \rightarrow \omega_7 = 68.06 \text{ rpm} \leftarrow \text{ANS}$$

2005/6/11

機構學 (C. F. Chang)

10

## Ex 12-7

Given:

$$\omega_2 = 100 \text{ rpm (ccw)}$$

Find:

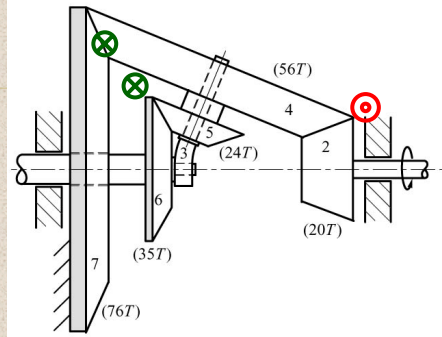
the angular velocity of gear 6,  $\omega_6$

Sol:

$$1. \omega_c = \omega_3$$

$$2. \omega_7 = 0 \text{ (gear 7 is a fixed gear)}$$

3. gears 2, 6, and 7 mesh with planet gears 4 and 5



$$(1) i = 2, j = 6$$

$$\frac{\omega_2 - \omega_c}{\omega_6 - \omega_c} = -\frac{N_6 N_4}{N_2 N_5} \rightarrow \frac{100 - \omega_3}{\omega_6 - \omega_3} = -\frac{35 \cdot 56}{20 \cdot 24}$$

(3) Solving (1) for  $\omega_6$  yields

$$\omega_6 = 1.444 \text{ rpm} \leftarrow \text{ANS}$$

$$(2) i = 2, j = 7$$

$$\frac{\omega_2 - \omega_c}{\omega_7 - \omega_c} = -\frac{N_7 N_4}{N_2 N_5} = -\frac{N_7}{N_2} \rightarrow \frac{100 - \omega_3}{0 - \omega_3} = -\frac{76}{20}$$

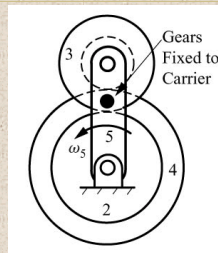
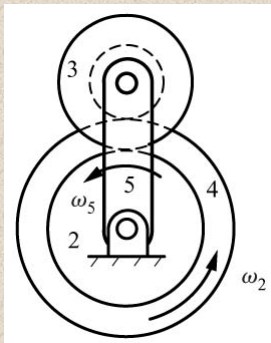
$$\omega_3 = 20.833 \text{ rpm}$$

2005/6/11

機構學 (C. F. Chang)

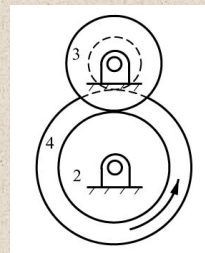
11

## Analysis of Planetary Gear Trains Using Tabular Method



rotate with the arm  
(gears locked to the arm)

+



relative to the arm  
(carrier fixed)

$${}^5\omega_2 = \omega_2 - \omega_5$$

2005/6/11

機構學 (C. F. Chang)

12



### Ex 12.8

Given:

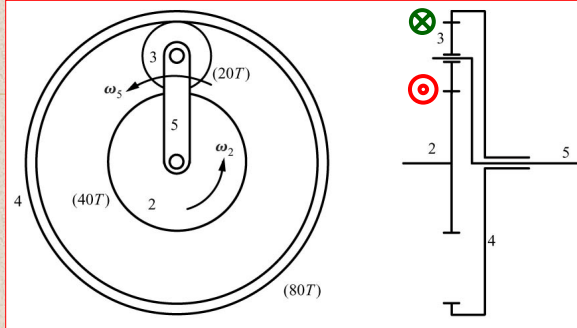
$\omega_2 = 100 \text{ rpm (ccw)}$

$\omega_5 = 200 \text{ rpm (ccw)}$

Find:

$\omega_3$  and  $\omega_4$

Sol:



	Carrier 5	Gear 2	Gear 3	Gear 4
Gears locked	200	200	200	200
Carrier fixed	0	-100	$100(N_2/N_3) = +200$	$200(N_3/N_4) = +50$
Total	200	100	400	250

2005/6/11

機構學 (C. F. Chang)

13

### Ex 12.10

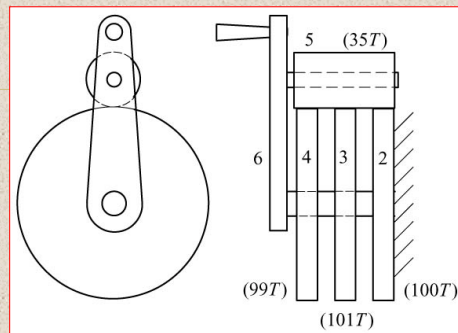
Given:

$\omega_6 = 100 \text{ rpm (ccw)}$

Find:

$\omega_3$ ,  $\omega_4$ , and  $\omega_5$

Sol:



	Carrier 6	Gear 2	Gear 3	Gear 4
Gears locked	100	100	100	100
Carrier fixed	0	-100	$-100(N_2/N_3) = -100/1.01$	$-100(N_2/N_4) = -100/0.99$
Total	100	0	$100(101-1)/100 = 1$	$100(99-100)/99 = -100/99$

2005/6/11

機構學 (C. F. Chang)

14