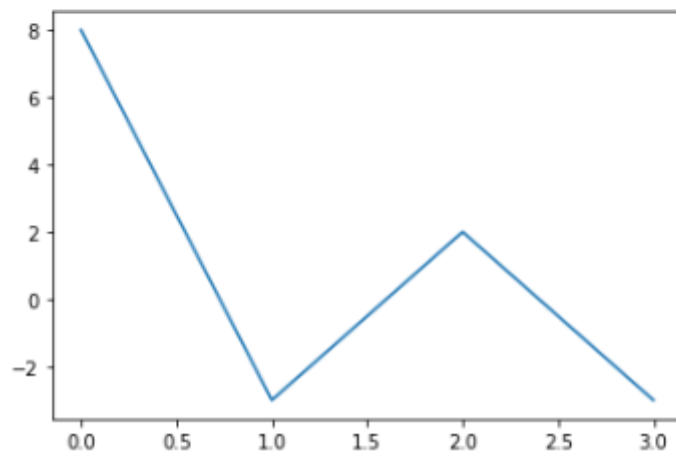


實戰(2)

```
1 import numpy as np
2 from numpy.fft import fft
3
4 x = np.array([1, 1, 4, 2])
5 X = fft(x)
6
7 print("x : ", x)
8 print("X : ", X)
9
10 plt.plot(X)
```

```
x : [1 1 4 2]
X : [ 8.+0.j -3.+1.j  2.+0.j -3.-1.j]
/usr/local/lib/python3.7/dist-packages/matplotlib/cbook.py:197:
return np.asarray(x, float)
[<matplotlib.lines.Line2D at 0x7f8c2e3be190>]
```



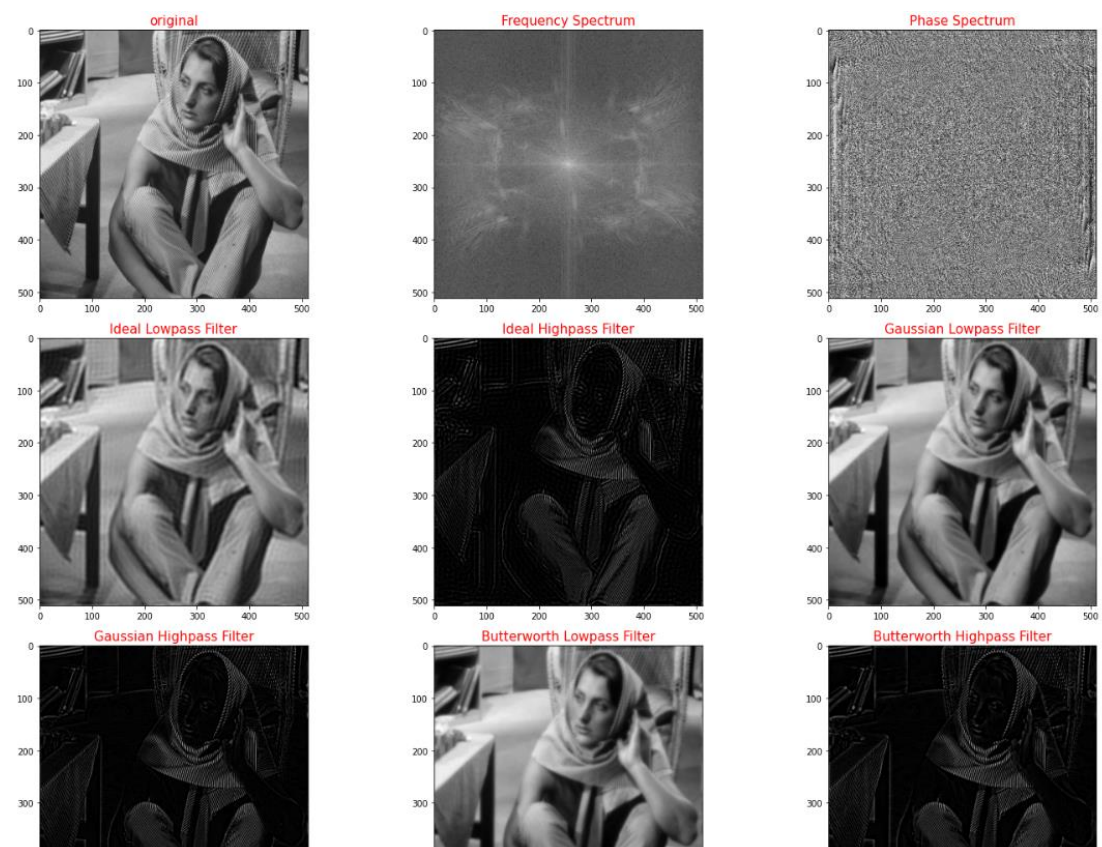
實戰(3)

[illegible]

```

43     if filter == 1:                                     # 理想低通濾波器
44         for u in range( nr ):
45             for v in range( nc ):
46                 dist = np.sqrt( ( u - nr / 2 ) * ( u - nr / 2 ) +
47                                 ( v - nc / 2 ) * ( v - nc / 2 ) )
48                 if dist > D0:
49                     G[u,v] = 0
50
51     elif filter == 2:                                     # 理想高通濾波器
52         for u in range( nr ):
53             for v in range( nc ):
54                 dist = np.sqrt( ( u - nr / 2 ) * ( u - nr / 2 ) +
55                                 ( v - nc / 2 ) * ( v - nc / 2 ) )
56                 if dist <= D0:
57                     G[u,v] = 0
58
59     elif filter == 3:                                     # 高斯低通濾波器
60         for u in range( nr ):
61             for v in range( nc ):
62                 dist = np.sqrt( ( u - nr / 2 ) * ( u - nr / 2 ) +
63                                 ( v - nc / 2 ) * ( v - nc / 2 ) )
64                 H = np.exp( -( dist * dist ) / ( 2 * D0 * D0 ) )
65                 G[u,v] *= H
66
67     elif filter == 4:                                     # 高斯高通濾波器
68         for u in range( nr ):
69             for v in range( nc ):
70                 dist = np.sqrt( ( u - nr / 2 ) * ( u - nr / 2 ) +
71                                 ( v - nc / 2 ) * ( v - nc / 2 ) )
72                 H = 1 - np.exp( -( dist * dist ) / ( 2 * D0 * D0 ) )
73                 G[u,v] *= H
74
75     elif filter == 5:                                     # 巴特沃斯低通濾波器
76         for u in range( nr ):
77             for v in range( nc ):
78                 dist = np.sqrt( ( u - nr / 2 ) * ( u - nr / 2 ) +
79                                 ( v - nc / 2 ) * ( v - nc / 2 ) )
80                 H = 1.0 / ( 1.0 + pow( dist / D0, 2 * order ) )
81                 G[u,v] *= H
82
83     elif filter == 6:                                     # 巴特沃斯高通濾波器
84         for u in range( nr ):
85             for v in range( nc ):
86                 dist = np.sqrt( ( u - nr / 2 ) * ( u - nr / 2 ) +
87                                 ( v - nc / 2 ) * ( v - nc / 2 ) )
88                 H = 1.0 - 1.0 / ( 1.0 + pow( dist / D0, 2 * order ) )
89                 G[u,v] *= H
90
91     gp = ifft2( G )                                     # 反離散傅立葉轉換
92
93     gp2 = np.zeros( [ nr, nc ] )                       # 後處理
94     for x in range( nr ):
95         for y in range( nc ):
96             gp2[x,y] = round( pow( -1, x + y ) * np.real( gp[x,y] ), 0 )
97     g = np.uint8( np.clip( gp2, 0, 255 ) )
98
99     return g
100
101
102 img1 = frequency_spectrum(img)
103 img2 = phase_spectrum(img)
104 img3 = frequency_filtering( img, 1, 50, 1 )
105 img4 = frequency_filtering( img, 2, 50, 1 )
106 img5 = frequency_filtering( img, 3, 50, 1 )
107 img6 = frequency_filtering( img, 4, 50, 1 )
108 img7 = frequency_filtering( img, 5, 50, 1 )
109 img8 = frequency_filtering( img, 6, 50, 1 )
110
111 titles = ['original', 'Frequency Spectrum', 'Phase Spectrum', 'Ideal Lowpass Filter', 'Ideal Highpass Filter', \
112          'Gaussian Lowpass Filter', 'Gaussian Highpass Filter', 'Butterworth Lowpass Filter', 'Butterworth Highpass Filter']
113 images = [img, img1, img2, img3, img4, img5, img6, img7, img8]
114
115 plt.figure(figsize=(20, 15))
116
117 for i in range(9):
118     plt.subplot(3, 3, i + 1), plt.imshow(images[i], 'gray')
119     plt.title(titles[i], fontsize = 15, color = 'r')
120
121 plt.tight_layout()
122 plt.show()

```



問答題

(1) 數位影像轉成頻率頻譜時，為何需要將頻譜影像中心化？

為了方便觀察頻率分量的分布，越接近影像中心代表是低頻區域，越離開影像中心，代表是高頻區域。

(2) 何謂卷積定理？

空間域卷積等同於頻域乘積。