

## Prac 1

Aim:

Write a program to demonstrate the following.

a) Addition of two complex numbers.

$$\rightarrow a = 4 + 2j.$$

$$b = 3 - 5j.$$

$$\text{print("Addition is:", a+b)}$$
o/p: Addition is: (7-3j).

b) Displaying the conjugate of complex numbers

$$\rightarrow a = 2 + 3j.$$

$$\text{print}(a.\text{conjugate}())$$
o/p: (2-3j).

1c) Plotting a set of complex numbers.  
→ import matplotlib.pyplot as plt.

$$x = 2 + 2j$$

$$a = [-2 + 4j, -1 + 2j, 0 + 2j, 1 + 2j, 2 + 2j, \\ -1 + 4j, 0 + 4j, 1 + 4j]$$

$$x = [x.\text{real for } x \text{ in } a]$$

$$y = [x.\text{imag for } x \text{ in } a]$$

$$\text{plt.scatter}(x, y, \text{color} = \text{"red"})$$

$$\text{plt.show}()$$

1d) Creating a new plot by rotating given number by degree.

i)  $90^\circ$

→ import matplotlib.pyplot as plt.

$$x = 2 + 4j$$

$$z = 1j$$

$$\text{plt.scatter}(x.\text{real}, x.\text{imag}, \text{color} = \text{"red"})$$

$$c = x * z$$

$$\text{plt.scatter}(c.\text{real}, c.\text{imag}, \text{color} = \text{"blue"})$$

$$\text{plt.show}()$$



1d) ii)  $180^\circ$ 

```
→ import matplotlib.pyplot as plt.  
x = 2 + 4j.  
plt.scatter(x.real, x.imag, color='red')  
plt.scatter(-1 * x.real, -1 * x.imag, color=  
plt.show() 'green')
```

1d) iii)  $270^\circ$ 

```
→ import matplotlib.pyplot as plt.  
x = 2 + 4j  
z = -1j.  
plt.scatter(x.real, x.imag, color='red')  
c = x * z  
plt.scatter(c.real, c.imag, color='green')  
plt.show()
```

1d) iv). Scaling by number  $a = 1/2, a = 1/3, a = 2$ 

```
→ import matplotlib.pyplot as plt.  
x = 2 + 4j.  
Scale = 0.5  
Scale 1 = 0.33  
Scale 2 = 2  
plt.scatter(x.real, x.imag, color='red')  
c = Scale  
d = Scale 1 * x  
e = Scale 2 * x  
plt.scatter(c.real, c.imag, color='green')  
plt.scatter(d.real, d.imag, color='blue')  
plt.show()
```

## Practical 2.

Aim: write program to do.

- enter vector u as list.
- enter another vector b as list.
- Find the vector  $au + bv$  for different values
- find dot product of u and v.

→. import numpy as np.

u = np.array([3, 4, 5])

v = np.array([1, 2, 7])

print("Vector u", u)

print("Vector v", v)

a = int(input("Enter value for a: "))

b = int(input("Enter value for b: "))

d = a \* u + b \* v

p = np.dot(u, v)

print("Vector  $au + bv$ ", d)

print("Dot product of u and v:", p)

o/p:

Vector u [3 4 5]

Vector v [1 2 7]

Enter the value for a: 2

Enter the value for b: 4

Vector  $au + bv$  [10 16 38]

Dot product of u and v: 46



### Practical 3.

Aim: Basic matrix operations

a) matrix addition, subtraction, multiplication

→ import numpy as np.

m1 = np.array([[1, 3, 4], [8, 5, 6]])

m2 = np.array([[8, 6, 9], [9, 0, 6]])

print("Add matrix")

a = np.add(m1, m2)

print(a)

print("Subtract matrix")

b = np.subtract(m2, m1)

print(b)

x = np.array([[1, 7, 5], [4, 5, 3], [3, 2, 1]])

y = np.array([[6, 7, 7], [2, 3, 1], [2, 2, 3]])

t = np.array([[0, 0, 0], [0, 0, 0], [0, 0, 0]])

print("Multiplication matrix")

for i in range(len(x)):

for j in range(len(y[0])):

for k in range(len(y)):

t[i][j] += x[i][k] \* y[k][j]

for r in t:

print(r)

3) o/p:

Add matrix.

$$\begin{bmatrix} 9 & 9 & 13 \end{bmatrix}$$

$$\begin{bmatrix} 17 & 5 & 12 \end{bmatrix}$$

Subtract matrix.

$$\begin{bmatrix} 7 & 3 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -5 & 0 \end{bmatrix}$$

Multiplication matrix.

$$\begin{bmatrix} 30 & 38 & 29 \end{bmatrix}$$

$$\begin{bmatrix} 40 & 49 & 42 \end{bmatrix}$$

$$\begin{bmatrix} 24 & 29 & 26 \end{bmatrix}$$



b) check if matrix is invertible and if yes then find inverse of matrix.

```
→ import numpy as np
m = np.array([[1, 2, 1], [2, 1, 0], [3, 0, 2]])
print("matrix is: ", m)
c = np.linalg.det(m)
print("Determinant is: ", c)
if (c != 0):
    minv = np.linalg.inv(m)
    print("inverse of matrix: ", minv)
else:
    print("matrix is not invertible")
```

O/P:

matrix is:  $\begin{bmatrix} 1 & 2 & 1 \\ 2 & 1 & 0 \\ 3 & 0 & 2 \end{bmatrix}$

Determinant is: -8.999999998

inverse of matrix is:

$\begin{bmatrix} -0.222222 & 0.444444 & 0.111111 \\ 0.444444 & 0.111111 & -0.222222 \\ 0.333333 & -0.666667 & 0.333333 \end{bmatrix}$

### Practical 4.

Aim: Write program to convert matrix into its row echelon form.

a)  $\rightarrow$  from sympy import \*

```
M = Matrix([[1, 0, 1, 3], [2, 3, 4, 7],  
            [-1, -3, -3, -4]])
```

```
print("Matrix: {}".format(M))
```

①  $M_{\text{rref}} = M.\text{rref}()$

```
print("The row echelon form of Matrix M  
and the pivot columns: {}".format(M_rref))
```

O/P:

Matrix :  $\begin{bmatrix} [1, 0, 1, 3], [2, 3, 4, 7], [-1, -3, -3, -4] \end{bmatrix}$   
The row echelon form of Matrix M and the  
pivot column

$\begin{bmatrix} [1, 0, 1, 3],$

$[0, 1, 2/3, 1/3],$

$[0, 0, 0, 0]]], (0, 1))$



b) Program to find rank of matrix.

```
→ import numpy as np
my_matrix = np.array([[1, 2, 1], [3, 4, 7],
                      [3, 6, 3]])
print("Matrix")
for row in my_matrix:
    print(row)
rank = np.linalg.matrix_rank(my_matrix)
print("Rank of given matrix is: ", rank)
```

O/P:

Matrix

[1 2 1]

[3 4 7]

[3 6 3]

Rank of the given matrix is: 2

## Practical 5.

Aim: Enter a vector B and find the projection of B orthogonal to given vector u.

```
→ import numpy as np
def opprojection (of_vec, on_vec):
    v1 = np.array (of_vec)
    v2 = np.array (on_vec)
    scal = np.dot (v1, v2) / np.dot (v2, v2)
    vec = scal * v2
    return round (scal, 10), np.around (vec,
    decimal = 10)
print (opprojection ([4, 0, 4, 0], [1, 0, 0, 0]))
print (opprojection ([4, 0, 4, 0], [8, 0, 2, 0]))
```

O/p:

```
(np.float64(4.0), array([4., 0., 0., 0.]))
(np.float64(0.5882352941), array([4.7058825]
```