

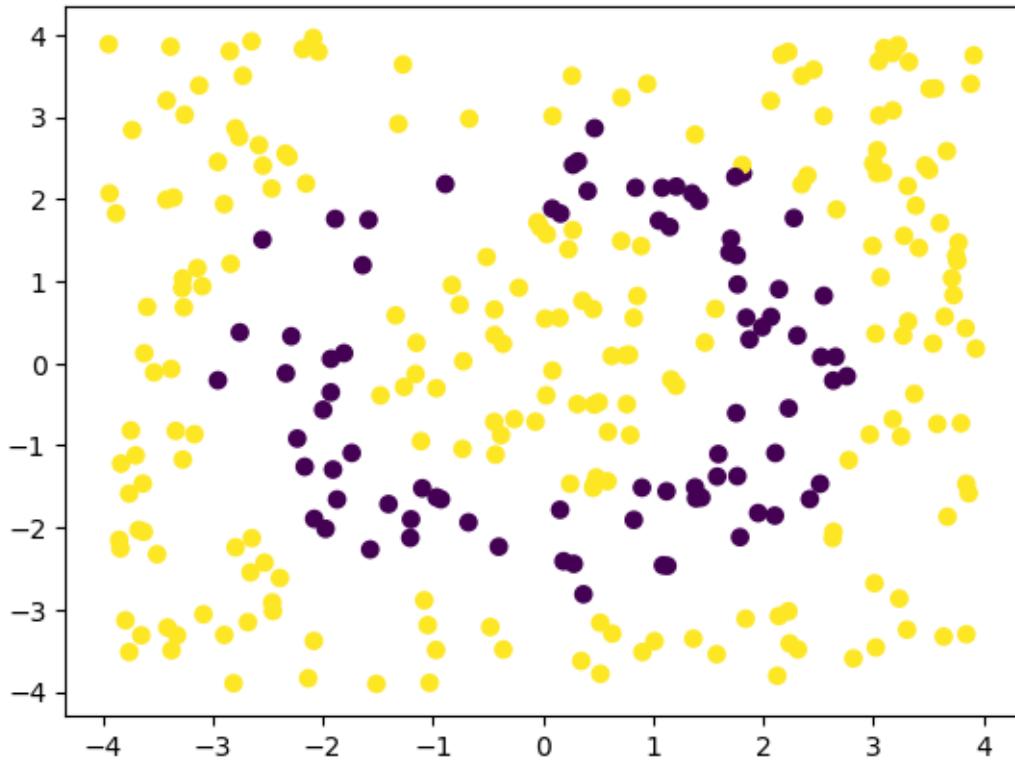
mmo

November 23, 2025

```
[1]: import numpy as np, matplotlib.pyplot as plt, torch
from pymoo.algorithms.moo.nsga2 import NSGA2
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from pymoo.optimize import minimize
from pymoo.termination import get_termination
from pymoo.visualization.scatter import Scatter
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from pymoo.termination import get_termination
from pymoo.optimize import minimize
from pymoo.visualization.scatter import Scatter
from pymoo.problems.functional import FunctionalProblem
```

```
[2]: def decison_bound (x,y):
    return x**2 + y**2 <=3 or x**2 + y**2 >=9
def generate_data (n=100, bound=decison_bound):
    X = np.random.uniform(-4,4,(n,2))
    Y = np.array([1 if bound(x[0],x[1]) else 0 for x in X])
    return X,Y

X,Y = generate_data(300)
plt.scatter(X[:,0],X[:,1],c=Y)
plt.show()
```



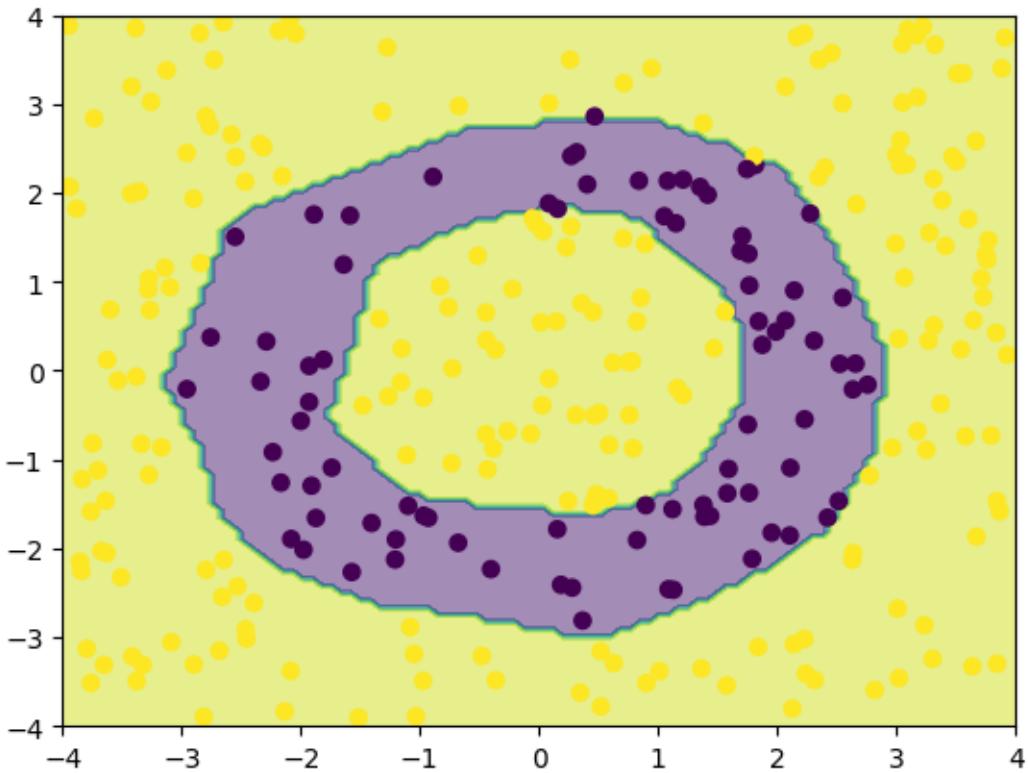
```
[3]: from torch.utils.data import TensorDataset, DataLoader
from torch import nn, optim
dataset = TensorDataset(torch.tensor(X).float(), torch.tensor(Y).long())
dataloader = DataLoader(dataset, batch_size=32, shuffle=True)
class SimpleNN (nn.Module):
    def __init__(self):
        super().__init__()
        self.net = nn.Sequential(
            nn.Linear(2,16),
            nn.ReLU(),
            nn.Linear(16,16),
            nn.ReLU(),
            nn.Linear(16,16),
            nn.ReLU(),
            nn.Linear(16,16),
            nn.ReLU(),
            nn.Linear(16,2)
        )
    def forward (self,x):
        return self.net(x)
model = SimpleNN()
```

```

criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=0.001)
for epoch in range(100):
    for xb, yb in dataloader:
        pred = model(xb)
        loss = criterion(pred, yb)
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
    if epoch % 10 == 0:
        print(f"Epoch {epoch}, Loss: {loss.item():.4f}")
# Visualize decision boundary
xx, yy = np.meshgrid(np.linspace(-4,4,100), np.linspace(-4,4,100))
grid = torch.tensor(np.c_[xx.ravel(), yy.ravel()]).float()
with torch.no_grad():
    Z = model(grid).argmax(dim=1).numpy().reshape(xx.shape)
plt.contourf(xx, yy, Z, alpha=0.5)
plt.scatter(X[:,0],X[:,1],c=Y)
plt.show()

```

Epoch 0, Loss: 0.7300
 Epoch 10, Loss: 0.6859
 Epoch 20, Loss: 0.5873
 Epoch 30, Loss: 0.4619
 Epoch 40, Loss: 0.1041
 Epoch 50, Loss: 0.1040
 Epoch 60, Loss: 0.0803
 Epoch 70, Loss: 0.1154
 Epoch 80, Loss: 0.0108
 Epoch 90, Loss: 0.0676



```
[46]: def make_cf_problem(model, x_star, Y_prime, X_obs, weights):

    model.eval()

    # ----- numpy pymoo numpy -----
    x_star_t = x_star.detach().cpu()
    X_obs_t = X_obs.detach().cpu()
    Y_prime_t = Y_prime.detach().cpu()
    w_t = weights.detach().cpu()

    x_star_np = x_star_t.numpy()                      # shape: (p,)
    X_obs_np = X_obs_t.numpy()                        # shape: (k, p)
    w_np = w_t.numpy()                                # shape: (k,)
    p = x_star_np.shape[0]                            #      p

    #      min/max
    xl = X_obs_np.min(axis=0)
    xu = X_obs_np.max(axis=0)

    feature_range = X_obs_np.max(axis=0) - X_obs_np.min(axis=0)
    feature_range[feature_range == 0] = 1.0      # 0
```

```

def delta_G_vec(x, y):
    # normalized |x - y| in [0, 1]
    return np.minimum(np.abs(x - y) / feature_range, 1.0)

# ----- 4      elementwise  1   x -----
# 1) Validity o1(f(x), Y') = 0 if f(x) in Y', else inf_{y' in Y'} |f(x) - y'|
#     f(x)      argmax Y'
#     0/1
def o1_validity(x):
    x_t = torch.from_numpy(x.astype(np.float32)).unsqueeze(0)  # shape: (1, p)
    with torch.no_grad():
        logits = model(x_t)                      # shape: (1, num_classes)
        y_hat_class = int(logits.argmax(dim=1).item()) #

    # Y_prime_t      1D
    target_labels = Y_prime_t.view(-1).long().tolist()

    # formal definition:
    # if f(x) in Y' -> 0
    # else inf_{y' in Y'} |f(x) - y'|, 0/1 -> 1
    if y_hat_class in target_labels:
        return 0.0
    else:
        return 1.0

# 2) Similarity x*
def o2_similarity(x):
    return float(delta_G_vec(x, x_star_np).mean())
EPS = 1e-6      # or something like 1e-8

def o3_sparsity(x):
    # ||x - x*||_0 = number of coordinates that changed
    diff = np.abs(x - x_star_np) > EPS
    return float(diff.sum())

def o4_plausibility(x):
    diffs = (X_obs_np - x) / feature_range          # (k, p)
    per_sample = np.sqrt((diffs ** 2).mean(axis=1))  # RMS distance per sample
    w_np_norm = w_np / w_np.sum()
    return float((per_sample * w_np_norm).sum())

objs = [o1_validity, o2_similarity, o3_sparsity, o4_plausibility]

```

```

problem = FunctionalProblem(
    n_var=p,
    objs=objs,
    xl=xl,
    xu=xu,
    elementwise=True #      x
)

return problem

```

```

[61]: for x, y in dataloader:
    x_star = torch.tensor([-3.0, -3.0])           # original feature vector, ↴
    ↴ tensor shape (p,)
    y_star = model(x_star.unsqueeze(0)).argmax(dim=1)           # original ↴
    ↴ label, tensor scalar
    Y_prime = 1 - y_star # target label = opposite class, still a tensor
    break

X_obs = dataset.tensors[0]                      # (k, p)
weights = torch.ones(len(X_obs)) / len(X_obs)    # normalized weights

# model:      PyTorch
# x_star:     shape (p,)
# Y_prime:    shape (n_y,)   tensor([1])
# X_obs:      shape (k, p)
# weights:    shape (k,)     weights.sum() == 1

problem = make_cf_problem(model, x_star, Y_prime, X_obs, weights)
print(f'problem: \n{x_star: {x_star} dtype={x_star.dtype}}\n{y_star} dtype={y_star.dtype}\nY_prime: {Y_prime} dtype={Y_prime.dtype}\n')

```

```

problem:
# name: FunctionalProblem
# n_var: 2
# n_obj: 4
# n_ieq_constr: 0
# n_eq_constr: 0

x_star: tensor([-3., -3.]) dtype=torch.float32
y_star: tensor([1]) dtype=torch.int64
Y_prime: tensor([0]) dtype=torch.int64

```

```

[62]: # 3. NSGA-II
algorithm = NSGA2(pop_size=200)

# 4.

```

```

termination = get_termination("n_gen", 150)

# 5.
res = minimize(
    problem,
    algorithm,
    termination,
    seed=1,
    verbose=True
)

F_mmo = res.F  # shape (n_points, 4) - 4
X_mmo = res.X  # x counterfactual

```

n_gen	n_eval	n_nds	eps	indicator
1	200	24	-	-
2	400	38	0.0161086118	f
3	600	56	0.0283300066	ideal
4	800	84	0.2918553079	nadir
5	1000	112	0.0161482289	ideal
6	1200	155	0.0029280554	f
7	1400	192	0.0016162887	f
8	1600	200	0.0031595497	f
9	1800	200	0.0236131650	nadir
10	2000	200	0.0025127633	ideal
11	2200	200	0.0008021693	f
12	2400	200	0.0016311007	f
13	2600	200	0.0020713096	f
14	2800	200	0.0028266040	f
15	3000	200	0.0007672678	f
16	3200	200	0.0012367182	f
17	3400	200	0.0014434369	f
18	3600	200	0.0017924985	f
19	3800	200	0.0020773360	f
20	4000	200	0.0021984108	f
21	4200	200	0.0022855866	f
22	4400	200	0.0024667144	f
23	4600	200	0.0027248130	ideal
24	4800	200	0.0010185664	f
25	5000	200	0.0012098361	f
26	5200	200	0.0014922058	f
27	5400	200	0.0616817970	nadir
28	5600	200	0.0005739704	f
29	5800	200	0.0008859201	f
30	6000	200	0.0012630944	f
31	6200	200	0.0016250452	f

32	6400	200	0.0017435239	f
33	6600	200	0.0018781713	f
34	6800	200	0.0020403752	f
35	7000	200	0.0021949866	f
36	7200	200	0.0021579430	f
37	7400	200	0.0023719035	f
38	7600	200	0.0024793777	f
39	7800	200	0.0024438316	f
40	8000	200	0.0025453579	f
41	8200	200	0.0006518537	f
42	8400	200	0.0011084829	f
43	8600	200	0.0013903594	f
44	8800	200	0.0020027985	f
45	9000	200	0.0021865842	f
46	9200	200	0.1499866316	nadir
47	9400	200	0.0005469937	f
48	9600	200	0.0012034132	f
49	9800	200	0.0013799873	f
50	10000	200	0.1748723706	nadir
51	10200	200	0.0007089263	f
52	10400	200	0.0012279786	f
53	10600	200	0.0014311530	f
54	10800	200	0.0018282268	f
55	11000	200	0.0019844647	f
56	11200	200	0.0021402982	f
57	11400	200	0.0028467112	f
58	11600	200	0.0005277270	f
59	11800	200	0.0010995733	f
60	12000	200	0.0015174655	f
61	12200	200	0.0018576030	f
62	12400	200	0.0021367447	f
63	12600	200	0.0024039789	f
64	12800	200	0.0025045061	f
65	13000	200	0.0005676409	f
66	13200	200	0.0011288650	f
67	13400	200	0.0013698472	f
68	13600	200	0.0016698545	f
69	13800	200	0.0020714754	f
70	14000	200	0.0020013490	f
71	14200	200	0.0020073841	f
72	14400	200	0.0021773045	f
73	14600	200	0.0025943011	f
74	14800	200	0.0006942584	f
75	15000	200	0.0012709383	f
76	15200	200	0.0020286453	f
77	15400	200	0.0022007383	f
78	15600	200	0.0018613290	f
79	15800	200	0.0027663059	f

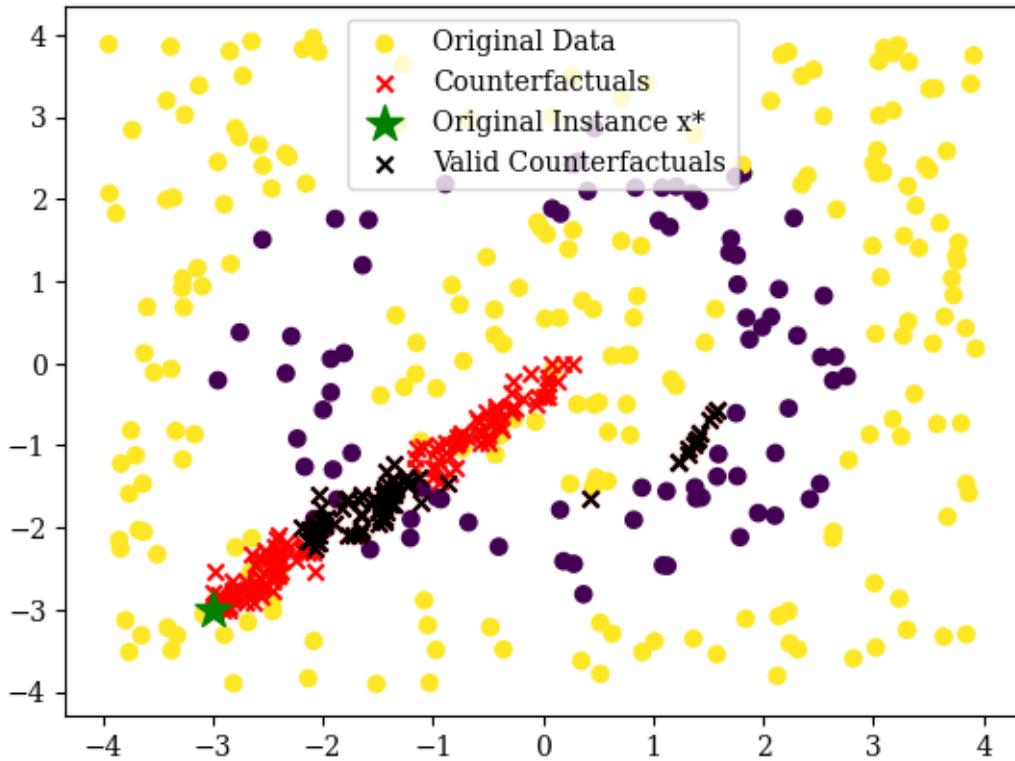
80	16000	200	0.0007024758	f
81	16200	200	0.0012642045	f
82	16400	200	0.0015793193	f
83	16600	200	0.0020380773	f
84	16800	200	0.0019854444	f
85	17000	200	0.0024173950	f
86	17200	200	0.0023310783	f
87	17400	200	0.0024011083	f
88	17600	200	0.0023468347	f
89	17800	200	0.0024014122	f
90	18000	200	0.0025506875	f
91	18200	200	0.0006558593	f
92	18400	200	0.0012192895	f
93	18600	200	0.0016064577	f
94	18800	200	0.0015203262	f
95	19000	200	0.0016269841	f
96	19200	200	0.0018887636	f
97	19400	200	0.0019557499	f
98	19600	200	0.0021626475	f
99	19800	200	0.0021709597	f
100	20000	200	0.0024227786	f
101	20200	200	0.0024543355	f
102	20400	200	0.0024662093	f
103	20600	200	0.0025881959	f
104	20800	200	0.0006869396	f
105	21000	200	0.0010990010	f
106	21200	200	0.0014809536	f
107	21400	200	0.0016570267	f
108	21600	200	0.0018601334	f
109	21800	200	0.0020965129	f
110	22000	200	0.0020427781	f
111	22200	200	0.0022907762	f
112	22400	200	0.0024092551	f
113	22600	200	0.0025829932	f
114	22800	200	0.0007899281	f
115	23000	200	0.0013524006	f
116	23200	200	0.0017630601	f
117	23400	200	0.0021071434	f
118	23600	200	0.0021589078	f
119	23800	200	0.0023120683	f
120	24000	200	0.0025575761	f
121	24200	200	0.0007593238	f
122	24400	200	0.0016386373	f
123	24600	200	0.0018383481	f
124	24800	200	0.0022710158	f
125	25000	200	0.0025229971	f
126	25200	200	0.0005995640	f
127	25400	200	0.0011227219	f

128	25600	200	0.0013707302	f
129	25800	200	0.0017976421	f
130	26000	200	0.0020612335	f
131	26200	200	0.0022007110	f
132	26400	200	0.0021280011	f
133	26600	200	0.0023599920	f
134	26800	200	0.0023482060	f
135	27000	200	0.0022551189	f
136	27200	200	0.0022732140	f
137	27400	200	0.0023231268	f
138	27600	200	0.0025053903	f
139	27800	200	0.0006328135	f
140	28000	200	0.0011412854	f
141	28200	200	0.0015436657	f
142	28400	200	0.0020454520	f
143	28600	200	0.0018502364	f
144	28800	200	0.0021361437	f
145	29000	200	0.0020407645	f
146	29200	200	0.0024657630	f
147	29400	200	0.0031008839	f
148	29600	200	0.0007825100	f
149	29800	200	0.0017450532	f
150	30000	200	0.0020029516	f

```
[109]: validated_F_mmo=np.array([f for f in F_mmo if f[0]==0])
validated_X_mmo=np.array([X_mmo[i] for i in range(len(F_mmo)) if F_mmo[i][0]==0])
not_validated_F_mmo=np.array([f for f in F_mmo if f[0]!=0])
not_validated_X_mmo=np.array([X_mmo[i] for i in range(len(F_mmo)) if F_mmo[i][0]!
                           !=0])
not_paterno_front_X=np.array([X_obs[i] for i in range(len(X_obs)) if i not in
                           res.opt.get("idx")]) # observed instances not in pareto front
```

```
[110]: # visualize the counterfactuals candidates in original data space
plt.figure()
plt.scatter(X[:,0],X[:,1],c=Y, label='Original Data')
plt.scatter(X_mmo[:,0], X_mmo[:,1], marker='x', c='red',_
           label='Counterfactuals')
plt.scatter(x_star[0], x_star[1], marker='*', c='green', s=200, label='Original_
           Instance x*')
# color black for valid counterfactuals
plt.scatter(validated_X_mmo[:,0], validated_X_mmo[:,1], marker='x', c='black',_
           label='Valid Counterfactuals')
plt.legend()
```

```
[110]: <matplotlib.legend.Legend at 0x204943d4310>
```

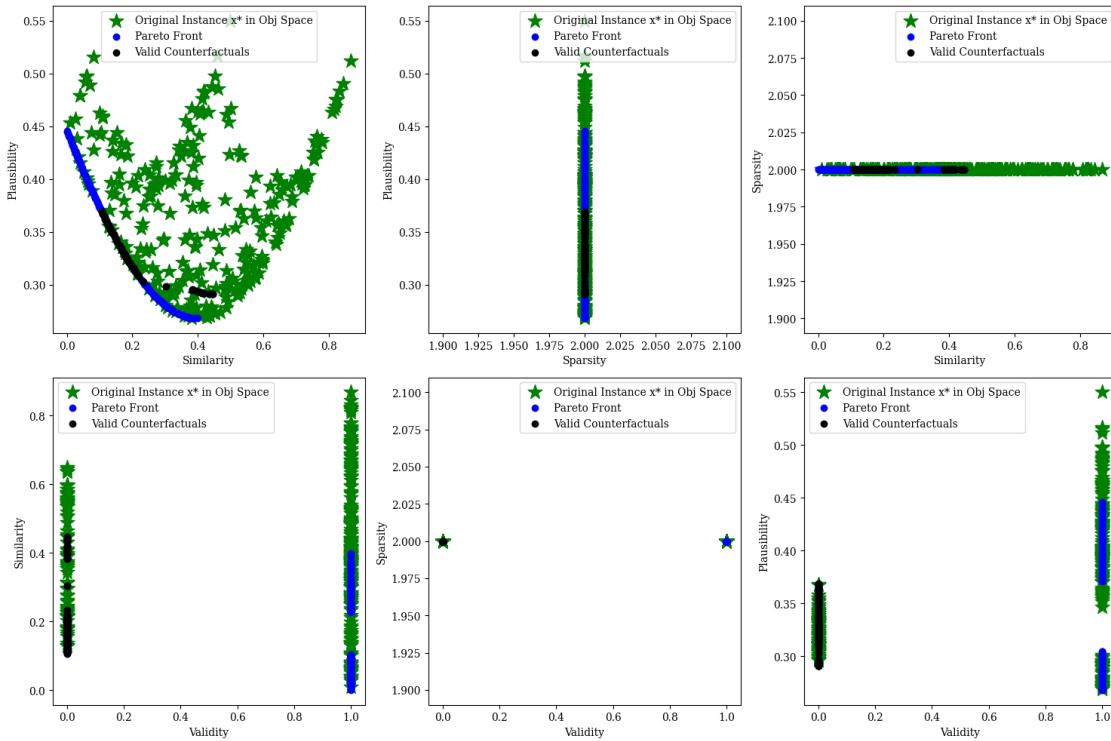


```
[111]: # visualize the Pareto front in objective space
fig, ax = plt.subplots(2, 3, figsize=(15, 10))

# Create pairs of objective indices to plot
obj_pairs = [(1, 3), (2, 3), (1, 2), (0, 1), (0, 2), (0, 3)]
obj_labels = ['Validity', 'Similarity', 'Sparsity', 'Plausibility']

for i, (obj_x, obj_y) in enumerate(obj_pairs):
    row = i // 3
    col = i % 3
    ax[row, col].scatter(problem.evaluate(X)[:, obj_x],
                          problem.evaluate(X)[:, obj_y],
                          marker='*', c='green', s=200, label='Original Instance')
    ↪x* in Obj Space')
    ax[row, col].scatter(F_mmo[:, obj_x], F_mmo[:, obj_y], c='blue',
    ↪label='Pareto Front')
    ax[row, col].scatter(valided_F_mmo[:, obj_x], valided_F_mmo[:, obj_y],
    ↪c='black', label='Valid Counterfactuals')
    ax[row, col].set_xlabel(obj_labels[obj_x])
    ax[row, col].set_ylabel(obj_labels[obj_y])
    ax[row, col].legend()
```

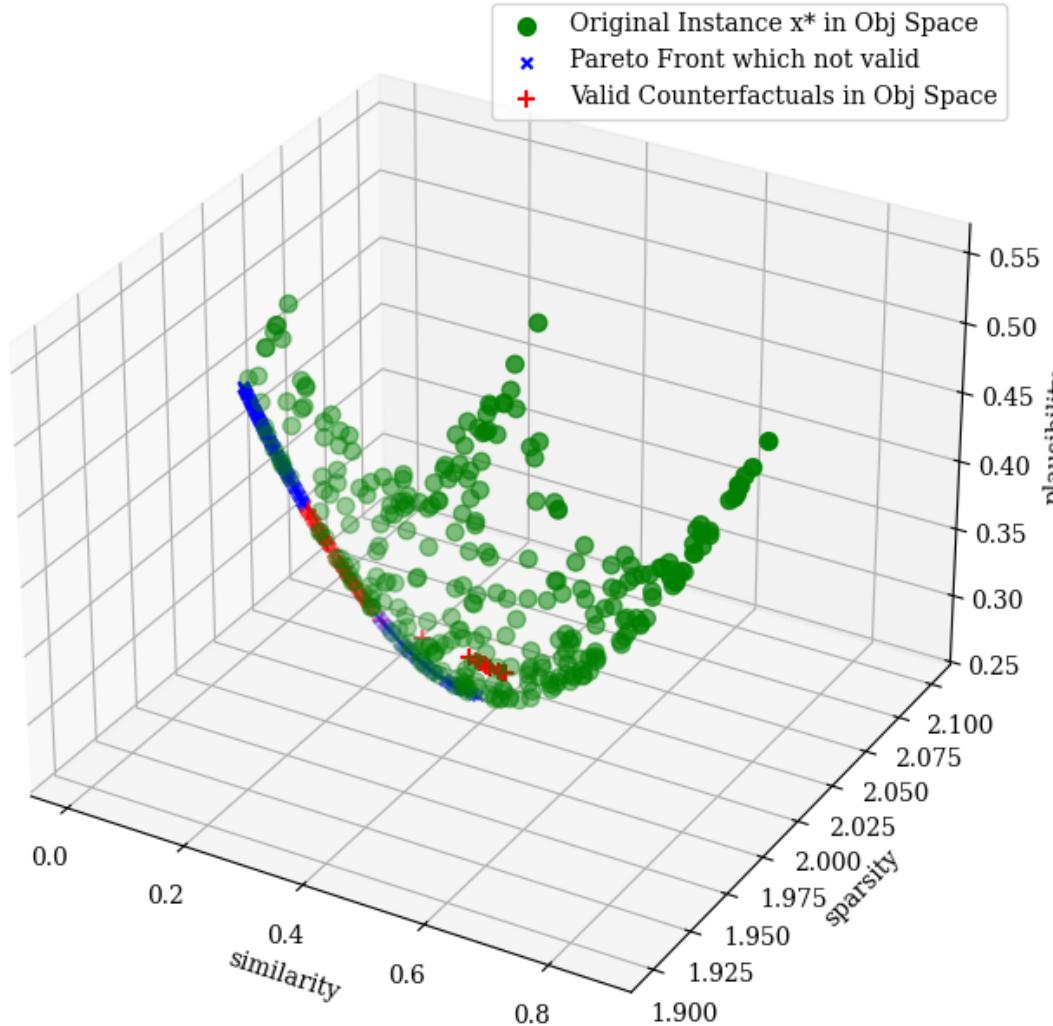
```
plt.tight_layout()
plt.show()
```



```
[114]: # visualize the Pareto front in 3D objective space
plt.figure(figsize=(10, 8))
from mpl_toolkits.mplot3d import Axes3D
ax = plt.axes(projection='3d')

ax.scatter(problem.evaluate(X)[:,1],
           problem.evaluate(X)[:,2],
           problem.evaluate(X)[:,3],
           marker='.', c='green', s=200, label='Original Instance x* in Obj\u202aSpace')
ax.scatter(not_valided_F_mmo[:,1], not_valided_F_mmo[:,2], not_valided_F_mmo[:,3], c='blue', label='Pareto Front which not valid', marker='x', s=20)
# color black for valid counterfactuals
ax.scatter(valided_F_mmo[:,1], valided_F_mmo[:,2], valided_F_mmo[:,3], c='red', label='Valid Counterfactuals in Obj Space', marker='+', s=50)
ax.set_xlabel('similarity')
ax.set_ylabel('sparsity')
ax.set_zlabel('plausibility')
```

```
plt.legend()  
plt.show()
```



```
[12]: poi=np.array([[0,0]])  
problem.evaluate(poi), model(torch.tensor(poi).float().unsqueeze(0)).  
argmax(dim=1), Y_prime
```

```
[12]: (array([[0.          , 0.20342529, 2.          , 0.26868186]]),  
tensor([[0, 0]]),  
tensor(1))
```