$$\boldsymbol{r}_1 = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix}$$

$$\boldsymbol{r}_3 = \begin{pmatrix} x_2 \\ y_2 \\ R + z_2 \end{pmatrix}$$

$\boldsymbol{\mu}_1$

$\boldsymbol{\mu}_2$

R

z

$\boldsymbol{r}_0$

$$\boldsymbol{r}_3 = \begin{pmatrix} 0 \\ 0 \\ R \end{pmatrix}$$