# Paperwork on Degree Project: Machine Learning Based Fault Prediction for Real-time Scheduling on Shop-floor

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Ensemble learning is the process by which multiple models, such as classifiers or experts,

### Ensemble Learning

are strategically generated and combined to solve a particular computational intelligence problem. Ensemble learning is primarily used to improve the (classification, prediction, function approximation, etc.) performance of a model, or reduce the likelihood of an unfortunate selection of a poor one. Other applications of ensemble learning include assigning a confidence to the decision made by the model, selecting optimal (or near optimal) features, data fusion, incremental learning, nonstationary learning and errorcorrecting. (Robi Polikar (2009) Ensemble learning. Scholarpedia, 4(1):2776.)[1] Kunwar P. Singh et al. developed tree ensemble models for seasonal discrimination and air quality prediction and found that their models outperforms SVMs(Atmospheric Environment)[2]. Anders Elowsson and Anders Friberg used ensemble learning model to predict performed dynamics of music audio and found the result well above that of individual human listeners (The Journal of the Acoustical Society of America 141, 2224 (2017))[3]. Kunwar P. Sing and Shikha Gupta used a few simple non-quantum mechanical molecular descriptors as an ensemble classifier to discriminate toxic and non-toxic chemicals and predict toxicity of chemicals in multi-species (Toxicology and Applied Pharmacology)[4]. Jinrong Bai and Junfeng Wang developed a multi-view ensemble learning model to improve malware detection and successfully reduced false alarm rate(Security

#### Overview

## Algorithm Details

and Communication Networks)[5].

Overall, medium computation time, high model complexity. Capable of learning complex patterns. Tricky model choice.

Step 1:

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Step n: equations

# References

- [1] Hassan K Khalil. *Nonlinear systems*. Prentice Hall, Upper Saddle river, 3. edition, 2002. ISBN 0-13-067389-7.
- [2] Tobias Oetiker, Hubert Partl, Irene Hyna, and Elisabeth Schlegl. The Not So Short Introduction to  $\not\!\! ET_E\!\! X \not\!\! 2_{\mathcal E}$ . Oetiker, OETIKER+PARTNER AG, Aarweg 15, 4600 Olten, Switzerland, 2008. http://www.ctan.org/info/lshort/.
- [3] Shankar Sastry. Nonlinear systems: analysis, stability, and control, volume 10. Springer, New York, N.Y., 1999. ISBN 0-387-98513-1.